

Gradient Descent

Friday, 16 March 2018 20:17

m : # training set

θ : parameter. $h_{\theta}(x)$: hypothesis function:

loss function: $J(\theta) = \frac{1}{2} \sum_{j=1}^m (h_{\theta}(x^{(j)}) - y^{(j)})^2$

min: $J(\theta)$

$$\theta_i := \theta_i - \alpha \frac{\partial}{\partial \theta_i} J(\theta)$$

$$\frac{\partial}{\partial \theta_i} J(\theta) = \frac{1}{2} \cdot 2 (h_{\theta}(x) - y) \cdot \frac{\partial}{\partial \theta_i} (h_{\theta}(x) - y)$$

$$= (h_{\theta}(x) - y) \cdot \frac{\partial}{\partial \theta_i} (\theta_0 x_0 + \dots + \theta_n x_n - y)$$

$$= (h_{\theta}(x) - y) \cdot x_i$$

update: $\theta_i := \theta_i - \alpha \sum_{j=1}^m (h_{\theta}(x^{(j)}) - y^{(j)}) \cdot x_i^{(j)}$
learning rate

repeat until convergence. (Batch Gradient Descent)

Stochastic Gradient Descent

Repeat {

For $j=1$ to m {

$$\theta_i := \theta_i - \alpha (h_{\theta}(x^{(j)}) - y^{(j)}) \cdot x_i^{(j)} \text{ for all } i$$

}

Linear Algebra:

$$\nabla_{\theta} J = \left[\frac{\partial J}{\partial \theta_0}, \dots, \frac{\partial J}{\partial \theta_n} \right]^T \in \mathbb{R}^{n+1}$$

Thus: Gradient descent:

$$\theta := \theta - \alpha \nabla_{\theta} J \quad // \theta, J \in \mathbb{R}^{n+1}$$

$$f: \mathbb{R}^{n \times n} \rightarrow \mathbb{R} \quad f(A)$$

$$\nabla_A f(A) = \begin{bmatrix} \frac{\partial f}{\partial A_{11}} & \dots & \frac{\partial f}{\partial A_{1n}} \\ \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial A_{n1}} & \dots & \frac{\partial f}{\partial A_{nn}} \end{bmatrix}$$

Fact:

$$\text{tr}(AB) = \text{tr}(BA) \quad \text{tr}(CAB) = \text{tr}(CBA) = \text{tr}(BCA)$$

$$\nabla_A \text{tr} AB = B^T$$

$$\nabla_A \text{tr} ABA^T C = CAB + C^T A B^T$$

Design Matrix:

$$X\theta = \begin{bmatrix} (x^{(1)})^T \\ (x^{(2)})^T \\ \vdots \\ (x^{(m)})^T \end{bmatrix} \theta = \begin{bmatrix} x^{(1)T} \theta \\ x^{(2)T} \theta \\ \vdots \\ x^{(m)T} \theta \end{bmatrix} = \begin{bmatrix} h_{\theta}(x^{(1)}) \\ \vdots \\ h_{\theta}(x^{(m)}) \end{bmatrix}$$

$$\vec{y} = [y^{(1)}, \dots, y^{(m)}]^T$$

$$X\theta - y = [h(x^{(1)}) - y^{(1)}, \dots, h(x^{(m)}) - y^{(m)}]^T$$

Recall: $Z^T Z = \sum_i Z_i^T Z_i$

$$\frac{1}{2} (X\theta - y)^T (X\theta - y) = \frac{1}{2} \sum_{j=1}^m (h(x^{(j)}) - y^{(j)})^2 = J(\theta)$$

Recall: $\min J(\theta)$

$$\nabla_{\theta} \frac{1}{2} (X\theta - y)^T (X\theta - y)$$

$$= \frac{1}{2} \nabla_{\theta} (\theta^T X^T X \theta - \theta^T X^T y - y^T X \theta + y^T y)$$

$$= \frac{1}{2} \nabla_{\theta} \text{tr} (\theta^T X^T X \theta - \theta^T X^T y - y^T X \theta + y^T y)$$

$$= \frac{1}{2} [\nabla_{\theta} \text{tr} \theta \theta^T X^T X - \nabla_{\theta} \text{tr} y^T X \theta - \nabla_{\theta} \text{tr} y^T X \theta]$$

$$\nabla_{\theta} \text{tr} \theta \theta^T \underbrace{X^T X}_C = \underbrace{X^T X}_A \theta + \underbrace{X^T X}_B \theta$$

$$\nabla_{\theta} \text{tr} \underbrace{y^T X}_B \theta = X^T y$$

$$\nabla_{\theta} J(\theta) = \frac{1}{2} [X^T X \theta + X^T X \theta - X^T y - X^T y] = 0$$

$$X^T X \theta - X^T y = 0$$

$$X^T X \theta = X^T y$$

Normal Equation.

$$\theta = (X^T X)^{-1} X^T y$$