



DISCRETE MATHEMATICS FOR COMPUTER SCIENCE

Dr. QI WANG

Department of Computer Science and Engineering

Office: Room903, Nanshan iPark A7 Building

Email: wangqi@sustc.edu.cn

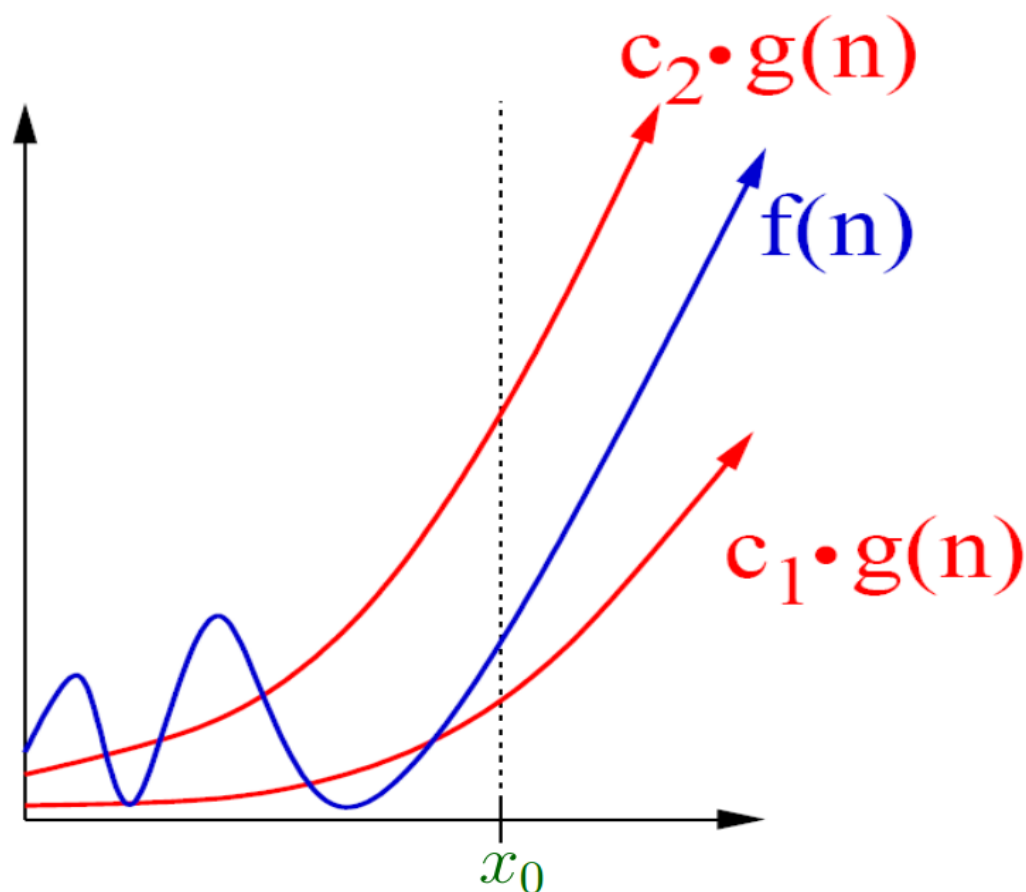
Assignment #1

Please submit your
assignments before class!



Big-Theta Notation (Big-O & Big-Omega)

- Two functions $f(n)$, $g(n)$ have the same order growth if $f(n) = O(g(n))$ and $g(n) = O(f(n))$. In this case, we say that $f(n) = \Theta(g(n))$, which is the same as $g(n) = \Theta(f(n))$.



Algorithms

- An *algorithm* is a finite sequence of **precise instructions** for performing a computation or for solving a problem.

A *computational problem* is a specification of the desired input-output relationship.

Example (Computational Problem and Algorithm)

The following procedure is an algorithm for **calculating the sum of n given numbers a_1, a_2, \dots, a_n .**

Step 1: set $S = 0$

Step 2: for $i = 1$ to n , replace S by $S + a_i$

Step 3: output S



Instance

- An *instance* of a problem is all the inputs needed to compute a solution to the problem.

Example (Instance of Problem)

$\langle 8, 3, 6, 7, 1, 2, 9 \rangle$

- A *correct algorithm* halts with the correct output for **every input instance**. We can then say that **the algorithm solves the problem**.



Time and Space Complexity

- The number of **machine operations**(addition, multiplication, comparison, replacement, etc) needed in an algorithm is the *time complexity* of the algorithm, and **amount of memory** needed is the *space complexity* of the algorithm.



Time and Space Complexity

- The number of **machine operations** (addition, multiplication, comparison, replacement, etc) needed in an algorithm is the *time complexity* of the algorithm, and **amount of memory** needed is the *space complexity* of the algorithm.

Example (Algorithm)

Step 1: set $S = 0$

Step 2: for $i = 1$ to n , replace S by $S + a_i$

Step 3: output S



Time and Space Complexity

- The number of **machine operations** (addition, multiplication, comparison, replacement, etc) needed in an algorithm is the *time complexity* of the algorithm, and **amount of memory** needed is the *space complexity* of the algorithm.

Example (Algorithm)

Step 1: set $S = 0$

Step 2: for $i = 1$ to n , replace S by $S + a_i$

Step 3: output S

Step 1 and Step 3 take **one operation**. Step 2 takes **$2n$ operations**. Therefore, altogether this algorithm takes $2n + 2$ operations. **The time complexity is $O(n)$.**



Horner's Algorithm and Its Complexity

■ Example

Consider the **evaluation** of $f(x) = 1 + 2x + 3x^2 + 4x^3$.

Direct computation takes **3** additions and **6** multiplications.

Can we do better?



Horner's Algorithm and Its Complexity

■ Example

Consider the **evaluation** of $f(x) = 1 + 2x + 3x^2 + 4x^3$.

Direct computation takes 3 additions and 6 multiplications.

Can we do better?

Another way is $f(x) = 1 + x(2 + x(3 + 4x))$, which takes 3 additions and 3 multiplications.



Horner's Algorithm and Its Complexity

■ Example

Consider the **evaluation** of $f(x) = 1 + 2x + 3x^2 + 4x^3$.

Direct computation takes **3** additions and **6** multiplications.

Can we do better?

Another way is $f(x) = 1 + x(2 + x(3 + 4x))$, which takes **3** additions and **3** multiplications.

Step 1: set $S = a_n$

Step 2: for $i = 1$ to n , replace S by $a_{n-i} + Sx$

Step 3: output S



Horner's Algorithm and Its Complexity

- Step 1: set $S = a_n$
- Step 2: for $i = 1$ to n , replace S by $a_{n-i} + Sx$
- Step 3: output S



Horner's Algorithm and Its Complexity

- Step 1: set $S = a_n$
- Step 2: for $i = 1$ to n , replace S by $a_{n-i} + Sx$
- Step 3: output S

The final value of S output at Step 3 is the desired value of $a_0 + a_1x + \cdots + a_nx^n$. The number of operations needed in this algorithm is $1 + 3n + 1 = 3n + 2$. So the time complexity of this algorithm is $O(n)$.



Time Complexity

- Determine the time complexity of the following algorithm:
 for $i := 1$ to n
 for $j := 1$ to n
 $a := 2 * n + i * j$;
 end for
 end for



Time Complexity

- Determine the time complexity of the following algorithm:

```
for  $i := 1$  to  $n$ 
  for  $j := 1$  to  $n$ 
     $a := 2 * n + i * j$ ;
  end for
end for
```

In the second loop, computing a takes **4 operations** (two multiplications, one addition, and one replacement). For each i , it takes **$4n$ operations** to complete the second loop. So it takes **$n \times 4n = 4n^2$** operations to complete the two loops. **The time complexity of this algorithm is $O(n^2)$.**



Time Complexity

- Determine the time complexity of the following algorithm:

$S := 0$

for $i := 1$ to n

 for $j := 1$ to i

$S := S + i * j;$

 end for

end for



Time Complexity

- Determine the time complexity of the following algorithm:

$S := 0$

for $i := 1$ to n

for $j := 1$ to i

$S := S + i * j;$

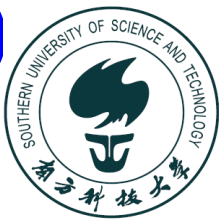
end for

end for

Computing S takes 3 operations. For each i , completing the second loop takes $3i$ operations. So altogether it takes

$$1 + \sum_{i=1}^n 3i = 1 + 3 \frac{n(n+1)}{2}$$

operations. So the complexity of this algorithm is $O(n^2)$



More on Time Complexity

■ **Example:** (Insertion Sort)

Input: $A[1 \dots n]$ is an array of numbers

for $j := 2$ to n

$key = A[j];$

$i = j - 1;$

 while $i \geq 1$ and $A[i] > key$ do

$A[i + 1] = A[i];$

$i --;$

 end while

$A[i + 1] = key;$

end for



More on Time Complexity

■ Example: (Insertion Sort)

Input: $A[1 \dots n]$ is an array of numbers

for $j := 2$ to n

$key = A[j];$

$i = j - 1;$

 while $i \geq 1$ and $A[i] > key$ do

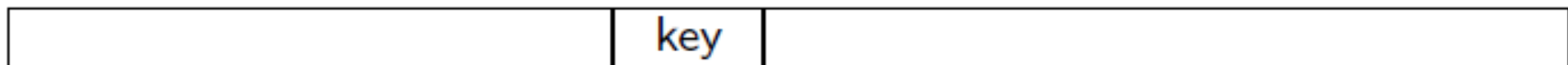
$A[i + 1] = A[i];$

$i --;$

 end while

$A[i + 1] = key;$

end for



Sorted

Unsorted

Where in the sorted part to put "key"?



Three Cases of Analysis: I

- **Best Case:** constraints on the input, other than size, resulting in the fastest possible running time for the given size.



Three Cases of Analysis: I

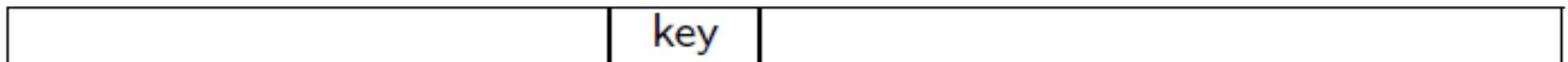
- **Best Case:** constraints on the input, other than size, resulting in the fastest possible running time for the given size.

Example: (Insertion Sort)

$$A[1] \leq A[2] \leq A[3] \leq \dots \leq A[n]$$

The number of comparisons needed is

$$\underbrace{1 + 1 + 1 + \dots + 1}_{n-1} = n - 1 = \Theta(n)$$



Sorted

Unsorted

"key" is compared to only the element right before it.



Three Cases of Analysis: II

- **Worst Case:** constraints on the input, other than size, resulting in the slowest possible running time for the given size.

Three Cases of Analysis: II

- **Worst Case:** constraints on the input, other than size, resulting in the slowest possible running time for the given size.

Example: (Insertion Sort)

$$A[1] \geq A[2] \geq A[3] \geq \dots \geq A[n]$$

The number of comparisons needed is

$$1 + 2 + 3 + \dots + (n - 1) = \frac{n(n-1)}{2} = \Theta(n^2)$$



Sorted

Unsorted

"key" is compared to everything element before it.



Three Cases of Analysis: III

- **Average Case:** average running time over every possible type of input for the given size (usually involve probabilities of different types of input)



Three Cases of Analysis: III

- **Average Case:** average running time over every possible type of input for the given size (usually involve probabilities of different types of input)

Example: (Insertion Sort)

$\Theta(n^2)$ assuming that each of the $n!$ instances are equally likely



Sorted

Unsorted

On average, "key" is compared to half of the elements before it.



Some Thoughts on Algorithm Design

- **Algorithm Design**, is mainly about designing algorithms that have **small Big- O running time**.



Some Thoughts on Algorithm Design

- **Algorithm Design**, is mainly about designing algorithms that have **small Big- O running time**.
- Being able to do good algorithm design lets you identify the **hard parts** of your problem and deal with them **effectively**.



Some Thoughts on Algorithm Design

- **Algorithm Design**, is mainly about designing algorithms that have **small Big- O running time**.
- Being able to do good algorithm design lets you identify the **hard parts** of your problem and deal with them **effectively**.
- Too often, programmers try to solve problems using **brute force techniques** and end up with **slow complicated code**!



Some Thoughts on Algorithm Design

- **Algorithm Design**, is mainly about designing algorithms that have **small Big- O running time**.
- Being able to do good algorithm design lets you identify the **hard parts** of your problem and deal with them **effectively**.
- Too often, programmers try to solve problems using **brute force techniques** and end up with **slow complicated code**!
- A few hours of abstract thought devoted to algorithm design could have **speeded up the solution substantially and simplified it**!



Dealing with Hard Problems

- What happens if you **can't** find an efficient algorithm for a given problem?



Dealing with Hard Problems

- What happens if you **can't** find an efficient algorithm for a given problem?

Blame yourself.



I couldn't find a polynomial-time algorithm.
I guess I am too dumb.

Dealing with Hard Problems

- What happens if you **can't** find an efficient algorithm for a given problem?

Show that **no**-efficient algorithm exists.



I couldn't find a polynomial-time algorithm,
because **no** such algorithm exists.

Dealing with Hard Problems

- Showing that a problem has an efficient algorithm is, relatively easy:



Dealing with Hard Problems

- Showing that a problem has an efficient algorithm is, **relatively easy**:
 - “All” that is needed is to demonstrate an algorithm.



Dealing with Hard Problems

- Showing that a problem has an efficient algorithm is, **relatively easy**:
“All” that is needed is to demonstrate an algorithm.
- Proving that no efficient algorithm exists for a particular problem is **difficult**:



Dealing with Hard Problems

- Showing that a problem has an efficient algorithm is, **relatively easy**:
“All” that is needed is to demonstrate an algorithm.
- Proving that no efficient algorithm exists for a particular problem is **difficult**:

How can we prove the non-existence of something?



Dealing with Hard Problems

- Showing that a problem has an efficient algorithm is, **relatively easy**:
“All” that is needed is to demonstrate an algorithm.
- Proving that no efficient algorithm exists for a particular problem is **difficult**:

How can we prove the non-existence of something?

We will now learn about **NP-Complete** problems, which provide us with a way to approach this question.



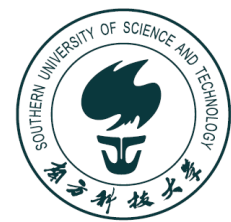
Introduction

- A very large class of thousands of practical problems for which it is **not** known if the problems have “**efficient**” solutions.



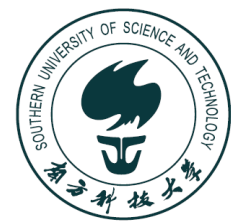
Introduction

- A very large class of thousands of practical problems for which it is **not** known if the problems have “**efficient**” solutions.
- It is known that if **any one** of the **NP-Complete** problems has an efficient solution then **all** of the NP-Complete problems have efficient solutions.



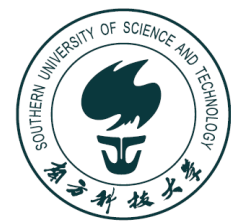
Introduction

- A very large class of thousands of practical problems for which it is **not** known if the problems have “**efficient**” solutions.
- It is known that if **any one** of the **NP-Complete** problems has an efficient solution then **all** of the NP-Complete problems have efficient solutions.
- Researchers have spent innumerable man-years trying to find efficient solutions to these problems but **failed**.



Introduction

- A very large class of thousands of practical problems for which it is **not** known if the problems have “**efficient**” solutions.
- It is known that if **any one** of the **NP-Complete** problems has an efficient solution then **all** of the NP-Complete problems have efficient solutions.
- Researchers have spent innumerable man-years trying to find efficient solutions to these problems but **failed**.
- So, **NP-Complete** problems are very likely to be **hard**.



Introduction

- A very large class of thousands of practical problems for which it is **not** known if the problems have “**efficient**” solutions.
- It is known that if **any one** of the **NP-Complete** problems has an efficient solution then **all** of the NP-Complete problems have efficient solutions.
- Researchers have spent innumerable man-years trying to find efficient solutions to these problems but **failed**.
- So, **NP-Complete** problems are very likely to be **hard**.
- What do you do: prove that **your problem is NP-Complete**.



Introduction

What do you actually do:



I couldn't find a polynomial-time algorithm,
but neither could all these other smart people!

Encoding the Inputs of Problems

- **Complexity** of a problem is measure w.r.t **the size of input**.



Encoding the Inputs of Problems

- **Complexity** of a problem is measure w.r.t **the size of input**.
- In order to formally discuss how hard a problem is, we need to be **much more** formal than before about the **input size** of a problem.



The Input Size of Problems

- The **input size** of a problem might be defined in a number of ways.



The Input Size of Problems

- The **input size** of a problem might be defined in a number of ways.

Definition The **input size** of a problem is the **minimum number** of bits ($\{0,1\}$) needed to **encode** the input of the problem.



The Input Size of Problems

- The **input size** of a problem might be defined in a number of ways.

Definition The **input size** of a problem is the **minimum number** of bits ($\{0,1\}$) needed to **encode** the input of the problem.

- The **exact** input size s , determined by an **optimal** encoding method, is **hard** to compute in most cases.



The Input Size of Problems

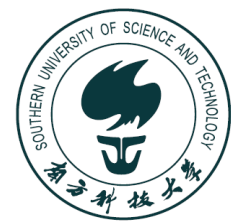
- The **input size** of a problem might be defined in a number of ways.

Definition The **input size** of a problem is the **minimum number** of bits ($\{0,1\}$) needed to **encode** the input of the problem.

- The **exact** input size s , determined by an **optimal** encoding method, is **hard** to compute in most cases.

However, we do **not** need to determine s **exactly**.

For most problems, it is sufficient to choose some **natural**, and (usually) **simple**, encoding and use the size s of this encoding.



Input Size Example: Composite

■ Example:

Given a positive integer n , are there integers $j, k > 1$ such that $n = jk$? (i.e., **is n a composite number?**)



Input Size Example: Composite

■ Example:

Given a positive integer n , are there integers $j, k > 1$ such that $n = jk$? (i.e., **is n a composite number?**)

Question:

What is the input size of this problem?



Input Size Example: Composite

■ Example:

Given a positive integer n , are there integers $j, k > 1$ such that $n = jk$? (i.e., **is n a composite number?**)

Question:

What is the input size of this problem?

Any integer $n > 0$ can be represented in the **binary number system** as a string $a_0a_1 \cdots a_k$ of length $\lceil \log_2(n+1) \rceil$.

Thus, a natural measure of input size is $\lceil \log_2(n+1) \rceil$ (or just **$\log_2 n$**)



Input Size Example: Sorting

■ Example:

Sort n integer a_1, \dots, a_n



Input Size Example: Sorting

■ Example:

Sort n integer a_1, \dots, a_n

Question:

What is the input size of this problem?



Input Size Example: Sorting

■ Example:

Sort n integer a_1, \dots, a_n

Question:

What is the input size of this problem?

Using fixed length encoding, we write a_i as a binary string of length $m = \lceil \log_2 \max(|a_i| + 1) \rceil$.

This coding gives an input size nm .



Complexity in terms of Input Size

- **Example:** (Composite)

The naive algorithm for determining whether n is composite compares n with the first $n - 1$ numbers to see if **any of them divides n**



Complexity in terms of Input Size

■ **Example:** (Composite)

The naive algorithm for determining whether n is composite compares n with the first $n - 1$ numbers to see if **any of them divides n**

This makes $\Theta(n)$ **comparisons**, so it might seem **linear** and very **efficient**.



Complexity in terms of Input Size

■ **Example:** (Composite)

The naive algorithm for determining whether n is composite compares n with the first $n - 1$ numbers to see if **any of them divides n**

This makes $\Theta(n)$ **comparisons**, so it might seem **linear** and very **efficient**.

But, note that the input size of this problem is $\text{size}(n) = \log_2 n$, so the number of comparisons performed is actually $\Theta(n) = \Theta(2^{\text{size}(n)})$, which is **exponential**.



Input Size of Problems

- **Definition** Two positive functions $f(n)$ and $g(n)$ are of the same type if

$$c_1 g(n^{a_1})^{b_1} \leq f(n) \leq c_2 g(n^{a_2})^{b_2}$$

for all large n , where $a_1, b_1, c_1, a_2, b_2, c_2$ are some positive constants.



Input Size of Problems

- **Definition** Two positive functions $f(n)$ and $g(n)$ are of the **same type** if

$$c_1 g(n^{a_1})^{b_1} \leq f(n) \leq c_2 g(n^{a_2})^{b_2}$$

for all large n , where $a_1, b_1, c_1, a_2, b_2, c_2$ are **some** positive constants.

Example:

All polynomials are of the **same type**, but *polynomials* and *exponentials* are of **different types**.



Input Size Example: Integer Multiplication

- **Example:** (Integer Multiplication problem)

Compute $a \times b$.



Input Size Example: Integer Multiplication

- **Example:** (Integer Multiplication problem)

Compute $a \times b$.

Question:

What is the input size of this problem?



Input Size Example: Integer Multiplication

- **Example:** (Integer Multiplication problem)

Compute $a \times b$.

Question:

What is the input size of this problem?

The minimum input size is

$$s = \lceil \log_2(a + 1) \rceil + \lceil \log_2(b + 1) \rceil.$$

A natural choice is to use $t = \log_2 \max(a, b)$ since $\frac{s}{2} \leq t \leq s$.



Decision Problems

- **Definition** A *decision problem* is a question that has two possible answers: *yes* and *no*.



Decision Problems

- **Definition** A *decision problem* is a question that has two possible answers: *yes* and *no*.

If L is the problem, and x is the input, we will often write $x \in L$ to denote a *yes* answer and $x \notin L$ to denote a *no* answer.



Optimization Problems

- **Definition** An *optimization problem* requires an answer that is an optimal configuration.



Optimization Problems

- **Definition** An *optimization problem* requires an answer that is an optimal configuration.

An *optimization problem* usually has a corresponding *decision problem*.



Optimization Problems

- **Definition** An *optimization problem* requires an answer that is an optimal configuration.

An *optimization problem* usually has a corresponding *decision problem*.

Examples:

Knapsack vs. Decision Knapsack (DKnapsack)

Subset Sum vs. Decision Subset Sum (DSubset Sum)



Knapsack vs. DKnapsack

- We have a knapsack of capacity W (a positive integer) and n objects with weights w_1, \dots, w_n and values v_1, \dots, v_n , where v_i and w_i are positive integers.



Knapsack vs. DKnapsack

- We have a knapsack of capacity W (a positive integer) and n objects with weights w_1, \dots, w_n and values v_1, \dots, v_n , where v_i and w_i are positive integers.

Optimization problem: (Knapsack)

Find the **largest value** $\sum_{i \in T} v_i$ of any subset T that fits in the knapsack, i.e., $\sum_{i \in T} w_i \leq W$.

Decision problem: (DKnapsack)

Given k , **is there a subset** of the objects that fits in the knapsack and has total value **at least k** ?



Subset Sum vs. DSubset Sum

- The input is a positive integer C and n objects whose values are positive integers s_1, \dots, s_n



Subset Sum vs. DSubset Sum

- The input is a positive integer C and n objects whose values are positive integers s_1, \dots, s_n

Optimization problem: (Subset Sum)

Among subsets of the objects with sum at most C , what is the **largest subset sum**?

Decision problem: (DSubset Sum)

Is there a subset of objects whose values add up to **exactly** C ?



Optimization and Decision Problems

- Given a subroutine for solving the optimization problem, solving the corresponding decision problem is usually trivial.



Optimization and Decision Problems

- Given a subroutine for solving the **optimization problem**, solving the corresponding **decision problem** is usually **trivial**.

First solve the **optimization problem**, then check the **decision problem**. If it does, answer **yes**, otherwise **no**.



Optimization and Decision Problems

- Given a subroutine for solving the optimization problem, solving the corresponding decision problem is usually trivial.

First solve the optimization problem, then check the decision problem. If it does, answer yes, otherwise no.

Thus, if we prove that a given decision problem is hard to solve efficiently, then it is obvious that the optimization problem must be (at least as) hard.



Complexity Classes

- The **Theory of Complexity** deals with
 - ◇ the classification of certain “**decision problems**” into several classes:
 - ◇ the class of “easy” problems
 - ◇ the class of “hard” problems
 - ◇ the class of “hardest” problems



Complexity Classes

- The **Theory of Complexity** deals with
 - ◇ the classification of certain “**decision problems**” into several classes:
 - ◇ the class of “easy” problems
 - ◇ the class of “hard” problems
 - ◇ the class of “hardest” problems
 - ◇ relations among the three classes



Complexity Classes

- The **Theory of Complexity** deals with
 - ◇ the classification of certain “**decision problems**” into several classes:
 - ◇ the class of “easy” problems
 - ◇ the class of “hard” problems
 - ◇ the class of “hardest” problems
 - ◇ relations among the three classes
 - ◇ properties of problems in the three classes



Complexity Classes

- The **Theory of Complexity** deals with
 - ◇ the classification of certain “**decision problems**” into several classes:
 - ◇ the class of “easy” problems
 - ◇ the class of “hard” problems
 - ◇ the class of “hardest” problems
 - ◇ relations among the three classes
 - ◇ properties of problems in the three classes

Question:

How to classify decision problems?



Complexity Classes

- The **Theory of Complexity** deals with
 - ◇ the classification of certain “**decision problems**” into several classes:
 - ◇ the class of “easy” problems
 - ◇ the class of “hard” problems
 - ◇ the class of “hardest” problems
 - ◇ relations among the three classes
 - ◇ properties of problems in the three classes

Question:

How to classify decision problems?

A. Use **polynomial-time algorithms**.



Polynomial-Time Algorithms

- **Definition** An algorithm is *polynomial-time* if its running time is $O(n^k)$, where k is a constant independent of n , and n is the *input size* of the problem that the algorithm solves.



Polynomial-Time Algorithms

- **Definition** An algorithm is *polynomial-time* if its running time is $O(n^k)$, where k is a constant independent of n , and n is the *input size* of the problem that the algorithm solves.

Whether we use n or n^a (for a fixed $a > 0$) as the input size, it will **not** affect the conclusion of whether an algorithm is *polynomial-time*.



Polynomial-Time Algorithms

- **Definition** An algorithm is *polynomial-time* if its running time is $O(n^k)$, where k is a constant independent of n , and n is the *input size* of the problem that the algorithm solves.

Whether we use n or n^a (for a fixed $a > 0$) as the input size, it will **not** affect the conclusion of whether an algorithm is *polynomial-time*.

Example:

The standard multiplication algorithm has time $O(m_1 m_2)$, where m_1, m_2 denote the number of digits in the two integers, respectively.



Nonpolynomial-Time Algorithms

- **Definition** An algorithm is *nonpolynomial-time* if the running time is **not** $O(n^k)$ for any fixed $k \geq 0$.



Nonpolynomial-Time Algorithms

- **Definition** An algorithm is *nonpolynomial-time* if the running time is **not** $O(n^k)$ for any fixed $k \geq 0$.

Let's return to the *Composite* problem.

- ◇ it checks, in time $\Theta((\log N)^2)$, whether K divides N for each K with $2 \leq K \leq N - 1$.
- ◇ The complete algorithm therefore uses $\Theta(N(\log N)^2)$ time.



Nonpolynomial-Time Algorithms

- **Definition** An algorithm is *nonpolynomial-time* if the running time is **not** $O(n^k)$ for any fixed $k \geq 0$.

Let's return to the *Composite* problem.

- ◇ it checks, in time $\Theta((\log N)^2)$, whether K divides N for each K with $2 \leq K \leq N - 1$.
- ◇ The complete algorithm therefore uses $\Theta(N(\log N)^2)$ time.

Conclusion: The algorithm is **nonpolynomial**!



Nonpolynomial-Time Algorithms

- **Definition** An algorithm is *nonpolynomial-time* if the running time is **not** $O(n^k)$ for any fixed $k \geq 0$.

Let's return to the *Composite* problem.

- ◇ it checks, in time $\Theta((\log N)^2)$, whether K divides N for each K with $2 \leq K \leq N - 1$.
- ◇ The complete algorithm therefore uses $\Theta(N(\log N)^2)$ time.

Conclusion: The algorithm is **nonpolynomial**!

Question:
Why?



Nonpolynomial-Time Algorithms

- **Definition** An algorithm is *nonpolynomial-time* if the running time is **not** $O(n^k)$ for any fixed $k \geq 0$.

Let's return to the *Composite* problem.

- ◇ it checks, in time $\Theta((\log N)^2)$, whether K divides N for each K with $2 \leq K \leq N - 1$.
- ◇ The complete algorithm therefore uses $\Theta(N(\log N)^2)$ time.

Conclusion: The algorithm is **nonpolynomial**!

Question:

Why?

In terms of the *input size*, the complexity is $\Theta(2^n n^2)$.



Polynomial- vs. Nonpolynomial-Time

- Nonpolynomial-time algorithms are **impractical**.

2^n for $n = 100$: it takes **billions** of years!!!



Polynomial- vs. Nonpolynomial-Time

- Nonpolynomial-time algorithms are **impractical**.

2^n for $n = 100$: it takes **billions** of years!!!

In reality, an $O(n^{20})$ algorithm is **not** really practical.



Polynomial-Time Solvable Problems

- **Definition** A problem is *solvable in polynomial time* (or more simply, the problem is *in polynomial time*) if there exists an algorithm which solves the problem in polynomial time (a.k.a. *tractable*).



Polynomial-Time Solvable Problems

- **Definition** A problem is *solvable in polynomial time* (or more simply, the problem is *in polynomial time*) if there exists an algorithm which solves the problem in polynomial time (a.k.a. *tractable*).

Definition (The **Class P**) The class P consists of all **decision problems** that are solvable in **polynomial time**. That is, there exists an algorithm that will decide in **polynomial time** if any given input is a **yes-input** or a **no-input**.



The Class P

- **Question:**

How to prove that a decision problem is in P?



The Class P

■ Question:

How to prove that a decision problem is in P?

A. Find a **polynomial-time** algorithm.



The Class P

■ Question:

How to prove that a decision problem is in P?

A. Find a **polynomial-time** algorithm.

Question:

How to prove that a decision problem is **not** in P?



The Class P

■ Question:

How to prove that a decision problem is in P?

A. Find a **polynomial-time** algorithm.

Question:

How to prove that a decision problem is **not** in P?

A. You need to prove that there is **no** polynomial-time algorithm for this problem. (much much **harder**)



Certificates and Verifying Certificates

- **Observation:** A **decision problem** is usually formulated as:
Is there an object **satisfying some conditions**?



Certificates and Verifying Certificates

- **Observation:** A **decision problem** is usually formulated as:
Is there an object **satisfying some conditions**?



Certificates and Verifying Certificates

- A *certificate* is a specific object corresponding to a *yes-input*, such that it can be used to show that the input is *indeed* a yes-input.



Certificates and Verifying Certificates

- A *certificate* is a specific object corresponding to a *yes-input*, such that it can be used to show that the input is *indeed* a yes-input.

Verifying a certificate: Given a presumed yes-input and its corresponding certificate, by making use of the given certificate, we verify that the input is actually a *yes-input*.



The Class NP

- **Definition** The class **NP** consists of all decision problems such that, for each **yes-input**, there exists a *certificate* which allows one to verify in **polynomial time** that the input is indeed a **yes-input**.



The Class NP

- **Definition** The class **NP** consists of all decision problems such that, for each **yes-input**, there exists a *certificate* which allows one to verify in **polynomial time** that the input is indeed a **yes-input**.

NP – “nondeterministic polynomial-time”



Composite \in NP

- For Composite, a **yes-input** is just the integer n that is **composite**.



Composite \in NP

- For Composite, a **yes-input** is just the integer n that is **composite**.

Question: (**Certificate**)

What is need to show n is actually a **yes-input**?



Composite \in NP

- For Composite, a **yes-input** is just the integer n that is **composite**.

Question: (**Certificate**)

What is need to show n is actually a **yes-input**?

A. An integer a ($1 < a < n$) with the property that $a|n$.



Composite \in NP

- For Composite, a **yes-input** is just the integer n that is **composite**.

Question: (**Certificate**)

What is need to show n is actually a **yes-input**?

A. An integer a ($1 < a < n$) with the property that $a|n$.

- ◇ Given a **certificate** a , check whether a divides n .
- ◇ This can be done in $O((\log n)^2)$.
- ◇ **Composite \in NP**



Composite \in NP

- For Composite, a **yes-input** is just the integer n that is **composite**.

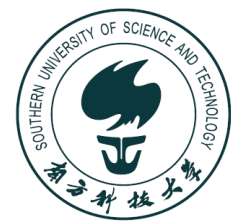
Question: (**Certificate**)

What is need to show n is actually a **yes-input**?

A. An integer a ($1 < a < n$) with the property that $a|n$.

- ◇ Given a **certificate** a , check whether a divides n .
- ◇ This can be done in $O((\log n)^2)$.
- ◇ **Composite \in NP**

DSubsetSum \in NP



Satisfiability (SAT)

- A given **Boolean formula** is called *satisfiable* if there is a way to assign **truth values** to the variables such that the final result is **1**.



Satisfiability (SAT)

- A given **Boolean formula** is called *satisfiable* if there is a way to assign **truth values** to the variables such that the final result is **1**.

SAT problem:

Determine whether an input Boolean formula is **satisfiable**.
If a Boolean formula is satisfiable, it is a **yes-input**;
otherwise, it is a **no-input**.



Satisfiability (SAT)

- A given **Boolean formula** is called *satisfiable* if there is a way to assign **truth values** to the variables such that the final result is 1.

SAT problem:

Determine whether an input Boolean formula is **satisfiable**.
If a Boolean formula is satisfiable, it is a **yes-input**;
otherwise, it is a **no-input**.

SAT problem \in NP



$P = NP?$

- One of the **most important** problems in CS is whether $P = NP$ or $P \neq NP$?



$P = NP?$

- One of the **most important** problems in CS is whether $P = NP$ or $P \neq NP$?
- Observe that $P \subseteq NP$.



$P = NP?$

- One of the **most important** problems in CS is whether $P = NP$ or $P \neq NP$?
- Observe that $P \subseteq NP$.
- Intuitively, $NP \subseteq P$ is **doubtful**.



$P = NP?$

- One of the **most important** problems in CS is whether $P = NP$ or $P \neq NP$?
- Observe that $P \subseteq NP$.
- Intuitively, $NP \subseteq P$ is **doubtful**.

Just being able to verify a certificate in polynomial time does **not** necessarily mean we can tell **whether an input is a yes-input or a no-input in polynomial time**.



$P = NP?$

- One of the **most important** problems in CS is whether $P = NP$ or $P \neq NP$?
- Observe that $P \subseteq NP$.
- Intuitively, $NP \subseteq P$ is **doubtful**.

Just being able to verify a certificate in **polynomial time** does **not** necessarily mean we can tell **whether an input is a yes-input or a no-input in polynomial time**.

However, we are still **no** closer to solving it and do not know the answer. The search for a solution, though, has provided us with deep insights into **what distinguishes an “easy” problem from a “hard” one**.



Announcements

■ Homework assignment 2

- ◇ P126 Ex. 45, P137 Ex. 40, 41, 46*, P155 Ex. 70, 76, 80*, P169 Ex. 35, 38*, 41*, P176 Ex. 16, 17, P203 Ex. 49, P217 Ex. 44, 45, 50, P218 Ex. 71, P229 Ex. 10, P230 Ex. 13 b), 14 b)
- ◇ Due on *Oct. 24th, 2017 at the beginning of class*
- ◇ Please try your best to solve problems marked with *
- ◇ Please write your homework **neatly**, as a courtesy to graders.



Next Lecture

- number theory, ...

