

Jiangbo WANG



+33 0663546952



JiangboWANGfr



jiangbo.wang@ensea.fr



1 place des Linandes Mauves, 95000, Cergy, FRANCE



Education

- 2024 – 2023 **Master. CY Cergy Paris Université** in Intelligent and Communicating Systems
Relevant Courses: *Parallel Computing, 5G MIMO, Wireless communication, uCOS Real-Time Systems, Autonomous Driving Sensors and Algorithms, Reliability of Digital Electronic Structures, IoT Energy-Saving Algorithms, FPGA*
- 2024 – 2022 **Engineering. ENSEA** in Electrical and Computer Engineering
Relevant Courses: *RF, Wireless Communication and Antennas, EMC, Component Noise Modeling, Communication Principles, Advanced Signal Processing, FPGA, Microelectronics, FreeRTOS, Linux Kernel Programming*
- 2022 – 2018 **Bachelor. Beijing Institute of Technology** in Automation

Research Publications

- 1 **J. Wang**, S. Zuckerman, and J. A. L. del Castillo, “Evaluation of multi-armed bandit algorithms for efficient resource allocation in edge platforms,” in *Euro-Par: 30th International European Conference on Parallel and Distributed Computing*, 2024.






Awards and Honors

- 2021 **RoboCup Robot Soccer World Cup**. National Second Prize.
- 2020 **RoboMaster Robotics Competition**. National Second Prize.
- 2019 **World Cup for College Students' Computer Game Competition**. National Third Prize.
- 2018 **ACM international collegiate programming contest**. University Level Third Prize.






Internships

- 2024.3 – 2024.10 **5G Low Carbon Footprint Wireless Network Modeling** in ETIS lab
- Extracted the actual locations of 5G base stations from Cartoradio. Modeled the wireless network using stochastic geometry.
 - Optimized network performance to maximize coverage while minimizing total energy consumption.
 - **Preparing to publish a paper.**
- 2023.4 – 2023.9 **Development of satellite Flight Software** in Centre Spatial de Polytechnique
- Developed CAN, UART, and I2C bus IPs in FPGA, achieving and verifying communication between the onboard computer and different payloads.
 - Use virtualization technology to virtualize the hardware to ensure the independent operation of different payload software.
 - Developed key modules of flight software for the IonSat satellite on the onboard computer (I/O Management (IOT), Mode Management and Data Loading (MMDL), Command Control SoftWare (CCSW)). Hardware/Software Event Manager (HSEM).

Research Work

- 2023.10 - 2024.4  **Integrated Multi-Armed Bandit Algorithm for Efficient Resource Allocation in IoT Clusters**
- Implemented task allocation scheduling system using two widely used MAB algorithms: EXP3 (Exponential Weighted Exploration and Exploitation Algorithm) and UCB (Upper Confidence Bound), and built a simulation platform for testing.
 - Constructed an actual distributed IoT cluster and developed OpenMPI parallel computing test programs based on NAS Parallel Benchmarks for practical testing.
- 2023.9 - 2024.1  **Robot Combat Competition Based on FreeRTOS Real-Time System**
- Selected chips and sensors, designed circuit diagrams, and created PCB schematics, completing the soldering of components.
 - Based on FreeRTOS, acquired data from LiDAR sensors and controlled the robot to complete obstacle avoidance and tracking tasks, successfully competing in a robot contest.
- 2022.9 - 2023.4  **Interpretability of Deep Learning Anomaly Detection Algorithms**
- Implemented three anomaly detection algorithms: Autoencoder, BiGAN, and LSTM, and compared their anomaly detection performance.
 - Developed three deep learning model interpretability algorithms: Macrobase, Exstream, and LIME, and compared their explanations of anomaly detection results.
- 2021.12 - 2022.7  **Robot Formation Control Based on Reinforcement Learning**
- Using the ROS system and traditional sensors, implemented dynamic obstacle avoidance and biaxial synchronous movement simulation for robot formations.
 - Trained a lead robot to navigate through "S" shaped curves while leading a formation using deep reinforcement learning, specifically the Double Deep Q-Network (DDQN) algorithm.
- 2020.9 - 2021.7  **Land Aircraft Carrier - Multi-Scenario Drone Landing Platform Design**
- Simulated the creation of a multi-scenario drone landing platform using a legged robot as a carrier, based on technologies such as wireless charging, image recognition, and six degrees of freedom platforms.
 - Second Prize in Beijing Science and Technology Competition.

Skills

- Languages  Mandarin Chinese(Native), English (TOEIC 855/990), French(B2)
- Electronic  RF, FPGA, Analog Analysis and Digital Analysis, Digital Communications
- Coding  Linux, Python, C, C++, Java, MATLAB, Mathematica
- A.I.  Deep Learning, Reinforcement Learning
- Misc.  5G wireless communication, Automatic Control Theory, Digital IC design, Image processing, signal processing