view_frames Result Recorded at time: 644.863 map Broadcaster: /amcl Average rate: 15.362 Hz Most recent transform: 645.339 (-0.476 sec old) Buffer length: 2.083 sec odom Broadcaster: /gazebo Average rate: 100.426 Hz Most recent transform: 644.854 (0.009 sec old) Buffer length: 2.111 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 100.235 Hz Average rate: 100.235 Hz Average rate: 81.517 Hz Average rate: 100.235 Hz Average rate: 81.517 Hz Average rate: 81.517 Hz Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 644.851 (0.012 sec old) Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 644.851 (0.012 sec old) Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.110 sec Buffer length: 2.125 sec Buffer length: 2.125 sec Buffer length: 2.125 sec Buffer length: 2.110 sec Buffer length: 2.110 sec r_wheel_link torso_lift_link estop_link laser_link torso_fixed_link l_wheel_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 100.235 Hz Average rate: 81.517 Hz Average rate: 81.517 Hz Average rate: 81.517 Hz Most recent transform: 644.851 (0.012 sec old) Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 644.851 (0.012 sec old) Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.125 sec Buffer length: 2.110 sec Buffer length: 2.110 sec Buffer length: 2.110 sec bellows_link shoulder_pan_link head_pan_link bellows_link2 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 81.517 Hz Average rate: 81.517 Hz Most recent transform: 644.851 (0.012 sec old) Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.110 sec Buffer length: 2.110 sec head_tilt_link shoulder_lift_link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 100.235 Hz Average rate: 81.517 Hz Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.110 sec Buffer length: 2.125 sec upperarm_roll_link head camera link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 100.235 Hz Average rate: 100.235 Hz Average rate: 81.517 Hz Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.125 sec Buffer length: 2.125 sec Buffer length: 2.110 sec head_camera_depth_frame head_camera_rgb_frame elbow_flex_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 100.235 Hz Average rate: 100.235 Hz Average rate: 81.517 Hz Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 645.363 (-0.500 sec old) Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.125 sec Buffer length: 2.125 sec Buffer length: 2.110 sec head_camera_depth_optical_frame head_camera_rgb_optical_frame forearm_roll_link Broadcaster: /robot_state_publisher Average rate: 81.517 Hz Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.110 sec wrist_flex_link Broadcaster: /robot_state_publisher Average rate: 81.517 Hz Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.110 sec wrist_roll_link Broadcaster: /robot_state_publisher Average rate: 100.235 Hz Most recent transform: 645.363 (-0.500 sec old) Buffer length: 2.125 sec gripper_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 81.517 Hz Average rate: 81.517 Hz Most recent transform: 644.851 (0.012 sec old) Most recent transform: 644.851 (0.012 sec old) Buffer length: 2.110 sec Buffer length: 2.110 sec r_gripper_finger_link l_gripper_finger_link