Problem Set 6

FEM solution of 1D unsteady-state diffusion equation

Write a finite-element program, using linear shape functions, to find the temperature T(x,t) in [0,L] such that (strong form)

$$\rho c_p \partial_t T - \partial_x (\kappa \partial_x T) = f$$

where ρ is the medium density, c_p is the the specific heat, κ is the conductivity, and f is a source or sink, with the following initial & boundary conditions:

$$T(L,t) = T_L$$
$$-\kappa \partial_x T(0,t) = q_0$$
$$T(x,0) = T_0(x)$$

Recipe:

Address this problem as follows:

1. Write the weak form of the equation, which translates into solving

$$M\dot{d} + Kd = F$$

where \mathbf{M} is the capacity matrix, defined as

$$M_{AB} = (N_A, \rho c_p N_B)$$
$$= \int_0^L \rho c_p N_A N_B dx$$

and K is the conductivity (or stiffness) matrix, defined as

$$K_{AB} = a(N_A, N_B)$$
$$= \int_0^L \kappa \, \partial_x N_A \partial_x N_B \, \mathrm{d}x$$

and ${\bf F}$ is the right-hand-side (force) vector , defined as

$$F_A = (N_A, f) + N_A(0)q_0 - a(N_A, N_{n+1})T_L - (N_A, \rho c_p N_{n+1})\dot{T}_L$$

finally, ${f d}$ are the unknown temperatures and $\dot{{f d}}=\partial_t {f d}.$

- 2. Define the local (element level) capacity & stiffness matrices and the right-hand-side vector.
- 3. Assemble these local matrices into global matrices (global level) using the Location Matrix (LM).
- 4. March in time, using the predictor-corrector algorithm:

• Predictor:

$$d_{n+1}=d_n+(1-\alpha)\Delta t\dot{d}_n$$
 $\dot{d}_{n+1}=0$ (initialization at the beginning of each time step)

• Solve:

$$rhs = F - M\dot{d}_{n+1} - Kd_{n+1}$$
$$\delta\dot{d}_{n+1} = M^{-1}rhs$$

• Corrector:

$$d_{n+1} = d_{n+1} + \alpha \Delta t \dot{d}_{n+1}$$

 $\dot{d}_{n+1} = \dot{d}_{n+1} + \delta \dot{d}_{n+1}$

where Δt is the time step.

The parameter α can take several values, leading to different methods with different level of stability (e.g., see Hughes, "The Finite Element Method - Linear Static and Dynamic Finite Element Analysis", page 459, for more details) such that

 $\alpha = 0$: Forward differences,

 $\alpha = 1/2$: Midpoint rule, Crank-Nicolson,

 $\alpha=1$: Backward differences.

For $\alpha \geq 1/2$ the scheme is unconditionally stable.

Use $\alpha = 1/2$.

Compare the FEM solution to the exact solution to the strong form, by plotting the temperature T versus x at different time steps. Solve the following two cases:

Problem A: Simple harmonic function

Single harmonic $T_0(x)$ as

$$T_0(x) = 1 + cos(x)$$
 in [0,L]

where $L=\frac{\pi}{2}$ and the following conditions & parameters:

$$f = 0$$

$$q_0 = 0$$

$$T_L = 1$$

$$\kappa = 1$$

$$\rho c_p = 1$$

Try
$$N_{el} = 10$$
.

The exact solution to this problem is $T(x,t) = 1 + e^{-t}\cos(x)$.

Problem B: Half-space cooling

Here we consider the uniformly hot half-space cooling (e.g., oceanic lithospheric cooling). The differential equation for this problem is

$$\rho c_p \partial_t \theta = \partial_x (\kappa \partial_x \theta) \text{ in } 0 < x < \infty,$$

where $\theta=rac{T-T_m}{T_0-T_m}$ is a non-dimensional variable, using the following boundary conditions:

$$T(0,t)=T_0$$
 (surface temperature) $T(x o\infty,t) o T_m$
$$T(x,0)=T_m ext{ (initial temperature)}$$

The exact solution to this problem is

$$\theta = \frac{T - T_m}{T_0 - T_m}$$
$$= \operatorname{erfc} \frac{x}{2\sqrt{\frac{\kappa}{\rho c_p} t}}$$

where $\operatorname{erfc}(\mathbf{x})$ is the complementary error function defined as $\operatorname{erfc}(x) = \frac{2}{\sqrt{\pi}} \int_x^\infty e^{-t^2} \mathrm{d}t$. Notice that you can use the same algorithm developed for (a), by changing variable y = L - x, such that you solve

$$\rho c_p \partial_t T - \partial_y (\kappa \partial_y T) = f$$

with the boundary conditions

$$T(L,t) = T_0$$
$$-\kappa \partial_y T(0,t) = q_0$$
$$T(y,0) = T_m$$

Let
$$L=20$$
, $\kappa=1$, $q_0=0$, $\rho c_p=1$, $f=0$, $T_0=0$, and $T_m=1$.

Please be aware that:

• The initial condition of this problem is not compatible with the boundary condition at

y=L. To handle that you can set the temperature value at y=L to be T_0 , and all the other nodes to be T_m . You can also try and use mode elements, which will make the transition from T_0 to T_m smoother.

• We are solving the problem for large L, that is, such that $L>>2\sqrt{\frac{\kappa}{\rho c_p}t}$, say L=20 and t=(0,9), therefore, we can approximately use the exact solution for the half-space problem as the analytical solution for our problem.