

From Datalog to FLIX: A Declarative Language for Fixed Points on Lattices

Magnus Madsen

University of Waterloo, Canada
mmadsen@uwaterloo.ca

Ming-Ho Yee

University of Waterloo, Canada
ming-ho.yee@uwaterloo.ca

Ondřej Lhoták

University of Waterloo, Canada
olhotak@uwaterloo.ca

Motivation

Implementation of static analyses is difficult:

- analyses are often interrelated:
 - (e.g. conditional constant propagation)
 - (e.g. points-to analysis and call graph construction)
- requires a complicated arrangement of work lists.

⇒ Hard to ensure correctness.

⇒ Hard to ensure performance/scalability.

⇒ Renewed interest in declarative programming.

What is Declarative Programming?

(aka logic programming)

The ***what***, not the ***how***.

Find x such that:

$$3 + x = 15$$

⇒ Easy to understand whether we
are solving the right problem!

What is Declarative Programming?

Separates the choice of:

- **evaluation strategy** (e.g. work list order)
- **data structures** (e.g. bitsets/hashsets/BDDs)

from the specification of the problem.

⇒ **We can leave these choices up to the solver
or override them when needed.**

What is Datalog?

A declarative language for constraints on relations:

- Prolog-style rules (horn clauses).
- Successfully used in large-scale points-to analyses
[[Bravenboer et al.](#)], [[Smaragdakis et al.](#)]

Useful theoretical and practical properties:

- Every Datalog program eventually terminates.
- Every Datalog program has a unique solution.

⇒ **Debugging is easier!**

Examples

- Computing your aunts and uncles:

```
AuntOrUncle(x, z) :- Parent(x, y), Brother(y, z).
```

```
AuntOrUncle(x, z) :- Parent(x, y), Sister(y, z).
```

- Computing the transitive closure of a graph:

```
Path(x, z) :- Path(x, y), Edge(y, z).
```

What we **can** and **can't** do in Datalog:

Analyses based on *relations*:

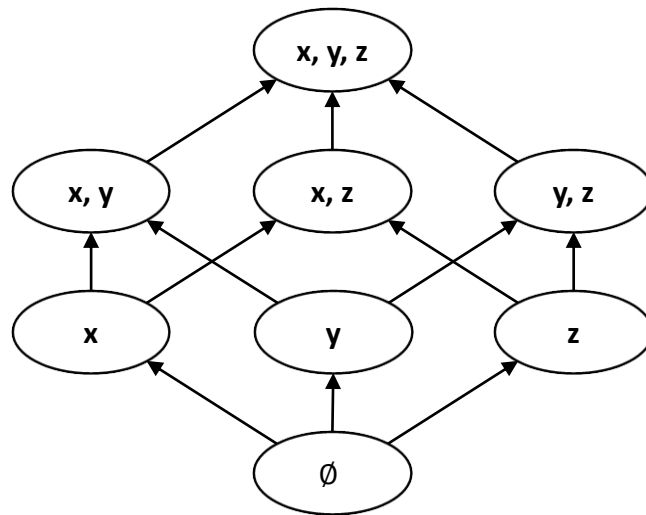
- Points-To
- Definite Assignment
- Reaching Definitions
- ...

Analyses based on *lattices*:

- Sign Analysis
- Constant Propagation
- Interval Analysis
- ...

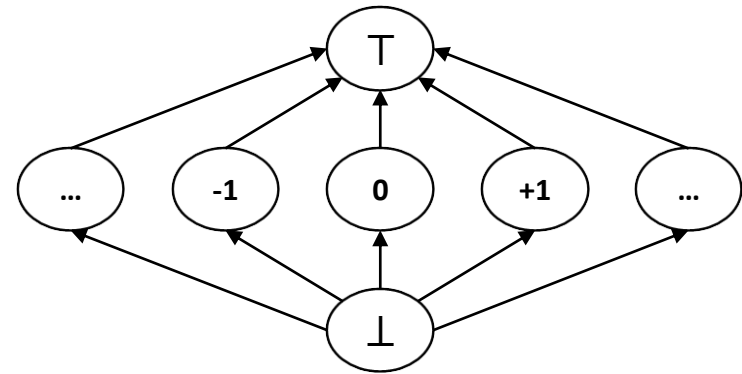
Example: Constant Propagation

What Datalog has:



fixed finite set

What we wanted:



infinite set

⇒ **We need lattices.**

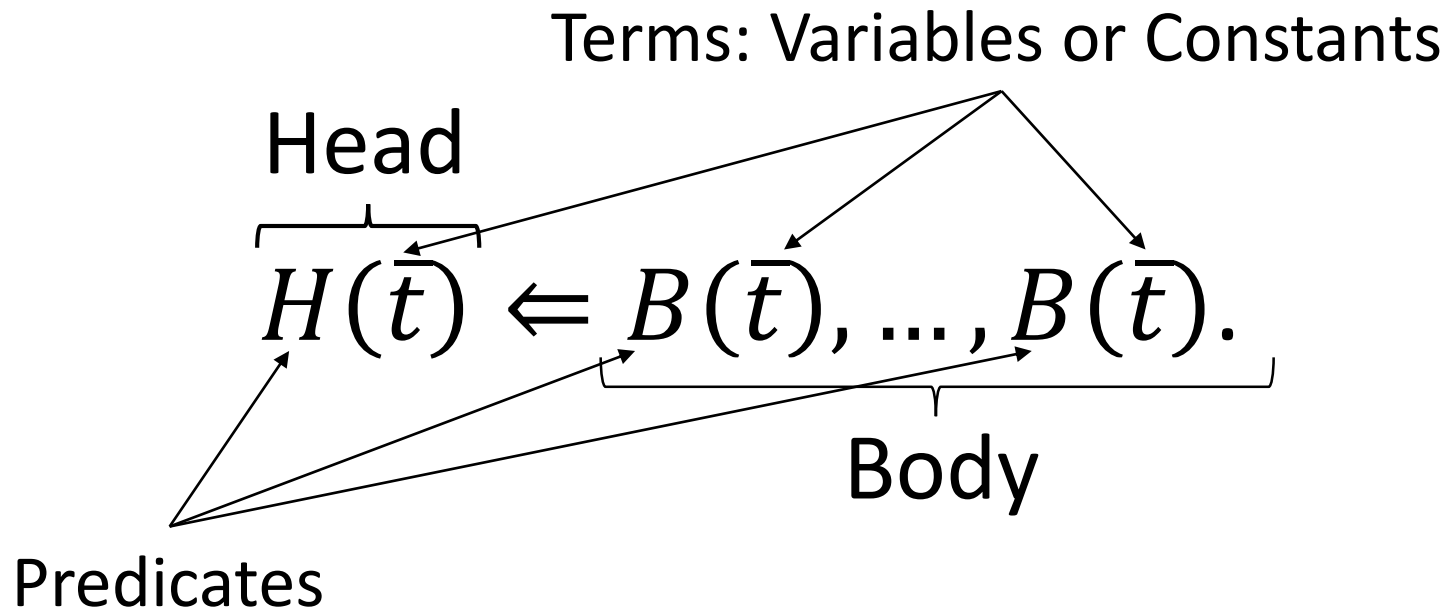
⇒ **We need functions.**

Introducing Flix

A blend of **Logic** and **Functional** programming.

- Inspired by Datalog.
- User-defined **lattices**.
- User-defined **monotone filter** and **transfer functions**.
- Interoperates with languages on the JVM.

The Anatomy of a **Datalog** Rule



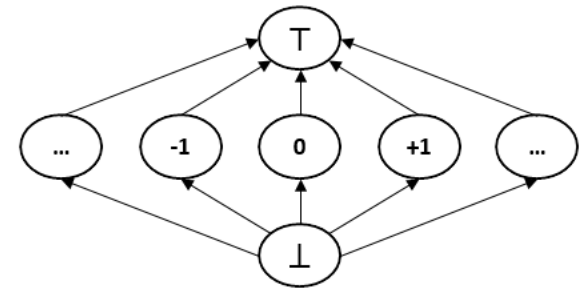
The Anatomy of a **Flix** Rule

Filter Function

$$H_{\ell}(\bar{t}, \underbrace{f(\bar{t})}_{\text{Transfer Function}}) \Leftarrow \overbrace{\varphi(\bar{t})}^{\text{Filter Function}}, B_{\ell}(\bar{t}), \dots, B_{\ell}(\bar{t}).$$

Transfer Function

Datalog vs. Flix



The **Datalog** program:

$A(\text{"foo"}).$

$A(\text{"bar"}).$

has the minimal model:

$\{A(\text{"foo"}), A(\text{"bar"})\}$

The **Flix** program:

$A(\text{Cst}(1)).$

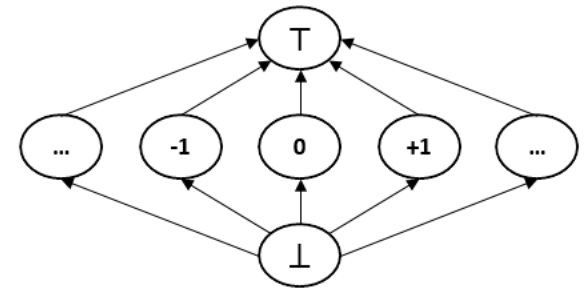
$A(\text{Cst}(2)).$

$B(\text{Cst}(3)).$

has the minimal model:

$\{A(\text{Top}), B(\text{Cst}(3))\}$

Flix Semantics



The **Flix** program:

```
A(Cst(1)). B(Cst(2)).
```

```
R(x) :- A(x).
```

```
R(x) :- B(x).
```

has the minimal model:

```
{A(Cst(1)),
```

```
  B(Cst(2)),
```

```
  R(Top)}
```

The **Flix** program:

```
A(Cst(1)). B(Cst(2)).
```

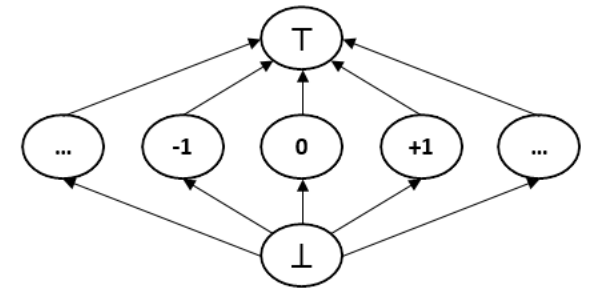
```
R(x) :- A(x), B(x).
```

has the minimal model:

```
{A(Cst(1)),
```

```
  B(Cst(2))}
```

Constant Propagation



Input Relations:

```
rel AddExp(r: Var, x: Var, y: Var)
```

r = **x** + **y**

```
rel DivExp(r: Var, x: Var, y: Var)
```

r = **x** / **y**

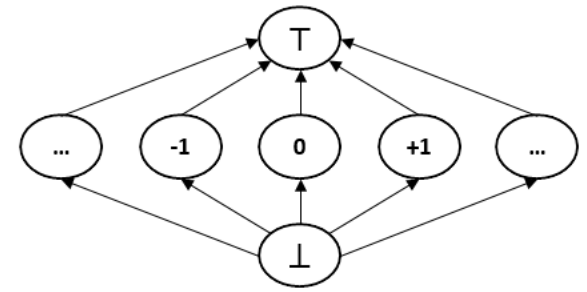
Computed Lattices:

```
lat LocalVar(x: Var, v: Constant)
```

key

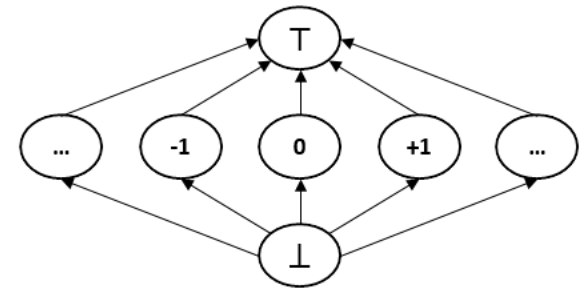
lattice

Lattice Definition



```
enum Constant {  
    case Top,  
    case Cst(Int),  
    case Bot  
}
```

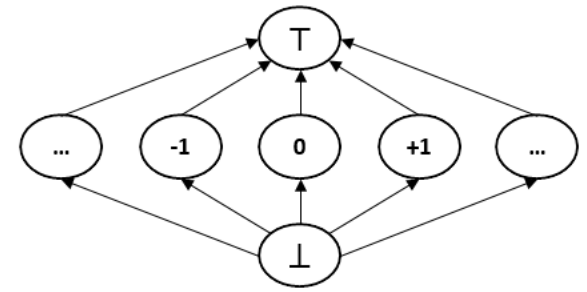
Lattice Definition



```
def leq(e1: Constant, e2: Constant): Bool
  = match (e1, e2) with {
    case (Bot, _)           => true
    case (Cst(n1), Cst(n2)) => n1 == n2
    case (_, Top)          => true
    case _                  => false
  }
```

And define `lub` and `glb` in similar way...

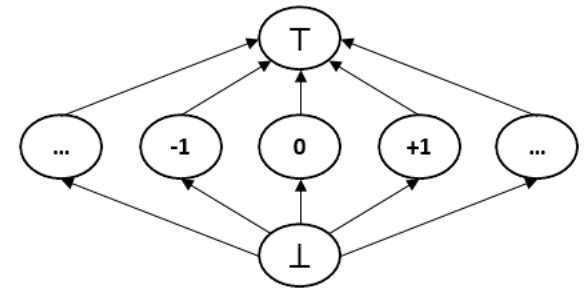
Analysis Rules



`LocalVar(r, sum(x, y)) :- AddExp(r, v1, v2),
LocalVar(v1, x),
LocalVar(v2, y).`

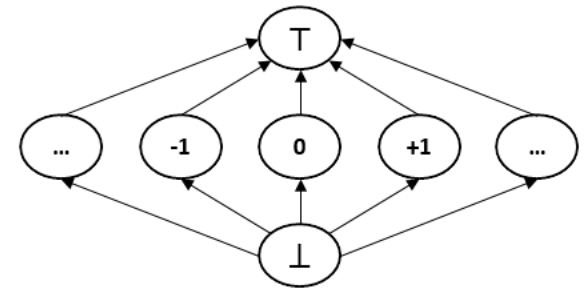
`LocalVar(r, div(x, y)) :- DivExp(r, v1, v2),
LocalVar(v1, x),
LocalVar(v2, y).`

Transfer Function



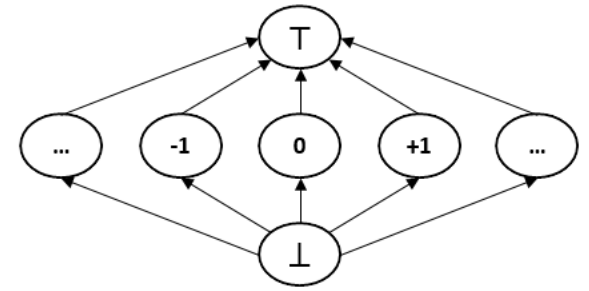
```
def sum(e1: Constant, e2: Constant): Constant
  = match (e1, e2) with {
    case (_, Bot)           => Bot
    case (Bot, _)           => Bot
    case (Cst(n1), Cst(n2)) => Cst(n1 + n2)
    case _                   => Top
  }
```

Example: Finding Bugs



```
ArithmeticError(r) :- isMaybeZero(y),  
                        DivExp(r, n, d),  
                        LocalVar(d, y).
```

Filter Function



```
def isMaybeZero(e: Constant): Bool
  = match e with {
    case Bot      => false
    case Cst(n)   => n == 0
    case Top      => true
  }
```

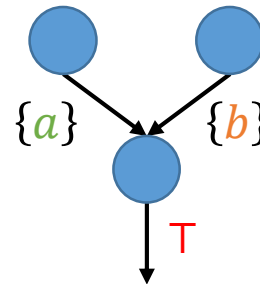
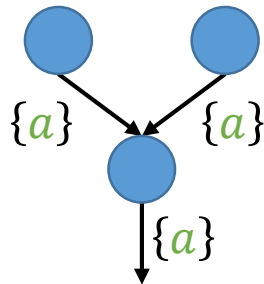
Experiments

We have expressed three analyses in Flix:

- The Strong Update Analysis [[Lhoták and Chung](#)]
- The IFDS algorithm [[Reps, Horwitz, and Sagiv](#)]
 - Instantiated with the Alias-Set analysis [[Naeem and Lhoták](#)]
- The IDE algorithm [[Sagiv, Reps, and Horwitz](#)]

Strong Update Analysis

- Hybrid points-to analysis for C programs:
 - *flow-sensitive* for *singleton* points-to sets.
 - *flow-insensitive* for everything else.



Strong Update Analysis

$$\begin{array}{lll}
 \ell : p = \&a & \{a\} \subseteq pt(p) & [\text{ADDROF}] \\
 \ell : p = q & pt(q) \subseteq pt(p) & [\text{COPY}] \\
 \ell : *p = q & \forall a \in pt(p) . pt(q) \sqsubseteq su[\underline{\ell}](a) & [\text{STORE}] \\
 & \forall a \in pt(p) . pt(q) \subseteq pt(a) & \\
 \ell : p = *q & \forall a \in pt(q) . ptsu[\bar{\ell}](a) \subseteq pt(p) & [\text{LOAD}] \\
 \ell_1 \in pred(\ell_2) & \forall a \in \mathcal{A} . su[\underline{\ell}_1](a) \sqsubseteq su[\bar{\ell}_2](a) & [\text{CFLOW}] \\
 \ell \in \mathcal{L} & \forall a \in \mathcal{A} \setminus kill(\ell) . su[\bar{\ell}](a) \sqsubseteq su[\underline{\ell}](a) & [\text{PRESERVE}]
 \end{array}$$

Where $ptsu[\bar{\ell}](a) \triangleq \begin{cases} su[\bar{\ell}](a) & \text{if } su[\bar{\ell}](a) \neq \top \\ pt(a) & \text{if } su[\bar{\ell}](a) = \top \end{cases}$

Strong Update Analysis

<code>Pt(p, a) :- AddrOf(p, a).</code>	[AddrOf]
<code>Pt(p, a) :- Copy(p, q), Pt(q, a).</code>	[Copy]
<code>SUAfter(l, a, Single(b)) :- Store(l, p, q), Pt(p, a), Pt(q, b).</code>	[Store]
<code>PtH(a, b) :- Store(l, p, q), Pt(p, a), Pt(q, b).</code>	
<code>Pt(p, b) :- Load(l, p, q), Pt(q, a), PtSU(l, a, b).</code>	[Load]
<code>SUBefore(l2, a, t) :- CFG(l1, l2), SUAfter(l1, a, t).</code>	[CFlow]
<code>SUAfter(l, a, t) :- SUBefore(l, a, t), Preserve(l, a).</code>	[Preserve]
<code>PtSU(l, a, b) :- PtH(a, b), SUBefore(l, a, t), filter(t, b).</code>	

IFDS & IDE

Inter-procedural context-sensitive dataflow analyses:

- expressed as graph reachability problems.
- Interprocedural Finite Distributive Subset (IFDS)
 - pure graph reachability.
- Inteprocedural Distributive Environments (IDE)
 - IFDS with composition of micro-functions along the path.
- Anecdotaly, these algorithms are hard to understand.

IFDS

```

declare PathEdge, WorkList, SummaryEdge: global edge set
algorithm Tabulate( $G_P^s$ )
begin
  [1] Let  $(N^s, E^s) = G_P^s$ 
  [2] PathEdge :=  $\{ \langle s_{main}, 0 \rangle \rightarrow \langle s_{main}, 0 \rangle \}$ 
  [3] WorkList :=  $\{ \langle s_{main}, 0 \rangle \rightarrow \langle s_{main}, 0 \rangle \}$ 
  [4] SummaryEdge :=  $\emptyset$ 
  [5] ForwardTabulateSLRPs()
  [6] for each  $n \in N^s$  do
  [7]    $X_n := \{ d_2 \in D \mid \exists d_1 \in (D \cup \{ 0 \}) \text{ such that } \langle s_{proc}(n), d_1 \rangle \rightarrow \langle n, d_2 \rangle \in \text{PathEdge} \}$ 
  [8] end
  procedure Propagate( $e$ )
  begin
  [9]   if  $e \notin \text{PathEdge}$  then Insert  $e$  into PathEdge; Insert  $e$  into WorkList fi
  end
  procedure ForwardTabulateSLRPs()
  begin
  [10]  while WorkList  $\neq \emptyset$  do
  [11]    Select and remove an edge  $\langle s_p, d_1 \rangle \rightarrow \langle n, d_2 \rangle$  from WorkList
  [12]    switch  $n$ 
  [13]    case  $n \in \text{Call}_p$ :
  [14]      for each  $d_1$  such that  $\langle n, d_2 \rangle \rightarrow \langle s_{calledProc}(n), d_3 \rangle \in E^s$  do
  [15]        Propagate( $\langle s_{calledProc}(n), d_1 \rangle \rightarrow \langle s_{calledProc}(n), d_3 \rangle$ )
  [16]      od
  [17]      for each  $d_1$  such that  $\langle n, d_2 \rangle \rightarrow \langle \text{returnSite}(n), d_3 \rangle \in (E^s \cup \text{SummaryEdge})$  do
  [18]        Propagate( $\langle s_p, d_1 \rangle \rightarrow \langle \text{returnSite}(n), d_3 \rangle$ )
  [19]      od
  [20]    end case
  [21]    case  $n = e_p$ :
  [22]      for each  $c \in \text{callers}(p)$  do
  [23]        for each  $d_1, d_2$  such that  $\langle c, d_1 \rangle \rightarrow \langle s_p, d_1 \rangle \in E^s$  and  $\langle e_p, d_2 \rangle \rightarrow \langle \text{returnSite}(c), d_3 \rangle \in E^s$  do
  [24]          if  $\langle c, d_1 \rangle \rightarrow \langle \text{returnSite}(c), d_3 \rangle \notin \text{SummaryEdge}$  then
  [25]            Insert  $\langle c, d_1 \rangle \rightarrow \langle \text{returnSite}(c), d_3 \rangle$  into SummaryEdge
  [26]            for each  $d_3$  such that  $\langle s_{proc}(c), d_3 \rangle \rightarrow \langle c, d_1 \rangle \in \text{PathEdge}$  do
  [27]              Propagate( $\langle s_{proc}(c), d_3 \rangle \rightarrow \langle \text{returnSite}(c), d_3 \rangle$ )
  [28]            od
  [29]          fi
  [30]        od
  [31]      od
  [32]    end case
  [33]    case  $n \in (N_s - \text{Call}_p - \{ e_p \})$ :
  [34]      for each  $\langle m, d_1 \rangle$  such that  $\langle n, d_2 \rangle \rightarrow \langle m, d_3 \rangle \in E^s$  do
  [35]        Propagate( $\langle s_p, d_1 \rangle \rightarrow \langle m, d_3 \rangle$ )
  [36]      od
  [37]    end case
  [38]  end switch
  [39] end

```

IDE

```

procedure ForwardComputeJumpFunctionsSLRPs()
begin
  [1] for all  $\langle s_p, d' \rangle, \langle m, d \rangle$  such that  $m$  occurs in procedure  $p$  and  $d', d \in D \cup \{ \Lambda \}$  do
  [2]   JumpFn( $\langle s_p, d' \rangle \rightarrow \langle m, d \rangle$ ) :=  $\lambda l. \top$  od
  [3] for all corresponding call-return pairs  $\langle c, r \rangle$  and  $d', d \in D \cup \{ \Lambda \}$  do
  [4]   SummaryFn( $\langle c, d' \rangle \rightarrow \langle r, d \rangle$ ) :=  $\lambda l. \top$  od
  [5] PathWorkList :=  $\{ \langle s_{main}, \Lambda \rangle \rightarrow \langle s_{main}, \Lambda \rangle \}$ 
  [6] JumpFn( $\langle s_{main}, \Lambda \rangle \rightarrow \langle s_{main}, \Lambda \rangle$ ) :=  $id$ 
  [7] while PathWorkList  $\neq \emptyset$  do
  [8]   Select and remove an item  $\langle s_p, d_1 \rangle \rightarrow \langle n, d_2 \rangle$  from PathWorkList
  [9]   let  $f = \text{JumpFn}(\langle s_p, d_1 \rangle \rightarrow \langle n, d_2 \rangle)$ 
  [10]  switch( $n$ )
  [11]  case  $n$  is a call node in  $p$ , calling a procedure  $q$ :
  [12]    for each  $d_3$  such that  $\langle n, d_2 \rangle \rightarrow \langle s_q, d_3 \rangle \in E^s$  do
  [13]      Propagate( $\langle s_q, d_3 \rangle \rightarrow \langle s_q, d_3 \rangle, id$ ) od
  [14]    let  $r$  be the return-site node that corresponds to  $n$ 
  [15]    for each  $d_3$  such that  $e = \langle n, d_2 \rangle \rightarrow \langle r, d_3 \rangle \in E^s$  do
  [16]      Propagate( $\langle s_p, d_1 \rangle \rightarrow \langle r, d_3 \rangle, \text{EdgeFn}(e) \circ f$ ) od
  [17]    for each  $d_3$  such that  $f_3 = \text{SummaryFn}(\langle n, d_2 \rangle \rightarrow \langle r, d_3 \rangle) \neq \lambda l. \top$  do
  [18]      Propagate( $\langle s_p, d_1 \rangle \rightarrow \langle r, d_3 \rangle, f_3 \circ f$ ) od endcase
  [19]  case  $n$  is the exit node of  $p$ :
  [20]    for each call node  $c$  that calls  $p$  with corresponding return-site node  $r$  do
  [21]      for each  $d_4, d_5$  such that  $\langle c, d_4 \rangle \rightarrow \langle s_p, d_1 \rangle \in E^s$  and  $\langle e_p, d_2 \rangle \rightarrow \langle r, d_5 \rangle \in E^s$  do
  [22]        let  $f_4 = \text{EdgeFn}(\langle c, d_4 \rangle \rightarrow \langle s_p, d_1 \rangle)$  and
  [23]         $f_5 = \text{EdgeFn}(\langle e_p, d_2 \rangle \rightarrow \langle r, d_5 \rangle)$  and
  [24]         $f' = (f_5 \circ f \circ f_4) \cap \text{SummaryFn}(\langle c, d_4 \rangle \rightarrow \langle r, d_5 \rangle)$ 
  [25]        if  $f' \neq \text{SummaryFn}(\langle c, d_4 \rangle \rightarrow \langle r, d_5 \rangle)$  then
  [26]          SummaryFn( $\langle c, d_4 \rangle \rightarrow \langle r, d_5 \rangle$ ) :=  $f'$ 
  [27]        let  $s_q$  be the start node of  $c$ 's procedure
  [28]        for each  $d_3$  such that  $f_3 = \text{JumpFn}(\langle s_q, d_3 \rangle \rightarrow \langle c, d_4 \rangle) \neq \lambda l. \top$  do
  [29]          Propagate( $\langle s_q, d_3 \rangle \rightarrow \langle r, d_5 \rangle, f' \circ f_3$ ) od fi od od endcase
  [30]  default:
  [31]    for each  $\langle m, d_3 \rangle$  such that  $\langle n, d_2 \rangle \rightarrow \langle m, d_3 \rangle \in E^s$  do
  [32]      Propagate( $\langle s_p, d_1 \rangle \rightarrow \langle m, d_3 \rangle, \text{EdgeFn}(\langle n, d_2 \rangle \rightarrow \langle m, d_3 \rangle) \circ f$ ) od endcase
  [33]    end switch od
  end

procedure Propagate( $e, f$ )
begin
  [34] let  $f' = f \cap \text{JumpFn}(e)$ 
  [35] if  $f' \neq \text{JumpFn}(e)$  then
  [36]   JumpFn( $e$ ) :=  $f'$ 
  [37] Insert  $e$  into PathWorkList fi
  end

procedure ComputeValues()
begin
  /* Phase II(i) */
  [1] for each  $n^i \in N^i$  do val( $n^i$ ) :=  $\top$  od
  [2] val( $\langle s_{main}, \Lambda \rangle$ ) :=  $\perp$ 
  [3] NodeWorkList :=  $\{ \langle s_{main}, \Lambda \rangle \}$ 
  [4] while NodeWorkList  $\neq \emptyset$  do
  [5]   Select and remove an exploded-graph node  $\langle n, d \rangle$  from NodeWorkList
  [6]   switch( $n$ )
  [7]   case  $n$  is the start node of  $p$ :
  [8]     for each  $c$  that is a call node inside  $p$  do
  [9]       for each  $d'$  such that  $f' = \text{JumpFn}(\langle n, d \rangle \rightarrow \langle c, d' \rangle) \neq \lambda l. \top$  do
  [10]        PropagateValue( $\langle c, d' \rangle, f' \cap \text{val}(\langle s_p, d \rangle)$ ) od od endcase
  [11]   case  $n$  is a call node in  $p$ , calling a procedure  $q$ :
  [12]     for each  $d'$  such that  $\langle n, d \rangle \rightarrow \langle s_q, d' \rangle \in E^s$  do
  [13]       PropagateValue( $\langle s_q, d' \rangle, \text{EdgeFn}(\langle n, d \rangle \rightarrow \langle s_q, d' \rangle) \cap \text{val}(\langle n, d \rangle)$ ) od endcase
  [14]   end switch od
  /* Phase II(ii) */
  [15] for each node  $n$ , in a procedure  $p$ , that is not a call or a start node do
  [16] for each  $d', d$  such that  $f' = \text{JumpFn}(\langle s_p, d' \rangle \rightarrow \langle n, d \rangle) \neq \lambda l. \top$  do
  [17]   val( $\langle n, d \rangle$ ) :=  $\text{val}(\langle n, d' \rangle) \cap f' \cap \text{val}(\langle s_p, d' \rangle)$  od od
  end

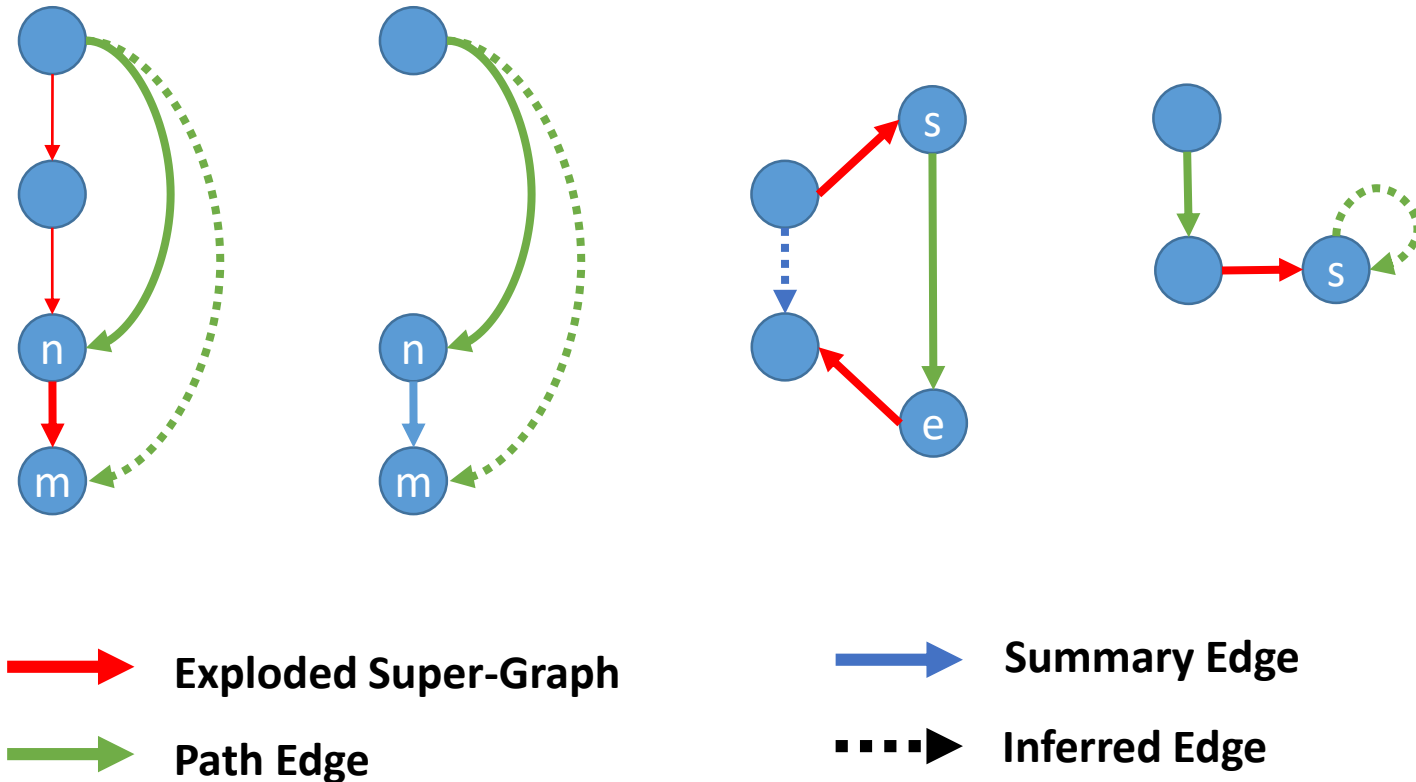
procedure PropagateValue( $n^i, v$ )
begin
  [18] let  $v' = v \cap \text{val}(n^i)$ 
  [19] if  $v' \neq \text{val}(n^i)$  then
  [20]   val( $n^i$ ) :=  $v'$ 
  [21] Insert  $n^i$  into NodeWorkList fi
  end

```

IFDS

- Input: the **exploded super-graph**.
 - The super-graph is the inter-procedural CFG.
 - The exploded super-graph is a copy of the CFG for each analysis element (in the distributive subset).
- Output: **Path Edges** + **Summary Edges**.

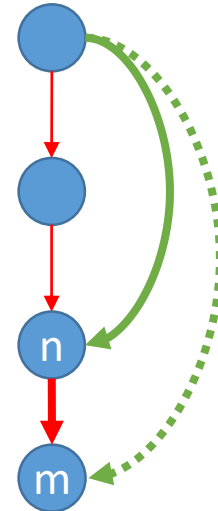
IFDS – Graphical Formulation



IFDS

(node, element)-pair

```
PathEdge(d1, m, d3) :-  
  PathEdge(d1, n, d2),  
  CFG(n, m),  
  d3 <- eshIntra(n, d2).
```



- The CFG is represented as a *tabulated relation*.
- The exploded super-graph (`eshIntra`) must be represented as a *function computed on-demand*.

IFDS



```

PathEdge(d1, m, d3) :-
    CFG(n, m),
    PathEdge(d1, n, d2),
    d3 <- eshIntra(n, d2).
PathEdge(d1, m, d3) :-
    CFG(n, m),
    PathEdge(d1, n, d2),
    SummaryEdge(n, d2, d3).
PathEdge(d3, start, d3) :-
    PathEdge(d1, call, d2),
    CallGraph(call, target),
    EshCallStart(call, d2, target, d3),
    StartNode(target, start).
SummaryEdge(call, d4, d5) :-
    CallGraph(call, target),
    StartNode(target, start),
    EndNode(target, end),
    EshCallStart(call, d4, target, d1),
    PathEdge(d1, end, d2),
    d5 <- eshEndReturn(target, d2, call).

EshCallStart(call, d, target, d2) :-
    PathEdge(_, call, d),
    CallGraph(call, target),
    d2 <- eshCallStart(call, d, target).

Result(n, d2) :-
    PathEdge(_, n, d2).
    
```

IDE

```

JumpFn(d1, m, d3, comp(long, short)) :-
    CFG(n, m),
    JumpFn(d1, n, d2, long),
    (d3, short) <- eshIntra(n, d2).
JumpFn(d1, m, d3, comp(caller, summary)) :-
    CFG(n, m),
    JumpFn(d1, n, d2, caller),
    SummaryFn(n, d2, d3, summary).
JumpFn(d3, start, d3, identity()) :-
    JumpFn(d1, call, d2, _),
    CallGraph(call, target),
    EshCallStart(call, d2, target, d3, _),
    StartNode(target, start),
    SummaryFn(call, d4, d5, comp(comp(cs, se), er)) :-
        CallGraph(call, target),
        StartNode(target, start),
        EndNode(target, end),
        EshCallStart(call, d4, target, d1, cs),
        JumpFn(d1, end, d2, se),
        (d5, er) <- eshEndReturn(target, d2, call).

EshCallStart(call, d, target, d2, cs) :-
    JumpFn(_, call, d, _),
    CallGraph(call, target),
    (d2, cs) <- eshCallStart(call, d, target).

InProc(p, start) :- StartNode(p, start).
InProc(p, m) :- InProc(p, n), CFG(n, m).

Result(n, d, apply(fn, vp)) :-
    ResultProc(proc, dp, vp),
    InProc(proc, n),
    JumpFn(dp, n, d, fn).

ResultProc(proc, dp, apply(cs, v)) :-
    Result(call, d, v),
    EshCallStart(call, d, proc, dp, cs).
    
```

flix/flix: The Flix Programming Language

GitHub, Inc. [US]https://github.com/flix/flix

This repository

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The Flix Programming Language <http://flix.github.io> — Edit

3,192 commits

2 branches

2 releases

4 contributors

Branch: master

New pull request

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olhotak

add Ondřej Lhoták to contributors

Latest commit ffb7637 a day ago

doc/cheatsheet	Added contributors. Delete CLAs.	2 days ago
examples	Fix parse error in TestVerifier test (fn no longer a keyword)	25 days ago
lib	Upgrade ScalaTest to 2.2.6	25 days ago
library	WIP library.	a month ago
main	Print out the N and seed value. Also use Map instead of HashMap and a...	2 days ago
.gitignore	add target to .gitignore	6 months ago
CONTRIBUTORS.md	add Ondřej Lhoták to contributors	a day ago
LICENSE.md	Added license.	6 months ago
README.md	WIP namespaces.	3 months ago
build.sbt	Upgrade ScalaTest to 2.2.6	25 days ago

README.md

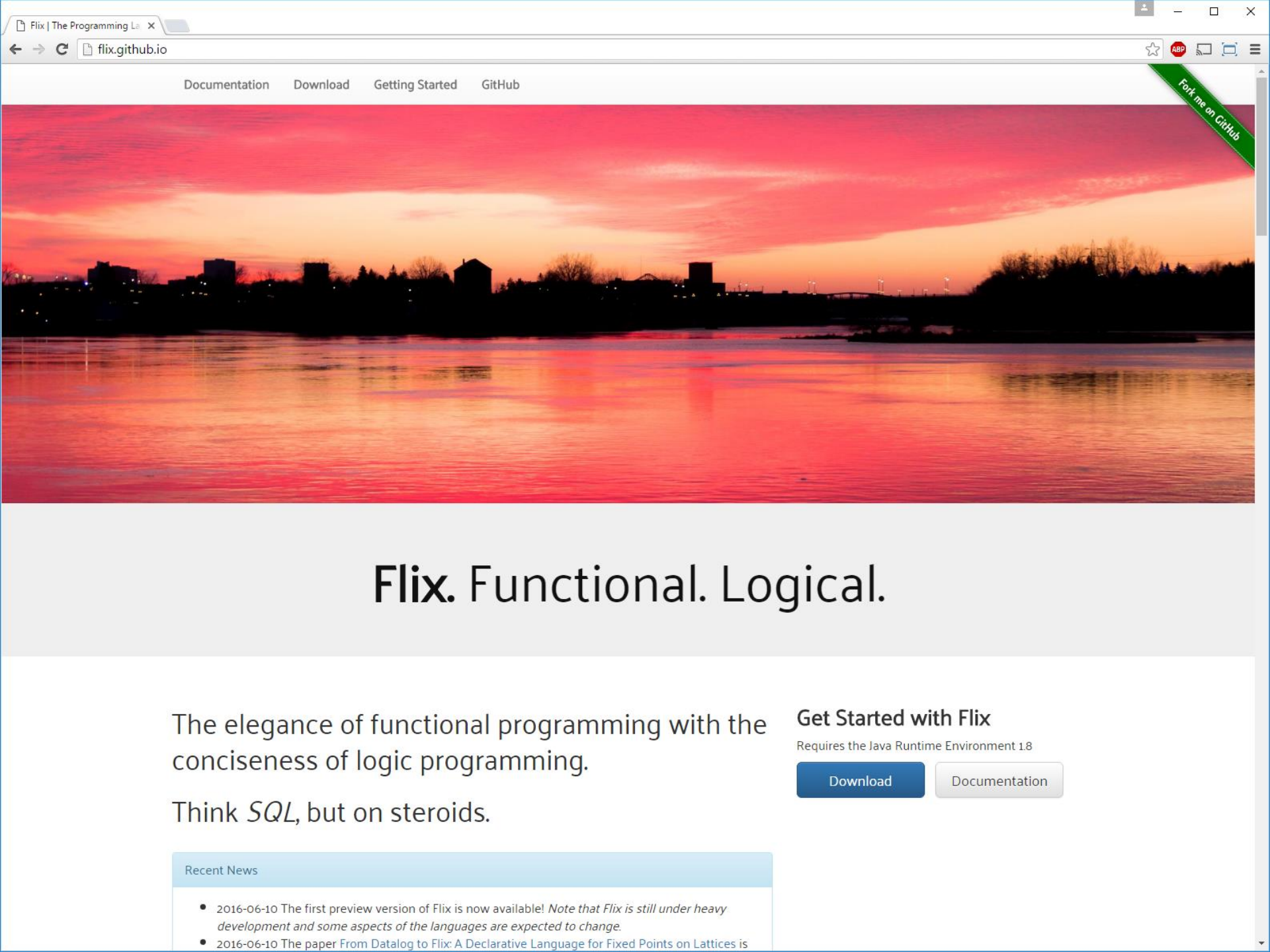
The Flix Programming Language

Main repository for the source code of the Flix compiler and run-time.

[See the official Flix website for more information.](#)

Reporting Bugs & Feature Requests

You are most welcome to report bugs or request features on this GitHub page.



Flix. Functional. Logical.

The elegance of functional programming with the conciseness of logic programming.

Think *SQL*, but on steroids.

Get Started with Flix

Requires the Java Runtime Environment 1.8

[Download](#)

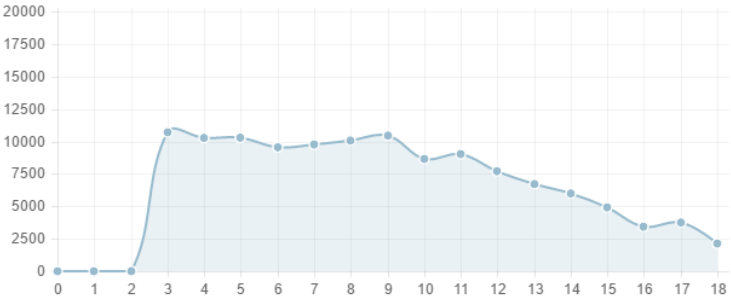
[Documentation](#)

Recent News

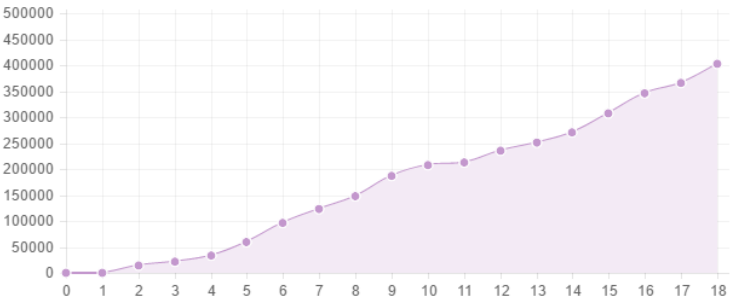
- 2016-06-10 The first preview version of Flix is now available! *Note that Flix is still under heavy development and some aspects of the languages are expected to change.*
- 2016-06-10 The paper *From Datalog to Flix: A Declarative Language for Fixed Points on Lattices* is

Welcome to the Flix Debugger

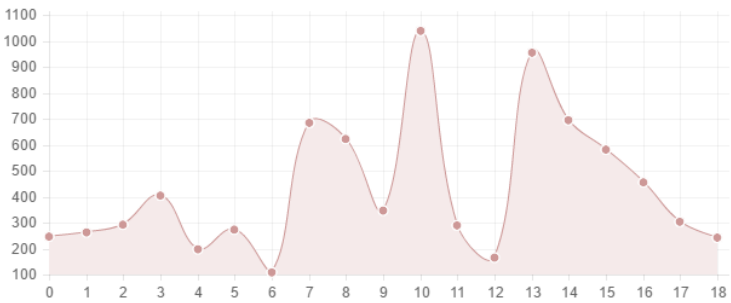
Worklist (2,130 items)



Database (402,530 facts)



Memory Usage (242 MB)



Relations

/PtH	292
/Phi	2,702
/Store	316
/Copy	481
/Clear	225
/CFG	4,525
/FiLoad	8
/FiStore	69
/Pt	4,124
/AddrOf	915
/Load	2,139
/Multi	148

Lattices

/SU	390,378
/Kill	2,967

Flix (localhost:8000)

localhost:8000/#

Flix Debugger

Minimal Model

Performance

Compiler

Refresh

Running

Performance / Rules

The table shows the number of milliseconds spent in evaluation of each rule.

Location	Rule	Hits	Total Time (msec)	Latency (msec/op)	Throughput (ops/msec)
SUopt.flix:102:1	SU(l2,a,t) :- CFG(l1, l2), SU(l1,a,t), killNot(a, k), Kill(l2,k).	918,300	18,582 msec	0.0202 msec/op	49 ops/msec
SUopt.flix:86:1	Pt(p,b) :- Load(l,p,q), Pt(q,a), filter(t, b), PtH(a,b), SU(l,a,t).	930,051	3,745 msec	0.0040 msec/op	248 ops/msec
SUopt.flix:101:1	SU(l2,a,t) :- CFG(l1, l2), SU(l1,a,t), Multi(a).	915,193	3,245 msec	0.0035 msec/op	282 ops/msec
SUopt.flix:112:1	SU(l,a,f(b)) :- Clear(l), PtH(a,b).	810	784 msec	0.9679 msec/op	1 ops/msec
SUopt.flix:118:1	Kill(l, top(42)) :- Phi(l,_,_).	1	133 msec	133.0000 msec/op	0 ops/msec
SUopt.flix:79:1	SU(l,a,f(b)) :- Store(l,p,q), Pt(p,a), Pt(q,b).	28,099	62 msec	0.0022 msec/op	453 ops/msec
SUopt.flix:81:1	PtH(a,b) :- Store(l,p,q), Pt(p,a), Pt(q,b).	28,099	50 msec	0.0018 msec/op	562 ops/msec
SUopt.flix:87:1	Pt(p,b) :- FILoad(p,q,_), Pt(q,a), PtH(a,b).	14,859	27 msec	0.0018 msec/op	550 ops/msec
SUopt.flix:82:1	PtH(a,b) :- FIStore(p,q,_), Pt(p,a), Pt(q,b).	28,099	25 msec	0.0009 msec/op	1,124 ops/msec
SUopt.flix:74:1	Pt(p,a) :- Copy(p,q), Pt(q,a).	14,050	23 msec	0.0016 msec/op	611 ops/msec
SUopt.flix:70:1	Pt(p,a) :- AddrOf(p,a).	1	17 msec	17.0000 msec/op	0 ops/msec
SUopt.flix:117:1	Kill(l,f(b)) :- Store(l,p,q), Pt(p,b).	14,050	14 msec	0.0010 msec/op	1,004 ops/msec

What's in the paper: **MATH**

(just a bit ...)

- From Datalog to Flix semantics:
 - explains the relationship between Datalog and Flix.
 - develops the model-theoretic semantics of Flix.
- Presents semi-naïve evaluation for Flix:
 - the basis for efficient Datalog and Flix solvers.
- Experimental results and details of analyses:
 - the Strong Update analysis, and
 - the IFDS Alias-Set analysis.

Summary: Flix!

- A new declarative and functional programming language for fixed point computations on lattices.
- Inspired by Datalog and extended with lattices and monotone transfer/filter functions.
- Implementation freely available:

<http://github.com/flix>

- Documentation and more information:

<http://flix.github.io>

Thank You!

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