



# Polymorphic Type Inference for Machine Code

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## The challenge

Given an optimized, real-world binary with no debug information, recover the original source-level types of program variables in the binary.

## What is it good for?

- Reverse-engineering and program understanding.
- Better decompilation [Schwartz et al., 2013]
- Narrowing the focus of further analysis passes.

# Why is type reconstruction difficult?

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## Challenges

- Accurate disassembly is hard!
- C and C++ have unsound type systems.
- Programmers introduce ad-hoc type disciplines.
- Polymorphic functions exist!
- Compiler optimizations can be performed on type-erased code.

## Examples

```
;; disassemble...  
call foo  
;; ...now keep going?
```

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## Examples

- Bit-twiddling
- Untagged unions and type-punning
- Quake III inverse sqrt
- Stealing unused pointer bits
- Downcasts (from generic to specific)
- xor-combined doubly-linked lists

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## Examples

- typedef aliases  
(HANDLE, size\_t)
- Basic types with specific purposes  
(file descriptors, IP addresses)
- Entire un-enforced type hierarchies!  
(HBRUSH *extends* HGDIOBJ)

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## Examples

- Nominal subtype polymorphism
- Physical subtype polymorphism  
`struct { FILE* x; char* y; }`  
*extends* `FILE*`
- Emulated polytypes  
(allocators, `memcpy`)

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## Examples

```
T * get_T(void)
{
    S * s = get_S();
    if (s == NULL) {
        return NULL;
    }
    T * t = S2T(s);
    return t;
}
```

```
get_T:
    call get_S
    test eax, eax
    jz    local_exit
    push eax
    call S2T
    add   esp, 4
local_exit:
    ret
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# Type system desiderata

Based on a survey of idioms found in optimized C and C++ binaries, we need

- Subtypes (nominal and physical)
- Polymorphic functions
- Recursive types

and a reconstruction algorithm that is

- Scalable
- Not unification-driven
- Does not require much sound points-to data

# Static approaches to type reconstruction

|                    | TIE            | SecondWrite        | Theory Prop.   | Retypd            |
|--------------------|----------------|--------------------|----------------|-------------------|
| Appeared in        | NDSS '11       | PLDI '13           | PPDP '13       | <u>PLDI '16</u>   |
| Allows subtypes?   | Limited        | No                 | No             | Yes               |
| Points-to oracle?  | Yes (DVSA)     | Best-effort pts-to | via SMT        | Stack only        |
| Recursive types?   | Indirect       | Indirect           | Yes            | Yes               |
| Polymorphic types? | No             | No                 | No             | Yes               |
| Type system        | C-like lattice | C-like lattice     | Rational trees | Decorated trees   |
| Concept            | Intervals      | Unsound pts-to     | SMT            | Pushdown automata |

- Lee et al. [2011]: infer types by tracking lattice constraints.
- ElWazeer et al. [2013]: sound points-to analysis may not be required.
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# The constraint system

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# From a program to a constraint set

- Abstract location  $X \rightsquigarrow$  basic type variable  $x$ .
- Dataflow between abstract locations  $\rightsquigarrow$  subtype constraints:

$$\text{mov } \text{eax}, \text{ebx} \rightsquigarrow \text{ebx}_p \sqsubseteq \text{eax}_q$$

- Observed capabilities of a type variable are encoded with field labels:

$$\text{mov } \text{eax}, [\text{ebx}] \rightsquigarrow \text{ebx}_p.\text{load}.\text{@0} \sqsubseteq \text{eax}_q$$

- ...even for function types!

$$X = F(Y) \rightsquigarrow f.\text{out}_{\text{eax}} \sqsubseteq x, \quad y \sqsubseteq f.\text{in}_{\text{stack0}}$$

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# Derived typing judgements

In addition to standard judgements for subtype relations, we would like to infer constraints between derived type variables.

$$x \sqsubseteq y, \quad x.@4 \text{ exists}, \quad y.@4 \text{ exists} \quad \vdash \quad x.@4 \sqsubseteq y.@4$$

**Caveat:** Some of the capabilities must act contravariantly!

Mutable references,  $x \sqsubseteq y$ :

$$\begin{aligned} x.\text{load} &\sqsubseteq y.\text{load} \\ y.\text{store} &\sqsubseteq x.\text{store} \end{aligned}$$

Functions,  $f \sqsubseteq g$ :

$$\begin{aligned} f.\text{out}_{\text{eax}} &\sqsubseteq g.\text{out}_{\text{eax}} \\ g.\text{in}_{\text{stack0}} &\sqsubseteq f.\text{in}_{\text{stack0}} \end{aligned}$$

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# Constraint entailment rules

$$\frac{\alpha \sqsubseteq \beta}{\alpha \text{ exists}} \text{ (T-Left)}$$

$$\frac{\alpha \sqsubseteq \beta}{\beta \text{ exists}} \text{ (T-Right)}$$

$$\frac{\alpha \text{ exists}}{\alpha \sqsubseteq \alpha} \text{ (S-Refl)}$$

$$\frac{\alpha \sqsubseteq \beta, \beta \sqsubseteq \gamma}{\alpha \sqsubseteq \gamma} \text{ (S-Trans)}$$

$$\frac{\alpha \sqsubseteq \beta, \alpha.l \text{ exists}}{\beta.l \text{ exists}} \text{ (T-InheritL)}$$

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$$\frac{\alpha.l \text{ exists}}{\alpha \text{ exists}} \text{ (T-Prefix)}$$

$$\frac{\alpha \sqsubseteq \beta, \beta.l \text{ exists, } l \text{ covariant}}{\alpha.l \sqsubseteq \beta.l} \text{ (S-Field}_{\oplus}\text{)}$$

$$\frac{\alpha \sqsubseteq \beta, \beta.l \text{ exists, } l \text{ contravariant}}{\beta.l \sqsubseteq \alpha.l} \text{ (S-Field}_{\ominus}\text{)}$$

$$\frac{\alpha.\text{load exists, } \alpha.\text{store exists}}{\alpha.\text{store} \sqsubseteq \alpha.\text{load}} \text{ (S-Pointer)}$$

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Challenge: Prove  $X \sqsubseteq Y$  for the program

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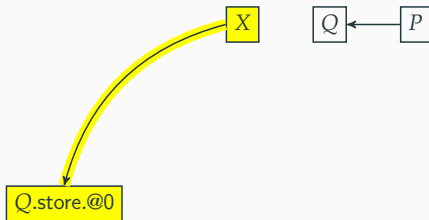


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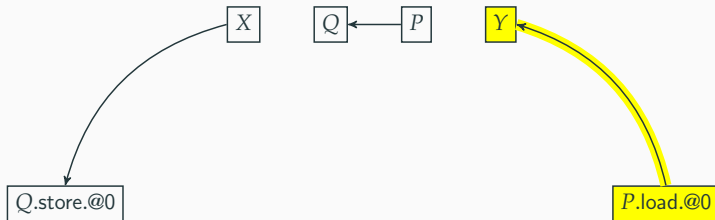


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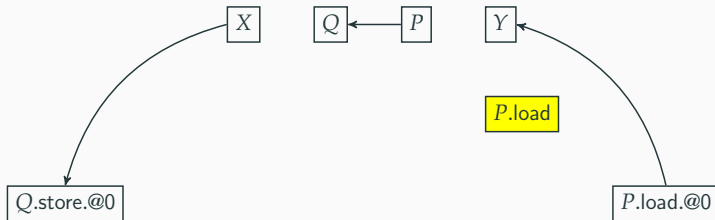


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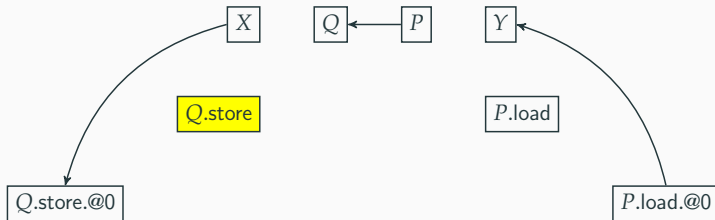
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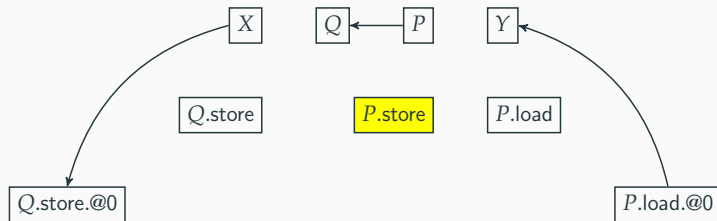
$$\frac{Q.\text{store}.\text{@0} \text{ exists}}{Q.\text{store} \text{ exists}} \text{ (T-Prefix)}$$

# Who needs points-to analysis?

**Challenge:** Prove  $X \sqsubseteq Y$  for the program

$$\begin{array}{l} q := p; \\ *q := x; \\ y := *p; \end{array} : \left\{ \begin{array}{l} P \sqsubseteq Q \\ X \sqsubseteq Q.\text{store}.\text{@0} \\ P.\text{load}.\text{@0} \sqsubseteq Y \end{array} \right\}$$

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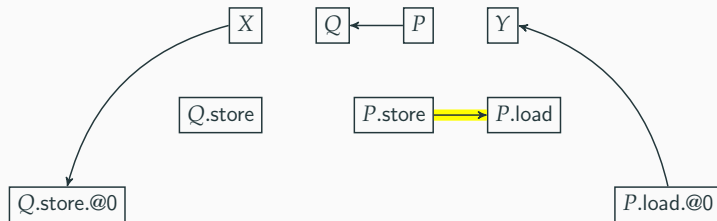
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$$\frac{P.\text{load exists}, \quad P.\text{store exists}}{P.\text{store} \sqsubseteq P.\text{load}} \text{ (S-Pointer)}$$

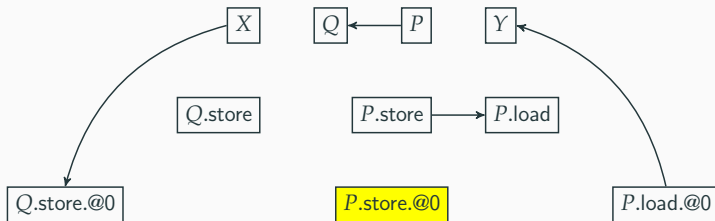


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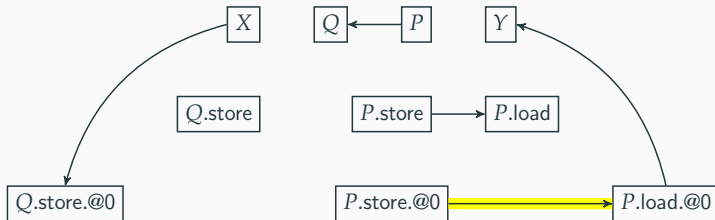
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$$\frac{\begin{array}{l} P.\text{store} \sqsubseteq P.\text{load}, \\ P.\text{load}.\text{@0} \text{ exists}, \\ \text{@0 covariant} \end{array}}{P.\text{store}.\text{@0} \sqsubseteq P.\text{load}.\text{@0}} \text{ (S-Field}_{\oplus}\text{)}$$

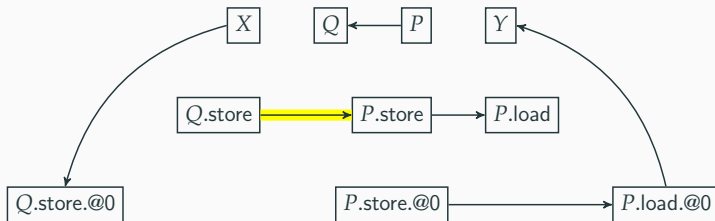
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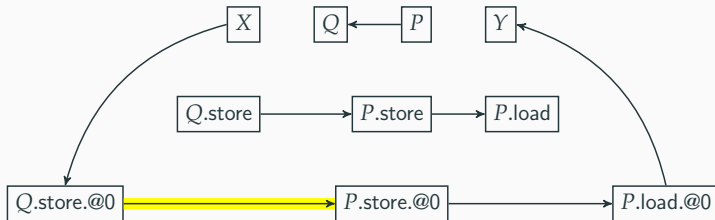
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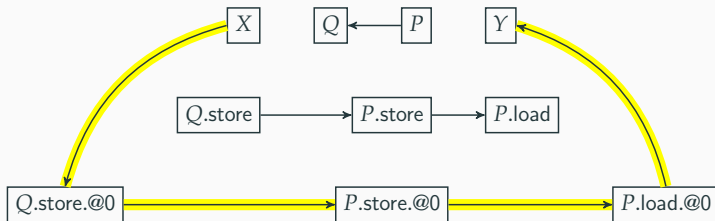
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## The problem with recursive constraints

One constraint entailed infinitely many; no finite graph suffices.

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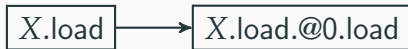
X.load

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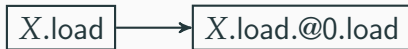


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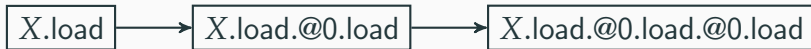


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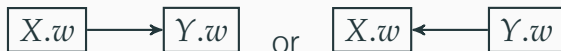
# Taming the infinite

---

# Abstracting the tails

What went wrong in the recursive example?

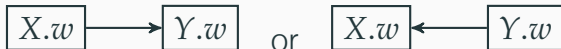
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**Solution: Abstract away the tails**

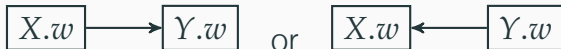
Collapse all of these edges into just two!



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Collapse all of these edges into just two!



$\{X.w \mid \mathcal{C} \vdash X.w \text{ exists} \wedge w \text{ covariant seq.}\}$

## Labeled edges in the finite graph

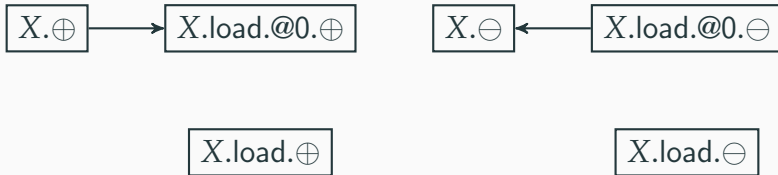
$$\mathcal{C} = \{X \sqsubseteq X.\text{load}.\text{@0}\}$$





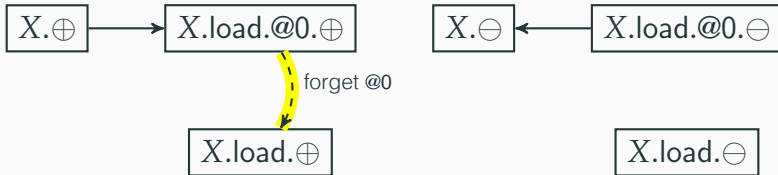
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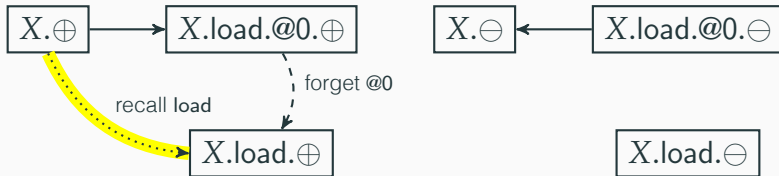
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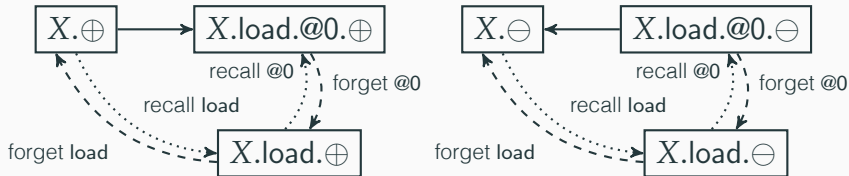
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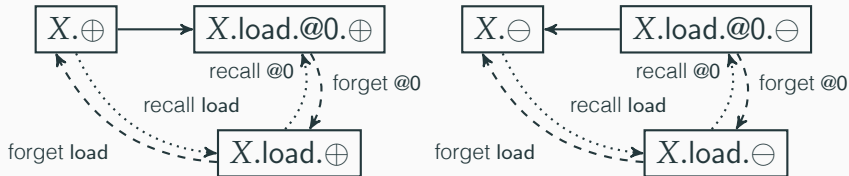
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$$\text{forget } \alpha \cdot \text{recall } \alpha = 1$$

$$\text{forget } \alpha \cdot \text{recall } \beta = 0$$

# What can you get from manipulating constraints as graphs?

- Automata that recognize the entailment closure  $\overline{\mathcal{C}} = \{c \mid \mathcal{C} \vdash c\}$
- Simplified / minimized constraint sets for type schemes.
- Satisfiability checks.
- Construction of sketches (marked regular trees) satisfying the constraints.

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## Example: A recursive type in the wild

```
#include <stdlib.h>

struct LL
{
    struct LL * next;
    int handle;
};

int close_last(struct LL * list)
{
    while (list->next != NULL)
    {
        list = list->next;
    }
    return close(list->handle);
}
```

```
close_last:
    push    ebp
    mov     ebp, esp
    sub     esp, 8
    mov     edx, dword [ebp+arg_0]
    jmp     loc_8048402

loc_8048400:
    mov     edx, eax

loc_8048402:
    mov     eax, dword [edx]
    test    eax, eax
    jnz     loc_8048400
    mov     eax, dword [edx+4]
    mov     dword [ebp+arg_0], eax
    leave
    jmp     __thunk_.close
```

## Example: A recursive type in the wild

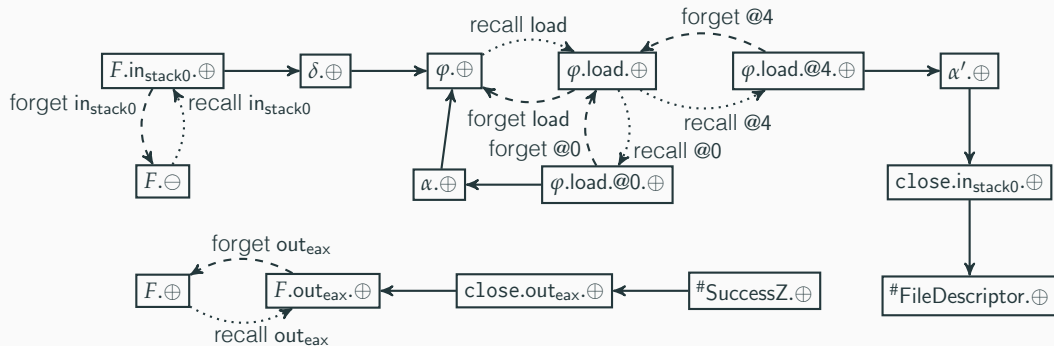
$$\begin{aligned} F.in_{stack0} &\sqsubseteq \delta \\ \alpha &\sqsubseteq \varphi \\ \delta &\sqsubseteq \varphi \\ \varphi.load.@0 &\sqsubseteq \alpha \\ \varphi.load.@4 &\sqsubseteq \alpha' \\ \alpha' &\sqsubseteq close.in_{stack0} \\ close.out_{eax} &\sqsubseteq F.out_{eax} \\ close.in_{stack0} &\sqsubseteq \#FileDescriptor \\ \#SuccessZ &\sqsubseteq close.out_{eax} \end{aligned}$$

```
close_last:
    push    ebp
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    sub     esp, 8
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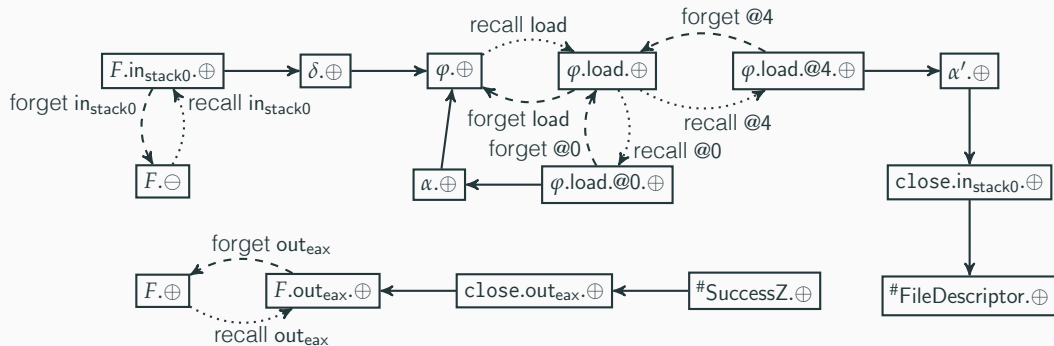
loc_8048402:
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## Example, cont'd: Simplifying constraint sets



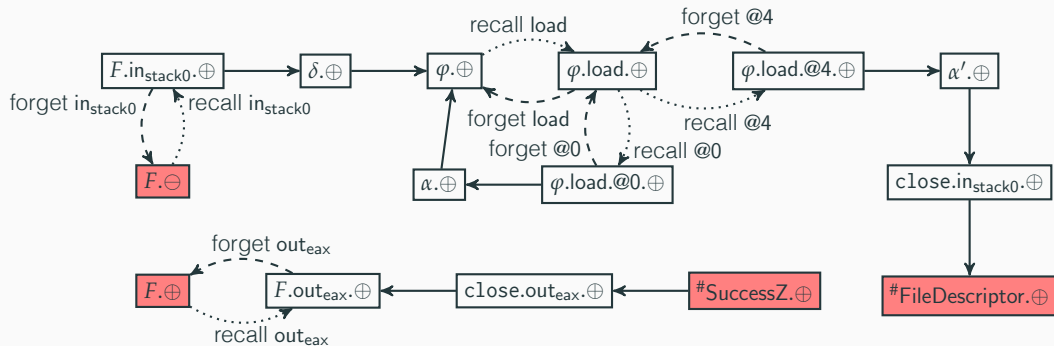
Step 1: From the constraint set, build a graph with an edge for each subtype constraint, and forget/recall-labeled edges describing the derived type variables.

## Example, cont'd: Simplifying constraint sets



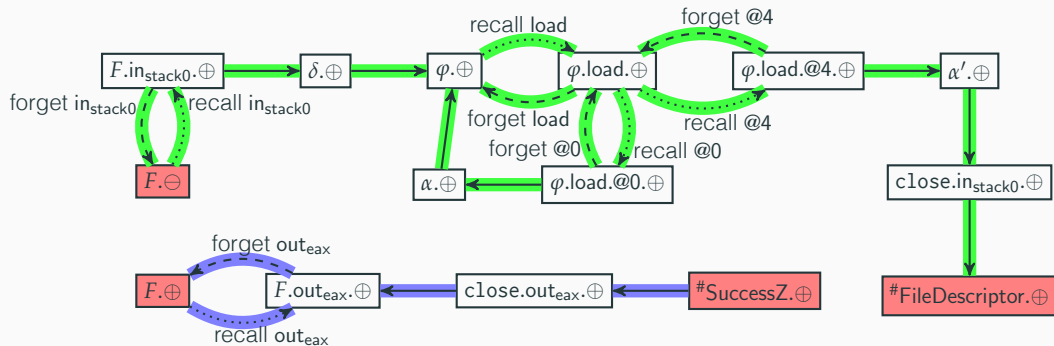
Step 2: Add edges to reify the relation  $\text{forget } \alpha \cdot \text{recall } \alpha = 1$ . Lazily instantiate applications of S-Pointer as needed.

## Example, cont'd: Simplifying constraint sets



Step 3: Identify the “externally-visible” type variables and constants; call that set  $\mathcal{E}$ .

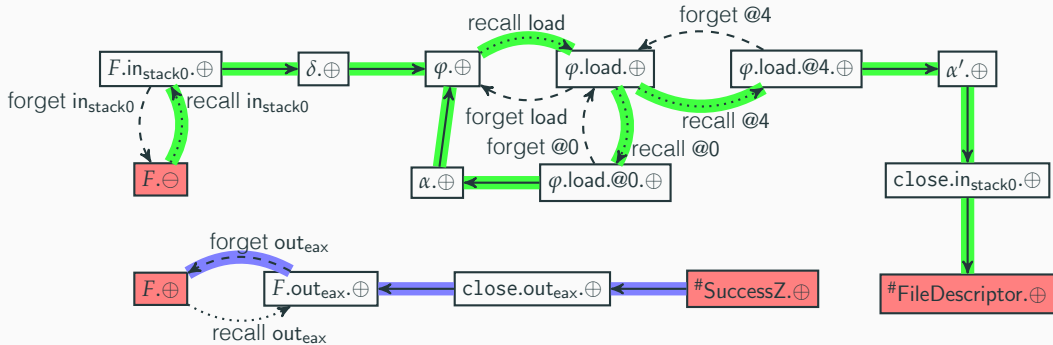
## Example, cont'd: Simplifying constraint sets



Step 4: Use Tarjan's path-expression algorithm to describe all paths that start and end in  $\mathcal{E}$  but only travel through  $\mathcal{E}^c$ .

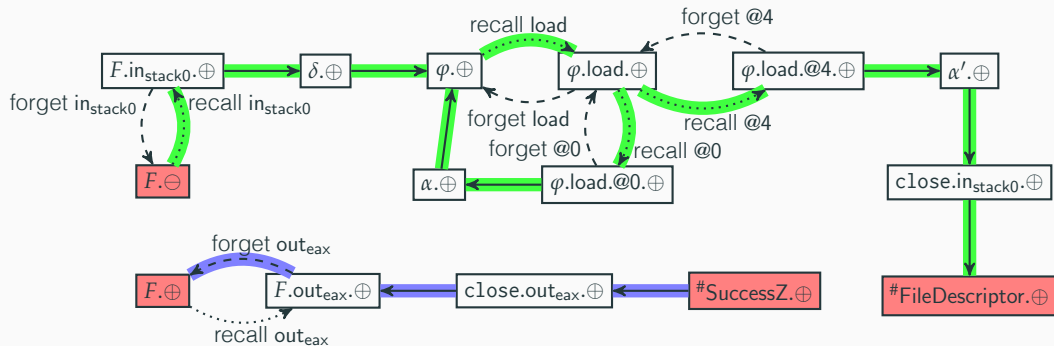


## Example, cont'd: Simplifying constraint sets



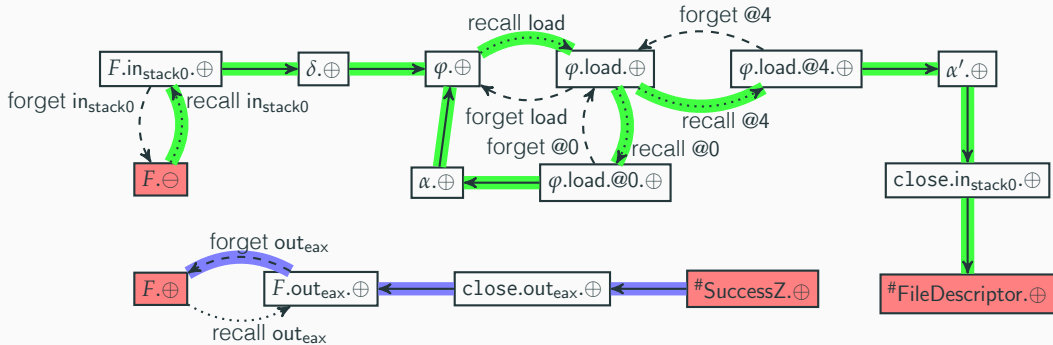
Step 5: Intersect the path expressions with the language  $(\text{recall } \_ )^*(\text{forget } \_ )^*$ .

## Example, cont'd: Simplifying constraint sets

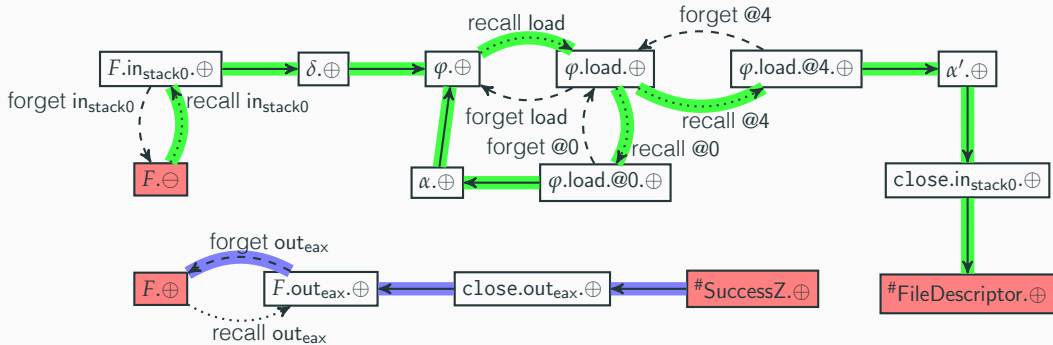


Step 6: Interpret the resulting language as a regular set of subtype constraints. (“forgets” on the right, “recalls” on the left)

## Example, cont'd: Simplifying constraint sets

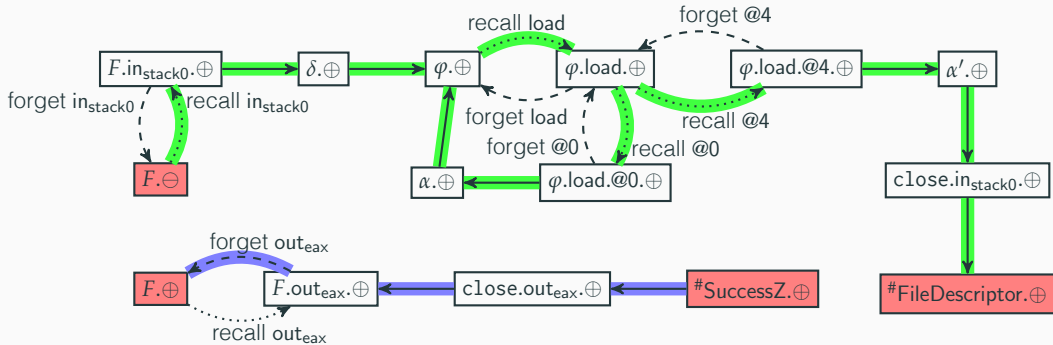

$$\begin{array}{ll} \# \text{SuccessZ} & \rightsquigarrow F : \text{forget out}_{\text{eax}} \\ F & \rightsquigarrow \# \text{FileDescriptor} : \text{recall } (\text{in}_{\text{stack0}} \cdot (\text{load} \cdot @0)^* \cdot \text{load} \cdot @4) \end{array}$$

## Example, cont'd: Simplifying constraint sets



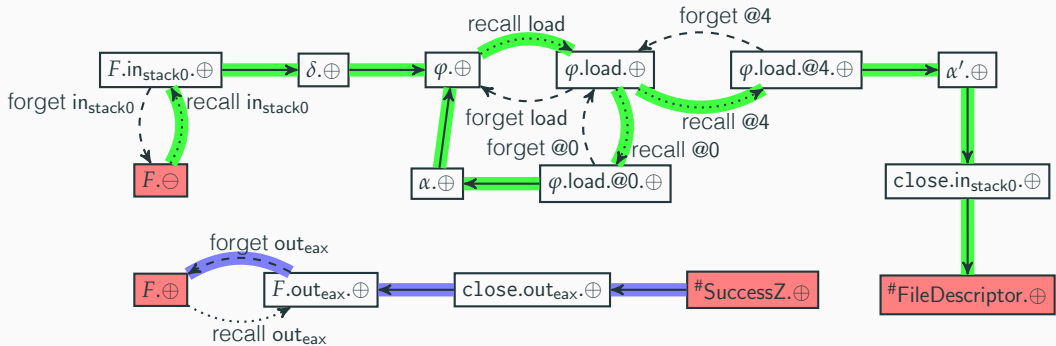
$$\mathcal{C} = \left\{ \begin{array}{l} \# \text{SuccessZ} \sqsubseteq F.\text{out}_{\text{eax}} \\ F.\text{in}_{\text{stack0}} \text{ (.load.@0)* .load.@4} \sqsubseteq \# \text{FileDescriptor} \end{array} \right\}$$

## Example, cont'd: Simplifying constraint sets



$$\mathcal{C} = \left\{ \begin{array}{l} \# \text{SuccessZ} \sqsubseteq F.\text{out}_{\text{eax}} \\ F.\text{in}_{\text{stack0}} (. \text{load} . @0)^* . \text{load} . @4 \sqsubseteq \# \text{FileDescriptor} \end{array} \right\}$$

## Example, cont'd: Simplifying constraint sets



$$\mathcal{C} = \exists \tau. \left\{ \begin{array}{l} \#SuccessZ \sqsubseteq F.out_{eax} \\ F.in_{stack0} \sqsubseteq \tau, \quad \tau.load.@0 \sqsubseteq \tau, \quad \tau.load.@4 \sqsubseteq \#FileDescriptor \end{array} \right\}$$

## Example, cont'd: Getting back to C types

```
#include <stdlib.h>

struct LL
{
    struct LL * next;
    int handle;
};

int close_last(struct LL * list)
{
    while (list->next != NULL)
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        list = list->next;
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## Example, cont'd: Getting back to C types

`close_last` :  $\forall F. (\exists \tau. \mathcal{C}) \Rightarrow F$

where

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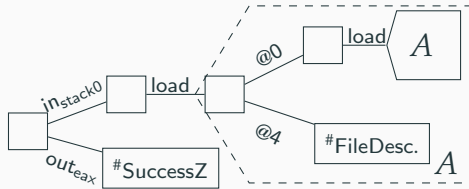


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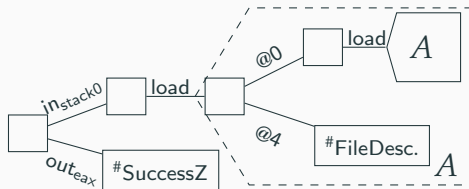


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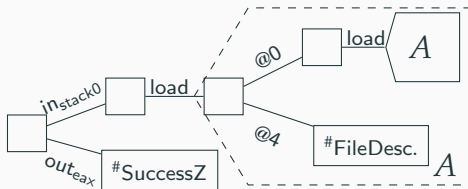
```
typedef struct Struct_0 {  
    struct Struct_0 * field_0;  
    int // #FileDescriptor  
        field_4;  
} Struct_0;  
  
int // #SuccessZ  
close_last(const Struct_0 *);
```

## Example, cont'd: Getting back to C types

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#include <stdlib.h>

struct LL
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    int handle;
};

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        list = list->next;
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## Evaluation of the technique

---

# Benchmark suite

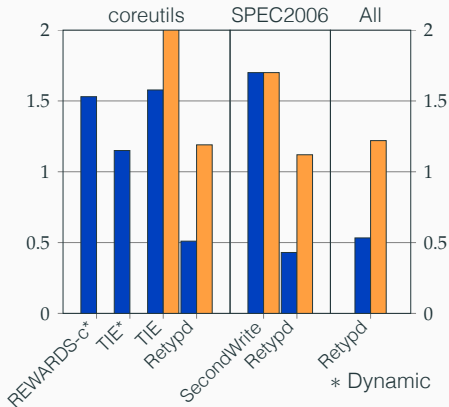
Retypd was evaluated on a suite of 160 optimized 32-bit x86 binaries with debug information removed. Separate optimized debug builds were used to establish ground truth.

The benchmark suite included:

- A suite of real-world Windows binaries compiled with Visual Studio.
- The SPEC2006 binaries used to evaluate type inference for SecondWrite.
- The coreutils binaries used to evaluate TIE.

# Does it work?

Distance to source type      Interval size

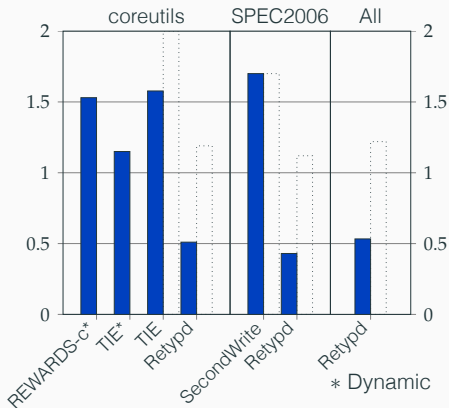


Retypd generates types that are:

- More accurate
- More tightly constrained than existing approaches.

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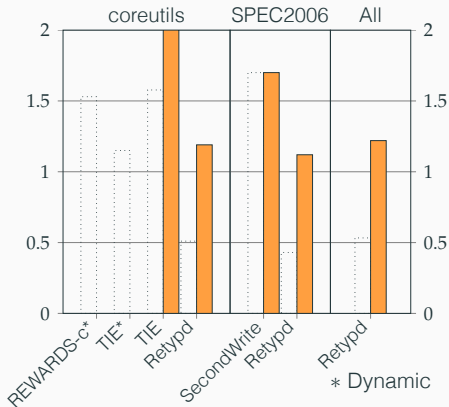


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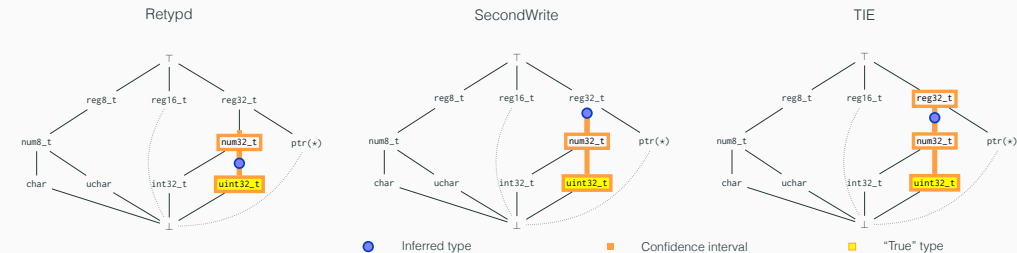
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- More tightly constrained

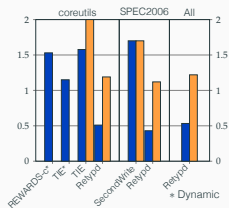
than existing approaches.



# Visualizing the precision improvement

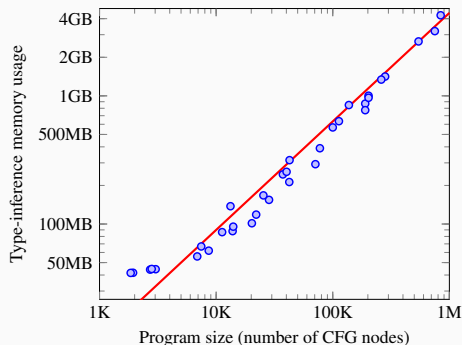
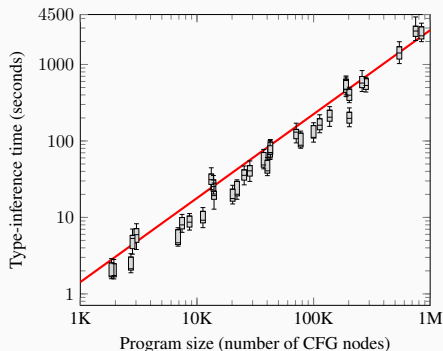


Distance to source type    Interval size



# Performance measurements

Real-world performance scales like  $N^{1.078}$  in time and  $N^{0.882}$  in memory.



# Summary

- Type reconstruction is impossible!
  - But we can do pretty well anyway.
- Common C and C++ idioms force us into an interesting corner of the type system design space, with
  - Subtypes
  - Recursive types
  - Polymorphic functions
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## References

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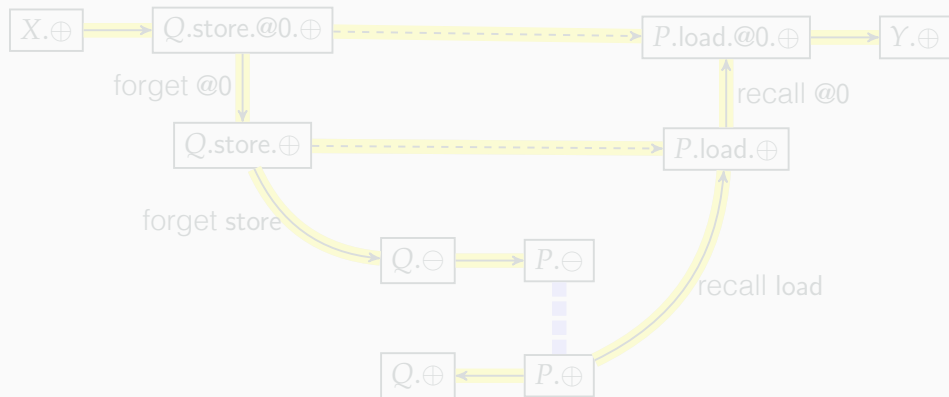


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- E. J. Schwartz, J. Lee, M. Woo, and D. Brumley. Native x86 decompilation using semantics-preserving structural analysis and iterative control-flow structuring. In Proceedings of the USENIX Security Symposium, page 16, 2013.

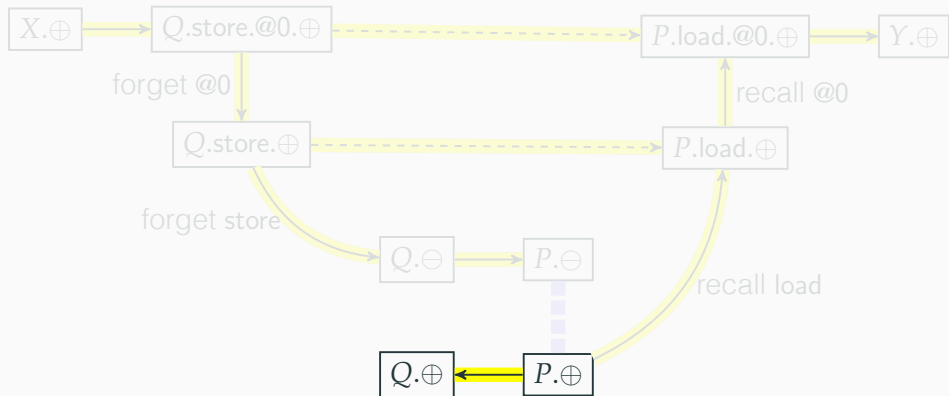
# Adding the missing edges

$$\{P \sqsubseteq Q, \quad X \sqsubseteq Q.\text{store}.\text{@0}, \quad P.\text{load}.\text{@0} \sqsubseteq Y\}$$



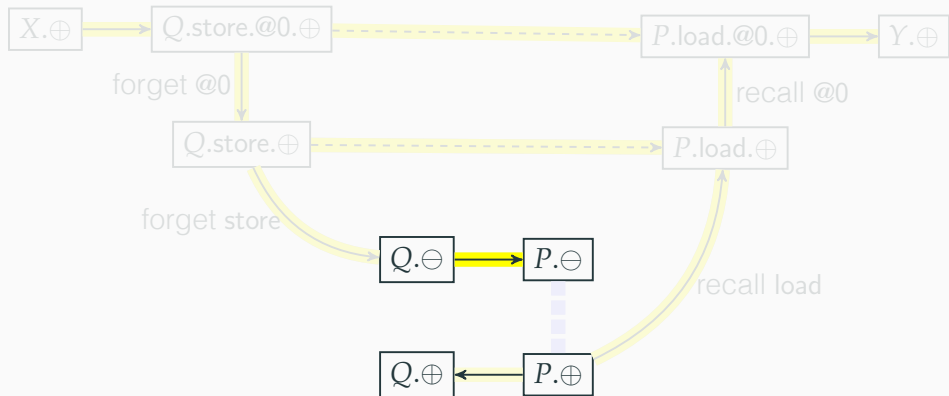
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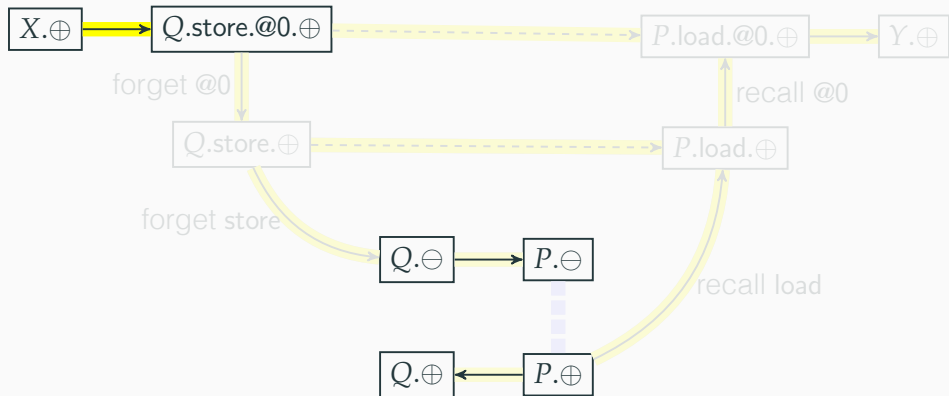
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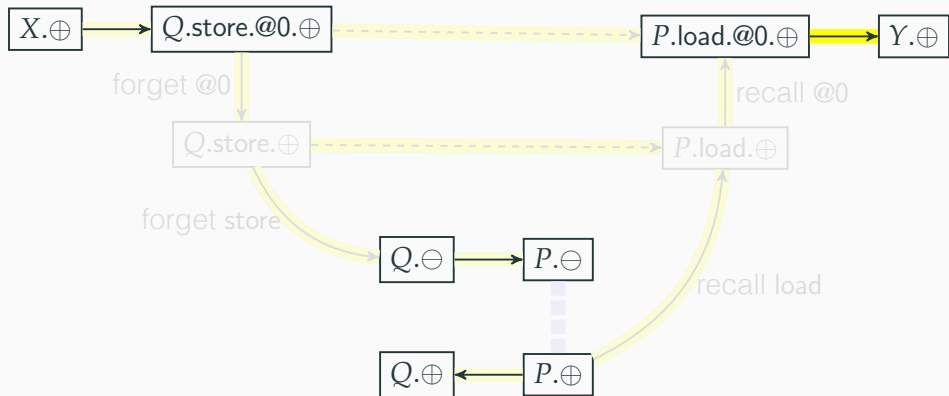
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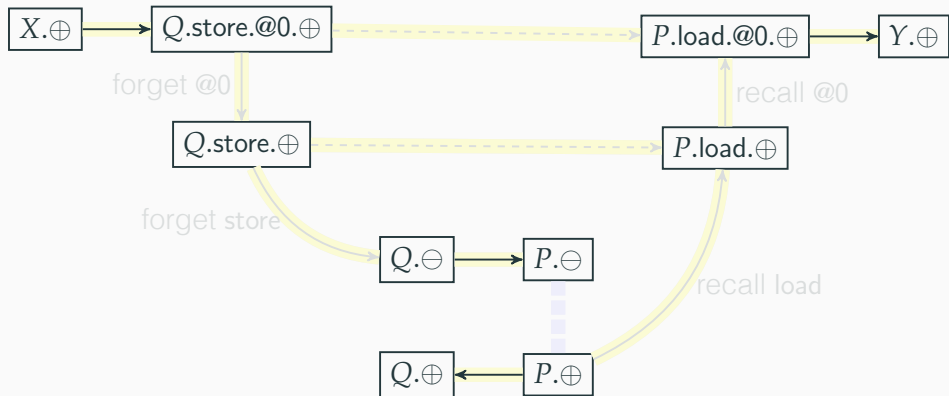
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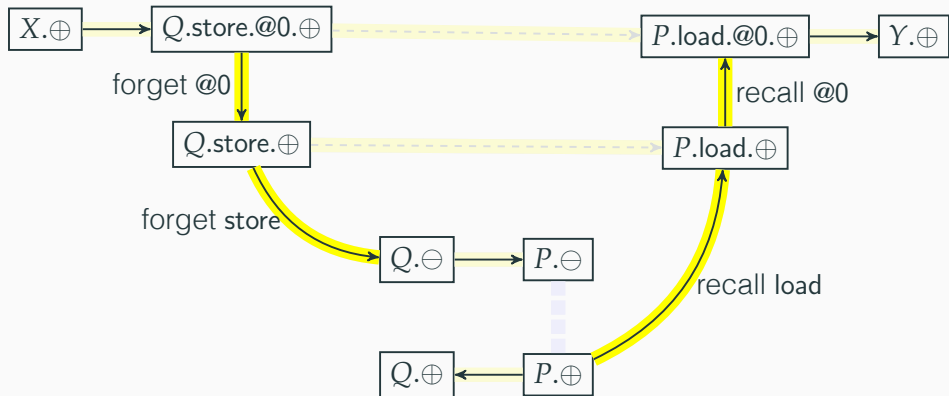
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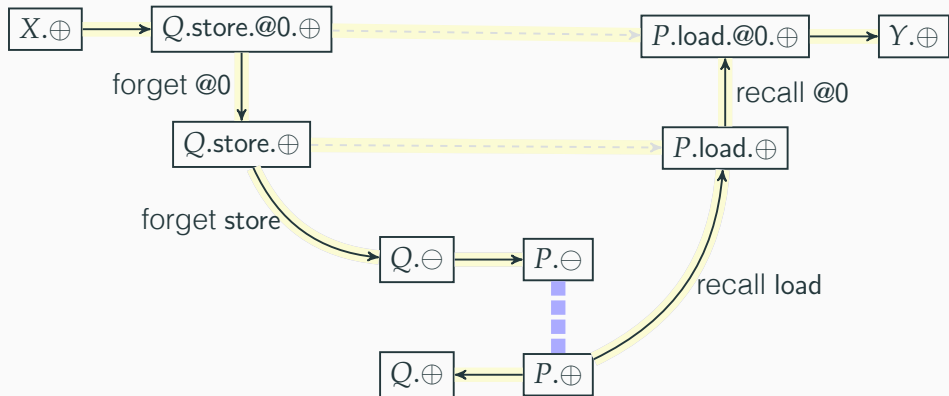
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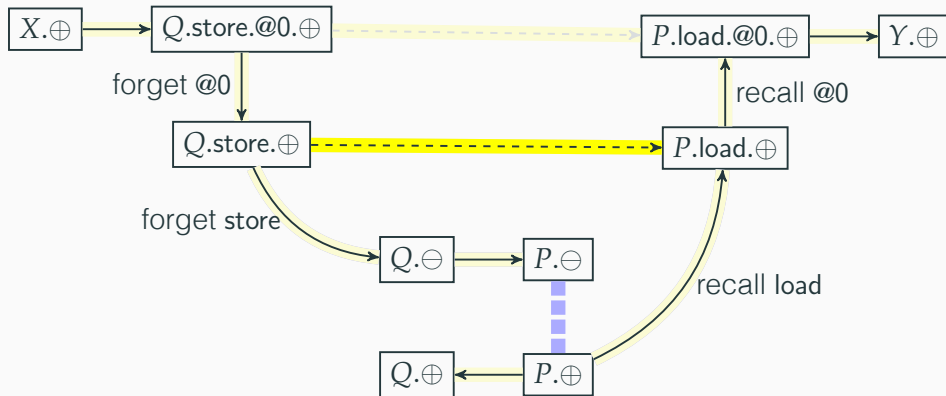
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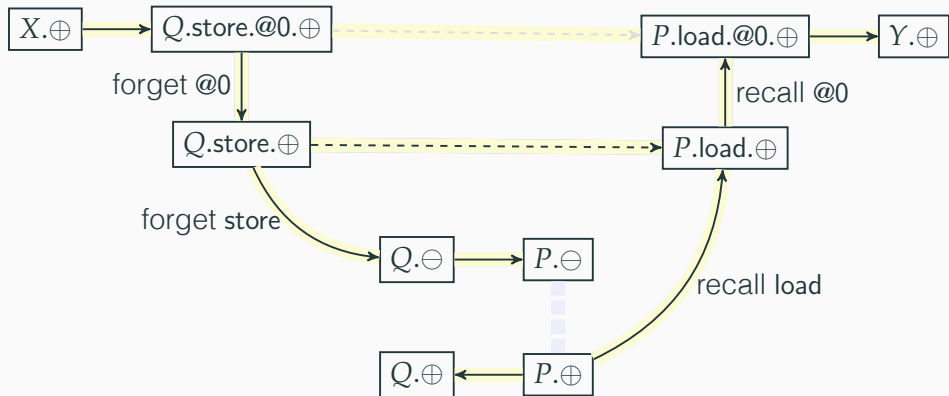
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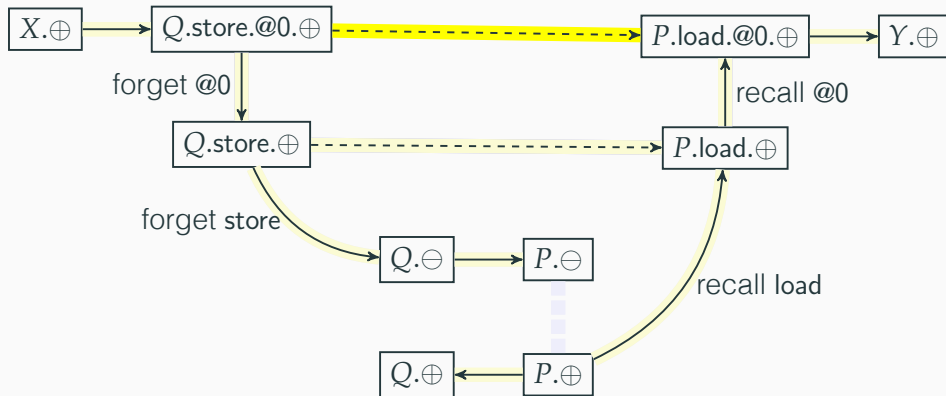
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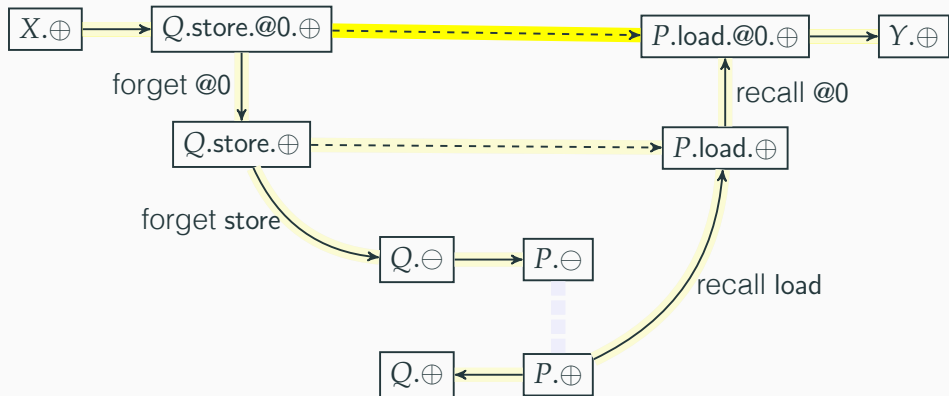
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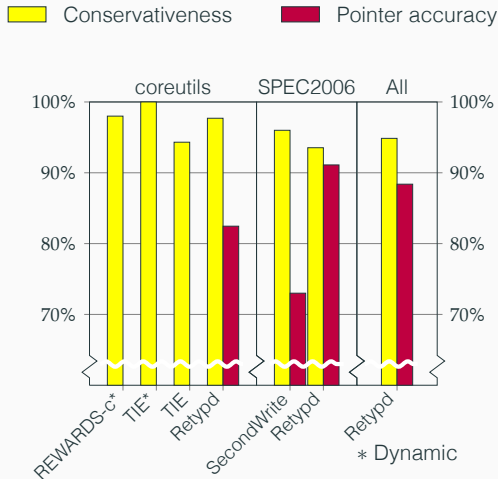
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# Does it work?

Retypd generates types that:

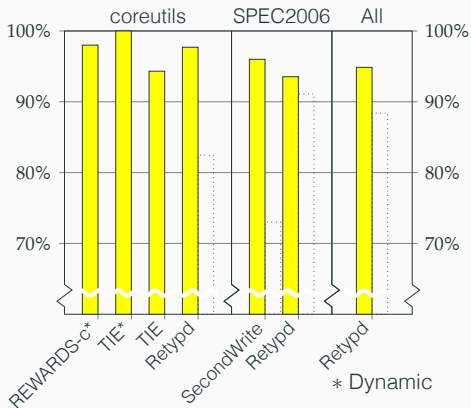
- Are comparably conservative to existing approaches
- Remain accurate at more levels of indirection [ElWazeer et al., 2013]



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Conservativeness      Pointer accuracy



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