# 02 - Network Analysis

# SYS 4582/6018 | Spring 2019

# 02-networks.pdf

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# 1 Network Intro

### 1.1 Required R Packages

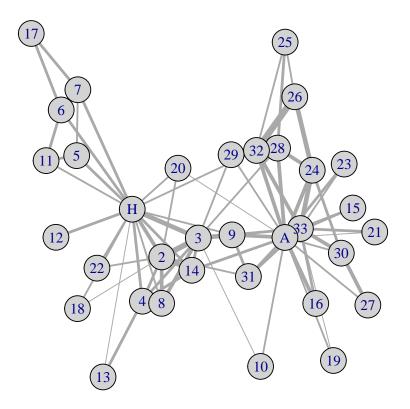
We will be using the R packages of:

- igraph for network modeling
- sand for data (supplement to book *Statistical Analysis of Network Data with R* by Kolaczyk and Csárdi)
- igraphdata for some network datasets

```
library(tidyverse)
library(igraph) # install.packages('igraph') if not installed
library(sand) # install.packages('sand') if not installed
library(igraphdata) # install.packages('igraphdata') if not installed
```

## 1.2 Example: Zachary's karate club network

```
library(igraphdata)
data(karate) # type: ?karate to see description
library(igraph)
plot(karate,
    layout=layout_with_fr(karate), # determines coordinates of nodes
    vertex.color="lightgrey", # color of vertices
    edge.width=E(karate) $weight) # edge weights
```



### **Your Turn #1**

The famous karate network is based on the social network of 34 members of a university karate club. To uncover the true relationships between club members, sociologist Wayne Zachary (Wayne W. Zachary. An Information Flow Model for Conflict and Fission in Small Groups. *Journal of Anthropological Research* Vol. 33, No. 4 452-473) documented 78 pairwise links between members who regularly interacted outside the club. The edge weights represent the

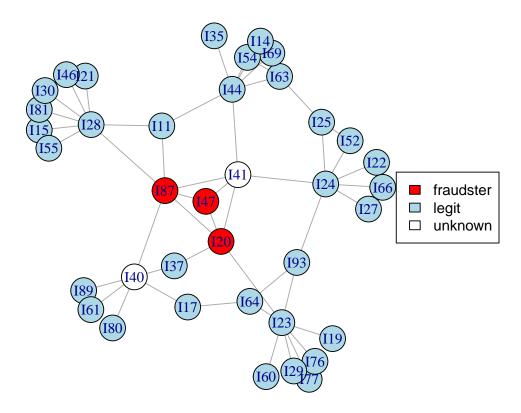
number of shared activities between the members.

The network experienced a singular event during the study period: a conflict between the club's president (Mr. Hi) and the instructor (John A) split the club into two; About half of the members followed the instructor and the other half the president. The breakup unveiled club's underlying community structure.

- 1. Do you think the graph can reveal which members will follow Mr. Hi? Why?
- 2. Which members will follow Mr. Hi? Why?

# 1.3 Example: Money Laundering Data

The DataCamp course Fraud Detection in R has some financial transaction data where some of the nodes (people) are engaged in fraudulence financial activities.



# **Your Turn #2**

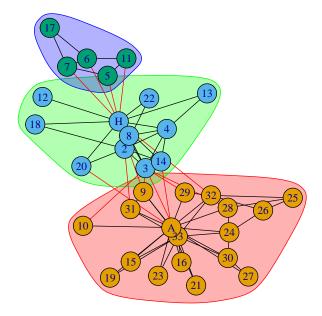
- 1. How would you classify node I40? Why?
- 2. How would you classify node I41? Why?
- 3. Does the graph layout inform your decision?

### 1.4 Community Detection for Karate

We are not going to go into details about community detection, but we can quickly run one community detection algorithm, termed *fast greedy* by igraph, that greedily optimizes something called the *modularity* score<sup>1</sup>. The basic idea of community detection (or network clustering) is to identify the nodes that form natural groups; usually based on the definition that nodes within the same community tend to have a higher probability of being connected to each other than to members of other communities.

Santo Fortunato is a good place to start if you are interested in learning more: - Community detection in networks: A user guide https://arxiv.org/abs/1608.00163 - Community detection in graphs https://arxiv.org/abs/0906.0612

```
#-- Run community detection
fg = cluster_fast_greedy(karate)
membership(fq)
   Mr Hi Actor 2 Actor 3 Actor 4 Actor 5 Actor 6 Actor 7
#>
         2
                      2
                            2
                                           3
  Actor 9 Actor 10 Actor 11 Actor 12 Actor 13 Actor 14 Actor 15 Actor 16
       1 1
                     3 2
                                   2
                                          2
                                                  1
#> Actor 17 Actor 18 Actor 19 Actor 20 Actor 21 Actor 22 Actor 23 Actor 24
       3 2
                     1 2 1
                                          2
                                                  1
#> Actor 25 Actor 26 Actor 27 Actor 28 Actor 29 Actor 30 Actor 31 Actor 32
  1 1 1 1 1
#> Actor 33 John A
       1
               1
#-- igraph has a built in plotting for communities
plot(fg, karate)
```



<sup>&</sup>lt;sup>1</sup>A Clauset, MEJ Newman, C Moore: Finding community structure in very large networks

# 2 Basic Network Concepts

### 2.1 Basic Definitions

- A graph can be represented by G = (V, E) where V are the set of vertices (also called nodes) and E is a set of edges (also called links).
- There are |V| nodes and |E| edges in G
- The edge set E is a collection of pairs, (u, v) where  $u, v \in V$ 
  - For undirected graphs, (u, v) is same as (v, u).
  - For directed graphs (digraph), (u, v) is distinct from (v, u)

### 2.2 Creating a Network

- A network needs two components:
  - 1. Nodes
  - 2. Edges
- Nodes: data frame of node labels and (optional) node attributes

- Edges: data frame of edges
  - Common to use from and to, even for undirected networks
  - optional edge attributes

```
edges = tibble(from=c(1,1,2,2,3,4,4,6,4,5,6,6),
               to= c(2,3,3,4,5,5,6,4,7,6,5,7),
               weight = c(1,1,2,2,3,3,2,2,1,1,2,2))
edges
#> # A tibble: 12 x 3
     from to weight
     <db1> <db1> <db1>
#> 1 1 2 1
         1
               3
#> 2 1 3
#> 3 2 3
#> 4 2 4
#> 5 3 5
#> 6 4 5
#> 7 4 6
#> 8 6 4
#> 8 6 4
                       2
                       3
               7
#> 9
        4
                        1
#> 10
         5
               6
                        1
#> 11
                5
                        2
#> 12 6
```

- Rigraph package
  - The igraph package is one package in R to help with network data

```
library(igraph)
#-- Undirected Graph
g = graph_from_data_frame(d=edges, vertices=nodes, directed=FALSE)
```

```
g
#> IGRAPH 19765f2 UNW- 7 12 --
#> + attr: name (v/c), group (v/n), weight (e/n)
#> + edges from 19765f2 (vertex names):
#> [1] 1--2 1--3 2--3 2--4 3--5 4--6 4--6 4--7 5--6 5--6 6--7

#-- Directed Graph
g2 = graph_from_data_frame(d=edges, vertices=nodes, directed=TRUE)
g2
#> IGRAPH 19765f2 DNW- 7 12 --
#> + attr: name (v/c), group (v/n), weight (e/n)
#> + edges from 19765f2 (vertex names):
#> [1] 1->2 1->3 2->3 2->4 3->5 4->5 4->6 6->4 4->7 5->6 6->5 6->7
```

• Node information is stored in the object V (g)

```
get.vertex.attribute(g)  # get all node attributes
#> $name
#> [1] "1" "2" "3" "4" "5" "6" "7"
#>
#> $group
#> [1] 1 1 2 2 1 2 1

V(g) $name  # get vector of the names
#> [1] "1" "2" "3" "4" "5" "6" "7"

V(g) $group # get vector of group info
#> [1] 1 1 2 2 1 2 1
```

• Edge information is stored in the object E (g)

```
get.edge.attribute(g)  # get all node attributes
#> $weight
#> [1] 1 1 2 2 3 3 2 2 1 1 2 2
E(g) $weight  # get vector of weights
#> [1] 1 1 2 2 3 3 2 2 1 1 2 2
```

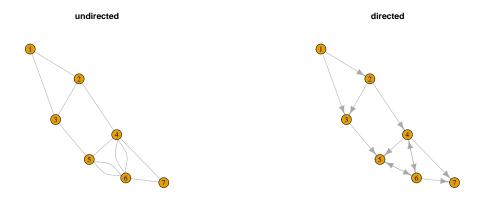
### 2.3 Visualizing a Network

#### 2.3.1 Graph Layout

Graph layouts are projections of the vertices and edges into some space. Different layouts reveal different aspects of a graph.

- Note: 2D layouts can be very misleading; don't trust your eyes
- Choose the layout to help reveal the structure. In igraph,
  - layout.fructerman.reingold is a spring-embedder method
  - layout.kamada.kawai is based on multidimensional scaling (MDS)
  - These will be a function of the *distance* between vertices

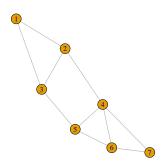
```
g.layout = layout_with_fr(g) # create layout (node coordinates)
plot(g, layout=g.layout, main="undirected") # plot undirected graph
plot(g2, layout=g.layout, main="directed") # plot directed graph
```



• Notice that we had multiple edges in the *undirected* graph. We can simplify the graph into a proper undirected graph (with only a single edge between nodes).

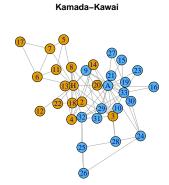
```
g = simplify(g)  # this removes multiple edges, loops, and combines edge attr.
plot(g, layout=g.layout, main="simplified undirected")  # plot undirected graph
```

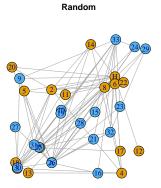
#### simplified undirected



• The layout can have a big influence on how you perceive the network

```
plot(karate, layout=layout_with_kk(karate), main="Kamada-Kawai")  # Kamada-Kawai layout
plot(karate, layout=layout_randomly(karate), main="Random")  # Random layout
```

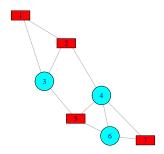




### 2.3.2 Graph Decoration

• The nodes and edges can be *decorated* with color, size, shape, etc.

```
plot(g, layout=g.layout,
    vertex.size=30,
    vertex.shape=ifelse(V(g)$group==1, "rectangle", "circle"),
    vertex.color=ifelse(V(g)$group==1, "red", "cyan"))
```

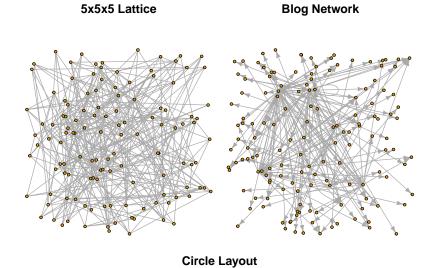


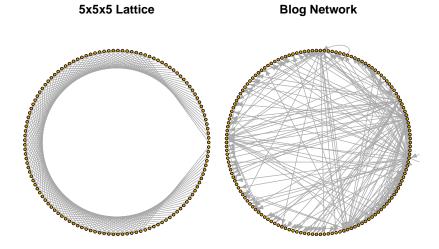
# 2.3.3 Some Examples

```
#- Aids blog network
library(sand)
data(aidsblog)
aidsblog = upgrade_graph(aidsblog)

#- lattice data
g.l <- graph.lattice(c(5, 5, 5))</pre>
```

# **Random Layout**

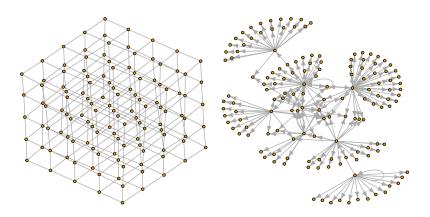




### **MDS Layout**



### **Blog Network**



### 2.4 Representations for Graphs

### 2.4.1 Edge List

An edge list is usually represented as a two-column matrix (or data.frame)

```
get.edgelist(g)
#>
         [,1] [,2]
    [1,] "1"
#>
#>
#>
    [3,] "2"
    [5,] "3"
#>
    [7,] "4"
#>
               "7"
   [8,] "4"
#> [9,1 "5"
               "6"
#> [10,] "6"
```

### 2.4.2 Adjacency Matrix

An adjacency matrix is the  $|V| \times |V|$  matrix, **A** such that

$$A_{ij} = \begin{cases} 1, & \text{if } \{i, j\} \in E, \\ 0, & \text{otherwise} \end{cases}$$

For undirected graphs, the adjacency matrix will by symmetric.

```
get.adjacency(g)  # binary and symmetric
#> 7 x 7 sparse Matrix of class "dgCMatrix"
#> 1 2 3 4 5 6 7
#> 1 . 1 1 . . . .
#> 2 1 . 1 1 . . .
#> 3 1 1 . . 1 . .
#> 4 . 1 . . 1 1 1
#> 5 . . 1 1 . 1 .
#> 6 . . . 1 1 . 1
#> 7 . . . 1 . 1 .
get.adjacency(g2)  # binary and not-symmetric
#> 7 x 7 sparse Matrix of class "dgCMatrix"
#> 1 2 3 4 5 6 7
```

### 2.4.3 Adjacency List

The adjacency list is an array (in R, a list) of size |V|, where the elements of the list indicate the set of vertices that are adjacent. It is essentially the sparse representation of the adjacency matrix.

```
get.adjlist(q)
#> $`1`
#> + 2/7 vertices, named, from 19887ae:
#> [1] 2 3
#>
#> $`2`
#> + 3/7 vertices, named, from 19887ae:
#> [1] 1 3 4
#>
#> $`3`
#> + 3/7 vertices, named, from 19887ae:
#> [1] 1 2 5
#>
#> $`4`
#> + 4/7 vertices, named, from 19887ae:
#> [1] 2 5 6 7
#>
#> $\^5\
#> + 3/7 vertices, named, from 19887ae:
#> [1] 3 4 6
#>
#> $`6`
#> + 3/7 vertices, named, from 19887ae:
#> [1] 4 5 7
#>
#> $`7`
#> + 2/7 vertices, named, from 19887ae:
#> [1] 4 6
```

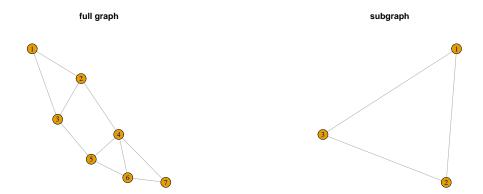
# 2.5 Weighted Edges

- Edges can have attributes that describe the nature of the connection between two vertices
- An example is to assign edge weights  $\{w_{ij}: e_{ij} \in E\}$ 
  - Weights can be measurements of things like: flow rate, number of transactions, call time, travel speed, etc.
- More generally, consider the weight matrix W, which is the  $|V| \times |V|$  matrix containing the edge weights. The weights will be  $W_{ij} = 0$  if  $A_{ij} = 0$ .
  - The adjacency matrix is a special case of weight matrix with binary weights

### 2.6 Subgraphs

- A graph  $H = (V_H, E_H)$  is a subgraph of  $G = (V_G, E_G)$  if  $V_H \subseteq V_G$  and  $E_H \subseteq E_G$ .
- An induced subgraph of graph G is a subgraph G' = (V', E') where  $V' \subseteq V$  is a pre-specified subset of vertices and  $E' \subseteq E$  is the collection of edges to be found in G among that subset of vertices.

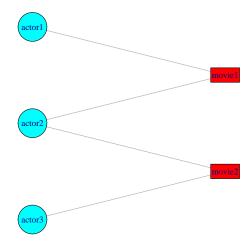
```
g3 = induced_subgraph(g, v=1:3) # only select vertices 1:3
plot(g, layout=g.layout, main='full graph')
plot(g3, main='subgraph')
```



# 2.7 Bipartite graphs

A bipartite graph (also called *two-mode*) is a graph G = (V, E) such that the vertex set V may be partitioned into two disjoint sets  $V_1$  and  $V_2$ , and each edge in E has one endpoint in  $V_1$  and the other in  $V_2$ .

```
g.bip <- graph.formula(actor1:actor2:actor3,</pre>
   movie1:movie2, actor1:actor2 - movie1,
   actor2:actor3 - movie2)
V(q.bip) $type <- grepl("^movie", V(q.bip) $name)</pre>
plot(g.bip, layout=-layout.bipartite(g.bip)[,2:1],
   vertex.size=30, vertex.shape=ifelse(V(g.bip)$type,
     "rectangle", "circle"),
   vertex.color=ifelse(V(g.bip)$type, "red", "cyan"))
get.incidence(q.bip)
                             # get the incidence matrix
#>
          movie1 movie2
#> actor1
              1
               1
#> actor2
                       1
#> actor3
```

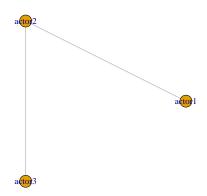


#### Some examples:

- Membership networks:  $V_1$  are the members and  $V_2$  the organizations
- Recommender data:  $V_1$  are the movies and  $V_2$  the reviewers
- Market basket data:  $V_1$  are the shoppers and  $V_2$  are the items in the store
- Travel:  $V_1$  are the people and  $V_2$  are the places they visit

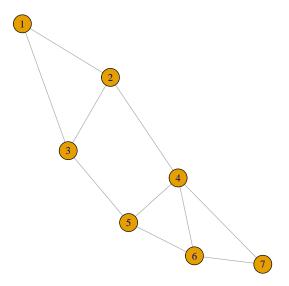
A bipartite graph can be accompanied by the induced subgraph formed by connecting the vertices, say  $V_1$ , by assigning an edge to vertices that edges in E to at least one common vertex in  $V_2$ 

#### **Actor Network**



### 2.8 Graphs and Matrix Notation

We will be using our example graph



### 2.8.1 Adjacency matrix

$$A_{ij} = \begin{cases} 1, & \text{if } \{i, j\} \in E, \\ 0, & \text{otherwise} \end{cases}$$

### 2.8.2 Degree

• The row sums give the vertex *degree*,

$$d_i = \sum_j A_{ij}$$

which is the number of edges vertex i is connected to

```
A = get.adjacency(g, sparse=FALSE)
     1 2 3 4 5 6 7
#> 1 0 1 1 0 0 0 0
#> 2 1 0 1 1 0 0 0
#> 3 1 1 0 0 1 0 0
#> 4 0 1 0 0 1 1 1
#> 5 0 0 1 1 0 1 0
#> 6 0 0 0 1 1 0 1
#> 7 0 0 0 1 0 1 0
rowSums (A)
                      # degree from adjacency matrix
#> 1 2 3 4 5 6 7
#> 2 3 3 4 3 3 2
                      # using igraph::degree() function
degree(q)
#> 1 2 3 4 5 6 7
#> 2 3 3 4 3 3 2
```

• For directed graphs (digraphs),  $d_i^{out} = \sum_j A_{ij}$  and  $d_i^{in} = \sum_j A_{ji}$  – rowsums or colsums

```
A2 = get.adjacency(g2, sparse=FALSE)
#>
   1 2 3 4 5 6 7
#> 1 0 1 1 0 0 0 0
#> 2 0 0 1 1 0 0 0
#> 3 0 0 0 0 1 0 0
#> 4 0 0 0 0 1 1 1
#> 5 0 0 0 0 0 1 0
#> 6 0 0 0 1 1 0 1
#> 7 0 0 0 0 0 0 0
degree(q2, mode="in") # colSums(A2)
#> 1 2 3 4 5 6 7
#> 0 1 2 2 3 2 2
degree (g2, mode="out") # rowSums (A2)
#> 1 2 3 4 5 6 7
#> 2 2 1 3 1 3 0
```

• For weighted graphs, the graph *strength* is the respective sums of the weight matrix *W*. See igraph::strength()

### 2.8.3 Movement on a graph

- A walk on a graph G describes a sequence of adjacent vertices  $(v_0, v_1, ..., v_n)$ , where each  $v_i$  is connected to  $v_{i+1}$  by an edge.
- A connected graph is one where a walk exists between every pair of vertices
- *Geodesic distance* (also called *number of hops*) is the length of the shortest path between two vertices

```
distances(g, weights=NA)  # geodesic or shortest-path distances
#> 1 2 3 4 5 6 7
#> 1 0 1 1 2 2 3 3
#> 2 1 0 1 1 2 2 2
#> 3 1 1 0 2 1 2 3
#> 4 2 1 2 0 1 1 1
#> 5 2 2 1 1 0 1 2
#> 6 3 2 2 1 1 0 1
#> 7 3 2 3 1 2 1 0
```

```
distances (g, weights=E(g) $weight) # use edge weights
#> 1 2 3 4 5 6 7
#> 1 0 1 1 3 4 6 4
#> 2 1 0 2 2 5 5 3
#> 3 1 2 0 4 3 6 5
#> 4 3 2 4 0 3 3 1
#> 5 4 5 3 3 0 3 4
#> 6 6 5 6 3 3 0 2
#> 7 4 3 5 1 4 2 0
```

• The matrix power,  $A^r$  gives the number of walks of length r between vertices

```
#- Direct method
Ar = diag(nrow(A))
for(i in 1:2) {Ar <- Ar %*% A}</pre>
                               \# r = 2
Ar
#>
       1 2 3 4 5 6 7
#> [1,] 2 1 1 1 1 0 0
#> [2,] 1 3 1 0 2 1 1
#> [3,] 1 1 3 2 0 1 0
#> [4,] 1 0 2 4 1 2 1
#> [5,] 1 2 0 1 3 1 2
#> [6,] 0 1 1 2 1 3 1
#> [7,] 0 1 0 1 2 1 2
#- eigen method
r = 2
eig = eigen(A)
Ar2 = eig$vectors %*% diag(eig$values^r) %*% solve(eig$vectors)
round (Ar2)
        [,1] [,2] [,3] [,4] [,5] [,6] [,7]
#>
          2 1 1
                         1 1
#> [1,]
#> [2,]
          1
              3
                    1
                        0
                             2
                    3
#> [3,]
         1
              1
                         2
                             0
                                   1
                                        0
              0
                             1
          1
                    2
                         4
                                   2
                                        1
#> [4,]
               2
                    0
                         1
                              3
#> [5,]
         1
                                   1
#> [6,]
         0
               1
                    1
                         2
                              1
                                   3
                                        1
                                        2
               1
                    0
                         1
                                   1
#> [7,] 0
```

• Graph Laplacian is the  $|V| \times |V|$  matrix L = D - A, where  $D = \text{diag}[d_i : i \in V]$  is the diagonal matrix with degree along the diagonal. It is useful for calculating:

$$\mathbf{x}^\mathsf{T} L \mathbf{x} = \sum_{\{i,j\} \in E} (x_i - x_j)^2$$

for  $\mathbf{x} \in \mathbb{R}^{|V|}$ .

# 3 Homophily, Assortativity, and Fraud Prediction

### 3.1 Homophily

McPherson et al (2001)<sup>2</sup> observed that people's personal/social networks are homogeneous with regard to many sociodemographic, behavioral, and intrapersonal characteristics. As such, contact contact between similar people occur at a higher rate than among dissimilar people; this principal is termed *homophily* (greek: same + love/affection).

### 3.1.1 Examples:

## • Political Blogs:<sup>3</sup>

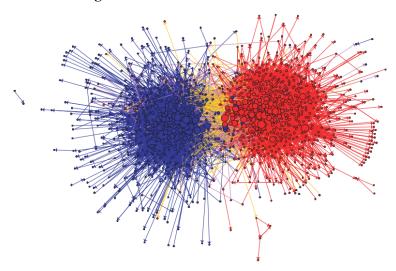


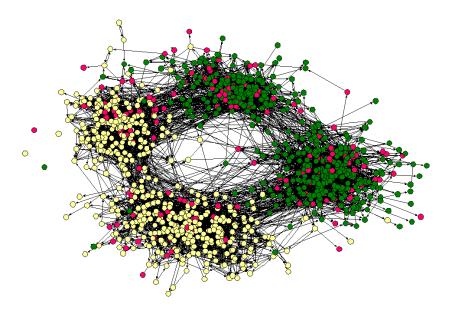
Figure 1: Community structure of political blogs (expanded set), shown using utilizing a GEM layout [11] in the GUESS[3] visualization and analysis tool. The colors reflect political orientation, red for conservative, and blue for liberal. Orange links go from liberal to conservative, and purple ones from conservative to liberal. The size of each blog reflects the number of other blogs that link to it

### School Segregation:<sup>4</sup>

<sup>&</sup>lt;sup>2</sup>McPherson, M., Smith-Lovin, L., & Cook, J. M. (2001). Birds of a Feather: Homophily in Social Networks. *Annual Review of Sociology*, 27, 415–444

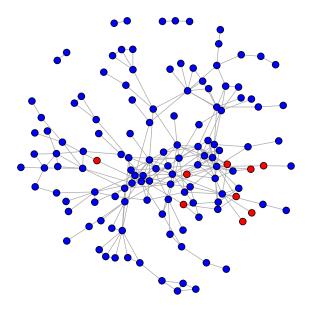
<sup>&</sup>lt;sup>3</sup>Lada A. Adamic and Natalie Glance. 2005. The political blogosphere and the 2004 U.S. election: divided they blog. In Proceedings of the 3rd international workshop on Link discovery (LinkKDD '05). ACM, New York, NY, USA

<sup>&</sup>lt;sup>4</sup>Moody (2001) "Race, school integration, and friendship segregation in America," *American Journal of Sociology* 107, 679-716. Figure taken from: http://networksciencebook.com/chapter/7#summary7. Text taken from: http://social-dynamics.org/homophily/



Nodes are students in a high school and two nodes are connected if one student named the other student as friend (the data was collected as part of the Add Health study). The color of the nodes corresponds to the race of the students. As we can see, "yellow" students are much more likely to be friends with other yellow students and "green" students are more likely to connect to other green students. (Interestingly, the "pink" students, who are in the vast minority seem to be distributed throughout the network.

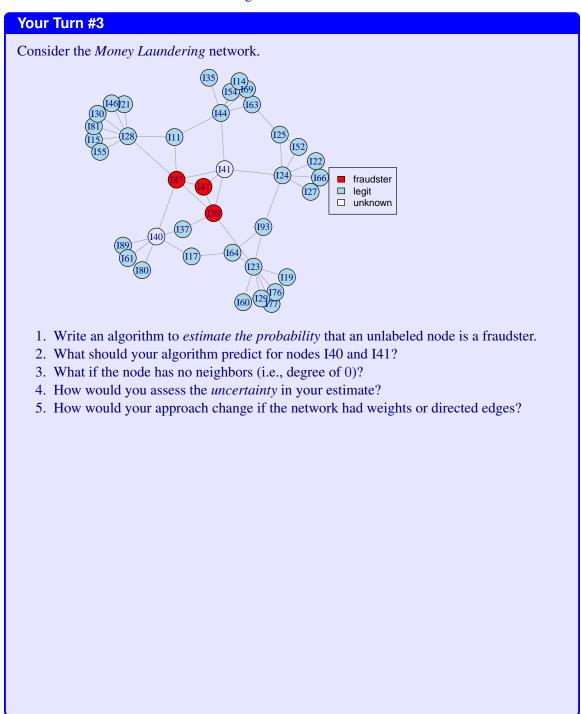
• Yeast protein interaction network<sup>5</sup> Notice that the red nodes are not connected to other red nodes.



<sup>&</sup>lt;sup>5</sup>X. Jiang, N. Nariai, M. Steffen, S. Kasif, E. Kolaczyk (2008) "Integration of relational and hierarchical network information for protein function prediction". *BMC Bioinform.* 9, 350. https://www.ncbi.nlm.nih.gov/pmc/articles/PMC2535605/. Data accessed from the Rsand package: data(ppi.CC, package="sand"). Color indicates whether the protein contains the 'rho GTPase-activating protein domain' (IPR000198) motif.

### 3.2 Node Prediction

- If there is homophily in the network, then we can expect **nodes with similar attributes to be connected by an edge**.
- More specifically, under homophily, we might expect that node attributes could be predicted from the attributes of its closest neighbors.



### 3.2.1 Testing the Node Prediction Algorithm

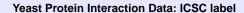
We can use a type of *resampling* to evaluate how well our algorithm might do on an actual network.

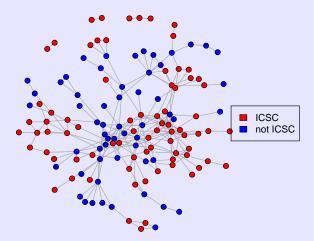
- 1. Take a real network with binary/categorical label
- 2. Randomly remove some node labels (for some fraction f)
- 3. Run the algorithm (using different values of k)

- 4. Record results
- 5. Evaluate effects of f and k.

# **Your Turn #4**

Evaluate how well the simple nearest neighbor method works on the Yeast Protein Interaction Data for predicting the ICSC attribute which indicates whether the protein is annotated with the "intracellular signaling cascade" GO term. It takes a binary (zero or one) value.





Examine the results for different values of f and k. See the R code node-predict.R from the course website for help.

### 3.3 Link Prediction

It can also be useful to have a model for estimating the presence of an edge between two nodes.

• Based on the notion of homophily, we can use some *similarity score* between nodes i and j to estimate the probability of  $e_{ij}$ .

# **Your Turn #5**

Think up 3 ways to measure the similarity of two nodes, when it is unknown whether an edge exists between them or not.

similarity scores between nodes (when the edge between them is unknown)

# 4 Node Importance: Vertex Centrality

Centrality tries to assess how "important" a vertex is.

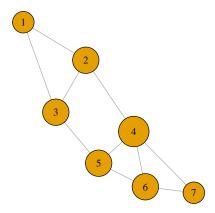
- Which actors in a social network seem to hold the 'reins of power'?
- How authoritative does a webpage seem to be considered?
- How critical is a router in the internet network?

### 4.1 Degree centrality

the number of edges (sum of weights) a vertex has is the most basic definition of importance

```
deg = degree(g)
cent.deg = deg/sum(deg)
plot(g,layout=g.layout,vertex.size=80*sqrt(cent.deg))
title("degree centrality")
```

### degree centrality



### 4.2 Closeness centrality

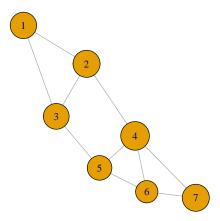
Measures the importance in terms of how 'close' a vertex is to the other vertices in the graph.

The standard approach is to let the centrality vary inversely with a measure of the total distance of a vertex to all the others:

$$c(v) = \frac{1}{\sum_{u \in V} \operatorname{dist}(v, u)}$$

```
close = closeness(g)
cent.close = close/sum(close)
plot(g,layout=g.layout,vertex.size=80*sqrt(cent.close))
title("closeness centrality")
```

### closeness centrality



# 4.3 Betweenness centrality

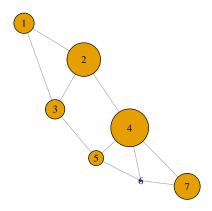
Measures how many paths cross through a vertex. An important vertex is one in which lots of information flows.

$$c(v) = \sum_{s \neq t \neq v \in V} \frac{\sigma(s, t|v)}{\sigma(s, t)}$$

where  $\sigma(s,t|v)$  is the total number of *shortest paths* between s and t that pass through v, and  $\sigma(s,t)$  is the total number of shortest paths between s and t (regardless of whether or note they pass through v).

```
between = betweenness(g)
cent.between = between/sum(between)
plot(g,layout=g.layout,vertex.size=80*sqrt(cent.between))
title("betweeness centrality")
```

#### betweeness centrality



# 4.4 Eigenvector centrality

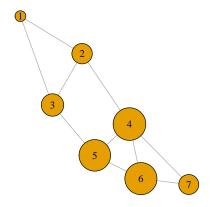
Based on the notion that an important vertex will be connected to other importance vertices.

$$c(v) = \alpha \sum_{\{u,v\} \in E} c(u)$$

- Notice that the centrality for vertex v is the sum of the centrality of the vertices that it is connected to.
- This is the in form  $A\mathbf{c} = \mathbf{c}$
- Or more generally,  $A\mathbf{c} = \lambda \mathbf{c}$  (the eigen equations where  $\mathbf{c}$  are the eigenvectors and  $\lambda$  the eigenvalues).
  - If A is not a stochastic matrix (rows sum to one, non-negative), then use the eigenvector corresponding to the largest magnitude eigenvalue
  - Standardize c to either have a maximum value of 1 or norm (sum of squares) of 1.

```
eigen = eigen_centrality(g) $vector # first eigenvalue (max of 1)
cent.eigen = eigen/sum(eigen)
plot(g,layout=g.layout,vertex.size=80*sqrt(cent.eigen))
title("Eigen centrality")
```

### Eigen centrality



• We can use the *power method* to solve  $\mathbf{c} = A\mathbf{c}$ 

$$c^{\mathrm{new}} = Ac^{\mathrm{old}}/||Ac^{\mathrm{old}}||$$

# 5 PageRank

More to come!

# 6 More Resources

- https://github.com/briatte/awesome-network-analysis
- Two nice R packages to help put graph analysis in the *tidyverse* are:
  - ggraph
  - tidygraph