Jianye Xu

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EDUCATION

RWTH Aachen University

Aachen, Germany

MSc in Automation Engineering (graduated with distinction)

Oct 2020 - Sep 2022

- **GPA:** 1.2/1.0 (corresponds to 3.8/4.0)
- Specialization: Control engineering, robotics, machine learning
- Master's thesis: Parallel Priority-Based Trajectory Planning with Safety Guarantees for Networked Vehicles (wrote in English, Grade: 1.0/1.0)

Beijing Institute of Technology

Beijing, China

BSc in Vehicle Engineering (graduated with distinction)

Aug 2016 - Aug 2020

- **GPA:** 92/100 (corresponds to 3.7/4.0, top 5%)
- Exchange experience: The final year at RWTH Aachen University (wrote bachelor's thesis here)
- Bachelor's thesis: Implementation and Comparison of Different Strategies for Maximum Torque Per Ampere Control of Permanent-Magnet Synchronous Machines with Saturation Effects (wrote in German, Grade: 1.7/1.0)

PROJECTS & EXPERIENCE

Cyber-Physical Mobility Group, RWTH Aachen University

Aachen, Germany

Master Thesis Project (contributes to project GROKO-Plan ご)

Apr 2022 - Sep 2022

- Aim: Enable parallel trajectory planning for networked control systems (demo video C, GitHub C)
- Involved methods: Model Predictive Control (MPC), graph-based trajectory planning, motion primitives, reachability analysis, graph partitioning algorithm, ROS communication

Cyber-Physical Mobility Group, RWTH Aachen University

Aachen, Germany

Lab Task - Control and Perception in Networked and Autonomous Vehicles

Oct 2021 - Feb 2022

• Tasks: Design controllers for the optimization formulation of a platoon of mobile robots

Institute of Automatic Control, RWTH Aachen University

Aachen, Germany

Project Task - Machine Learning in Control Engineering

Nov 2021 - Feb 2022

• Tasks: Given raw sensor data, train data-driven machine learning models (support vector machine, gaussian process, neural network) for MPC-based control of a rolling machine and design virtual sensors (Kalman filter, extended Kalman filter) to close the control loop

Institute of Automatic Control, RWTH Aachen University

Aachen, Germany

Seminar on Control Engineering

Nov 2021 - Feb 2022

- Aim: As a supplement deepening of control engineering in the degree program to other advanced courses; provides students with a broad spectrum of methods for controller design; cultivates their ability to acquire new control methods from technical literature independently
- **Topics:** Parameter space design; control of distributed parameter systems; machine learning control; fuzzy control; feedforward control; self-tuning control; control allocation; multi-agent systems

Institute of Automatic Control, RWTH Aachen University

Aachen, Germany

Lab of Automatic Control

Apr 2021 - Aug 2021

• Aim: Deepen knowledge from control theory through independently designing controllers and implement them on real-life applications

November 25, 2022

• Tasks: Control of quarter vehicle and inverse pendulum; identification and control of three-tank system

School of Mechanical Engineering, Beijing Institute of Technology

Beijing, China

Training Program: Innovation Entrepreneurial Practice Project

Dec 2018 - Jan 2020

- Aim: Increase students' comprehensive quality such as awareness of innovation, practical ability and scientific literacy through supervisors' detailed guidance on their career planning, academic development, ideological and psychological development.
- Outcome: Successfully applied for a patent, see below (graded top 3%)

School of Mechanical Engineering, Beijing Institute of Technology

Beijing, China Sep 2017 – Oct 2017

Undergraduate Teaching Assistant

• Task: Give digital design training lectures on a CAD software to freshmen

AWARDS & HONORS

2021 | German National Scholarship | Awarded by RWTH Aachen University

2021 | Patent: Quick Locking and Unlocking Device for Vehicle-Mounted Power Battery Box

(see Google Patents 2) | Authorized by China National Intellectual Property Administration

2020 | German National Scholarship | Awarded by RWTH Aachen University

2020 | Outstanding Undergraduate | Honored by Beijing Institute of Technology

2018 | China National Scholarship | Awarded by Ministry of Education of the People's Republic of China

2018 | Second Prize in National Student Mechanical Product Digital Design Competition

Awarded by China Mechanical Discipline Steering Committee

2017 | Outstanding Student | Honored by Beijing Institute of Technology

2017 | First Prize in Beijing Student Engineering Design Expression Competition | Awarded by Beijing Institute of Technology

2017 | First Prize in Engineering Design Expressions Competition | Awarded by Beijing Municipal Commission of Education

2017 | First Prize in National Student Drafting and Modelling Innovation Competition | Awarded by China Cartographic Association

SKILLS

Programming: MATLAB/Python (advanced), C/C++/JavaScript/HTML/CSS (intermediate)

CAD: SolidWorks, Inventor, Siemens NX

Soft skills: Teamwork, Problem-solving, Self-motivation

Languages: Chinese (native), English (proficient), German (proficient)

Others: Simulink, LATEX, Git, ROS, Docker, Linux, Inkscape, video editing

Licenses & Certifications

2021 | Introduction to TensorFlow for Artificial Intelligence, Machine Learning, and Deep Learning (certificate ♂) | authorized by DeepLearning.AI | offered through Coursera

2021 | Neural Networks and Deep Learning (certificate $\ ^{\circ}$) | authorized by DeepLearning.AI | offered through Coursera

November 25, 2022