

AME554-Additive Manufacturing Technologies

Project Presentation

COVID-19 Killer-A Smart Alcohol Sanitizing Robot

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Contents





Goals and Background



• Additive Manufacturing



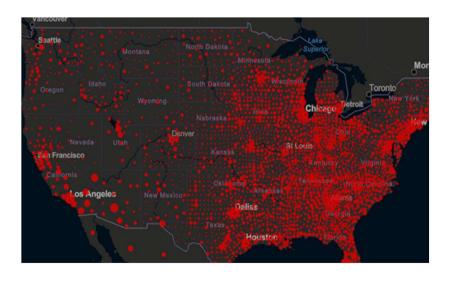
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Conclusions & Future Works







Time-consuming And Laborious

Difficult To Reach Narrow Places

Expensive Equipment

Wild COVID-19 Spreading



Floor Sanitation



Fully Automatic

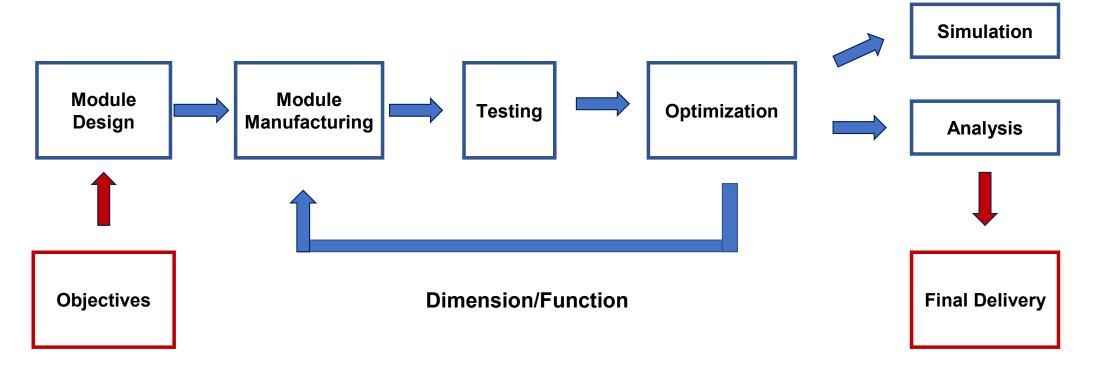


Small Size



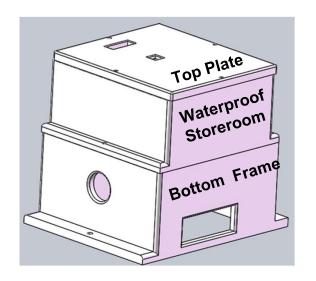
Low Cost

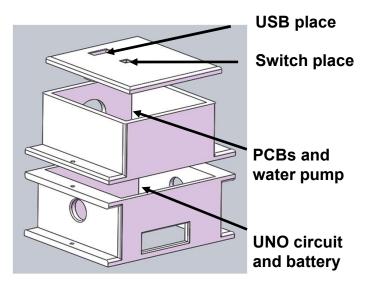


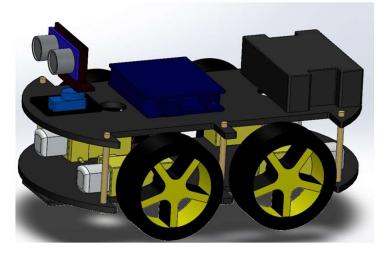




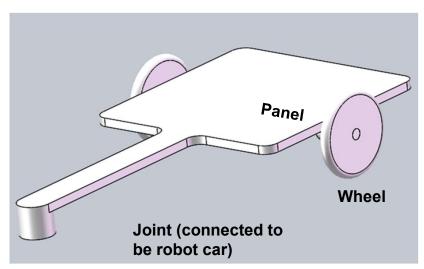
Prototyping



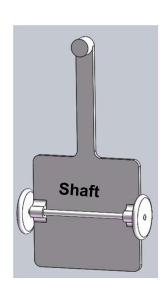




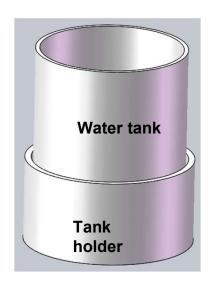
Isolation shelfs





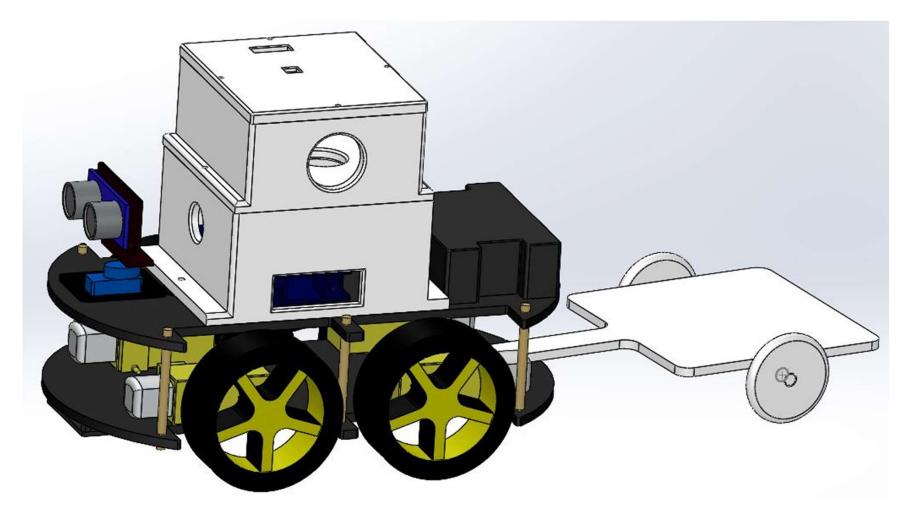


□ Robot CAR









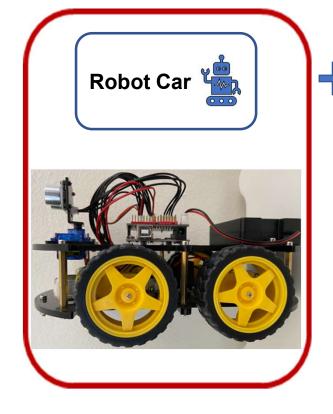
□ CAD Assembly



Components





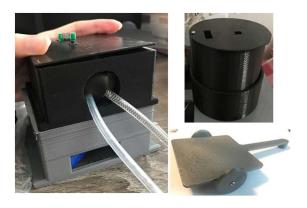








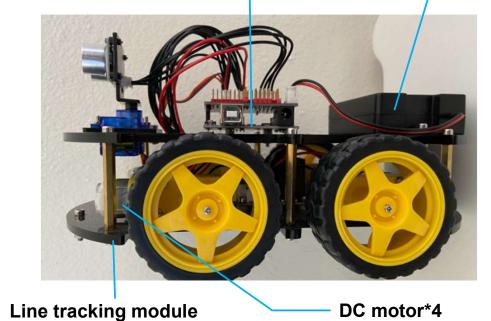




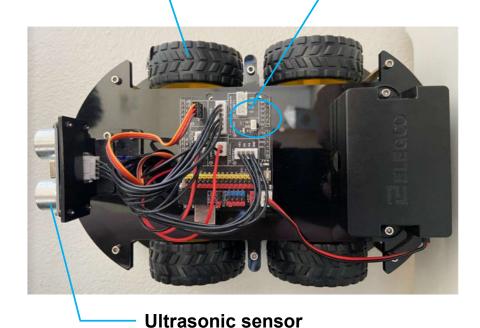




UNO R3 board (with IO expansion board) Battery compartment



Wheels Infrared receiver



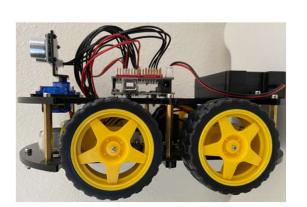
Control Methods:

- **Infrared Control**
- Obstacle Avoidance
- Line Tracking
- Bluetooth Control
- Write-in Path Planning



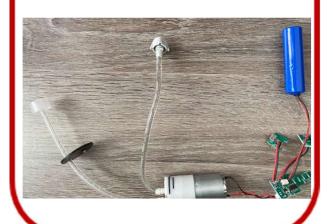






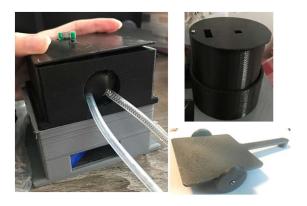


Spraying Device



3D Printed Components

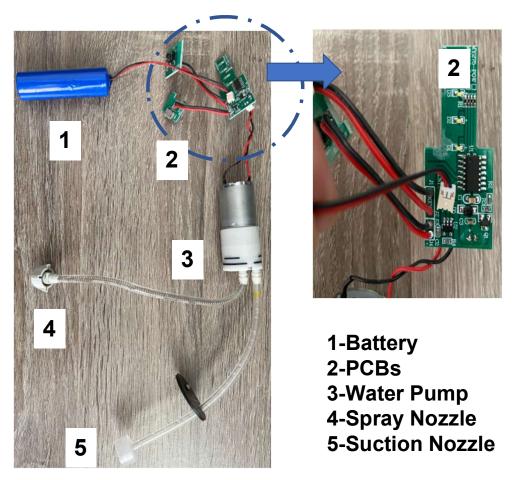


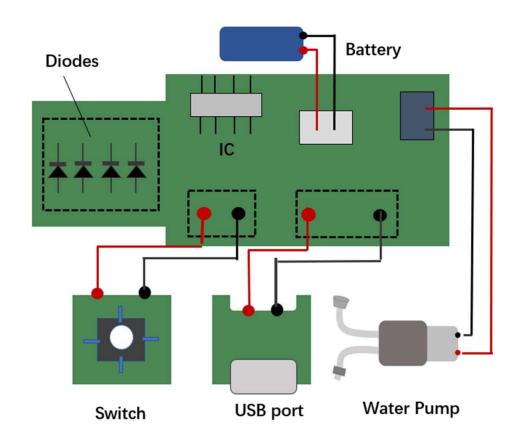




Disinfectant Spraying Device







• Spray System Components

• 2- PCB Schematic









DISINFECTANT
Spraying Device



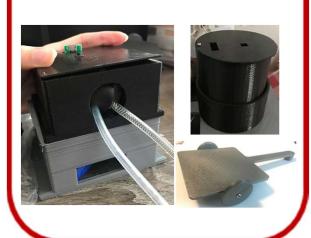


Components **3D Printed**











Components

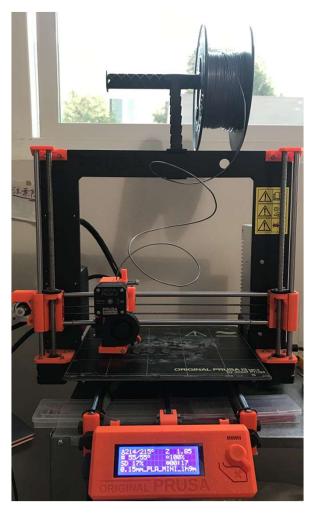






3D Printer and Filament Material





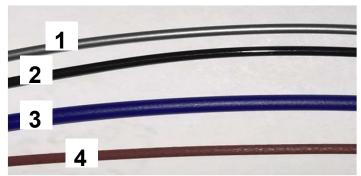
PRUSA i3 MK2







Filament Spools

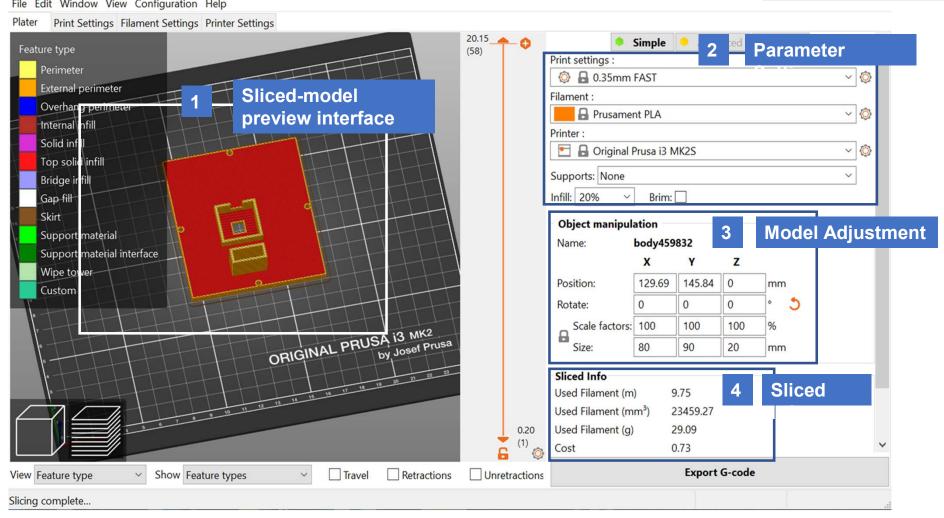


- 1. PLA (1.5mm grey)
- 2. PLA (1.5mm black)
- 3. TPU (3.0mm blue)
- 4. TPU (1.5mm red)



nterface
PrusaSlicer-2.2.0 based on Slic3r
File Edit Window View Configuration Help







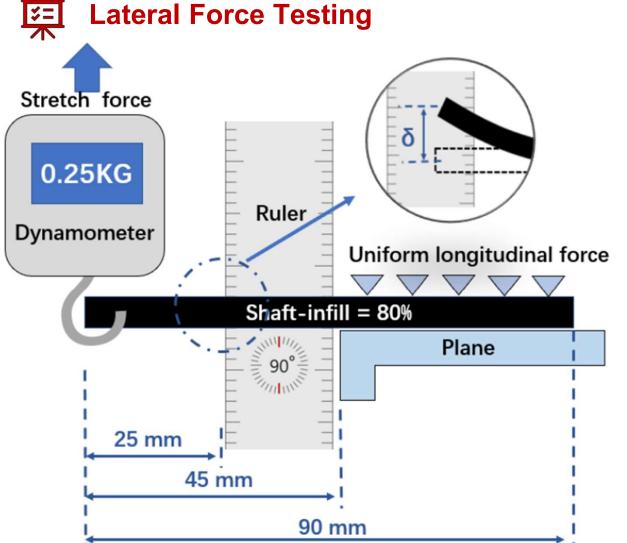
Summary of Model Printing Information

	Name		Infill (%)	Infill shape	Filament width(mm)	Method	Time	Weight(g)
	Isolation shelf	Top plate	10%	Rectangular	0.35	FAST	1h15m	26.9
		Storeroom	20%				3h4m	70.5
		Bottom Frame					3h20m	72.6
	Trailer	wheel		Concentric	0.10	DETAIL	33m	4.2
		Panel		Triangular	0.20	NORMAL	2h52m	40.1
		Shaft	50%	Triangular + Concentric	0.10	DETAIL	1h2m	2.3
		Shaft (for experiment use)	20%				50m	1.9
			80%				1h18m	2.7
			90%				1h22m	2.9
	Water Tank	Tank	20%	Concentric	0.35	FAST	1h59m	50.1
		Tank Holder					2h1m	44.4

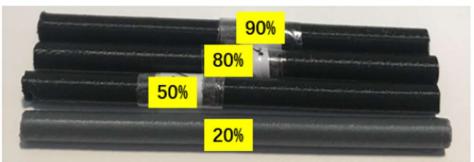




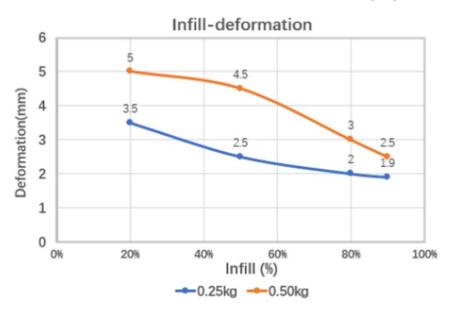
Multichip Antenna Printing







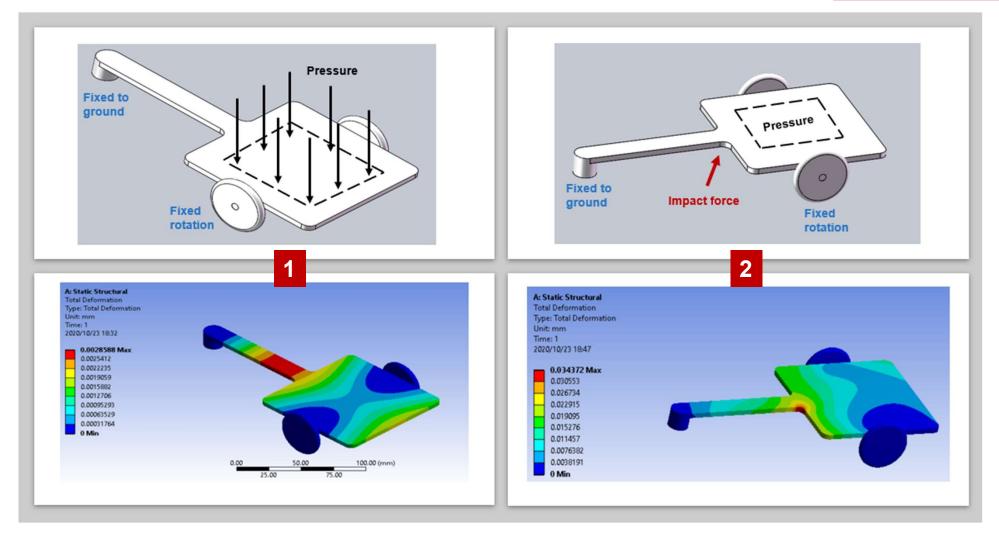
✓ Shaft with different infill(%)



✓ Deformation Curve











Filament Width (mm)

[0.10mm, 0.15mm, 0.20mm, 0.35mm]

Method

Number	Method		
1	ULTRADETAIL		
2	DETAIL		
3	LINEAR ADVANCE		
4	OPTIMAL		
5	NORMAL		
6	FAST		

Infill (%):

[5%, 10%-90% (Δ =10%)]

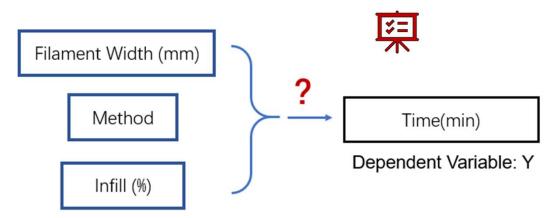


Printing complexity



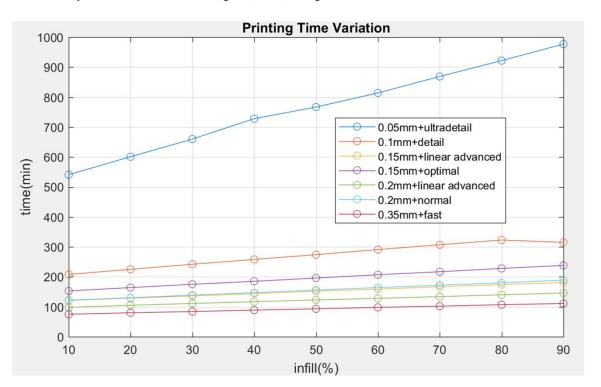
Time(mins)

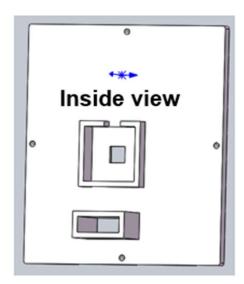
Structural Strength





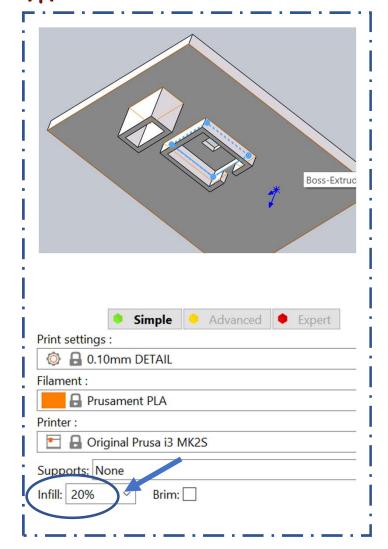
Independent Variable: [X1, X2, X3]

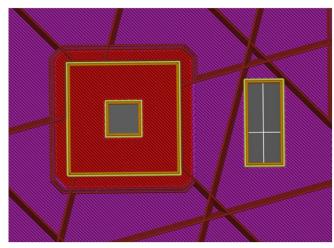


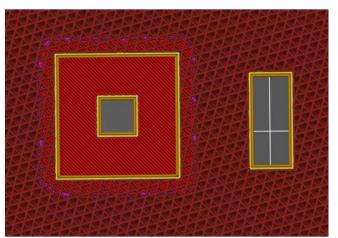


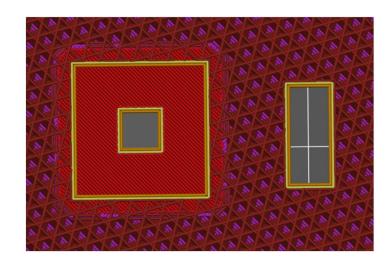


PRUSA i3 MK2-infill setting







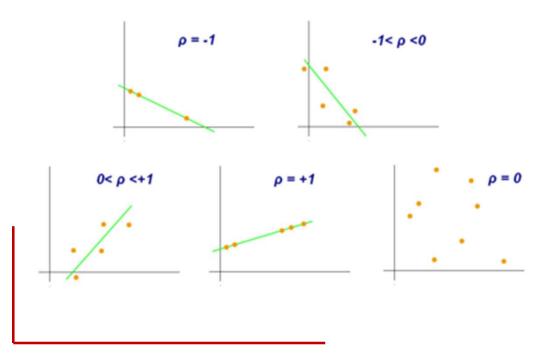


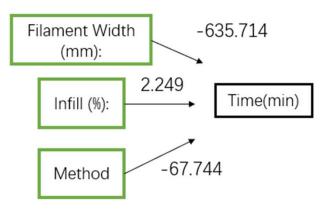




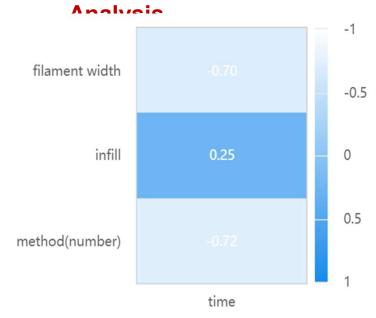
Parameter → Printing Efficiency (time)

Time(min) = 494.241 - 635.714*Filament_Width(mm) + 2.249*Infill - 67.744*Method(i)





Linear Regression



> Pearson Correlation Analysis

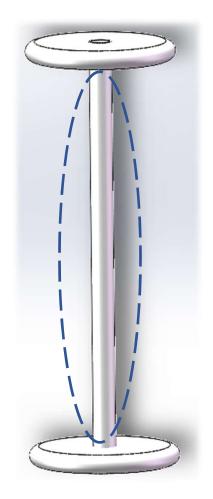


Problems and Optimization

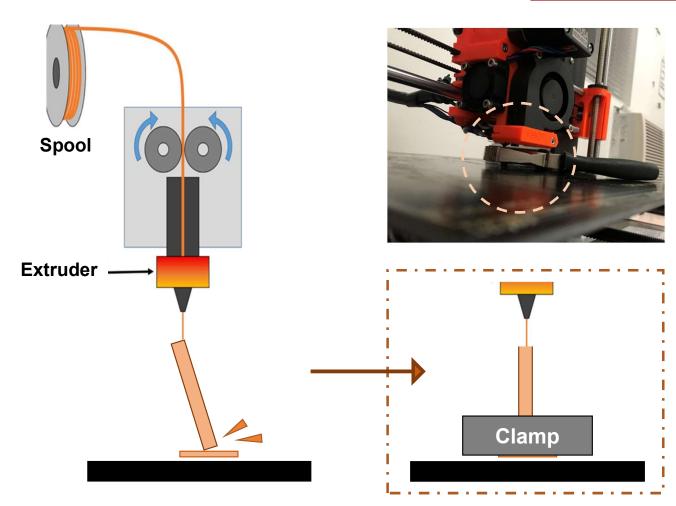


Problems and Optimization



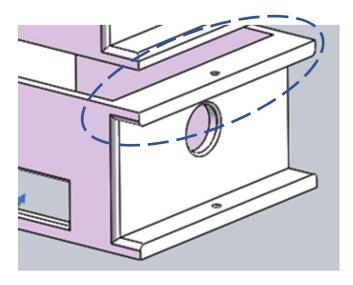


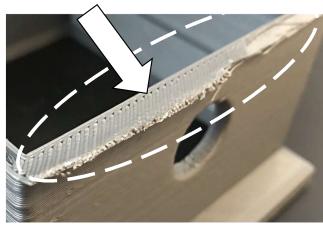
Axle of the wheel

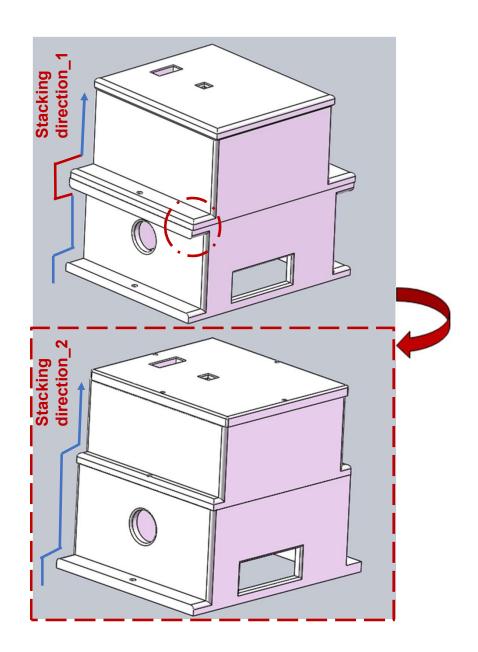




Problems and Optimization







References

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- [2] Hauke J, Kossowski T. Comparison of Values of Pearson's and Spearman's Correlation Coefficients on the Same Sets of Data[J]. Quaestiones Geographicae, 2011, 30(2):87-93.
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- [2] Sun Dao-de. Selection of the Linear Regression Model According to the Parameter Estimation[J]. Wuhan University Journal of Natural Sciences, 2000, 5(4):400-405.
- [3] Barassi M R. Microeconometrics; Methods and Applications by A. Colin Cameron; Pravin K. Trivedi[J]. 2005.