Jiaoran WANG

jiaoranw@usc.edu | TEL: 213-284-4964 | Los Angeles, CA, 90007 LinkedIn: https://www.linkedin.com/in/jiaoranw/

SUMMARY

- **Objective:** Applying for 2021 Fall Mechanical Engineering Ph.D. Program
- Research Interests: Advanced Manufacturing, Bio-inspired Robotics, FEA, Structural Design and Optimization, Control and Automation

EDI	ICA	ΓΙΟΝ
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09/2019 - 05/2021 **University of Southern California (USC)** Los Angeles, CA, USA M.S. in Mechanical Engineering. GPA: 3.84/4.0 09/2015 - 07/2019 Harbin Engineering University (HEU) Harbin, China B.E. in Aerospace Engineering (Flight Vehicle Design and Engineering) GPA: 3.42/4.0 (Major GPA: 3.46/4.0) Dissertation: Design and Experimental Study of Thermoelectric Structure in Aerospace Aircraft

QUALIFICATIONS

Programming Language:

		C/C++ (familiar), Octave (familiar)
\diamond	Web Application Language:	HTML5, CSS3, PHP, JavaScript, SQL (familiar)
\diamond	CAD Software:	SolidWorks (proficient), Auto-CAD (proficient), UG-NX (familiar), CATIA (familiar)
\diamond	Simulation Software:	ANSYS (proficient in APDL/FLUENT/CFX), COMSQL (familiar with Multiphysics)

Equipment:

EXPERIENCE 01/2021 - 06/2021 Flexible Pressure Sensing Device Fabrication, CAM Lab, USC Los Angeles, CA, USA Graduate Research Assistant (Advisor: Prof. Hangbo Zhao)

Experiment: convert the small thrust and pull force into the color rendering of the liquid film of the sensor

MATLAB-Simulink (proficient), Python (good at data structure), R/RStudio (familiar),

3D Printer (proficient), Laser Cutting Machine, CNC Machine and other machine tools

- Test and analysis: test and get the push and pull stress and sensor grayscale curve, used for micro sensor applications
- 01/2020 05/2021 Bio-inspired Biped Robot Project, Brain-Body Dynamics Lab, USC Los Angeles, CA, USA Graduate Research Assistant (Advisor: Prof. Francisco Valero-Cuevas)
 - Implemented proprioceptive artificial skin fabrication and signal testing of biomechanical leg for Center of Pressure (CoP) estimation
 - Conducted K-Nearest Neighbors (KNN) algorithm for clustered data evaluation and prediction

01/2020 - 05/2020 Additive Manufacturing Research, CAM Lab, USC

Los Angeles, CA, USA

Directed Research (Advisor: Prof. Satyandra K. Gupta)

- Worked on Additive Manufacturing 3D Printing of Conformal Antenna
- Designed an Arduino Python UDP communication system for manually and remotely control for robot 3D printing with linear control and robotic path planning algorithm involved

09/2019 - 11/2019 Design Project on Automatic Test-tube Sorting System, Yaskawa America, Inc.

Los Angeles, CA, USA

Course Project (Advisor: Prof. Satvandra K. Gupta)

- Conceived a design proposal using rollers and conveyers for rapid Test-tube Sorting System
- Designed OpenCV (visual image recognition technology) for tube identification

02/2019 - 06/2019 Harbin, China Design and Experimental Study of Thermoelectric Structure in Aerospace Aircraft, HEU

Capstone Project (Advisor: Prof. Jia Yu)

- Invented the thermoelectric piece architecture among annular thermoelectric module at gunship nozzle, and the temperature difference experiment was carried out
- Proposed a method to determine the optimal size based on the conversion efficiency extremum. Increased the thermoelectric conversion efficiency by 37.30% and the output power by 285.14%

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2016 - 2019	 Aircraft Model Aerodynamic Optimization, Aircraft Innovation Lab, HEU Harbin, Ch Renovated the overall process of aircraft model manufacturing, including designing, painting with software like Auto-CAD and UG, Mastered the use of 3D printers and large laser cutting machines 	
12/2017 - 04/2018	National University Students Innovation and Entrepreneurship Training • Finished research on a new-type giant magneto strictive material and tried to use this material connect a high-density coil to produce a high frequency vibrator	
11/2017 - 12/2018	amic Analysis and Motion Accuracy Evaluation, Tsinghua University ote Research Project (Advisor: Prof. Yi Yang) Topic: Dynamic analysis and motion accuracy evaluation of multibody system with clearance mechanism considering uncertain parameters Introduced OpenCV flow field modeling for flight environmental construction	
03/2017 - 06/2017	 Industrial Metalworking Practice, Engineering Training Center, HEU Studied the operation methods of milling machines, planers, lathes and grinding machines, miniature-semiconductor spot welding and electric-arc welding, robot installment and operation, CNC machine tool programming and wire-electrode cutting, benchwork, etc. 	
PUBLICATION		
♦ Darío Urbina-l Proprioceptive	Meléndez, Jiaoran Wang , et al. "Estimating Center of Pressure of a Bipedal Mechanism Us Synthetic Skin around its Ankles." 2021 43rd Annual International Conference of the IEEE Engineer Biology Society (EMBC). (in submission)	
INTERNSHIPS		
06/2020 - 07/2020	BCG Virtual Experience Program, InsideSherpa 2020 (online) Participated in the open access Digital Technology Data Analytics Program Virtual Experience: Categorize and process data structures Data visualization	
02/2019 - 03/2019	 Intern, China Academy of Launch Vehicle Technology (CALT) Worked in the structure of transportation rocket projector and participated in the unit part grinding and assembly process 	
07/2018 - 09/2018	 Intern, AVIC Shenyang Aircraft Co., Ltd. Visited the workshops of civil and military aviation and learnt practical aircraft manufacturing knowledge and skills as well as the differences in the procedures of manufacturing 	
AWARDS Issue Date	Name Issuing Organizat	
06/2019	Name 2019 Outstanding Dissertation • Dissertation: Design and Experimental Study of Thermoelectric Structure in Aerospace Aircraft • Won the award of Meritorious Winner	
02/2018	 2018 Interdisciplinary Contest in Modeling Addressed analysis model for climate change influences regional instability using AHP Won the prize of Honorable Mention Consortium Mathematics and Application.	
11/2017	 HEU Students Innovation Training Program Design a degeneration control deicing robot with infrared detection wires and assemble a robot model Committee Aerosp Engineer 	

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Won the Award of Excellence

Department, HEU

2015 - 2019 **HEU Outstanding scholarship** **HEU**

Merit Student and Outstanding Party Member: Twice University-level Excellent Scholarship: Six Times

EXCHANGE EXPERIENCE

International Programs, UC San Diego Extension San Diego, CA, USA 02/2018 - 03/2018 Program: English for Engineering and Technology

Grade: A

Course Leaning Program, University of Minnesota 01/2018 - 02/2018

Minneapolis, MN, USA

- Department: Chemical Engineering and Material Science
- Core Courses: Reactor and reaction engineering, Chemical engineering laboratory, Numerical methods in chemical applications

LICENCES & CERTIFICATES

Issue Date	Name	Issuing Organization
08/2020	Control of Mobile Robots	Coursera (Georgia
	♦ Credential: https://www.coursera.org/account/accomplishments/certifi	Institute of
	cate/HG7HQRA6QB6W	Technology)
08/2020	Data Processing and Feature Engineering with MATLAB	Coursera (MathWorks)
	♦ Credential: https://www.coursera.org/account/accomplishments/certificate/VQVCQZ8TKA8S	
08/2020	Digital Manufacturing & Design	Coursera (The State
	♦ Credential: https://www.coursera.org/account/accomplishments/certifi	University of New
	cate/TKJTUZV8E7WD	York)
07/2020	Improving Deep Neural Networks: Hyperparameter tuning,	
	Regularization and Optimization	Coursera
	♦ Credential: https://www.coursera.org/account/accomplishments/certificate/DUTMMYEAC8H7	(Deeplearning.ai)
06/2020	R Programming	Coursera (Johns
	♦ Credential: https://www.coursera.org/account/accomplishments/certificate/HH6LDFV5BNJA	Hopkins University)
06/2020	MATLAB-Deep Learning Onramp	MATLAB-Online
	♦ Credential: https://matlabacademy.mathworks.com/progress/share/cert ificate.html?id=9284795f-2558-4dcf-836b-1881ccc339a3	Training Service
05/2020	Python Data Structures	Coursera (University of
	♦ Credential: https://www.coursera.org/account/accomplishments/verify	Michigan)
	<u>/K2SS6NVE756G</u>	

PERSONAL INTERESTS

- Arduino programing for robot car control.
- Models (Keen on collecting Lego models of aerospace series).
- MIDI keyboard controller for electrical song arrangement.