

Chebop/linop roadmap

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3:03 PM

The current state of chebop/linop is still a transitional one. Here is how I see things progressing.

linop is a subclass of chebop, because a linear operator "is a" operator. Thus, `isa(L,'chebop')` and `isa(L,'linop')` are both true for linop L.

Currently, linops maintain their own functional expressions via the `oparray` class. Since chebops maintain functional expressions anyway, this part of linops should go away. (Composition of quasimatrix-style functions may end up being significantly more efficient than the `oparray` system.)

Chebops have boundary conditions, so linops should avoid duplicating this feature. However, the BC of a linop is always linear. Thus is it conceptually (as well as algorithmically) significant to distinguish linear chebops as linops. I propose that one use the linop constructor to designate a linop:

```
chebop(d,@(u) diff(u)) will not be recognized as linear
linop(d,@(u) diff(u)) will be known as linear, and take a Jacobian to get diff(d)
diff(d) will call linop(d,@(u) diff(u),[],[],@(n) diffmat(n))
```

A big lingering issue is the performance on systems. Part of this may be the poor way `oparrays` work. That will be gone, so perhaps things will improve. Right now, `horzcat` and `vertcat` are done in "lazy" fashion, which may be inefficient as it's done over and over for the leaves of a large expression tree. Or it might be that the `anon` class will help, or that new ideas are needed.

chebop properties

domain
op
all bcfields
ID number
guess
optype, if needed

linop properties

varmat
difforder
blocksize?