Finite Difference Methods I

30/3

我们已冷知道如何相子PDE

B-S PDZ
$$\frac{\partial V}{\partial t}$$
 + rs $\frac{\partial V}{\partial S}$ + $\frac{1}{2}$ $\frac{\partial^2 S^2}{\partial S^2}$ - rV = 0

exchange
$$\frac{\partial w}{\partial t} + \frac{1}{2} \delta_1^2 \gamma^2 \frac{\partial^2 w}{\partial \gamma^2} = 0$$

quanto
$$\frac{\partial V}{\partial t} + (Y - d - pose) ---$$

=> European Call / Put formula

⇒ Get parameters, for a binomial tree 这样我们就概念 American/Barrier 近川了

接下来我们安 Valming { American options Callable Autocall

Using PDE directly 使用 Finite Difference Methods

理论上和二叉树有很多相似之处

But more Need Payoff at T set-up wit = Choose all step sires =

Use approximation to ot, os os

来解PDZ

Tree steps based on 7.N.6

(e.g. $n=e^{alot}$)

Binomial Tree

Need Payoff on T

用二又松往前道. V。=e***E***[以了]

下面里详细介绍

首为时一切是估 parameters. 是么估的呢?用树上的数据. Taylor Expansion Formula. 具体如何做呢?

$$V(S + \Delta S, t) = V(S, t) + \Delta S \frac{\partial V}{\partial S} + \frac{1}{2} (\Delta S)^2 \frac{\partial^2 V}{\partial S^2} + O(\Delta S^3) (1)$$

$$V(S - \Delta S, t) = V(S, t) - \Delta S \frac{\partial V}{\partial S} + \frac{1}{2} (\Delta S)^2 \frac{\partial^2 V}{\partial S^2} + O(\Delta S^3) (2)$$

$$V(S, t + \Delta t) = V(S, t) + \Delta t \frac{\partial V}{\partial t} + \frac{1}{2} (\Delta t)^2 \frac{\partial^2 V}{\partial t^2} + O(\Delta t^3) (3)$$

我们想算 动, 动, 动,

$$\frac{1}{\delta S} = \frac{V(S + \Delta S, t) - V(S, t)}{\Delta S} - \frac{1}{2} \Delta S \frac{\partial^2 V}{\partial S^2} + O((\Delta S)^2)$$

$$= \frac{V(S + \Delta S, t) - V(S, t)}{\Delta S} + O(\Delta S)$$

$$\mathbb{L}\frac{\partial V}{\partial S} = \frac{V(S + \Delta S, t) - V(S - \Delta S, t)}{2\Delta S} + O((\Delta S)^2)$$

Quiz 对于 参考的那个的呢? In 因为 I的没是比 I 的所更小

$$\frac{\partial^2 V}{\partial S^2} = \frac{V(S + \Delta S, t) - 2V(S, t) + V(S + \Delta S, t)}{(\Delta S)^2} + O((\Delta S)^2)$$

$$\frac{\partial V}{\partial t} = \frac{V(S, t + \Delta t) - V(S, t)}{\Delta t} + \frac{1}{2} \Delta t \frac{\partial^2 V}{\partial t^2} + O((\Delta t)^2)$$

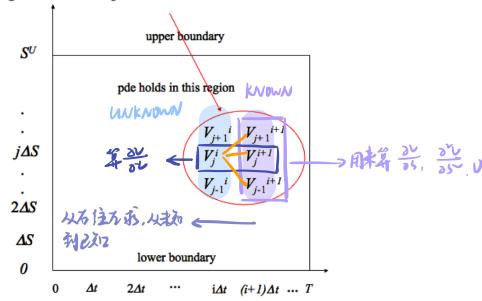
$$= \frac{V(S, t + \Delta t) - V(S, t)}{\Delta t} + \underline{O(\Delta t)}$$

但是 能 很有趣. 我们并没有用 V(s,t) - V(s,t-ot) 这T叫饭 formand differencing

我们把 P吓里所有的系数都信出来了,这样就能从外到里把网络中的通和形案

Quiz: Whore about down-and-out option? SL=B!

Focus attention on i, j-th value V_j^i , and a little piece of the grid around that point



$$\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + (r - \delta) S \frac{\partial V}{\partial S} - rV = 0$$

$$\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + (r - \delta) S \frac{\partial V}{\partial S} - rV = 0$$

$$0 = \frac{V_j^{i+1} - V_j^i}{\Delta t} + \frac{1}{2}\sigma^2 j^2 (\Delta S)^2 \frac{V_{j+1}^{i+1} - 2V_j^{i+1} + V_{j-1}^{i+1}}{(\Delta S)^2} + (r - \delta) j \Delta S \frac{V_{j+1}^{i+1} - V_{j-1}^{i+1}}{2\Delta S} - rV_j^i$$

型理-丁坻式:
$$V_{j}^{i}=rac{1}{1+r\Delta t}\left(AV_{j+1}^{i+1}+BV_{j}^{i+1}+CV_{j-1}^{i+1}
ight)$$

$$egin{array}{lcl} A & = & \left(rac{1}{2}\sigma^2j^2 + rac{(r-\delta)j}{2}
ight)\Delta t \ B & = & 1-\sigma^2j^2\Delta t \ C & = & \left(rac{1}{2}\sigma^2j^2 - rac{(r-\delta)j}{2}
ight)\Delta t \end{array}
ight\}$$

注意这个包括 Barnday, 用的是Barnday 的值



但 Birt 是有一些问题的. ABC 我们以为是 prob.

$$B = 1 - \delta^{2} j^{2} \text{ at } G(0, 1)$$

$$\Delta t < \frac{1}{\delta^{2} j^{2}}$$

如果没有限判条件的话,会编系很大 longe 了程单周变化的

$$\hat{J} = 0$$
.... $\hat{J}_{max} = \#$ of 9. difference between Su and 9.

但是会有 constraint

$$\Delta t < \frac{1}{\delta \tilde{J}^2} \Rightarrow \frac{T}{i_{max}} = \Delta t < \frac{1}{\delta \tilde{J}^{nax}} \Rightarrow i_{max} > T \cdot \delta^2 \tilde{J}^{nax}$$

ì安比了"还不,所以 ì 的要求比较高 否则 55mm 会比较高清 然后算 Boundary Condition:

us Call Option ABY

$$V_j^{imax} = max(jos-k, 0)$$
 $V_j^{in} = jose^{-d(T-iot)} - ke^{-r(T-iot)}$
 $V_j^{in} = 0$

然有比面的 ABC 搞一下就可以

这样就解解出来了! L面就是 General Method

接下来讲一下上面的问题:

$$0 = \frac{V_j^{i+1} - V_j^i}{\Delta t} + \frac{1}{2}\sigma^2 j^2 (\Delta S)^2 \frac{V_{j+1}^{i+1} - 2V_j^{i+1} + V_{j-1}^{i+1}}{(\Delta S)^2} + (r - \delta)j\Delta S \frac{V_{j+1}^{i+1} - V_{j-1}^{i+1}}{2\Delta S} - rV_j^{i+1}$$

这样ABC就不是prob、了、虽论上面那下也比较难

附分以有答案
$$V_j^i = \left(AV_{j+1}^{i+1} + BV_j^{i+1} + CV_{j-1}^{i+1}
ight)$$

$$A = \left(\frac{1}{2}\sigma^2 j^2 + \frac{(r-\delta)j}{2}\right) \Delta t$$

$$B = 1 - r\Delta t - \sigma^2 j^2 \Delta t$$

$$C = \left(\frac{1}{2}\sigma^2 j^2 - \frac{(r-\delta)j}{2}\right) \Delta t$$

Quiz:利用 imax > 7·62 jmax 解限制条件

Quiz: Stability. Operons A non-linearity emor