

## Math 473 HW 4

1. Let  $x, y$  be two 1D signals of the same length, it is known that the circular convolution of  $x, y$  is  $x * y = M_y x$  where  $M_y$  is a circulant matrix. Prove that  $M_x M_y = M_{x*y}$ .
2.  $l_1$  sparsity based deconvolution: Let  $X$  be a 2D image,  $H$  be a 2D kernel, one can show that the vectorized version of  $X * H$  (circulant convolution using period boundary conditions for  $X$ ) can be represented as  $Ax$  with  $x$  the vectorized version of  $X$ ,  $A$  a block circulant and circulant block (BCCB) matrix. One can prove that this matrix  $A$  is diagonalizable under Fourier transform, i.e.,  $A = F \Lambda F^{-1}$  where  $F$  is the Fourier transform matrix.

Download data PartPhantomEg.mat. It contains a sparse image  $X$  with few non-zero intensities.

Simulate a blurred and noisy image  $J$  from the clean and sharp image  $X$  using

```
n = 5;
sigma = 1;
psf = fspecial('gauss',[n n],sigma); % Gaussian PSF
load PartPhantomEg.mat X;
[nr nc] = size(X);
P = zeros(nr,nc);
P(1:n,1:n) = psf; % zero pad psf
ctr = [ceil(n/2) ceil(n/2)]; % center of psf
S = fft2(circshift(P,1-ctr));
J = ifft2(S.*fft2(X));
J = real(J);
```

Note that  $psf$  is separable and  $P$  is a zero padding extension of it. The upper left corner of  $P$  is  $psf$ . Since convolution theorem is used to simulate the blurry data, circular convolution is done, i.e., periodic boundary condition is used.

```
c = 0.01;
E = randn(size(J));
E = E/norm(E,'fro');
B = J + c*E*norm(J,'fro');
```

Let  $b$  denote the vectorized version of  $B$  and assume this is the only given data, then we can find an approximation to  $x$  by solving the following inverse problem using ADMM:  $\min_x \frac{1}{2} \|Ax - b\|_2^2 + \lambda \|x\|_1$  as  $x$  is sparse. Note the parameter  $\lambda$  should be tuned. Assume the result after reshaping to a matrix is  $\hat{\lambda}$ , one can compare this approximation to the ground truth  $X$  by calculating SNR and MSE. Try five values of different magnitude order and list a table to compare the SNR and MSE as the value of  $\lambda$  varies. Choose and display the result corresponding to the largest SNR or the smallest MSE.