for λ algebraic multiplicity: the multiplicity of root λ in characteristic eq. example: $(\lambda-2)^3=0$ alg. multiplicity of $\lambda=2$ is 3 geometric multiplicity: the dimension of Nul $(A-\lambda I)$

HANDOUT 13

JIASU WANG

• Diagonalizable, eigenvector basis, (algebraic/geometric) multiplicity, similar Matrix A is diagonalizable if and only if A has n linearly independent eigenvectors. **Exercise1**: What are the eigenvalues of A and their algebraic multiplicities if A is similar to the following diagonal matrix?

eigenvalues:
$$\lambda=1$$
, 3, 2
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$
 multiplicity for $\lambda=3$: 1 multiplicity for $\lambda=2$: 1

• How to diagonalize matrix

Exercise2: Is the following matrix diagonalizable? If so, diagonalize it.

det
$$(A - \lambda I) = (2 - \lambda)(3 - \lambda)^2$$

characteristic eq.
 $(2 - \lambda)(3 - \lambda)^2 = 0$
roots: $\lambda = 2$, $\lambda = 3$

①
$$\lambda = 2$$
. $(A-21)X = 0$
Solution set: $\{x = \begin{pmatrix} -1 \\ -1 \end{pmatrix} s : s \in \mathbb{R}^3$

 $A = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 3 & 0 \\ 1 & 0 & 3 \end{bmatrix}$ $\begin{cases} \lambda = 3 & (A - 31) \times -0 \\ \text{solution set} \end{cases}$ $\begin{cases} x = \begin{pmatrix} 0 \\ 1 \end{pmatrix} s + \begin{pmatrix} 0 \\ 1 \end{pmatrix} t : s.t \in \mathbb{R} \end{cases}$

3 eigenvectors:
$$V_{1}=\begin{pmatrix} 1\\-1\\-1 \end{pmatrix}$$
, $V_{2}=\begin{pmatrix} 0\\1\\0 \end{pmatrix}$, $V_{3}=\begin{pmatrix} 0\\0\\0 \end{pmatrix}$
 \Rightarrow by definition. A is diagonalizable.
Let $P=\begin{pmatrix} V_{1} & V_{2} & V_{3} \end{pmatrix}$, $P^{T}AP=\begin{pmatrix} 2&0&0\\0&3&3&0\\0&0&3&3 \end{pmatrix}$ trices are diagonalizable. Determine also if

Exercise3: Determine if the following matrices are diagonalizable. Determine also if they are similar.

(1)
$$\begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix}$$
 and $\begin{bmatrix} 2 & 3 \\ 0 & 2 \end{bmatrix}$.

$$(2) \begin{bmatrix} 1 & 1 \\ -2 & 4 \end{bmatrix} \text{ and } \begin{bmatrix} -1 & 3 \\ -4 & 6 \end{bmatrix}.$$

(1)
$$A = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}$$
 det $(A - \lambda I) = (2 - \lambda)^2$
characteristic eq. $(2 - \lambda)^2 = 0$
 $\lambda = 2$. $(A - 2I) \times = 0$
Sol. set $\{x = \begin{pmatrix} 1 \\ 0 \} s : s \in \mathbb{R}^3\}$
 \Rightarrow eigenvector $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$$B = \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix} \text{ det } (B - \lambda I) = (2 - \lambda)^{2}$$

$$\text{Characteristic eq. } (E - \lambda)^{2}$$

$$\lambda = 2 \quad (A - 2I) \times = 0$$

$$\text{Sol. set } \{\chi = \begin{pmatrix} 1 \\ 0 \end{pmatrix} S : S \in [R] \}$$

$$\Rightarrow \text{ eigen vector } \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

However A and B are similar because the alg. and geo. multiplicity of $\lambda=2$ for A equals that of $\lambda=2$ for B.

motrix A is similar to B iff both the algebraic and geometric multiplicity of eigenvalues of A equals that of B

example:
$$A = \begin{array}{c|cccc} \lambda & alg. & geo. \\ \hline 3 & 2 & 1 \\ \hline 2 & 1 & 1 \end{array} \Rightarrow A \sim B$$

in Exercise 3 (1)

$$A = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix} \qquad \frac{\lambda \quad alg. \quad geo.}{2 \quad 2 \quad 1}$$

(2)
$$A=\begin{pmatrix} 1 & 1 \\ -2 & 4 \end{pmatrix}$$
 det $(A-\lambda I)=(1-\lambda)(4-\lambda)+2$
= $\lambda^2-5\lambda+6$

characteristic eq. $\lambda^2-5\lambda+6=0$

$$(\lambda^{2}-5\lambda+6) = (\lambda-2)(\lambda-3) \implies \lambda = 2. \text{ or } 3$$

$$\lambda = 2. \quad (A-21) \times = 0 \quad \begin{pmatrix} -1 & 1 \\ -2 & 2 \end{pmatrix} \times = 0$$

sol. set
$$\{x = \begin{pmatrix} 1 \\ 1 \end{pmatrix} 5 : 5 \in \mathbb{R} \}$$

$$\lambda = 3$$
 $(A-31) \times = 0$ $\begin{pmatrix} -2 & 1 \\ -2 & 1 \end{pmatrix} \times = 0$

501. set
$$\left\{ x = \begin{pmatrix} 1 \\ 2 \end{pmatrix} t : t \in \mathbb{R} \right\}$$

=> A diagonalisable

eroise 3 (1)
$$A = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix} \xrightarrow{\lambda \text{ alg. }} \begin{cases} geo. \\ 2 & 2 \end{cases} \xrightarrow{B} \begin{cases} B = \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix} \xrightarrow{\lambda \text{ alg. }} \begin{cases} geo. \\ 2 & 2 \end{cases} \xrightarrow{A}$$

$$B = \begin{pmatrix} -1 & 3 \\ -4 & 6 \end{pmatrix} dot (B-\lambda I) = (1-\lambda)(b-\lambda) + 12$$
$$= \chi^2 - 5\lambda + 6$$

Characteristic eq. 2-52+6=0

$$\lambda=2$$
 or 3
 $\lambda=2$ (B-21) $\times=0$ $\begin{pmatrix} -3 & 3 \\ -4 & 4 \end{pmatrix} \times=0$
Sol. set $\{x=\begin{pmatrix} 1 \\ 1 \end{pmatrix} S: S \in \mathbb{R}\}$

$$\lambda = 3$$
 $(B-31) \times = 0$ $\begin{pmatrix} -4 & 3 \\ -4 & 3 \end{pmatrix} \times = 0$
 $50 \mid .$ $50 \mid \times = \begin{pmatrix} 3 \\ 4 \end{pmatrix} t : t \in \mathbb{R}$

⇒ B diagonalièable.

• Complex eigenvalue: The roots of characteristic equation can be complex.

Exercise4: Find the eigenvalues of the following matrix, as well as the corresponding -matrix

$$A = \begin{bmatrix} 1 & -2 \\ 4 & 5 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -2 \\ 4 & 5 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -2 \\ 4 & 5 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -2 \\ 4 & 5 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -2 \\ 4 & 5 \end{bmatrix}$$

det
$$(A-\lambda 1) = (I-\lambda)(5-\lambda) + 8 = \lambda^2 - 6\lambda + 13$$

$$\lambda - 3 = \pm \sqrt{4}$$
Characteristic eq: $\lambda^2 - 6\lambda + 13 = 0$

$$\lambda^2 - 6\lambda + 9 + 4 = 0$$

$$(or $\lambda = 3 + 2\dot{\gamma}, 3 - 2\dot{\gamma})$$$

$$\frac{\lambda^2 - (\lambda + 9 + 4)}{(\lambda - 3)^2 + 4}$$

• Eigenvalue and eigenvector of linear transformation.

Exercise5: Let $A = \begin{bmatrix} 1 & 3 & 2 \\ 1 & 3 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ and $T : \mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation such

that T(x) = Ax. Consider vector $v = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$. Find T(v). Is v an eigenvector of A? If so,

what is the associated eigenvalue?

$$T(v) = \begin{pmatrix} 1 & 3 & 2 \\ 1 & 3 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 0 \end{pmatrix} = 4 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = 4v$$

$$\Rightarrow v \text{ is an eigenvector of } T$$
the associated eigenvalue is 4

• Matrix of a linear transformation Given a linear transformation $T:V\to V$ and vector space V with basis $\mathcal{B} = \{b_1, b_2, \dots, b_n\}$. For any $x \in V$, if $x = r_1b_1 + r_2b_2 + \dots + r_nb_n$, rank (T) = rank of motrix TB

$$[x]_{\mathcal{B}} = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_n \end{bmatrix}, \quad [T(x)]]_{\mathcal{B}} = \underbrace{\begin{bmatrix} [T(b_1)]_{\mathcal{B}} & [T(b_2)]_{\mathcal{B}} & \cdots & [T(b_n)]_{\mathcal{B}} \end{bmatrix}}_{[x]_{\mathcal{B}}} [x]_{\mathcal{B}}.$$

Exercise6: (Geometric interpretation of similar matrices) Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be given by $T(e_1) = e_1 - e_2, T(e_2) = e_1 + e_2.$

- (1) Find the matrix T_B of T under the basis $B = \{e_1, e_2\}$.
- (2) Find the matrix T_C of T under the basis $C = \{e_1, e_1 + e_2\}$.
- (3) Find the change of coordinate matrix from B to C, i.e., a matrix A such that the coordinate of a vector under basis B is the coordinate of the vector under basis B, left multiplied by the matrix A.
- (4) Show that $T_B \rightarrow AT_C A^{-1}$. $T_C = A T_B A^{-1}$

(1)
$$T_B = [T(e_1)]_B [T(e_2)]_B]$$
 $B = \{e_1, e_2\}$

$$T(e_1) = e_1 - e_2 \Rightarrow [T(e_2)]_B = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \Rightarrow T_B = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$T(e_2) = e_1 + e_2 \Rightarrow [T(e_2)]_B = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

(2)
$$T_{c} = [T(e_{1})]_{c} [T(e_{1}+e_{1})]_{c}] C = \{e_{1}, e_{1}+e_{2}\}$$

$$T(e_{1}) = e_{1} - e_{2} = 2e_{1} - (e_{1}+e_{2}) \Rightarrow [T(e_{1})]_{c} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$T(e_{1}+e_{2}) = T(e_{1}) + T(e_{2}) = e_{1}-e_{2} + e_{1}+e_{2} = 2e_{1} \Rightarrow [T(e_{1}+e_{2})]_{c} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$\begin{array}{lll}
(3) A = P_{B \to C} = \begin{bmatrix} e_{1} \\ 0 \end{bmatrix} & e_{1} = -e_{1} + (e_{1} + e_{2}) & e_{2} = -e_{1} + (e_{1} + e_{2}) \\
A = P_{B \to C} = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$$

$$A^{-1} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

$$A^{-1} = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 2 & 0 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 2 & 2 \\ -1 & 0 \end{pmatrix}$$

HANDOUT 13

• Linear transformation on \mathcal{RR}^n and matrix similarity

Exercise7: Find the \mathcal{B} -matrix for the transformation $x \to Ax$ when $\mathcal{B} = \{b_1, b_2, b_3\}$

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Exercise 7: Find the B-matrix for the transformation
$$x \to Ax$$
 when $B = \{b_1, b_2, b_3\}$

$$A = \begin{bmatrix} -14 & 4 & -14 \\ -33 & 9 & -31 \\ 11 & -4 & 11 \end{bmatrix}, \quad b_1 = \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}, \quad b_2 = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}, \quad b_3 = \begin{bmatrix} -1 \\ -2 \\ 0 \end{bmatrix}$$

$$Solve \quad (b_1 b_2 b_3) \times = Ab_2 \quad \times = \begin{pmatrix} 20 \\ -12 \\ -6 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_2 \quad \times = \begin{pmatrix} 9 \\ -5 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 9 \\ -5 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -2 \end{pmatrix} \quad (b_1 b_2 b_3) \times = Ab_3 \quad \times = \begin{pmatrix} 6 \\ -12 \\ -$$

Exercise8:Let $T: V \to V$ be a linear transformation with $\dim V = n$.

(1) Show that if T is not onto, then it has an eigenvector.

(2) Show that $\lambda \in \mathbb{R}$ is an eigenvalue for T if and only if $\operatorname{rank}(T - \lambda I) < n$.

(a) show that
$$X \in \mathbb{R}$$
 is all typical to T trains only T trains only T .

Let $S = \{b_1, b_2, \dots, b_n\}$ denote a bosis of V .

 $V : V = V$. X has $B = coordinate [v]_{B}$.

 $T : V \to V$ has B motrix. T_B i.e.

 $[T(v)]_B = T_B [v]_B$ here $T_B = [T(b)]_B [T(b)]_B \cdots [T(b)]_B$

Since T is not onto. there exists $Y \in V$ such that for any $v \in V$. $T(v) \neq Y$ it implies there exists $b = [V]_B \in \mathbb{R}^n$ sit $T_B \times = b$ has no sol.

 $\Rightarrow dim(Col(T_B)) < n$

Since $dim(Col(T_B)) + dim(Nul(T_B)) = n$

so $dim(Nul(T_B)) > 1$ There exists X_0 sit $T_B \times = 0$

Let $V = (b_1 b_2 \cdots b_n) \times n$
 $T(v) = 0 \cdot V$ $\Rightarrow V$ is an eigenvector.

) is an eigenvalue of T (2) =) there exists v =0 such that T(v) = \(\lambda v \) $o = T(v) - \lambda v = (T - \lambda 1)(v)$

L time T-27 ON S

denote the linear transformance | ...

We have S(v) = 0Let $\$ = \{b_1, b_2, ..., b_n\}$ denote a basis of V.

Then we have \$ - matrix for S, say S\$. S(v) = 0 means: S\$ [v] \$ = 0 $\implies dim (Vul(S\$)) > 0$ Then, rank S = rank S\$ = dim (ol(S\$)) = 0 = n - dim Nul(S\$) < n.