Question 1:

1.1

- From $https: //en.wikipedia.org/wiki/Tree(graph_theory)$: In graph theory, a tree is an undirected graph in which any two vertices are connected by exactly one path, or equivalently a connected acyclic undirected graph.
- So we are looking for a graph that: is acyclic and has only one path for any two vertices.
- For 'whether there is a cycle' part, use DFS, which gives the answer in O(V+2E)=O(n).
- For 'the connected vertices' part, this question is the same as: do we have n-1 edges for n vertices? So we count the number of vertices:
- Go through the adjacency list to get the number of edges, if the number = 2(n-1) (n is the number of vertices and in the list every edge is counted twice so the number is doubled), which also takes O(n) and also DFS tells that there is no cycle in graph, then we can say this graph is a tree.

1.2

• By using adjacency matrix, DFS would become $O(V^2) = O(n^2)$, and counting the edges also is the same, so total $O(n^2)$

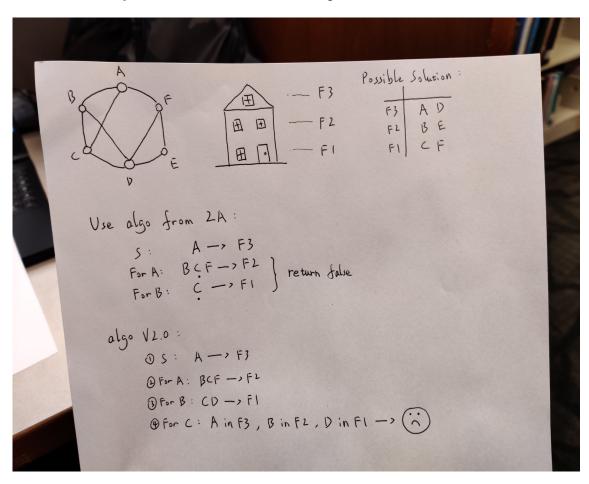
Question 2:

2.1

- Use an undirected graph to represent the relation, vertice: person, edge: hate each other. So the problem becomes: Can I seperate all vertices into two that no edge appears within any of the two groups.
- How to do that: Use BFS but look for update each time. Start from a random person S (this works since every one has at least someone he/she hates so starting point does not matter), put him/her to floor 1. look for the neighbors, put them into floor 2 and look for their neighbors and put them into floor 1, so on and so forth. This function stops when we want to put a person on one floor but find him/her been assigned to another floor already, then the function returns false and we can say this mission is impossible.
- Time: O(V + E) = O(n + k)

2.2

• It does not always work. And here is an example:



definitely not lax house

- As shown in the picture, these 6 persons can be put into a f=3 house properly, however, if we use the original algorithm, this will happen:
- We put A into F3, then search for its neighbor and find BCF, we put them into F2 and continue search for neighbors of B and also find C, we need to put C into F1 and the function will tell us that since C has been reassigned, the mission is impossible. So the original one fails.

- Let me redesign it and add another rule: when we encounter a person that needs to be reassigned to another place, try doing so first and only stop the function when it is impossible to reassign and then return false.
- Algo v2.0:
- First we start with A: put A into F3
- Then we put A's neighbor into F2
- Then we put B's neighbor into F1
- Now it is turn for C's neighbor and we find that 3 neighbors of C: A is in F3, B is in F2 and D is in F1, no place to move, the function returns false. (However possible solution exists so this algo does not work in this example)

Question 3:

- For SSSP and no negative weight, use Dijkstra:
- Build two heaps for both virus (xheap) and antidote (yheap)
- For each vertice, we should record these info: its name, its shortest path to X: xdist, its shortest path to Y: ydist, and its status: neutral, infected, protected or damaged.
- Algorithm:
- Start with initializing all the vertices with $xdist = \infty$, $ydist = \infty$ and status: neutral. For X: xdist = 0, status: infected; Y: ydist = 0, status: protected
- Run Dijkstra
- The following function stops when either heap is empty or every vertice has its distance calculated:
- take the min elements from both xheap and yheap:
- If these two (xmin and ymin) have same name and have xdist = ydist, mark both as damaged
- If xmin.xdist > ymin.ydist, mark ymin as protected, and relax its neighbors in ydist, pop it from xheap and reinsert xmin into xheap
- If xmin.xdist < ymin.ydist, mark xmin as infected, and relax its neighbors in xdist, pop it from yheap and reinsert ymin into yheap
- Runtime: overall O(ElogV), but compare to the original Dijkstra, we have to spend extra O(1) time to update the info for vertices and O(logn) to rearrange heaps
- (with help from Ashley Wicks)