

## Question 1:

### 1.1

- From [https://en.wikipedia.org/wiki/Tree\\_\(graph\\_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory)):  
In graph theory, a tree is an undirected graph in which any two vertices are connected by exactly one path, or equivalently a connected acyclic undirected graph.
- So we are looking for a graph that: is acyclic and has only one path for any two vertices.
- For 'whether there is a cycle' part, use DFS, which gives the answer in  $O(V + 2E) = O(n)$ .
- For 'the connected vertices' part, this question is the same as: do we have  $n - 1$  edges for  $n$  vertices? So we count the number of vertices:
- Go through the adjacency list to get the number of edges, if the number  $= 2(n - 1)$  ( $n$  is the number of vertices and in the list every edge is counted twice so the number is doubled), which also takes  $O(n)$  and also DFS tells that there is no cycle in graph, then we can say this graph is a tree.

### 1.2

- By using adjacency matrix, DFS would become  $O(V^2) = O(n^2)$ , and counting the edges also is the same, so total  $O(n^2)$

## Question 2:

### 2.1

- Use an undirected graph to represent the relation, vertice: person, edge: hate each other. So the problem becomes: Can I separate all vertices into two that no edge appears within any of the two groups.
- How to do that: Use BFS but look for update each time. Start from a random person S (this works since every one has at least someone he/she hates so starting point does not matter), put him/her to floor 1. look for the neighbors, put them into floor 2 and look for their neighbors and put them into floor 1, so on and so forth. This function stops when we want to put a person on one floor but find him/her been assigned to another floor already, then the function returns false and we can say this mission is impossible.
- Time:  $O(V + E) = O(n + k)$

## 2.2

- It does not always work. And here is an example:

Possible Solution:

F3	A D
F2	B E
F1	C F

Use algo from 2A:

S: A  $\rightarrow$  F3  
 For A: B, C, F  $\rightarrow$  F2  
 For B: C  $\rightarrow$  F1 } return false

algo V2.0:

① S: A  $\rightarrow$  F3  
 ② For A: B, C, F  $\rightarrow$  F2  
 ③ For B: C, D  $\rightarrow$  F1  
 ④ For C: A in F3, B in F2, D in F1  $\rightarrow$  😞

definitely not lax house

- As shown in the picture, these 6 persons can be put into a  $f = 3$  house properly, however, if we use the original algorithm, this will happen:
- We put A into F3, then search for its neighbor and find BCF, we put them into F2 and continue search for neighbors of B and also find C, we need to put C into F1 and the function will tell us that since C has been reassigned, the mission is impossible. So the original one fails.

- Let me redesign it and add another rule: when we encounter a person that needs to be reassigned to another place, try doing so first and only stop the function when it is impossible to reassign and then return false.
- Algo v2.0:
- First we start with A: put A into F3
- Then we put A's neighbor into F2
- Then we put B's neighbor into F1
- Now it is turn for C's neighbor and we find that 3 neighbors of C: A is in F3, B is in F2 and D is in F1, no place to move, the function returns false. (However possible solution exists so this algo does not work in this example)

### Question 3:

- For SSSP and no negative weight, use Dijkstra:
- Build two heaps for both virus (xheap) and antidote (yheap)
- For each vertice, we should record these info: its name, its shortest path to X:  $xdist$ , its shortest path to Y:  $ydist$ , and its status: neutral, infected, protected or damaged.
- Algorithm:
- Start with initializing all the vertices with  $xdist = \infty$ ,  $ydist = \infty$  and status: neutral. For X:  $xdist = 0$ , status: infected; Y:  $ydist = 0$ , status: protected
- Run Dijkstra
- The following function stops when either heap is empty or every vertice has its distance calculated:
- take the min elements from both xheap and yheap:
- If these two ( $xmin$  and  $ymin$ ) have same name and have  $xdist = ydist$ , mark both as damaged
- If  $xmin.xdist > ymin.ydist$ , mark  $ymin$  as protected, and relax its neighbors in  $ydist$ , pop it from xheap and reinsert  $xmin$  into xheap
- If  $xmin.xdist < ymin.ydist$ , mark  $xmin$  as infected, and relax its neighbors in  $xdist$ , pop it from yheap and reinsert  $ymin$  into yheap
- Runtime: overall  $O(E \log V)$ , but compare to the original Dijkstra, we have to spend extra  $O(1)$  time to update the info for vertices and  $O(\log n)$  to rearrange heaps
- (with help from Ashley Wicks)