Tailoring Differentially Private Bayesian Inference to Distance Between Distributions

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Objectives

- 1. Designing a differentially private Bayesian inference mechanism.
- 2. Calibrating mechanism noise by the same probabilistic metric we want to measure accuracy with.
- 3. Applying smooth sensitivity in mechanism to achieve better accuracy. This is motivated by Fig. 1 that local sensitivity is very steep and much higher in edge but very smooth in center part.

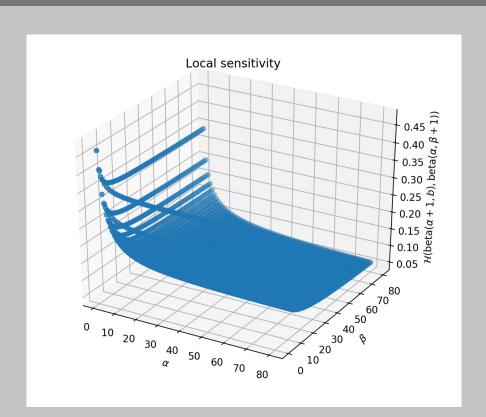


Figure 1: Hellinger Sensitivity

Bayesian Inference Background

Conjugate prior distribution, **beta**(α , β), with hyperparameters α , $\beta \in \mathbb{R}^+$;

- Observed data set \mathbf{x} : $\mathbf{x} = (x_1, \dots x_n), x_i \in \{0, 1\}, n \in \mathbb{N};$
- Bernoulli likelihood function: $\Pr(\mathbf{x}|\theta) \equiv \theta^{\Delta\alpha} (1-\theta)^{n-\Delta\alpha}$, where $\Delta\alpha = \sum x_i$;
- Posterior distribution derived: $Pr(\theta|x) = beta(\alpha + \Delta\alpha, \beta + n \Delta\alpha)$.

Differentially Private Bayesian inference

Release a private version of posterior distribution $(\tilde{\alpha}, \tilde{\beta}) = (\alpha + \Delta \alpha, \beta + n - \Delta \alpha)$. In a baseline approach, we sample noise from $Lap(\mu,\nu)$ mechanism, i.e., $\Delta \alpha \sim Lap(\Delta \alpha, \frac{2}{\epsilon})$.

Smoothed Hellinger Distance Based Exponential Mechanism

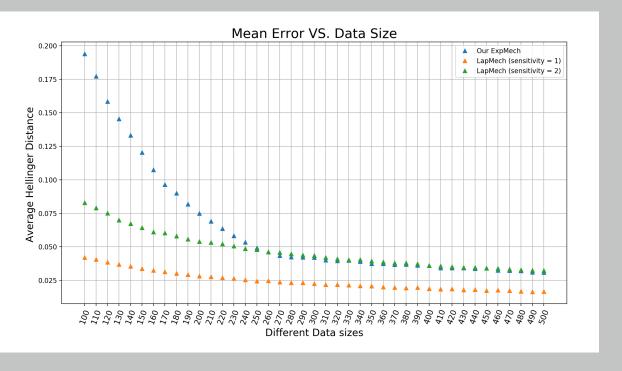
Our approach defines the mechanism $\mathcal{M}_{\mathcal{H}}^{B}$:

given in input an observations **x**, parameters $\epsilon > 0$ and $\delta > 0$.

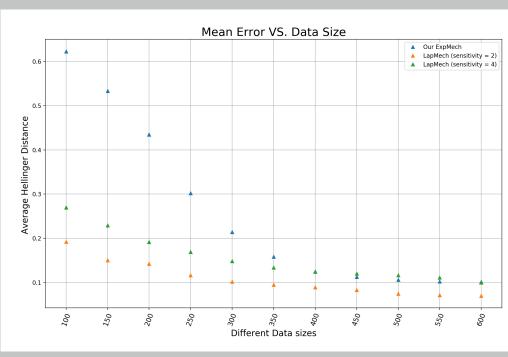
- \mathcal{R}_{post} , the candidates set defined as $\{ beta(\alpha', \beta') \mid \alpha' = \alpha + \Delta \alpha, \beta' = \beta + n \Delta \alpha \}$, given the prior distribution $\beta_{prior} = beta(\alpha, \beta)$ and observed data set size n;
- $-\mathcal{H}(BI(x), r)$, the scoring function instantiated by Hellinegr distance;
- S(x), the smooth sensitivity: $S(x) = \max_{x' \in \{0,1\}^n} \left\{ LS(x') \cdot e^{-\gamma \cdot d(x,x')} \right\}$, where:
- \triangleright d: Hamming distance between two datasets,

Preliminary Experimental Results

Fig. 2 gives the average Hellinger distance between the sampled results and true posterior, by sampling for 10k times under each data size configuration. In baseline approach (i.e., Laplace mechanism), it is enough to add noise with sensitivity 1 in 2-dimensional and 2 in higher dimensional by their equivalence to histogram, giving us the red points in plots. Without the knowledge of equivalence, Laplace usually add noise with sensitivity scale to dimensions, giving us green points. Points in blue are our smoothed Hellinger distance based exponential mechanism.

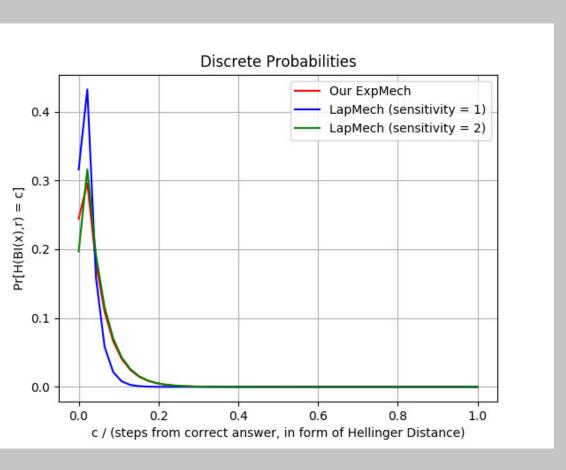


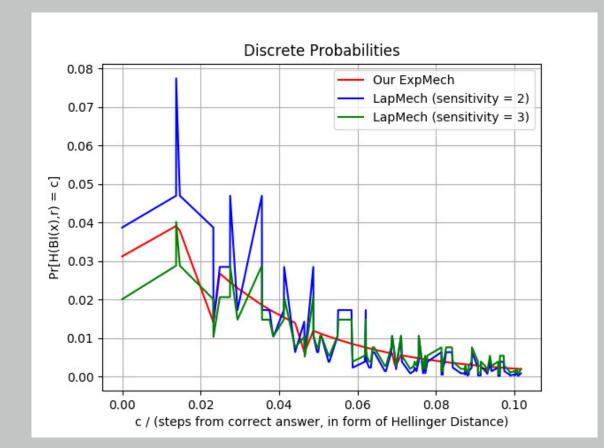


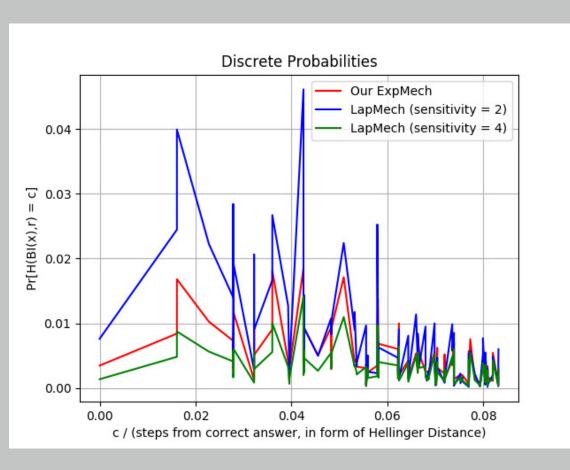


- (a) 2-dimensional, data size \in [100, 500]
- Figure 2: Increasing data size
- (b) 3-dimensional, data size $\in [100, 500]$ (c) 4-dimensional, data size $\in [100, 600]$

Fig. 3 gives us the concrete probabilities of outputting candidates with certain Hellinegr distance from the correct posterior in 2, 3 and 4 dimensional respectively.







(a) 2-dimensional

(b) 3-dimensional

(c) 4-dimensional

Figure 3: The concrete outputting probabilities under different dimensions with data set of size 600

Two groups of experiments both with unit prior beta(1,1), beta(1,1,1) and beta(1,1,1,1), balanced datasets and parameters $\epsilon=1.0$ and $\delta=10^{-8}$.

Conclusion

 \triangleright The smoothed Hellinger distance based exponential mechanism outperforms the ℓ_1 -norm approach when data size growing under the case that Laplace noise doesn't have knowledge of the implicit histogram equivalence.

References