Notes on the project Parametric Acoustic Array

Jiaxin Zhong

October 16, 2018

Contents

L	List of Symbols
2	Theoretical Model and Analytical Solutions
	2.1 KZK Equation
	2.1.1 Rectangular profile
	2.2 Spectral Solutions
	2.3 Coupled PDEs
	2.3.1 Rectangular Profile
	2.4 Boundary Conditions
	2.4.1 Circular Profile
	2.4.2 Rectangular Profile
	NT
5	Numerical Methods
	3.1 Discretization
	3.1.1 Rectangular Profile
Į	Legacy
	4.1 Matrix Form
ξ.	Crank-Nicolson Method
,	
	5.1 Data Set: Kamakura 1989

1 List of Symbols

Symbols	Descriptions
a	radius of the source
c_0	isentropic speed of sound at ambient values of pressure and density
f_1, f_2	$f_1 = N_1 f_{\rm b}, f_2 = N_2 f_b$, primary frequencies
$f_{ m b}$	$f_1 = f_1, f_2 = f_2, f_3, \text{ primary frequences}$ = $\gcd f_2 - f_1, \text{ basic frequency}$
$f_{ m m}$	= $(f_1 + f_2)/2$, mean primary frequency
<i>J</i> m <i>k</i> :	$=(f_1+f_2)/2$, mean primary frequency = $2\pi f/c_0$ wavenumber
$k_{ m m}$	$=(k_1+k_2)/2$ wavenumber of the mean primary frequency
$l_{ m D}$	
	$= (\beta k \epsilon)^{-1}$, shock formation distance of a plane wave
L_x, L_y	the size of the rectangular transducer in x, y direction, and $L_y \geqslant L_y$
$N_{ m m}$	$L_x = (N_1 + N_2)/2$
p	pressure
-	ambient pressure
$rac{p_0}{ar{p}}$	= $(p - p_0)/P_0$, acoustic pressure normalized to P_0
P_0	$\rho_0 c_0 v_0$, acoustic pressure peak amplitude on the source
$R_{ m D}$	$p_0c_0c_0$, acoustic pressure peak amplitude on the source $=ka^2/2=\pi a^2/\lambda$, Rayleigh distance of primary frequency
	$=k_{\rm m}a^2/2=\pi a^2/\lambda_{\rm m}$, Rayleigh distance of mean primary fre-
$R_{ m Dm}$	
+	quency
<i>t</i>	time $(x_1, x_2) = \pi/I$ $(x_1, x_2)/I$
u	$=(u_x, u_y) = \mathbf{r}/L_y = (x, y)/L_y$
v_0	characteristic velocity peak amplitude on the source
x, y, z	dimensional coordinates, z along the direction of propagation
r	(x,y)
r	r sharmtion coefficient in Nonen non motor
α	absorption coefficient, in Neper per meter
eta	parameter of nonlinearity
ϵ	$= u_0/c_0$, Mach number
σ	$=z/R_{\rm D}$, nondimensional z
$\sigma_{ m D}$	$=l_{ m D}/R_{ m D}$
$\sigma_{ m Dm}$	$=l_{ m Dm}/R_{ m Dm}$
χ	$=x/R_{\mathrm{Dm}}$
ψ	$=y/R_{ m Dm}$
γ	$=L_y/L_x$, the aspect ratio
$ abla^2_{x,y}$	$= \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$ $\frac{\partial^2}{\partial \mathbf{u}^2} = \frac{1}{u} \frac{\partial}{\partial u} \left(u \frac{\partial}{\partial u} \right)$ $= \frac{\partial^2}{\partial \chi^2} + \frac{\partial^2}{\partial \psi^2}$
	$\frac{\partial x^2}{\partial x^2} = \frac{\partial y^2}{\partial x^2}$
∇^2_u	$\frac{\partial}{\partial u^2} = \frac{1}{2} \frac{\partial}{\partial u} \left(u \frac{\partial}{\partial u} \right)$
	$\partial \mathbf{u}^{-} u \partial u \setminus \partial u f$ $\partial u = \partial u + \partial$
$ abla^2_{\chi,\psi}$	$=\frac{0}{2}+\frac{0}{2}$
A) T	$O\chi^2 - O\psi^2$

2 Theoretical Model and Analytical Solutions

2.1 KZK Equation

Nonlinear propagation of finite amplitude sound waves in dissipative and homogenous fluid is decribed by the following KZK equation:

$$\frac{\partial^2 \bar{p}}{\partial \sigma \partial \tau} = \alpha R_{\rm D} \frac{\partial^3 \bar{p}}{\partial \tau^3} + \frac{1}{4} \nabla_{\perp}^2 \bar{p} + \frac{1}{2\sigma_{\rm D}} \frac{\partial^2 (\bar{p})^2}{\partial \tau^2}$$
 (1)

If the source is bifrequency, i.e.

$$f_i = N_i f_b, \quad N_i \in \mathbb{N}^+, \quad i = 1, 2$$
 (2)

2.1.1 Rectangular profile

The Eq. (1) is written as

$$\frac{\partial^2 \bar{p}}{\partial \sigma \partial \tau} = \alpha R_{\rm D} \frac{\partial^3 \bar{p}}{\partial \tau^3} + \frac{1}{\pi \gamma} \nabla_u^2 \bar{p} + \frac{1}{2\sigma_{\rm D}} \frac{\partial^2 (\bar{p})^2}{\partial \tau^2}$$
(3)

The transformations are:

$$\sigma_{\rm m} = z/R_{\rm Dm}, \quad T = (1 + \sigma_{\rm m})\bar{p}, \quad \tau_{\rm m} = \tau - \frac{\pi\gamma}{4} \frac{\xi^2}{N_{\rm m}(1 + \sigma_{\rm m})}, \quad (\chi, \psi) = \frac{(u_x, u_y)}{1 + \sigma_{\rm m}}$$
 (4)

Then, the transformed KZK equation is obtained by Eq. (3)

$$\frac{\partial^2 T}{\partial \sigma_{\rm m} \partial \tau_{\rm m}} = \frac{\alpha_{\rm m}}{N_{\rm m}^2} R_{\rm Dm} \frac{\partial^3 T}{\partial \tau_{\rm m}^3} + \frac{N_{\rm m}}{\pi \gamma (1 + \sigma_{\rm m})^2} \nabla_{\chi,\psi}^2 T + \frac{1}{2N_{\rm m} \sigma_{\rm Dm} (1 + \sigma_{\rm m})} \frac{\partial^2 (T^2)}{\partial \tau_{\rm m}^2}$$
(5)

2.2 Spectral Solutions

A solution of Eq. (3) is sought in the form of a Fourier series

$$\bar{p} = \sum_{n=1}^{\infty} (g_n \sin n\tau + h_n \cos n\tau) = \sum_{n=1}^{\infty} \bar{p}_n$$
(6)

where g_n and h_n are functions of spatial coordinates.

The solution of Eq. (5) is

$$T = \sum_{n=1}^{\infty} [g_n(\chi, \psi, \sigma_{\rm m}) \sin n\tau_{\rm m} + h_n(\chi, \psi, \sigma_{\rm m}) \cos n\tau_{\rm m}] = \sum_{n=1}^{\infty} T_n$$
 (7)

2.3 Coupled PDEs

We thus obtain the following set of coupled partial differential equations for g_n and h_n .

2.3.1 Rectangular Profile

$$\frac{\partial g_{n}}{\partial \sigma} = -\alpha_{n} R_{\text{Dm}} g_{n} + \frac{1}{\pi \gamma n (1 + \sigma_{\text{m}})^{2}} \nabla_{\chi,\psi}^{2} h_{n} + \frac{n}{2N_{\text{m}} \sigma_{\text{Dm}} (1 + \sigma_{\text{m}})} \\
\times \left[\frac{1}{2} \sum_{m=1}^{n-1} (g_{m} g_{n-m} - h_{m} h_{n-m}) - \sum_{m=n+1}^{\infty} (g_{m-n} g_{m} + h_{m-n} h_{m}) \right] \qquad (8)$$

$$\frac{\partial h_{n}}{\partial \sigma} = -\alpha_{n} R_{\text{Dm}} h_{n} - \frac{1}{\pi \gamma n (1 + \sigma_{\text{m}})^{2}} \nabla_{\chi,\psi}^{2} g_{n} + \frac{n}{2N_{\text{m}} \sigma_{\text{Dm}} (1 + \sigma_{\text{m}})} \\
\times \left[\sum_{m=1}^{n-1} g_{m} h_{n-m} + \sum_{m=n+1}^{\infty} (h_{m-n} g_{m} - g_{m-n} h_{m}) \right] \qquad (9)$$

2.4 Boundary Conditions

The boundary condition for g_n and h_n at $\sigma = \sigma_{\rm m} = 0$ is

$$g_n = \frac{1}{\pi} \int_{-\pi}^{\pi} c \sin n\tau_{\rm m} \, d\tau_{\rm m}$$
$$h_n = \frac{1}{\pi} \int_{-\pi}^{\pi} c \cos n\tau_{\rm m} \, d\tau_{\rm m}$$

2.4.1 Circular Profile

The boundary condition at $\sigma = \sigma_{\rm m} = 0$ is

$$\bar{p}(\sigma_{\rm m} = 0, \boldsymbol{\xi}, \tau) = c(\boldsymbol{\xi}, \tau) \tag{10}$$

Suppose it is

$$\bar{p}(\sigma_{\rm m} = 0, \boldsymbol{\xi}, \tau) = c_1(\boldsymbol{\xi}) \sin N_1 \tau + c_2(\boldsymbol{\xi}) \sin N_2 \tau \tag{11}$$

2.4.2 Rectangular Profile

The boundary condition at $\sigma = \sigma_{\rm m} = 0$ is

$$\bar{p}(\sigma_{\rm m} = 0, \mathbf{u}, \tau) = c(\mathbf{u}, \tau)$$
 (12)

Suppose it is

$$\bar{p}(\mathbf{u}, \sigma_{\mathrm{m}} = 0, \tau) = c_{1}(\mathbf{u}) \sin N_{1}\tau + c_{2}(\mathbf{u}) \sin N_{2}\tau
= c_{1}(\mathbf{u}) \left[\cos \left(\frac{\pi \gamma N_{1}}{4N_{\mathrm{m}}} \xi^{2} \right) \sin N_{1}\tau_{\mathrm{m}} + \sin \left(\frac{\pi \gamma N_{1}}{4N_{\mathrm{m}}} \xi^{2} \right) \cos N_{1}\tau_{\mathrm{m}} \right]
+ c_{2}(\mathbf{u}) \left[\cos \left(\frac{\pi \gamma N_{1}}{4N_{\mathrm{m}}} \xi^{2} \right) \sin N_{2}\tau_{\mathrm{m}} + \sin \left(\frac{\pi \gamma N_{1}}{4N_{\mathrm{m}}} \xi^{2} \right) \cos N_{2}\tau_{\mathrm{m}} \right]$$
(13)

Then

$$g_{N_i}(\chi, \psi, \sigma_{\rm m} = 0) = c_i(\chi, \psi) \cos\left[\frac{\pi \gamma N_i}{4N_{\rm m}}(\chi^2 + \psi^2)\right], \quad i = 1, 2$$
 (15)

$$h_{N_i}(\chi, \psi, \sigma_{\rm m} = 0) = c_i(\chi, \psi) \sin\left[\frac{\pi \gamma N_i}{4N_{\rm m}}(\chi^2 + \psi^2)\right], \quad i = 1, 2$$
 (16)

$$g_n(\chi, \psi, \sigma_{\rm m} = 0) = h_n(\chi, \psi, \sigma_{\rm m} = 0) = 0, \quad n \neq N_1, N_2$$
 (17)

3 Numerical Methods

3.1 Discretization

3.1.1 Rectangular Profile

$$\begin{split} \sigma_i &= i\Delta\sigma, \quad i = 0, 1, \cdots, I-1, I, \quad \sigma_0 = 0, \quad \sigma_I = \sigma_{\max}, \quad \Delta\sigma = \frac{\sigma_{\max}}{I} \\ \chi_j &= j\Delta\chi, \quad j = 0, 1, \cdots, J-1, J, \quad \chi_0 = 0, \quad \chi_J = \chi_{\max}, \quad \Delta\chi = \frac{\chi_{\max}}{J} \\ \psi_k &= k\Delta\psi, \quad k = 0, 1, \cdots, K-1, K, \quad \psi_0 = 0, \quad \psi_K = \psi_{\max}, \quad \Delta\psi = \frac{\psi_{\max}}{K} \end{split}$$

For $\partial g_n/\partial \sigma$ or $\partial h_n/\partial \sigma$, we adopt Backward Implicit Finite Difference

$$\frac{\partial g_n(\chi, \psi, \sigma_{\mathbf{m}})}{\partial \sigma_{\mathbf{m}}} \bigg|_{i,j,k} = \frac{g_n^{i,j,k} - g_n^{i-1,j,k}}{\Delta \sigma_{\mathbf{m}}}, \quad i = 1, 2, \cdots, I \tag{18}$$

where

$$g_n^{i,j,k} \approx g_n(\chi_j, \psi_k, \sigma_{m,i})$$

$$h_n^{i,j,k} \approx h_n(\chi_j, \psi_k, \sigma_{m,i})$$
(19)

For $\nabla^2_{\chi,\psi}g_n$ or $\nabla^2_{\chi,\psi}h_n$, 4 cases are considered: (1) $j=1,2,\cdots,J-1$, and $k=1,2,\cdots,K-1$

$$\nabla_{\chi,\psi}^2\big|_{i,j,k} = \frac{g_n^{i,j-1,k} - 2g_n^{i,j,k} + g_n^{i,j+1,k}}{(\Delta\chi)^2} + \frac{g_n^{i,j,k-1} - 2g_n^{i,j,k} + g_n^{i,j,k+1}}{(\Delta\psi)^2}$$
(20)

(2) $j = 1, 2, \dots, J - 1$, and k = 0

$$\nabla_{\chi,\psi}^2\big|_{i,j,0} = \frac{g_n^{i,j-1,0} - 2g_n^{i,j,0} + g_n^{i,j+1,0}}{(\Delta\chi)^2} + \frac{-2g_n^{i,j,0} + 2g_n^{i,j,1}}{(\Delta\psi)^2}$$
(21)

(3) j = 0, and $k = 1, 2, \dots, K - 1$

$$\left. \nabla_{\chi,\psi}^2 \right|_{i,0,k} = \frac{-2g_n^{i,0,k} + 2g_n^{i,1,k}}{(\Delta \chi)^2} + \frac{g_n^{i,0,k-1} - 2g_n^{i,0,k} + g_n^{i,0,k+1}}{(\Delta \psi)^2}$$
 (22)

(4) j = 0, and k = 0

$$\nabla_{\chi,\psi}^2\big|_{i,0,0} = \frac{-2g_n^{i,0,0} + 2g_n^{i,1,0}}{(\Delta\chi)^2} + \frac{-2g_n^{i,0,0} + 2g_n^{i,0,1}}{(\Delta\psi)^2}$$
 (23)

where the symmetric conditions are used

$$\frac{\partial g_n}{\partial \chi}\Big|_{\chi=0} = \frac{\partial h_n}{\partial \chi}\Big|_{\chi=0} = 0, \quad n = 1, 2, \dots, N$$

$$\frac{\partial g_n}{\partial \psi}\Big|_{\psi=0} = \frac{\partial h_n}{\partial \psi}\Big|_{\psi=0} = 0, \quad n = 1, 2, \dots, N$$
(24)

Discrete Eq. (8) and Eq. (9), we have

(1) $j = 1, 2, \dots, J - 1$, and $k = 1, 2, \dots, K - 1$

$$g_n^{i,j,k} - g_n^{i-1,j,k} = -\Delta \sigma_{\rm m} \alpha_n R_{\rm Dm} g_n^{i,j,k} + \mathcal{G}_n^{i-1,j,k} + \frac{\Delta \sigma_{\rm m}}{\pi \gamma n (1 + \sigma_{\rm m,i})^2} \times \left[\frac{h_n^{i,j-1,k} - 2h_n^{i,j,k} + h_n^{i,j+1,k}}{(\Delta \chi)^2} + \frac{h_n^{i,j,k-1} - 2h_n^{i,j,k} + h_n^{i,j,k+1}}{(\Delta \psi)^2} \right]$$
(25)

$$h_n^{i,j,k} - h_n^{i-1,j,k} = -\Delta \sigma_{\rm m} \alpha_n R_{\rm Dm} h_n^{i,j,k} + \mathcal{H}_n^{i-1,j,k} - \frac{\Delta \sigma_{\rm m}}{\pi \gamma n (1 + \sigma_{\rm m,i})^2} \times \left[\frac{g_n^{i,j-1,k} - 2g_n^{i,j,k} + g_n^{i,j+1,k}}{(\Delta \gamma)^2} + \frac{g_n^{i,j,k-1} - 2g_n^{i,j,k} + g_n^{i,j,k+1}}{(\Delta \psi)^2} \right]$$
(26)

(2) $j = 1, 2, \dots, J - 1$, and k = 0

$$g_n^{i,j,0} - g_n^{i-1,j,0} = -\Delta \sigma_{\rm m} \alpha_n R_{\rm Dm} g_n^{i,j,0} + \mathcal{G}_n^{i-1,j,0} + \frac{\Delta \sigma_{\rm m}}{\pi \gamma n (1 + \sigma_{\rm m,i})^2} \times \left[\frac{h_n^{i,j-1,0} - 2h_n^{i,j,0} + h_n^{i,j+1,0}}{(\Delta \chi)^2} + \frac{-2h_n^{i,j,0} + 2h_n^{i,j,1}}{(\Delta \psi)^2} \right]$$
(27)

$$h_n^{i,j,0} - h_n^{i-1,j,0} = -\Delta \sigma_{\rm m} \alpha_n R_{\rm Dm} h_n^{i,j,0} + \mathcal{H}_n^{i-1,j,0} - \frac{\Delta \sigma_{\rm m}}{\pi \gamma n (1 + \sigma_{\rm m,i})^2} \times \left[\frac{g_n^{i,j-1,0} - 2g_n^{i,j,0} + g_n^{i,j+1,0}}{(\Delta \chi)^2} + \frac{-2g_n^{i,j,0} + 2g_n^{i,j,1}}{(\Delta \psi)^2} \right]$$
(28)

(3) j = 0, and $k = 1, 2, \dots, K - 1$

$$g_n^{i,0,k} - g_n^{i-1,0,k} = -\Delta \sigma_{\rm m} \alpha_n R_{\rm Dm} g_n^{i,0,k} + \mathcal{G}_n^{i-1,0,k} + \frac{\Delta \sigma_{\rm m}}{\pi \gamma n (1 + \sigma_{\rm m,i})^2} \times \left[\frac{-2h_n^{i,0,k} + 2h_n^{i,1,k}}{(\Delta \chi)^2} + \frac{h_n^{i,0,k-1} - 2h_n^{i,0,k} + h_n^{i,0,k+1}}{(\Delta \psi)^2} \right]$$
(29)

$$h_n^{i,0,k} - h_n^{i-1,0,k} = -\Delta \sigma_{\rm m} \alpha_n R_{\rm Dm} h_n^{i,0,k} + \mathcal{H}_n^{i-1,0,k} - \frac{\Delta \sigma_{\rm m}}{\pi \gamma n (1 + \sigma_{\rm m,i})^2} \times \left[\frac{-2g_n^{i,0,k} + 2g_n^{i,1,k}}{(\Delta \chi)^2} + \frac{g_n^{i,0,k-1} - 2g_n^{i,0,k} + g_n^{i,0,k+1}}{(\Delta \psi)^2} \right]$$
(30)

(4) j = 0, and k = 0

$$g_n^{i,0,0} - g_n^{i-1,0,0} = -\Delta \sigma_{\rm m} \alpha_n R_{\rm Dm} g_n^{i,0,0} + \mathcal{G}_n^{i-1,0,0} + \frac{\Delta \sigma_{\rm m}}{\pi \gamma n (1 + \sigma_{\rm m,i})^2} \times \left[\frac{-2h_n^{i,0,0} + 2h_n^{i,1,0}}{(\Delta \chi)^2} + \frac{-2h_n^{i,0,0} + 2h_n^{i,0,1}}{(\Delta \psi)^2} \right]$$
(31)

$$h_n^{i,0,0} - h_n^{i-1,0,0} = -\Delta \sigma_{\rm m} \alpha_n R_{\rm Dm} h_n^{i,0,0} + \mathcal{H}_n^{i-1,0,0} - \frac{\Delta \sigma_{\rm m}}{\pi \gamma n (1 + \sigma_{\rm m,i})^2} \times \left[\frac{-2g_n^{i,0,0} + 2g_n^{i,1,0}}{(\Delta \gamma)^2} + \frac{-2g_n^{i,0,0} + 2g_n^{i,0,1}}{(\Delta \psi)^2} \right]$$
(32)

where

$$\mathcal{G}_{n}^{i,j,k} = \frac{n\Delta\sigma_{\rm m}}{2N_{\rm m}\sigma_{\rm Dm}(1+\sigma_{\rm m,i})} \left[\frac{1}{2} \sum_{m=1}^{n-1} (g_{m}^{i,j,k} g_{n-m}^{i,j,k} - h_{m}^{i,j,k} h_{n-m}^{i,j,k}) - \sum_{n+1}^{N} (g_{m}^{i,j,k} g_{m-n}^{i,j,k} + h_{m}^{i,j,k} h_{m-n}^{i,j,k}) \right]$$
(33)

$$\mathcal{H}_{n}^{i,j,k} = \frac{n\Delta\sigma_{\rm m}}{2N_{\rm m}\sigma_{\rm Dm}(1+\sigma_{\rm m,i})} \left[\sum_{m=1}^{n-1} g_{m}^{i,j,k} h_{n-m}^{i,j,k} + \sum_{n+1}^{N} (g_{m}^{i,j,k} h_{m-n}^{i,j,k} - h_{m}^{i,j,k} g_{m-n}^{i,j,k}) \right]$$
(34)

4 Legacy

4.1 Matrix Form

$$I_{2(J-1)} \begin{bmatrix} G_n^i - G_n^{i-1} \\ H_n^i - H_n^{i-1} \end{bmatrix} = \begin{bmatrix} B_{(J-1)\times(J-1)} & A_{(J-1)\times(J-1)} \\ -A_{(J-1)\times(J-1)} & B_{(J-1)\times(J-1)} \end{bmatrix} \begin{bmatrix} G_n^i \\ H_n^i \end{bmatrix} + \begin{bmatrix} \mathcal{H}_n^i \\ \mathcal{G}_n^i \end{bmatrix} + \begin{bmatrix} S_n^{i-1} \\ T_n^{i-1} \end{bmatrix}$$

$$(i = 1, 2, \dots, I-1, I)$$

It can be written as

$$\begin{pmatrix}
I_{2(J-1)} - \begin{bmatrix} B & A \\ -A & B \end{bmatrix}
\end{pmatrix} \begin{bmatrix} G_n^i \\ H_n^i \end{bmatrix} = I_{2(J-1)} \begin{bmatrix} G_n^{i-1} \\ H_n^{i-1} \end{bmatrix} + \begin{bmatrix} \mathcal{H}_n^i \\ \mathcal{G}_n^i \end{bmatrix} + \begin{bmatrix} S_n^{i-1} \\ T_n^{i-1} \end{bmatrix}$$
(36)

where

$$G_{n}^{i} = \begin{bmatrix} g_{n}^{i,1} \\ g_{n}^{i,2} \\ \vdots \\ g_{n}^{i,J-1} \end{bmatrix}, \quad G_{n}^{i-1} = \begin{bmatrix} g_{n}^{i-1,1} \\ g_{n}^{i-1,2} \\ \vdots \\ g_{n}^{i-1,J-1} \end{bmatrix}, \quad H_{n}^{i} = \begin{bmatrix} h_{n}^{i,1} \\ h_{n}^{i,2} \\ \vdots \\ h_{n}^{i,J-1} \end{bmatrix}, \quad H_{n}^{i-1} = \begin{bmatrix} h_{n}^{i-1,1} \\ h_{n}^{i-1,2} \\ \vdots \\ h_{n}^{i-1,J-1} \end{bmatrix}$$
(37)

$$\mathcal{G}_{n}^{i} = \begin{bmatrix} a_{1}g_{n}^{i,0} \\ O_{(J-3)\times 1} \\ b_{J-1}g_{n}^{i,J} \end{bmatrix}, \quad \mathcal{H}_{n}^{i} = \begin{bmatrix} a_{1}h_{n}^{i,0} \\ O_{(J-3)\times 1} \\ b_{J-1}h_{n}^{i,J} \end{bmatrix}, \quad h_{n}^{i,J} = h_{n}(\sigma_{i},\xi_{J}) = h_{n}(\sigma_{i},\xi_{\max}) = 0$$
 (38)

$$A = \begin{bmatrix} q & b_1 \\ a_2 & q & b_2 \\ & & \vdots \\ & & a_{J-2} & q & b_{J-2} \\ & & & a_{J-1} & q \end{bmatrix}, \begin{cases} a_j = (1 - 0.5/j) \frac{\Delta \sigma}{4n(\Delta \xi)^2} \\ b_j = (1 + 0.5/j) \frac{\Delta \sigma}{4n(\Delta \xi)^2} \\ & & j = 1, 2, \dots, J-1 \quad (39) \end{cases}$$

$$B = -\Delta \sigma \alpha_n R_{\rm D} I_{J-1} \tag{40}$$

$$S_n^{i-1} = \begin{bmatrix} S_n^{i-1,1} \\ S_n^{i-1,2} \\ \vdots \\ S_n^{i-1,J-1} \end{bmatrix}, \quad T_n^{i-1} = \begin{bmatrix} T_n^{i-1,1} \\ T_n^{i-1,2} \\ \vdots \\ T_n^{i-1,J-1} \end{bmatrix}$$

$$(41)$$

$$S_{n}^{i-1,j} = \Delta \sigma n \frac{R_{\rm D}}{2l_{\rm D}} \left[\frac{1}{2} \sum_{m=1}^{n-1} (g_{m}^{i-1,j} g_{n-m}^{i-1,j} - h_{m}^{i-1,j} h_{n-m}^{i-1,j}) - \sum_{m=n+1}^{M} (g_{m-n}^{i-1,j} g_{m}^{i-1,j} + h_{m-n}^{i-1,j} h_{m}^{i-1,j}) \right]$$
(42)

$$T_n^{i-1,j} = \Delta \sigma n \frac{R_D}{2l_D} \left[\frac{1}{2} \sum_{m=1}^{n-1} (h_m^{i-1,j} g_{n-m}^{i-1,j} + g_m^{i-1,j} h_{n-m}^{i-1,j}) + \sum_{m=n+1}^{M} (h_{m-n}^{i-1,j} g_m^{i-1,j} - g_{m-n}^{i-1,j} h_m^{i-1,j}) \right]$$
(43)

$$g_n^{i,0} = (1 - \Delta\sigma\alpha_n R_D)g_n^{i-1,0} + \frac{\Delta\sigma}{n(\Delta\xi)^2}(h_n^{i-1,1} - h_n^{i-1,0}) + S_n^{i-1,0}$$
(44)

$$h_n^{i,0} = (1 - \Delta \sigma \alpha_n R_D) h_n^{i-1,0} - \frac{\Delta \sigma}{n(\Delta \xi)^2} (g_n^{i-1,1} - g_n^{i-1,0}) + T_n^{i-1,0}$$

$$(i = 1, 2, \dots, I)$$

$$(45)$$

5 Crank-Nicolson Method

(46)

5.1 Data Set: Kamakura 1989

Fig. 6

$$\Delta\sigma = 3\times 10^{-4},\quad \sigma_{\rm max} = 10,\quad \Delta\xi = 0.03,\quad \xi_{\rm max} = 6,\quad T = 23.7^{\circ}{\rm C},\quad h_{\rm r} = 65.2\%$$

$$M = 18,\quad f_1 = 25{\rm kHz},\quad f_2 = 30{\rm kHz},\quad P_0(25{\rm kHz}) = 109.5{\rm dB},\quad P_0(30{\rm kHz}) = 108.5{\rm dB}$$

$$a = 0.21{\rm m}$$