

Formation of transverse cracks from the growth of multiple adjacent debonds on consecutive fibers in UD composites: debond-debond interaction in and between columns of partially debonded fibers

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Abstract

Models of Repeating Unit Cell (RUC) are developed to represent different Representative Volume Elements (RVEs) of UD composites of infinite size. Several damage states are studied in the form of different geometrical configurations of partially debonded and fully bonded fibers. It is found that the energetically most favorable cases for fiber/matrix interface crack (debond) growth are those where debonds grow on vertically (i.e. along thickness direction) aligned fibers. A maximum of Energy Release Rate (ERR) magnification is found when the vertically aligned partially debonded fibers are also contiguous.

Keywords: Polymer-matrix Composites (PMCs), Transverse Failure, Debonding, Finite Element Analysis (FEA)

1. Introduction

Transverse cracks (or micro- or matrix cracks) make their appearance in the very early stages of damage in Fiber Reinforced Polymer Composite (FRPC) laminates. A full understanding of the factors determining their onset and propagation would help identify the micro- and macro-structural aspects of material design beneficial to the delay, and even suppression, of transverse cracking, which would result in increased energy absorbing capabilities of polymer composites. Early microscopic observations in glass fiber-epoxy cross-ply laminates

determined that onset of transverse cracking is determined by the appearance
of fiber-matrix interface cracks (also: debonds), which grow along the arc direc-
tion of the fiber until reaching a critical size, then kink out of the interface and
coalesce with other debonds to form what is macroscopically seen as a trans-
verse crack [1, 2]. In particular, the evolution of damage at these very early
stages has been categorized into four stages of development [1, 2, 3, 4]: multiple
isolated debonds appear in the composite; a series of consecutive debonds ap-
proximately aligned in the through-the-thickness is formed; these debonds grow
along the fiber arc direction until they kink out of the interface once a critical
size is reached; coalescence of debonds occur and the macroscopic through-the-
thickness transverse crack is formed. Understanding the mechanisms of trans-
verse cracks onset thus means studying the growth of debonds and how the
latter is influenced by the characteristics of the surrounding microstructure.

Analytical models of a single partially debonded fiber in an infinite matrix were
firstly solved by Perlman and Sih [5], who provided the solution in terms of
stress and displacement fields, and Toya [6], who analyzed the Energy Release
Rate (ERR) at the crack tip. A closed-form analytical solution could only be
found however for the *open crack* case, which assumes that no contact between
debond faces occurs and provides, for large debonds, a non-physical solution
that implies inter-penetration of crack faces. Numerical treatment of the prob-
lem soon followed, in particular with the Boundary Element Method (BEM)
solution by Paris et al. [7]. The numerical analysis of the single fiber model al-
lowed first to understand the importance of crack face contact in the mechanics
of fiber-matrix debonding [8], confirming earlier results regarding the straight
bi-material interface crack [9]. Fiber-matrix debonding was thus investigated
in models of a single fiber embedded in an effectively infinite matrix under re-
mote tension [7] and remote compression [10]. Residual thermal stresses were
also analyzed [11]. The effect of a second nearby fiber was furthermore stud-
ied under the effect of different uniaxial and biaxial tensile and compressive
loads [12, 13, 14, 15]. Debond growth in a hexagonal cluster of fibers embed-
ded in an effectively homogenized UD composite was investigated by Zhuang

et al. [16]. The interaction of two debonds facing each other on two nearby
 fibers was addressed in [17] for a cluster of fibers immersed in a homogenized
 UD, while models of kinking were developed for a single fiber in an infinite ma-
 trix [3] and a partially debonded fiber in a cluster of fibers inside a homogenized
 UD [18].

If a few studies of kinking [3, 18] and linking of debonds [17] are present in the
 literature, it seems that no attention has still been paid to modeling the second
 stage of transverse crack initiation, just before kinking and coalescence start
 to take place and when multiple consecutive debonds are present on a series of
 fibers roughly aligned along the through-the-thickness (vertical) direction. It is
 this stage of transverse crack initiation that we want to address in this paper.

2. RVE models & FE discretization

2.1. Introduction & Nomenclature

We focus in this article on debond growth in unidirectional (UD) composites
 subjected to in-plane transverse tensile loading. In particular, the interaction
 between debonds is studied through the development of models of Repeating
 Unit Cells (RUC) of laminates (see Fig. 1 to Fig. 3). Only the central fiber in
 the RUC cell is in a damaged state in the form of a debond. The composite
 RUC is repeating both in the in-plane transverse direction and in the composite
 thickness direction; it thus corresponds to an infinite composite which models,
 in a limiting case, the behavior of a thick UD composite (free surfaces very far
 from the debonds). According to the proposed RUC design, the composite with
 debonds is considered as a sequence of stacked damaged and undamaged fiber
 rows, with each row having only one fiber in the thickness direction. Given that
 all the RUCs are characterized by a regular microstructure with fibers orga-
 nized in a square-packing arrangement, they are as well Representative Volume
 Elements (RVE) of composites with a specific spatial distribution of debonds.
 In order to facilitate the treatment of models, let us introduce the in-plane co-
 ordinates x and y , where x is in the transverse direction of the UD composite

(z is consequently the through-the-thickness direction). Two considerations lie
70 at the basis of the chosen RVE models. First, upon application of a load in the
 x -direction, the strain response in the y -direction is small due to the very small
minor Poisson's ratio of the UD composite. Second, debonds are considered to
be significantly longer in the fiber longitudinal direction than in the arc direc-
tion. We therefore use 2D models under the assumption of plane strain and
75 defined in the $x - z$ section of the composite. The analysis presented applies
to long debonds and focuses on understanding the mechanisms of growth along
the arc direction. Transverse tensile strain is applied to the composites in the
form of a constant displacement in the x -direction along the vertical boundary
of the RUC as shown in Figures 1 to 4. As models are distinguished by the
80 number of rows of fibers and by the spacing between debonds along the vertical
and horizontal directions, the corresponding RUCs can be categorized based on
the number n of fibers in the horizontal direction and k in the vertical direction.
Vertical displacement coupling is always applied along the free surfaces. Thus,
we introduce the common notation $n \times k$ - *coupling* to denote a RUC with $n \times k$
85 fibers and kinematic coupling applied to it. In Section 2.2, a detailed account of
the selected combinations of n , k , and boundary conditions is provided as well
as a description of the corresponding models of damaged composite.

2.2. Models of Representative Volume Element (RVE)

The model shown in Fig. 1 represents an infinite UD laminate in which
90 debonds appear regularly every n^{th} undamaged fiber in horizontal fiber rows
and fiber rows containing damaged fibers appear every k^{th} row of only un-
damaged fibers. The model is used to study the interaction between debonds
appearing at regular but potentially different intervals along the horizontal and
vertical direction, measured in terms of fully bonded (undamaged) fibers present
95 between them. By changing the value of parameters n and k (number of fibers
respectively in the horizontal and vertical direction) different distribution of
debonds can be investigated: from isolated debonds far apart from each other
(early stages of damage) to a UD with all the fibers partially debonded (an

unphysical limit case). The model of Fig. 1 is referred to as $n \times k$ – coupling.

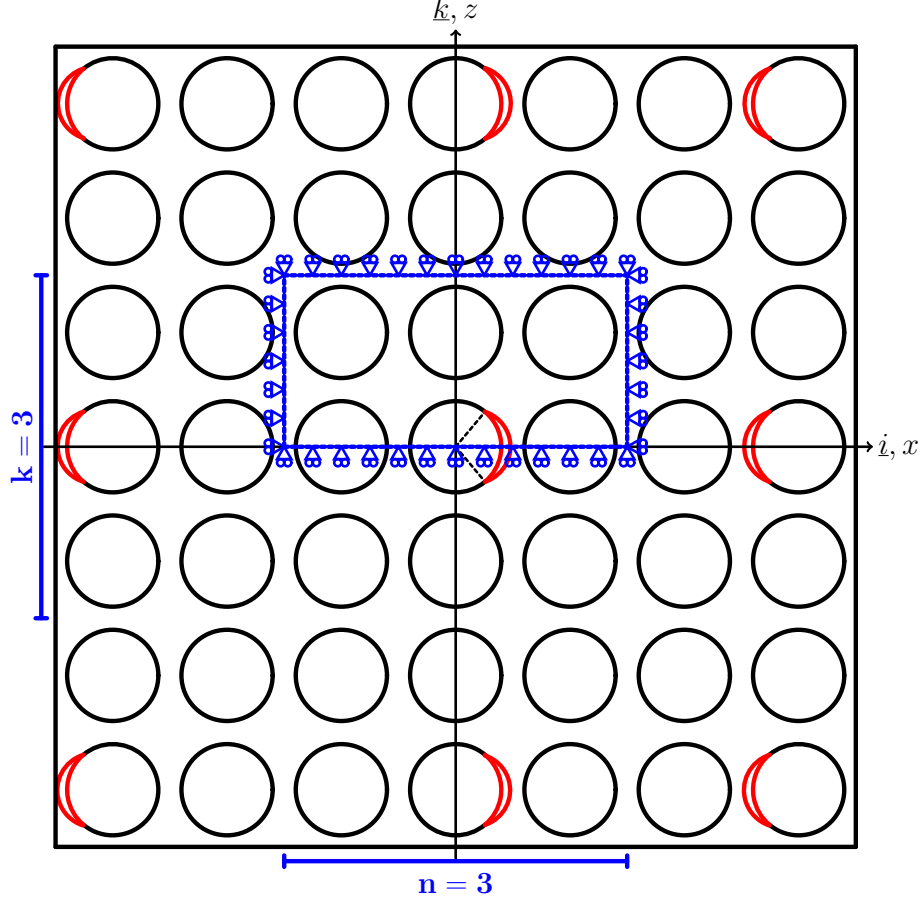


Figure 1: Rows of fibers with debonds repeating at different distances along the horizontal direction and rows with debonded fibers repeating at different distances along the vertical direction: models $n \times k$ – coupling.

100 Models in Figures 2 and 3 represent instead a UD composite with respec-
tively vertical lines and horizontal rows of partially debonded fibers repeating
at the regular intervals respectively in the horizontal and vertical direction,
measured respectively in terms of vertical lines and horizontal rows of fully
bonded (undamaged) fibers. According to the nomenclature introduced in Sec-
105 tion 2.1, these two models are identified respectively by $n \times 1$ – coupling and
 $1 \times k$ – coupling.

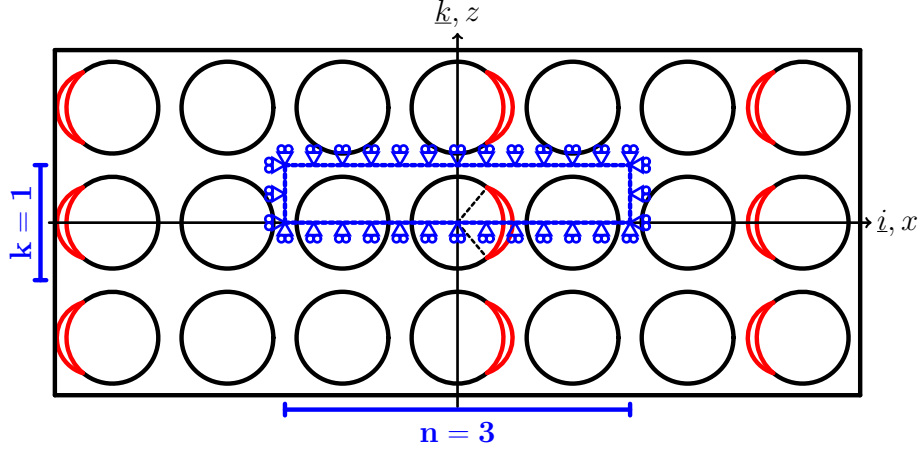


Figure 2: Vertical lines of fibers with debonds repeating at different distances along the horizontal direction: models $n \times 1$ – *coupling*.

Model $n \times 1$ – *coupling* in Figure 2 is studied to investigate the interaction of debonds in a configuration that represents, although in an idealized form, the stage preceding coalescence of debonds and formation of macroscopic transverse cracks.

On the other hand, model $n \times 1$ – *coupling* in Figure 3 addresses a configuration of debonds that has not been observed in in-situ analyses of UD composites in transverse tension and can thus be deemed unphysical, but has nonetheless the potential to shed light on debonds' interaction mechanisms that makes this configuration unobservable.

2.3. Finite Element (FE) discretization

Discretization and analysis of RUCs is performed with the Finite Element Method (FEM) within the Abaqus environment, a commercial FEM software [19]. Length l and height h of the model are respectively determined by the number of fibers n in the horizontal direction and k across the thickness (see Sec. 2.2) according to Eq. 1:

$$l = 2nL \quad h = kL; \quad (1)$$

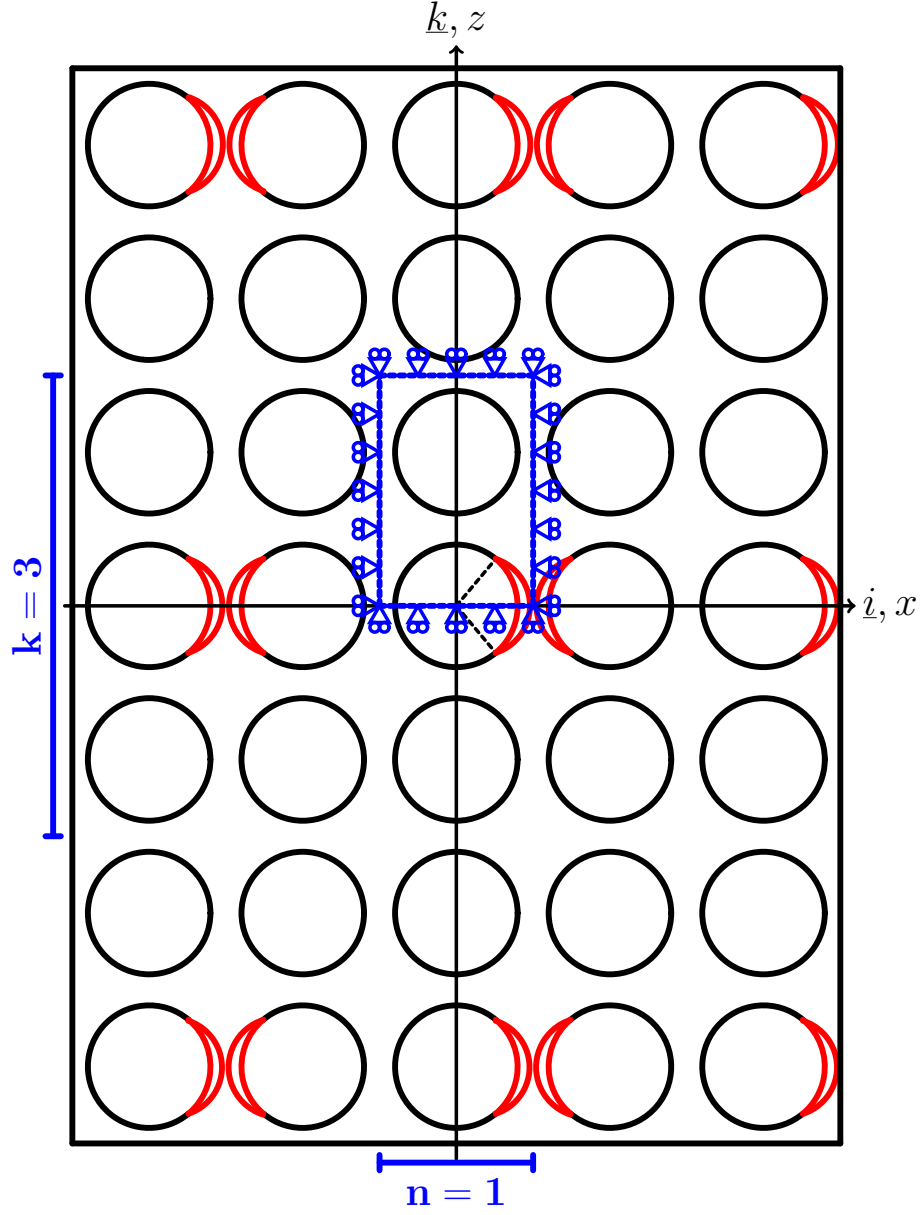


Figure 3: Horizontal rows of fibers with debonds repeating at different distances along the vertical direction: models $1 \times k$ - coupling.

where $2L$ is the length of a one-fiber unit, see Fig. 4, and L is defined as a

function of the fiber volume fraction V_f and the fiber radius R_f according to

$$L = \frac{R_f}{2} \sqrt{\frac{\pi}{V_f}}. \quad (2)$$

R_f is assumed to be the same for every fiber and equal to $1 \mu m$. The
 125 choice of the previous value is not dictated by physical considerations but for
 simplicity. It is thus useful to remark here that, in a linear elastic solution as the
 one considered in the present work, the ERR is proportional to the geometrical
 dimensions of the model and, consequently, recalculation of the ERR for fibers
 of any size requires a simple multiplication. Notice also that relationships in
 130 Eqs. 1 and 2 imply that the local and global V_f are everywhere equal.

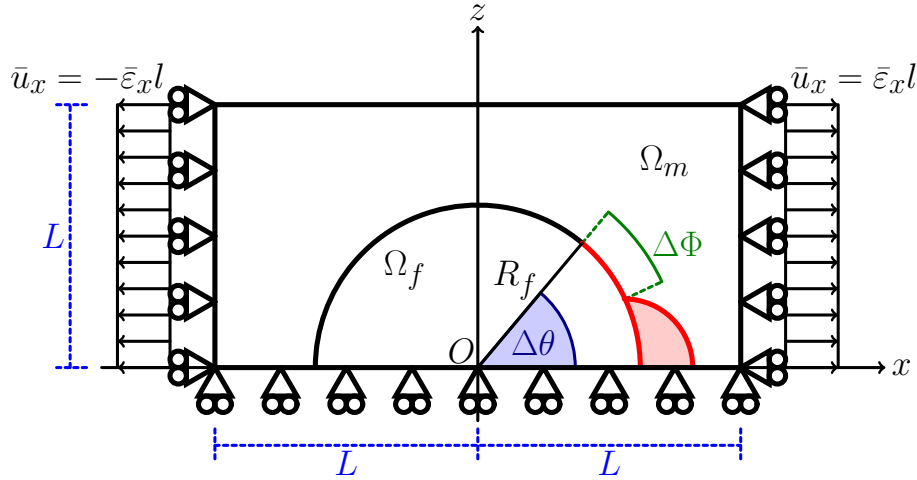


Figure 4: Schematic of the model with its main parameters.

The debond is placed symmetrically with respect to the x axis (see Fig. 4)
 and it is characterized by an angular size of $\Delta\theta$ (making the full debond size
 equal to $2\Delta\theta$). For large debond sizes (at least $\geq 60^\circ - 80^\circ$), a region $\Delta\Phi$ of
 variable size appears at the crack tip where the crack faces are in contact with
 135 each other but free to slide relatively to each other. In order to model crack
 faces motion in the contact zone, frictionless contact is considered between the
 two crack faces to allow free sliding and avoid interpenetration. Symmetry with
 respect to the x axis is applied on the lower boundary and coupling of vertical

displacement on the upper boundary. Kinematic coupling on the x -displacement
140 is applied along the left and right sides of the RUC in the form of a constant
 x -displacement $\pm \bar{\epsilon}_x l$, corresponding to transverse strain $\bar{\epsilon}_x$ equal to 1%.

Table 1: Summary of the mechanical properties of fiber and matrix. E stands for Young’s modulus, μ for shear modulus and ν for Poisson’s ratio.

Material	E [GPa]	μ [GPa]	ν [–]
Glass fiber	70.0	29.2	0.2
Epoxy	3.5	1.25	0.4

Meshing of the model is accomplished with second order, 2D, plane strain tri-
angular (CPE6) and quadrilateral (CPE8) elements. A regular mesh of 8-node
(2nd order rectangular) elements with almost unitary aspect ratio is enforced at
145 the crack tip in order to ensure the convergence of the ERR. The angular size
 δ of an element in the crack tip neighborhood is always equal to 0.05° . The
crack faces are modeled as element-based surfaces and a small-sliding contact
pair interaction with no friction is imposed between them. The Mode I, Mode
II and total Energy Release Rates (ERRs) (respectively referred to as G_I , G_{II}
150 and G_{TOT}) are the main result of FEM simulations; they are evaluated using
the VCCT [20] implemented in a in-house Python routine and, for G_{TOT} only,
the J-integral [21] is calculated by use of the Abaqus built-in command. A glass
fiber-epoxy UD composite is treated in the present work, and it is assumed that
their response lies always in the linear elastic domain. The material properties
155 of glass fiber and epoxy are reported in Table 1. Validation is performed with
respect to the results reported in [3, 14], which were obtained with the Boundary
Element Method (BEM) for a model of a single fiber with a symmetric debond
placed in an infinite matrix. As discussed in more detail in [22], the agreement
between FEM (present work) and BEM [3, 14] solutions is good and the dif-
160 ference between the two does not exceed 5%. This provides us with a level of
uncertainty with which we can analyze the significance of observed trends: any
relative difference in ERR between different RUCs smaller than 5% cannot be

reliably distinguished from numerical uncertainty and its discussion should thus be avoided.

165 **3. Results & Discussion**

3.1. Interaction between isolated debonds in infinite UD composites

The effect on Mode I and Mode II ERR of the interaction between debonds appearing at regular distances (in terms of fully bonded fibers) in the horizontal and vertical directions (models $n \times k$ –*coupling*) is shown respectively in Figure 5
170 and Figure 6. It can be observed that it is the distance between debonds in the horizontal direction that presents a relevant effect on ERR: the number of fully bonded fibers between consecutive debonds in the vertical direction has a negligible influence on Mode I and a very modest effect, below or at the limit of the 5% accuracy of the model, on Mode II.

175 On the other hand, increasing the number of fully bonded fibers between debonds in the horizontal direction leads to a significant increase in both Mode I and Mode II ERR, due to the magnification of the x -strain in the crack tip neighborhood [22]. A critical distance (in terms of undamaged fibers) at which a non-interacting solution can be observed is apparent for Mode I (Figure 5).
180 Given that Mode II ERR for models 21×3 –*coupling*, 21×21 –*coupling*, 101×3 –*coupling* and 101×101 –*coupling* is in a $\leq 5\%$ range with respect to each other and thus their difference is not significant taking into account model accuracy, it can be argued that also in Mode II a critical distance exists at which a non-interacting solution appears.

185 *3.2. Debond-debond interaction between horizontal rows of partially debonded fibers in infinite UD composites*

The results presented in Figures 7 and 8 for respectively Mode I and Mode II ERR of models $1 \times k$ –*coupling* confirm the observations presented in Section 3.1. Models $1 \times k$ –*coupling* represents the RVE of an infinite UD composite with
190 horizontal fiber rows that appear at regular intervals (measured in terms of

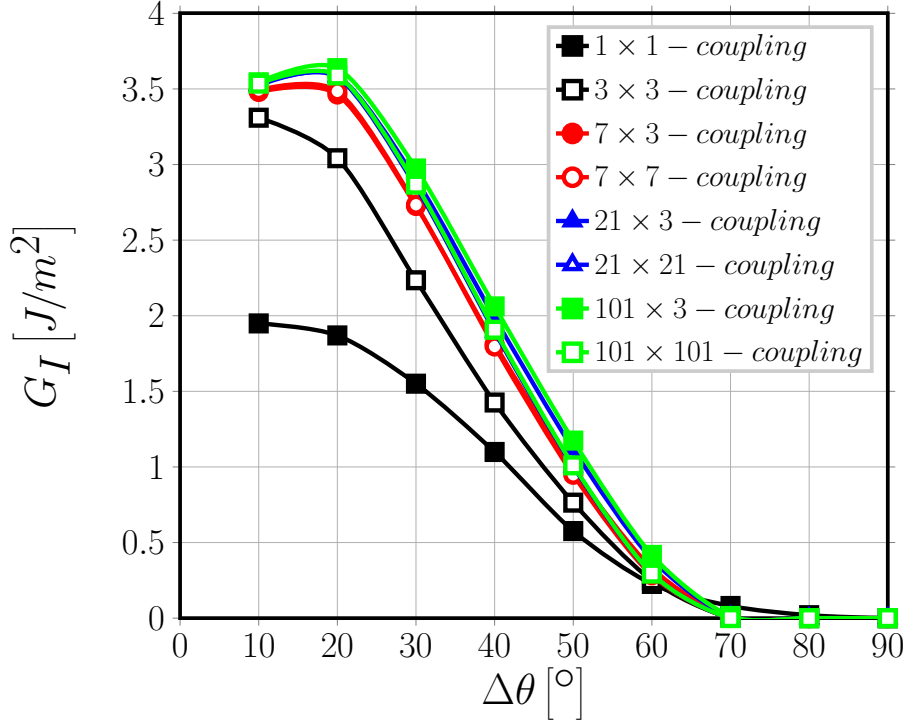


Figure 5: Effect of debond-debond interaction in infinite UD composites on Mode I ERR: models $n \times k$ – coupling. $V_f = 60\%$, $\varepsilon_x = 1\%$.

fully bonded fibers) and in which fibers are all partially debonded (see Fig. 3 for reference).

Varying the number k of undamaged fibers between fiber rows of only partially debonded fibers does not have any effect on ERR, neither in Mode I (Figure 7) nor in Mode II (Figure 8). The observations of Sec. 3.1 are thus confirmed: it is the presence of fully bonded fibers only in the horizontal direction, i.e. the loading direction, that affects the debond ERR through x -strain magnification.

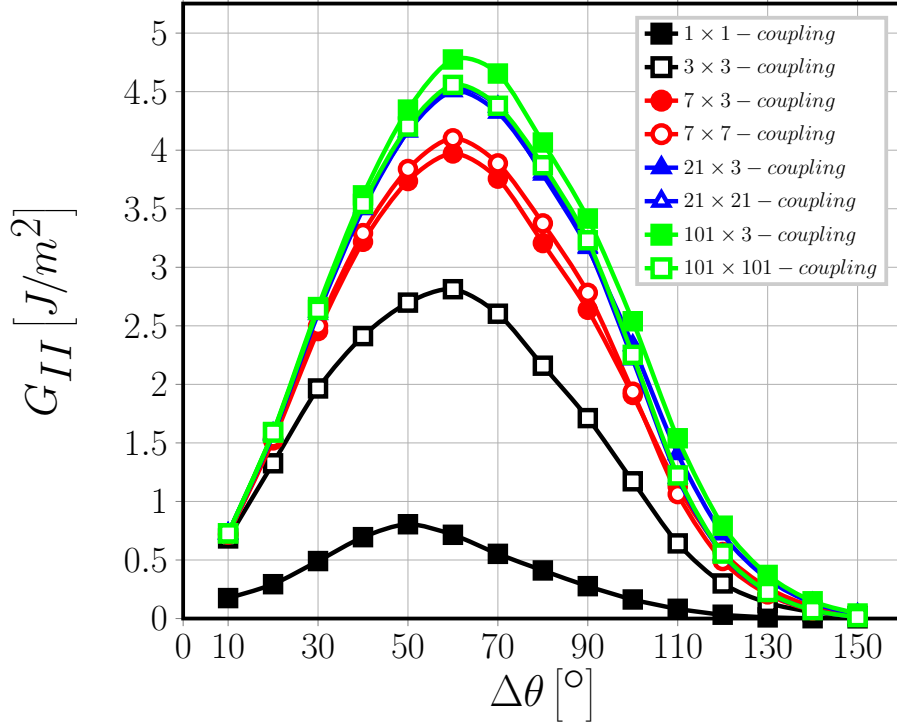


Figure 6: Effect of debond-debond interaction in infinite UD composites on Mode II ERR: models $n \times k$ – coupling. $V_f = 60\%$, $\varepsilon_x = 1\%$.

3.3. Debond-debond interaction between vertical lines of partially debonded fibers in infinite UD composites

Figures 9 and 10 report respectively Mode I and Mode II ERR for models $1 \times k$ – coupling, which correspond to the RVEs of UD composites with vertical lines of partially debonded fibers appearing at regular intervals (in terms of undamaged fibers) in the horizontal direction (see Fig. 2 for reference).

As it can be expected from the discussion of Sec. 3.1 and Sec. 3.2, increasing the number of fully bonded fibers between two consecutive lines of partially debonded fibers is responsible for significant increases in both Mode I and Mode II ERR.

However, comparison of Fig. 9 with Fig. 7 and of Fig. 10 with Fig. 8 provides an additional interesting result: the presence of fully bonded fibers between

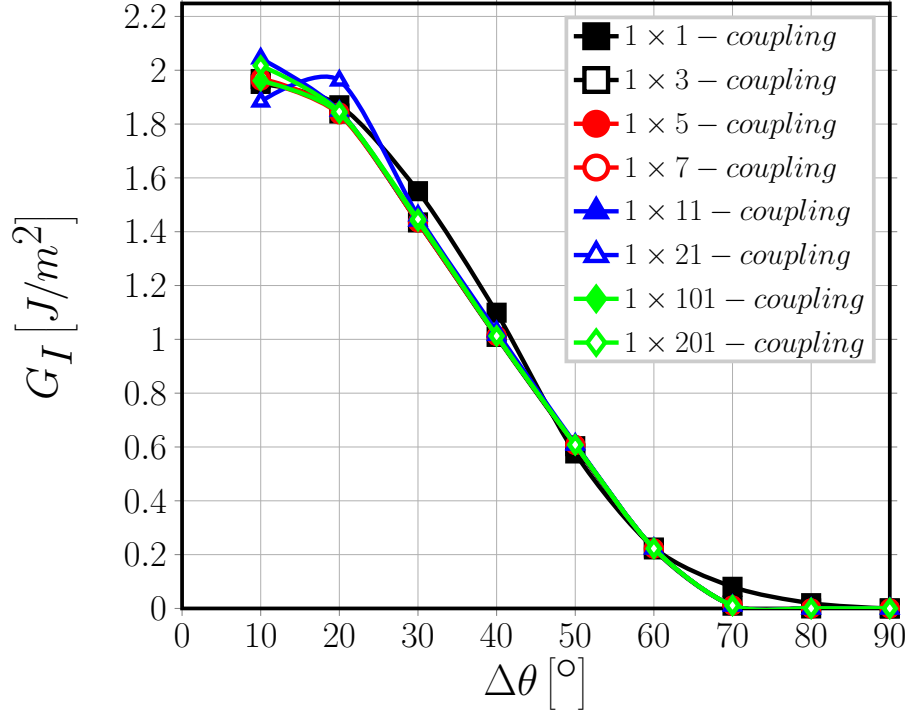


Figure 7: Effect of debond-debond interaction in infinite UD composites on Mode I ERR: models $1 \times k$ – coupling. $V_f = 60\%$, $\varepsilon_x = 1\%$.

debonds appearing on vertically aligned fibers reduces both G_I and G_{II} . On the other hand, for the same horizontal distance between debonded fibers, the energetically most favorable configuration is achieved when debonds are contiguous along the vertical direction. Two further effects can be observed: the onset of the contact zone is delayed up to a debond size of $\sim 100^\circ$ (Fig. 9); the peak value of G_{II} is shifted to a debond size of up to 90° (Fig. 10). Thus, larger debonds are in general favored. This behavior can be related to the local deformation of the matrix. Between two vertically aligned debonds, the matrix strip between the two partially debonded fibers has, locally, both the lower and the upper surface free to deform. Due to Poisson's effect, the two surfaces move towards each other, imposing an opening displacement on the crack tip. This in turn favors Mode I and delays the onset of the contact zone. Furthermore,

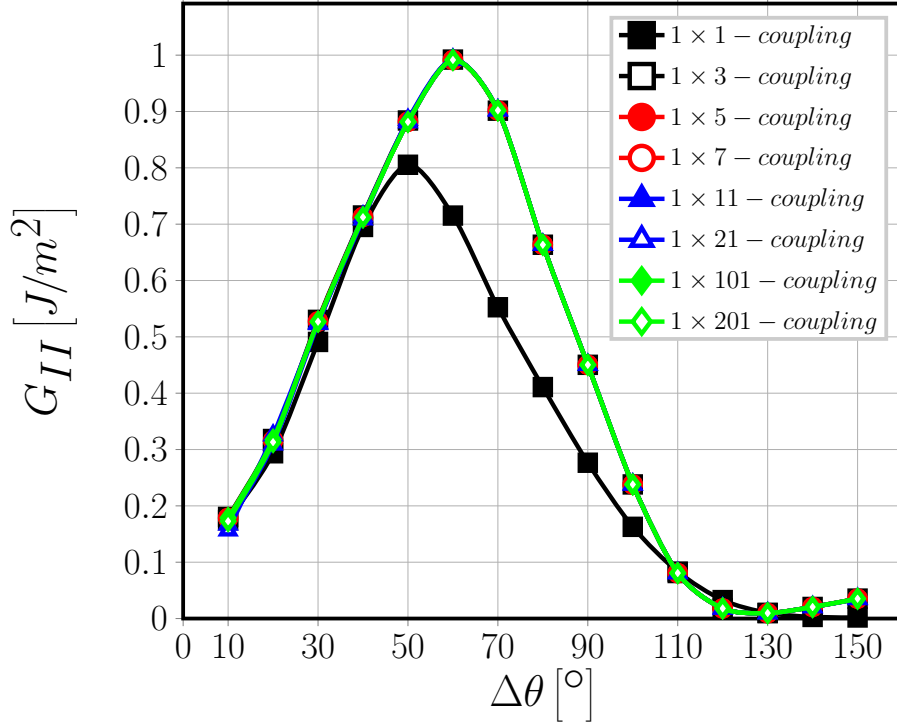


Figure 8: Effect of debond-debond interaction in infinite UD composites on Mode II ERR: models $1 \times k$ – coupling. $V_f = 60\%$, $\varepsilon_x = 1\%$.

taking into account that fibers are more rigid than the surrounding matrix, when the fiber on top of the debonded one is undamaged (fully bonded), the x -displacement field in the matrix is restrained by the requirement of continuity at the interface. When instead another partially debonded fiber is present, a matrix strip is created with an upper and lower free surfaces, i.e. detached from the upper and lower fibers. The displacement field in this matrix strip is thus not restrained by the more rigid fibers and a magnification effect of the x -strain takes place. This in turn causes an increase in G_I for smaller debonds (the x -displacement is the major component of the crack opening displacement at the crack tip) and in G_{II} for larger ones (the x -displacement is the major component of the crack shear displacement at the crack tip).

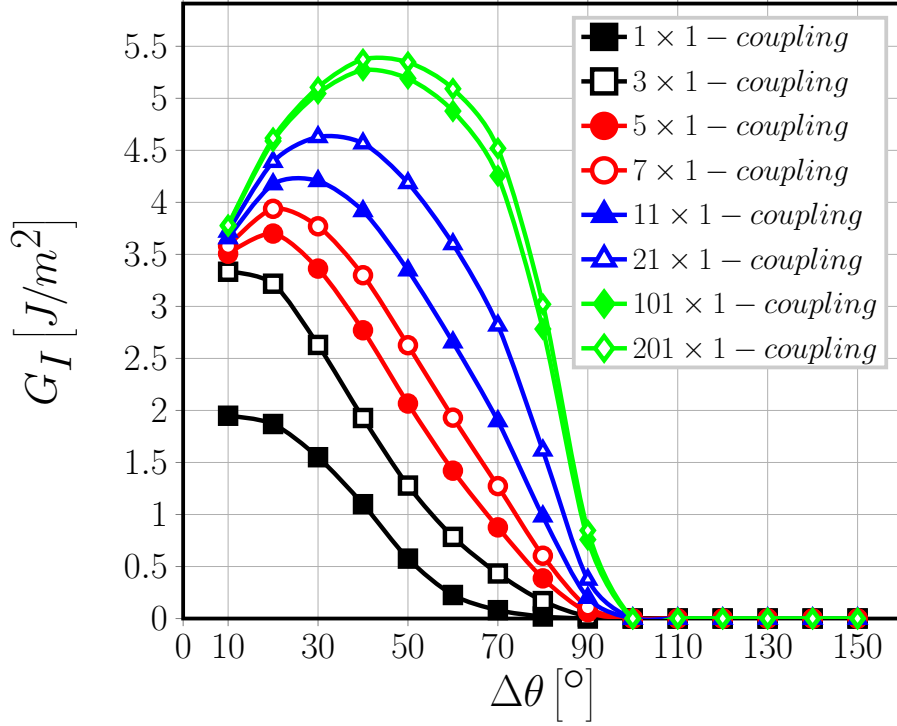


Figure 9: Effect of debond-debond interaction in infinite UD composites on Mode I ERR: models $n \times 1 - coupling$. $V_f = 60\%$, $\varepsilon_x = 1\%$.

4. Conclusions & Outlook

235 Different models of infinite UD composites have been studied with different configurations of multiple interacting debonds in order to investigate their effect of Mode I and Mode II Energy Release Rate.

Building upon the observations made in the previous section, several conclusions can be drawn about the growth of debonds in UD composites:

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- at given strain level, multiple debonds can appear on not consecutive vertically-aligned fibers;
 - at a given strain level, the vertical lines of fibers on which debonds grow are determined by the horizontal distance from pre-existing debonds;
 - a minimum non-interactive distance exists for the Energy Release Rate;

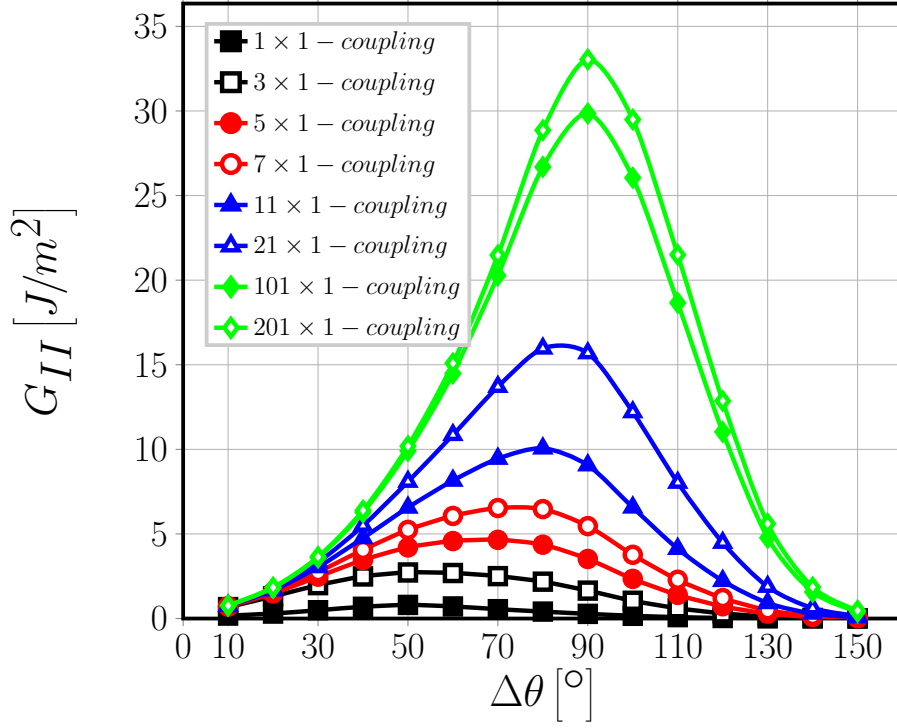


Figure 10: Effect of debond-debond interaction in infinite UD composites on Mode II ERR: models $n \times 1$ – coupling. $V_f = 60\%$, $\varepsilon_x = 1\%$.

- when spacing between vertical lines of debonds is lower than the minimum non-interactive distance, the ERR decreases;
- thus, conversely, when spacing between vertical lines of debonds is lower than the minimum non-interactive distance, higher levels of strain are needed to grow debonds;
- growth of debonds appearing on contiguous vertically-aligned fibers is energetically the most favorable;
- larger debonds are favored on contiguous vertically aligned partially debonded fibers.

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