

# Analysis of stresses and strains

Luca Di Stasio<sup>a</sup>, Janis Varna<sup>a</sup>

<sup>a</sup>Luleå University of Technology, University Campus, SE-97187 Luleå, Sweden

---

## Abstract

---

### 1. Introduction

### 2. Models of Representative Volume Element (RVE)

### 3. Stresses at the interface

#### 3.1. $\sigma_{rr}$

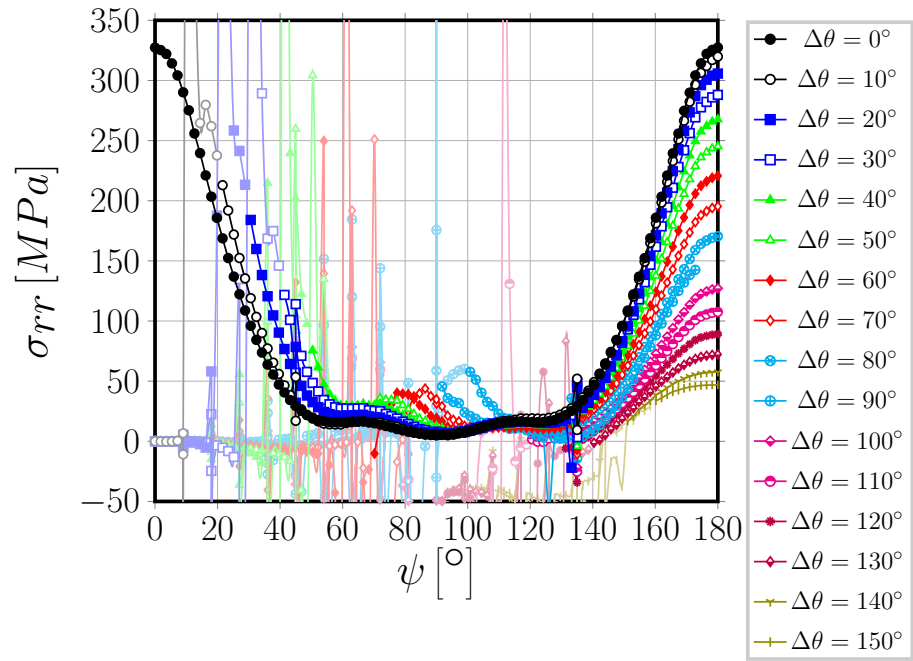


Figure 1:  $\sigma_{rr}$ ,  $11 \times 1 - free$ .  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

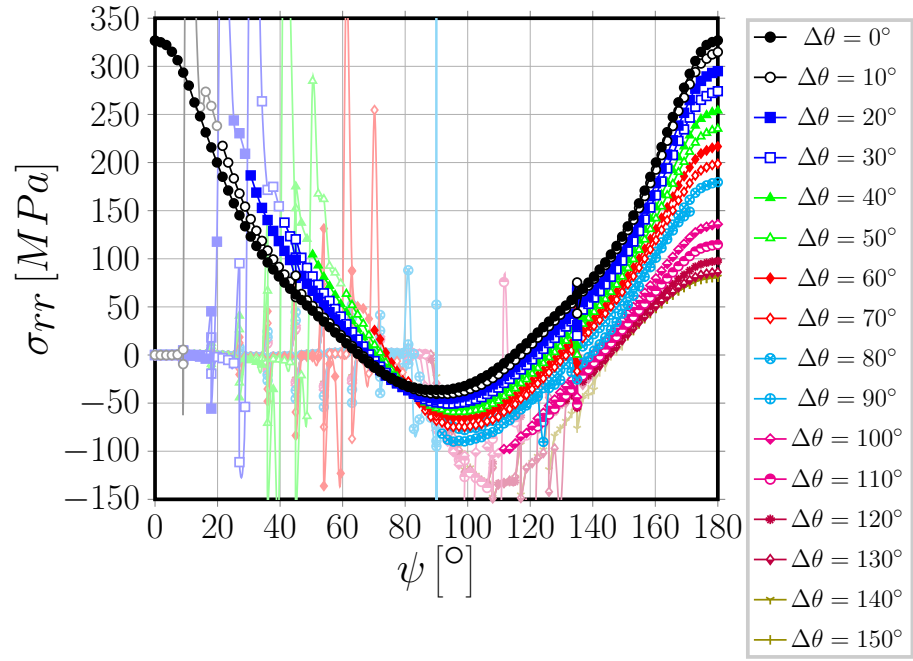


Figure 2:  $\sigma_{rr}$ ,  $11 \times 1 - 1 \cdot t_{90^\circ}$ .  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

5 3.2.  $\sigma_{\theta\theta}$

3.3.  $\tau_{r\theta}$

#### 4. Conclusions

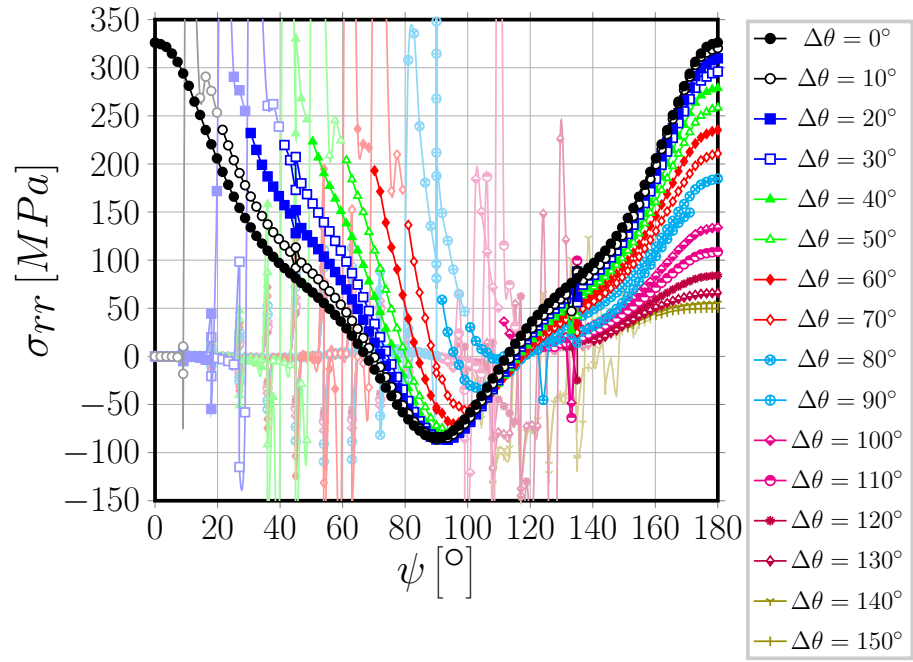


Figure 3:  $\sigma_{rr}$ ,  $11 \times 1 - symm$ .  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

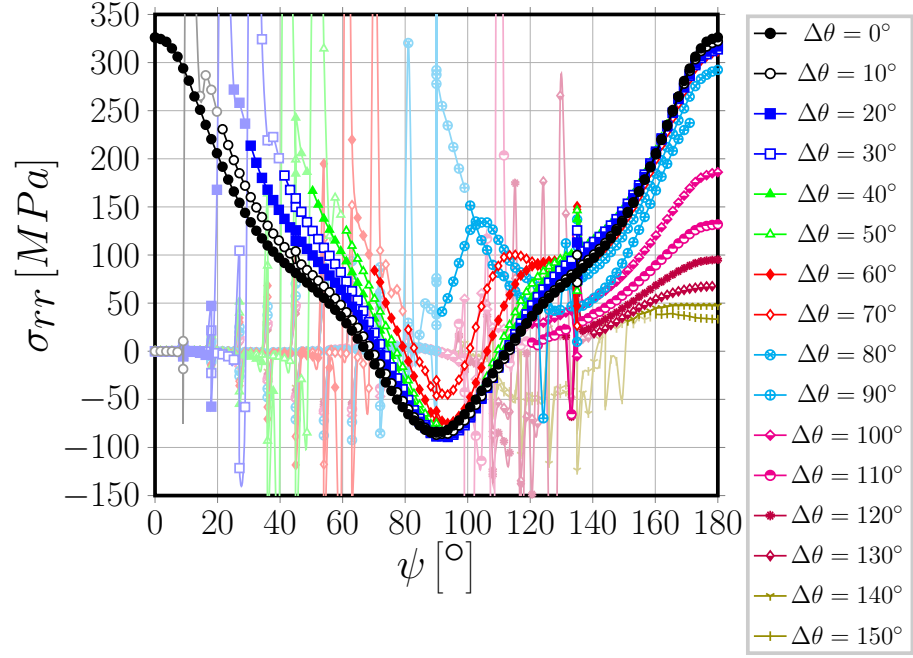


Figure 4:  $\sigma_{rr}$ ,  $11 \times 1 - asymm$ .  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

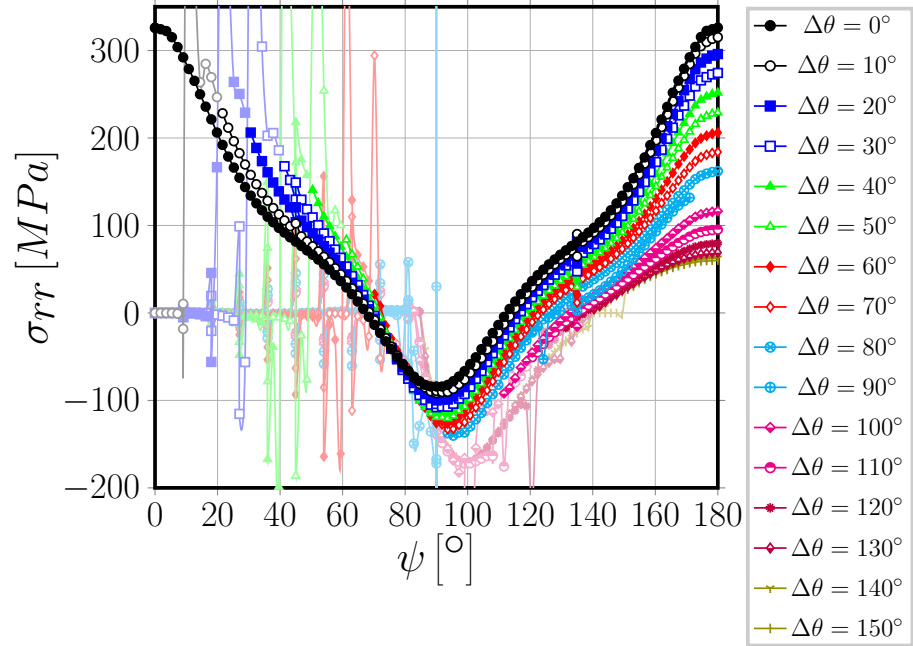


Figure 5:  $\sigma_{rr}$ ,  $11 \times 3 - free$ .  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

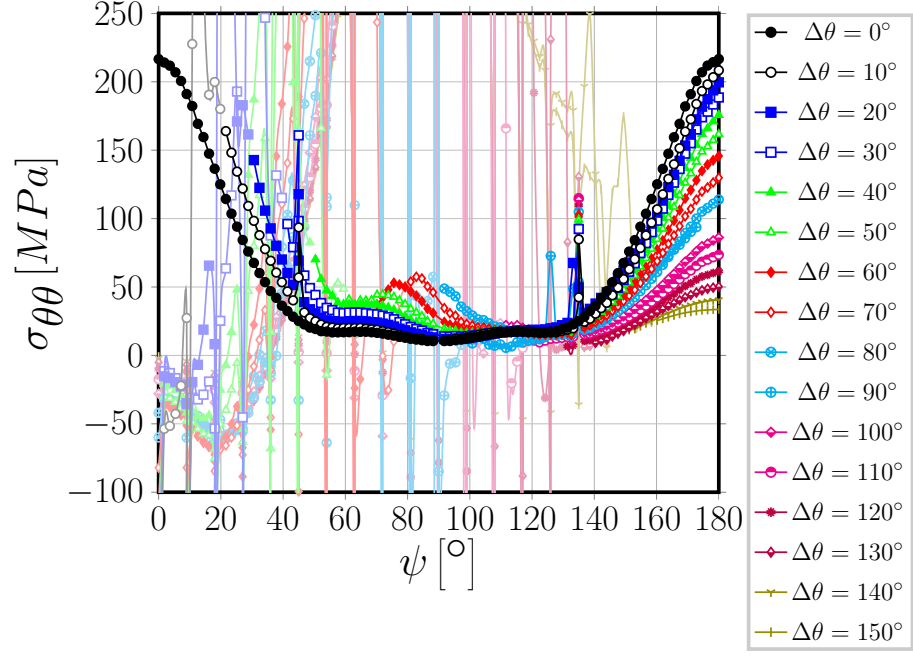


Figure 6:  $\sigma_{\theta\theta}$ ,  $11 \times 1 - free$ .  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

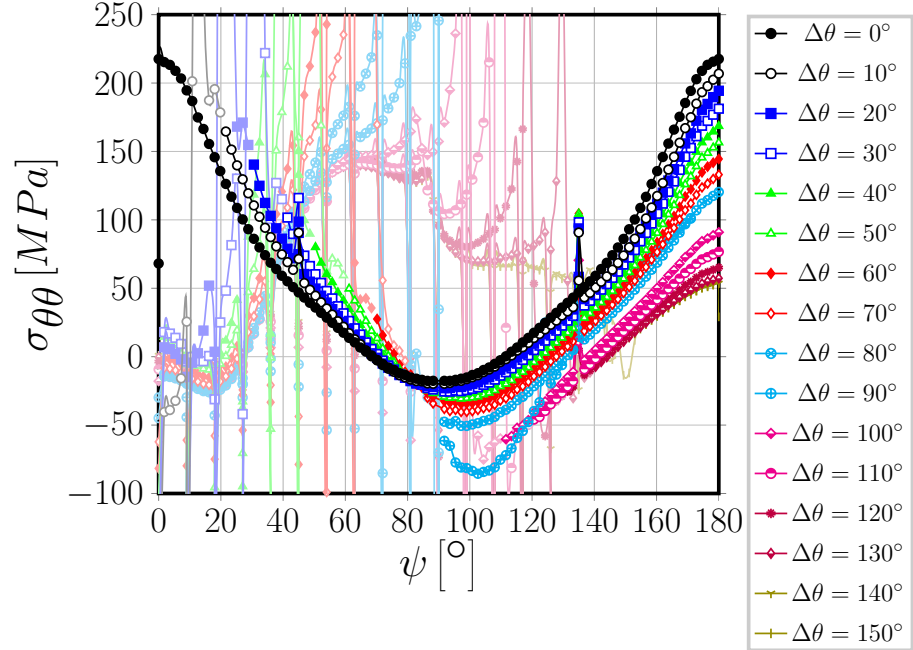


Figure 7:  $\sigma_{\theta\theta}$ ,  $11 \times 1 - 1 \cdot t_{90^\circ}$ .  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

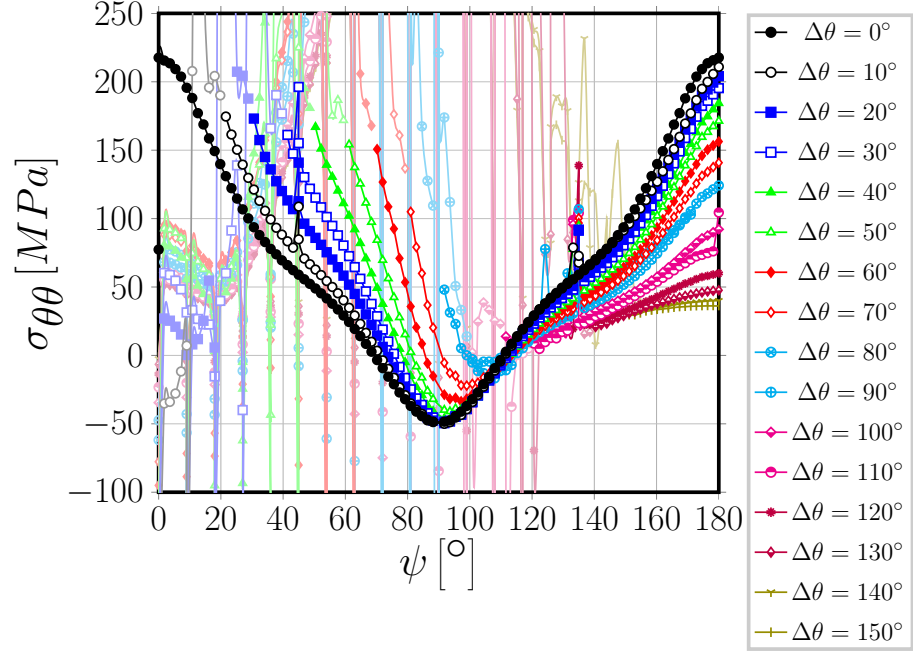


Figure 8:  $\sigma_{\theta\theta}$ ,  $11 \times 1$  - *symm*.  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

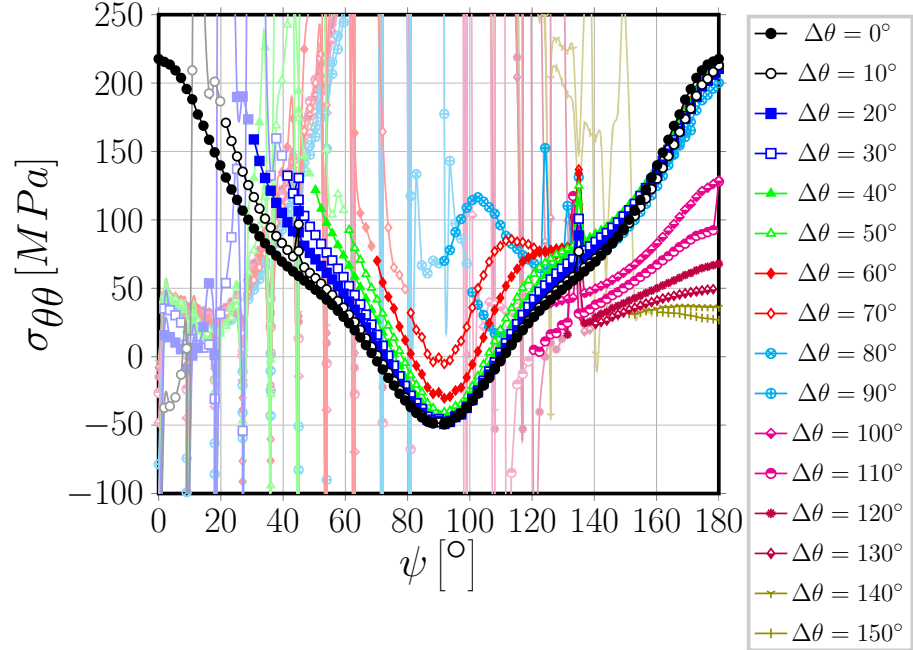


Figure 9:  $\sigma_{\theta\theta}$ ,  $11 \times 1$  - *asymm*.  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

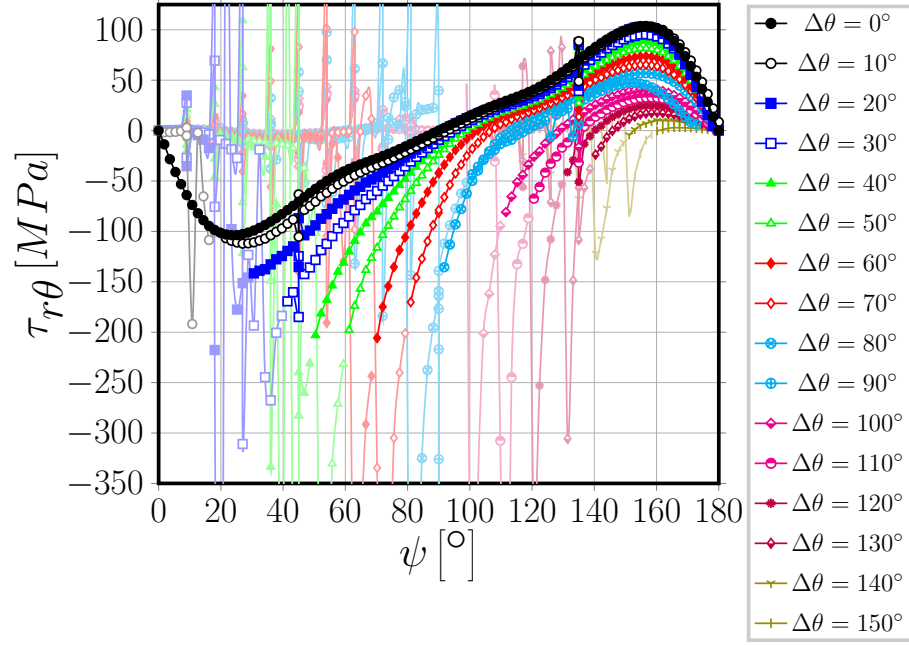


Figure 10:  $\tau_{r\theta}$ ,  $11 \times 1$  - free.  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

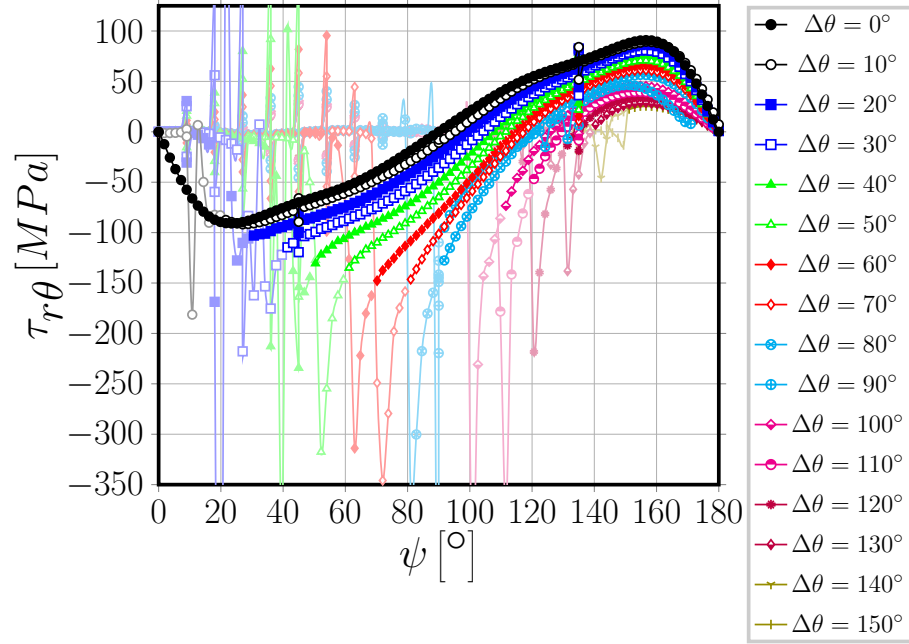


Figure 11:  $\tau_{r\theta}$ ,  $11 \times 1 - 1 \cdot t_{90^\circ}$ .  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

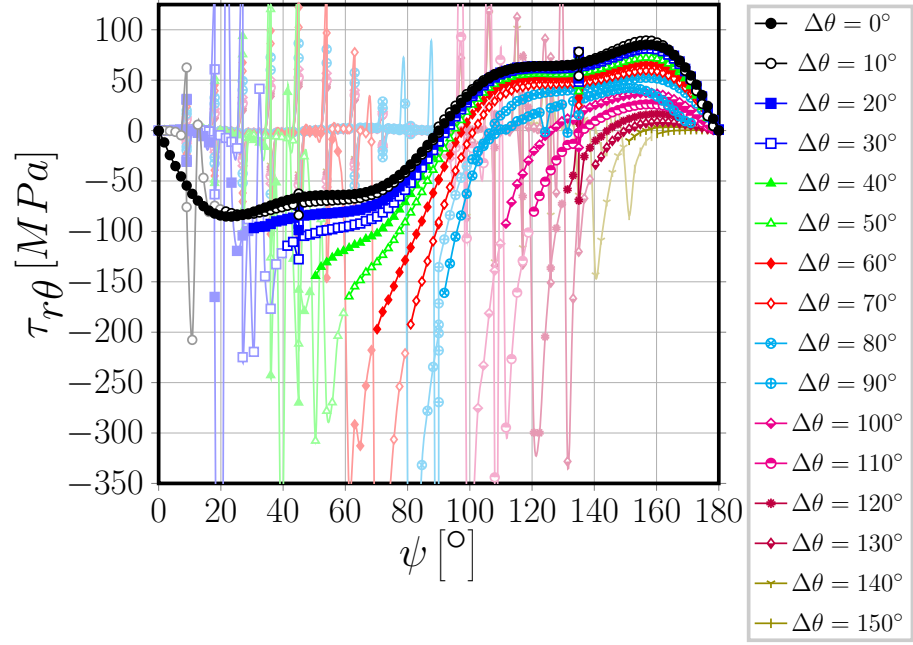


Figure 12:  $\tau_{r\theta}$ ,  $11 \times 1$  – *symm*.  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .

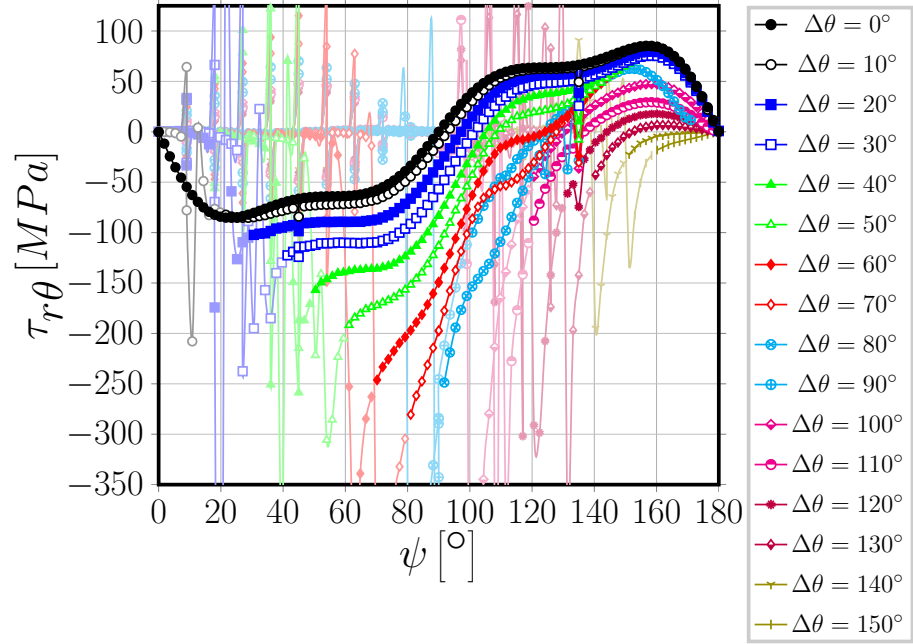


Figure 13:  $\tau_{r\theta}$ ,  $11 \times 1$  – *asymm*.  $V_f = 60\%$ ,  $\varepsilon_x = 1\%$ .