

**Additional Exercise 12.6 [Boyd & Vandenberghe, 2017]**

*Ans:* (a) Assuming in the discretization  $\theta^{tar}$  remains to be a node. Since  $M \geq \max\{|G(\theta)| \mid |\theta_k - \theta^{tar}| \geq \Delta\}$  is equivalent to  $M^2 \geq \max\{|G(\theta)|^2 \mid |\theta_k - \theta^{tar}| \geq \Delta\}$ , we can write the SOCP

$$\begin{aligned} & \text{minimize} && t \\ & \text{subjected to} && G(\theta^{tar}, \omega) = 1 \\ & && |G(\theta_k, \omega)|^2 \leq t \text{ for } k \text{ such that } |\theta_k - \theta^{tar}| \geq \Delta \end{aligned}$$

(b) The code associated with this problem is attached here.

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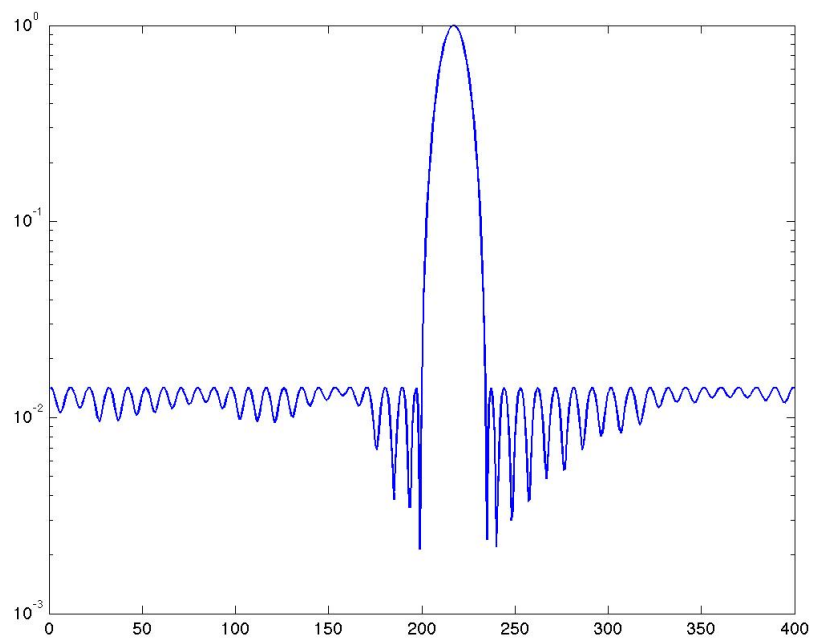
rand('state',0);
n = 40;
x = 30 * rand(1,n);
y = 30 * rand(1,n);

N = 400;
theta = linspace(-pi,pi,N)';
theta_tar = pi/12;
[~, tar_k] = min(abs(theta-theta_tar));
theta_tar_approx = theta(tar_k);
Delta = pi/12;
outside_index = (abs(theta-theta_tar)>= Delta);
G = @(omega) exp(1i*(cos(theta)*x+sin(theta)*y))*omega;
G_tar = @(omega) exp(1i*(cos(theta_tar_approx)*x+sin(theta_tar_approx)*y))*omega;

cvx_begin
    variable omega(n) complex
    variable t
    minimize t;
    subject to
        diag(outside_index)*abs(G(omega)) <= t*ones(N,1)
        G_tar(omega) == 1
cvx_end

h=semilogy(abs(G(omega)),'b-','LineWidth',1.2);
saveas(h, 'hw6P126','jpg');
```

The graph of  $|G(\theta)|$  with logarithm scaling is attached here.



**Additional Exercise 4.4 [Boyd & Vandenberghe, 2017]**

*Ans:* The KKT condition to the problem is ①  $x^T x - t = 0$ , ② (No inequality constraint. Skipped.), ③ (No inequality constraint. Skipped.), ④ the vanishing gradient (w.r.t.  $x$  and  $t$ ) of Lagrangian,

$$\sum_{k=1}^m -4 \left( t - 2y_k^T x + \|y_k\|_2^2 - d_k^2 \right) y_k + 2\nu x = 0$$

$$\sum_{k=1}^m 2 \left( t - 2y_k^T x + \|y_k\|_2^2 - d_k^2 \right) - \nu = 0$$

Rearrange the above two equations we can solve for  $x$  and  $t$  once  $\nu$  is given. The Lagrangian dual function is

$$\begin{aligned} g(\nu) &= \inf_{x,t} \left( \sum_{k=1}^m \left( t - 2y_k^T x + \|y_k\|_2^2 - d_k^2 \right)^2 + \nu(x^T x - t) \right) \\ &= \inf_{x,t} \left( \sum_{k=1}^m \left( \|x - y_k\|_2^2 - d_k^2 - x^T x + t \right)^2 + \nu(x^T x - t) \right) \end{aligned}$$

**Exercise 4.43 (b, c) [Boyd & Vandenberghe, 2004]**

*Ans:* (b) Note that the smallest eigenvalue  $\lambda_m(x) = \lambda_{\min}(A(x))$  also has a similar relation

$$\lambda_{\min}(A) \geq s \iff A \succeq sI$$

Therefore the problem can be formulated as

$$\begin{aligned} & \text{minimize} && t - s \\ & \text{subjected to} && A(x) \preceq tI \\ & && sI \preceq A(x) \end{aligned}$$

(c) We need to do the problem

$$\begin{aligned} & \text{minimize} && \lambda/\gamma \\ & \text{subjected to} && A(x) \preceq \lambda I \\ & && \gamma I \preceq A(x) \\ & && 0 \prec \gamma I \end{aligned}$$

Following the hint to change the variable,  $y = \frac{x}{\gamma}, t = \frac{\lambda}{\gamma}, s = \frac{1}{\gamma}$ , then  $A(x) = A_0 + x_1 A_1 + \dots + x_n A_n = \gamma(sA_0 + y_1 A_1 + \dots + y_n A_n)$ , and the problem becomes

$$\begin{aligned} & \text{minimize} && t \\ & \text{subjected to} && sA_0 + y_1 A_1 + \dots + y_n A_n \preceq tI \\ & && I \preceq sA_0 + y_1 A_1 + \dots + y_n A_n \end{aligned}$$

□

**Exercise 5.19 [Boyd & Vandenberghe, 2004]**

Ans: (a) The optimal value is

$$\max \left\{ \sum_{i=1}^n y_i x_i \mid y_i \in [0, 1], \sum_{i=1}^n y_i = r \right\}$$

Since this is linear in  $x$ , the optimal value can only be lumping the weights ( $y_i$ 's) on the largest  $r$  components of  $x$ .

(b) The Lagrangian dual function is (note the original problem is maximizing  $x^T y$ , so I translated it to minimizing  $-x^T y$ .)

$$\begin{aligned} g(\lambda_1, \lambda_2, \nu; x) &= \inf_y -x^T y - \lambda_1^T y + \lambda_2^T (y - \mathbf{1}) + \nu(\mathbf{1}^T y - r) \\ &= \inf_y y^T (-x - \lambda_1 + \lambda_2 + \nu \mathbf{1}) - \mathbf{1}^T \lambda_2 - \nu r \\ &= \begin{cases} -\mathbf{1}^T \lambda_2 - \nu r, & -x - \lambda_1 + \lambda_2 + \nu \mathbf{1} = 0 \\ \infty, & \text{else} \end{cases} \end{aligned}$$

The dual problem is then

$$\begin{aligned} &\text{maximize} && -\mathbf{1}^T \lambda_2 - \nu r \\ &\text{subjected to} && -x - \lambda_1 + \lambda_2 + \nu \mathbf{1} = 0 \\ &&& \lambda_1 \succeq 0 \\ &&& \lambda_2 \succeq 0 \end{aligned}$$

Or if we let  $\lambda_2 = u, \nu = t$  and combine the two constraints of  $\lambda_1$ ,

$$\begin{aligned} &\text{maximize} && -\mathbf{1}^T u - tr \\ &\text{subjected to} && -x + u + t\mathbf{1} \succeq 0 \\ &&& u \succeq 0 \end{aligned}$$

This is essentially the same as given in the problem. The three conditions  $rt + \mathbf{1}^T u \leq \alpha, t\mathbf{1} + u \succeq x, u \succeq 0$  just mean that the optimal value of the dual LP (which is the same as the primal LP, which is  $f(x)$ ) is less than or equal to  $\alpha$ .

(c) Here the constraint  $\sum_{i=1}^{\lfloor 0.1n \rfloor} x_{[i]} \leq 0.8$  yields  $r = \lfloor 0.1n \rfloor, \alpha = 0.8$ ; that is, the prob-

lem can be formulated using the technique discussed above as

$$\begin{array}{ll}\text{minimize} & x^T \Sigma x \\ \text{subjected to} & \bar{p}^T x \geq r_{\min} \\ & \mathbf{1}^T x = 1 \\ & x \succeq 0 \\ & \lfloor 0.1n \rfloor t + \mathbf{1}^T u \leq 0.8 \\ & t\mathbf{1} + u \succeq x \\ & u \succeq 0\end{array}$$

with variables  $x \in \mathbb{R}^n, t \in \mathbb{R}, u \in \mathbb{R}^n$ .

□

**Exercise 5.21 (a, b, c) [Boyd & Vandenberghe, 2004]**

*Ans:* (a) For sure  $\frac{d^2}{dx^2}e^{-x} = (-1)^2e^{-x} = e^{-x} > 0$ , the cost function is convex. Let  $f_1(x, y) = x^2/y$ .

$$\begin{aligned}\nabla f_1(x, y) &= \begin{bmatrix} 2x/y & -x^2/y^2 \end{bmatrix} \\ H_{f_1}(x, y) &= \begin{bmatrix} \frac{2}{y} & \frac{-2x}{y^2} \\ \frac{-2x}{y^2} & \frac{2x^2}{y^3} \end{bmatrix}\end{aligned}$$

and  $H_{f_1}(x, y) \succeq 0$  since  $\frac{2}{y} > 0$  and  $\det(H_{f_1}(x, y)) = \frac{4x^2}{y^4} - \frac{4x^2}{y^4} = 0 \geq 0$ . The constraint function is essentially ruling  $x = 0$  since the domain  $\mathcal{D}$  restricts  $y > 0$ ; with this observation, we conclude the optimal value to the problem is  $e^{-0} = 1$ .

(b) First observe the Lagrangian is always positive for nonnegative  $\lambda$ ,

$$L(x, y, \lambda) = e^{-x} + \lambda \frac{x^2}{y} \geq 0$$

since  $e^{-x} > 0$  and  $x^2/y \geq 0$ . Now consider  $y = \lambda x^4$  as  $x \rightarrow \infty$ , then

$$L(x, y, \lambda, \nu) = e^{-x} + \lambda \frac{x^2}{y} = e^{-x} + \frac{1}{x^2} \rightarrow 0$$

That is, the Lagrangian dual function

$$g(\lambda) = \inf_{x, y} L(x, y, \lambda) = 0$$

is the zero constant function regardless of the input  $\lambda$ . Hence any  $\lambda \geq 0$  can be optimal solution to the dual problem

$$\begin{aligned}\text{minimize} \quad & g(\lambda) \\ \text{subjected to} \quad & \lambda \geq 0\end{aligned}$$

and the optimal value  $d^* = 0$ . Notice a optimal duality gap  $p^* - d^* = 1 - 0 = 1$ .

(c) Note that the Slater's condition does not hold for this problem since there exists no  $x$  and  $y$  such that  $x^2/y < 0$  and  $y > 0$ .  $\square$

**Additional Exercise 4.30 [Boyd & Vandenberghe, 2017]**

Ans: (a) The Lagrangian dual function is

$$\begin{aligned} g(\lambda) &= \inf_{x,y} \left( c^T x + \frac{1}{\mu} \sum_{i=1}^m \log(1 + e^{\mu y_i}) + \lambda^T (Ax - b - y) \right) \\ &= -\lambda^T b + \inf_{x,y} \left( x^T (c + A^T \lambda) + \frac{1}{\mu} \sum_{i=1}^m \log(1 + e^{\mu y_i}) - \lambda^T y \right) \end{aligned}$$

The  $y$  part is minimized when

$$\frac{1}{\mu} \cdot \frac{\mu e^{\mu y_i}}{1 + e^{\mu y_i}} - \lambda_i = 0 \text{ for } i = 1, \dots, m$$

or

$$y_i = \frac{1}{\mu} \log \left( \frac{\lambda_i}{1 - \lambda_i} \right) \text{ for } i = 1, \dots, m$$

therefore,

$$\begin{aligned} g(\lambda) &= -\lambda^T b + \inf_{x,y} \left( x^T (c + A^T \lambda) + \frac{1}{\mu} \sum_{i=1}^m \log(1 + e^{\mu y_i}) - \lambda^T y \right) \\ &= -\lambda^T b + \frac{1}{\mu} \sum_{i=1}^m \log \left( \frac{1}{1 - \lambda_i} \right) - \sum_{i=1}^m \frac{\lambda_i}{\mu} \log \left( \frac{\lambda_i}{1 - \lambda_i} \right) + \inf_x x^T (c + A^T \lambda) \\ &= -\lambda^T b - \frac{1}{\mu} \sum_{i=1}^m ((1 - \lambda_i) \log(1 - \lambda_i) + \lambda_i \log(\lambda_i)) + \inf_x x^T (c + A^T \lambda) \\ &= \begin{cases} -b^T \lambda + \frac{1}{\mu} \sum_{i=1}^m \log(\lambda_i^{\lambda_i} (1 - \lambda_i)^{1 - \lambda_i}), & c + A^T \lambda = 0 \\ -\infty, & \text{else} \end{cases} \end{aligned}$$

with the domain restriction that  $\lambda_i \in (0, 1)$  for  $i = 1, \dots, m$ .

(b) (Note I used  $\lambda$  as my dual variable where it's  $z$  in the problem.) The Lagrangian dual of the dual linear program is

$$\tilde{g}(z) = \begin{cases} -b^T z, & A^T z + c = 0 \\ -\infty, & \text{else} \end{cases}$$

Assuming strong duality (assume so because the linear program and its dual has it), the optimal value of problem (25) is  $q^* = g(\lambda^*)$  for some  $\lambda^*$ . Now since  $z^*$  is an optimal solution to the dual linear program, we see it provides an upper bound

$$q^* \leq g(z^*) = -b^T z^* + \frac{1}{\mu} \sum_{i=1}^m \log \left( z_i^{*z_i^*} (1 - z_i^*)^{1 - z_i^*} \right) \leq p^* + \frac{1}{\mu} \sum_{i=1}^m \log 2$$

the last inequality follows from that  $0 \preceq z^* \preceq \mathbf{1}$ . The other side of the inequality required is not much but from the fact that  $p^* \leq g(\lambda)$  whenever  $g(\lambda)$  is defined.  $\square$