

**Problem 1**

$V$  is a vector space and  $S \subseteq V$ .

(a)  $W$  is a subspace of  $V$  if  $W$  is a vector space with the same operations (addition and scalar multiplication) defined on  $V$ .

(b)  $\text{span}(S)$  is the set of all linear combinations of vectors in  $S$ .

(c)  $S$  is linearly dependent if there exists  $v_1, \dots, v_n \in S$  and scalars  $a_1, \dots, a_n \in F$  such that

$$a_1v_1 + \dots + a_nv_n = 0$$

and not all  $a_i$ 's are zero.

(d)  $S$  is a basis of  $V$  if  $S$  is linearly independent and  $\text{span}(S) = V$ .

(e)  $\dim(V)$  is the unique number of vectors in each basis of  $V$ .

**Problem 2**

$V$  is a vector space,  $S \subseteq V$  is linearly independent and  $v \in V \setminus S$ . Prove that  $S \cup \{v\}$  is linearly dependent if and only if  $v \in \text{span}(S)$ .

" $\Rightarrow$ " Suppose  $S \cup \{v\}$  is linearly dependent, take the vectors  $v_1, \dots, v_n \in S \cup \{v\}$  and scalar  $a_1, \dots, a_n$  such that

$$a_1v_1 + \dots + a_nv_n = 0$$

Without loss of generality we can assume  $v$  is among these vectors, say,  $v_1 = v$ . If  $a_1 = 0$ , then we get

$$a_2v_2 + \dots + a_nv_n = 0$$

with  $v_2, \dots, v_n \in S$  and not all  $a_2, \dots, a_n$  are zero. This contradicts the assumption that  $S$  is linearly independent. If  $a_1 \neq 0$ , then we can divide the equation by  $a_1$  and get

$$v + \frac{a_2}{a_1}v_2 + \dots + \frac{a_n}{a_1}v_n = 0$$

Therefore  $v = -\frac{a_2}{a_1}v_2 - \dots - \frac{a_n}{a_1}v_n$  is a linear combination of vectors  $v_2, \dots, v_n \in S$  and  $v \in \text{span}(S)$ .

" $\Leftarrow$ " Suppose  $v \in \text{span}(S)$ ; write  $v = c_1u_1 + \dots + c_nu_n$  where  $u_1, \dots, u_n \in S$  and  $c_1, \dots, c_n$  are scalars. We see

$$\begin{aligned} 0 &= -v + c_1u_1 + \dots + c_nu_n \\ &= (-1)v + c_1u_1 + \dots + c_nu_n \end{aligned}$$

is a linear combination of vectors  $v, u_1, \dots, u_n \in S \cup \{v\}$  with not all zero coefficients. In particular, the coefficient of  $v$  is  $(-1) \neq 0$ .  $\square$

**Problem 3**

(a) ① The zero matrix  $O = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$  certainly is a diagonal matrix with zeros as diagonal entries. For diagonal matrices  $A = \begin{bmatrix} a_1 & 0 \\ 0 & a_2 \end{bmatrix}$ ,  $B = \begin{bmatrix} b_1 & 0 \\ 0 & b_2 \end{bmatrix}$  and scalar  $c \in \mathbb{R}$ , ② the sum  $A + B = \begin{bmatrix} a_1 + b_1 & 0 \\ 0 & a_2 + b_2 \end{bmatrix}$  and ③ the scalar multiple  $cA = \begin{bmatrix} ca_1 & 0 \\ 0 & ca_2 \end{bmatrix}$  are both diagonal. Therefore  $W$  is closed under addition and scalar multiplication. By Theorem in textbook,  $W$  is a subspace of  $M_{2 \times 2}(\mathbb{R})$ .

(b, c)  $S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\} \subseteq W$  is a basis since

$$a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \Leftrightarrow a = b = 0 \text{ (linear independence)}$$

and

$$\forall A = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \in W, A = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \in \text{span}(S) \text{ (} S \text{ spans } W \text{)}$$

Also,  $\dim(W) = \#S = 2$ .

(d) Consider  $T = \left\{ \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right\}$ ;  $S \cup T$  is a basis of  $M_{2 \times 2}(\mathbb{R})$  because

$$a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} + c \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} a & c \\ d & b \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \Leftrightarrow a = b = c = d = 0$$

and

$$\forall A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in M_{2 \times 2}(\mathbb{R}), A = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \in \text{span}(S \cup T)$$

**Problem 4**

(a)  $V$  is a vector space and  $W_1, W_2$  are subspaces of  $V$ . Prove that if  $W_1$  and  $W_2$  are finite dimensional then so is  $W_1 + W_2$ .

Take basis  $\beta_1 = \{v_1, \dots, v_n\}$ ,  $\beta_2 = \{u_1, \dots, u_m\}$  of  $W_1, W_2$ , respectively, then

$$W_1 = \{a_1 v_1 + \dots + a_n v_n \mid a_1, \dots, a_n \in F\}, W_2 = \{c_1 u_1 + \dots + c_m u_m \mid c_1, \dots, c_m \in F\}$$

Now by definition of summed spaces,

$$W_1 + W_2 = \{(a_1 v_1 + \dots + a_n v_n) + (c_1 u_1 + \dots + c_m u_m) \mid a_1, \dots, a_n, c_1, \dots, c_m \in F\} = \text{span}(\beta_1 \cup \beta_2)$$

is generated by a finite set  $\beta_1 \cup \beta_2$ . By theorem in textbook, we can reduce the generating set  $\{v_1, \dots, v_n, u_1, \dots, u_m\}$  to a basis, which can contain at most  $n + m$  vectors and is

henceforth finite.

(b) Take basis  $\beta_0 = \{t_1, \dots, t_r\}$  of  $W_1 \cap W_2$ ; extend  $\beta_0$  to a basis of  $W_1$  as  $\{t_1, \dots, t_r, v_{r+1}, \dots, v_n\}$  (note the dimension of  $W_1$  is still  $n$  as in the previous part), extend it similarly with  $W_2$  and get  $\{t_1, \dots, t_r, u_{r+1}, \dots, u_m\}$ . With the same notion in part (a), we get

$$W_1 + W_2 = \text{span}(\{t_1, \dots, t_r, v_{r+1}, \dots, v_n, u_{r+1}, \dots, u_m\})$$

Suppose  $a_1 t_1 + \dots + a_r t_r + b_{r+1} v_{r+1} + \dots + b_n v_n + c_{r+1} u_{r+1} + \dots + c_m u_m = 0$ , then

$$u = c_{r+1} u_{r+1} + \dots + c_m u_m = -(a_1 t_1 + \dots + a_r t_r) - (b_{r+1} v_{r+1} + \dots + b_n v_n) \in W_1 \cap W_2$$

Since  $t_1, \dots, t_r$  is a basis of  $W_1 \cap W_2$ , we can represent  $u = \alpha_1 t_1 + \dots + \alpha_r t_r$ , and

$$u = \alpha_1 t_1 + \dots + \alpha_r t_r = -(a_1 t_1 + \dots + a_r t_r) - (b_{r+1} v_{r+1} + \dots + b_n v_n)$$

Or  $(\alpha_1 + a_1)t_1 + \dots + (\alpha_r + a_r)t_r + b_{r+1}v_{r+1} + \dots + b_nv_n = 0$ . Since  $t_1, \dots, t_r, v_{r+1}, \dots, v_n$  is a basis of  $W_1$ , we must get  $b_{r+1} = \dots = b_n = 0$ . Similarly, we shall have  $c_{r+1} = \dots = c_m = 0$ . That is, we have

$$a_1 t_1 + \dots + a_r t_r = 0$$

and again since  $t_1, \dots, t_r$  is linearly independent, we have  $a_1 = \dots = a_r = 0$ . We just proved  $\{t_1, \dots, t_r, v_{r+1}, \dots, v_n, u_{r+1}, \dots, u_m\}$  is a linearly independent set. My proof to this part is a little tedious; perhaps the instructor will have a shorter proof.

(c) Consider  $V = \mathbb{R}^3$ ,  $W_1 = \{x\text{-}y \text{ plane}\} = \text{span} \left( \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right)$ ,  $W_2 = \{y\text{-}z \text{ plane}\} = \text{span} \left( \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right)$ . In this case,  $W_1 \cap W_2 = \{y\text{-axis}\} = \text{span} \left( \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right) \neq \{0\}$  and indeed  $W_1 + W_2 = \text{span} \left( \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right) = \mathbb{R}^3$ .

### Problem 5

(a) False.  $\begin{bmatrix} -1 \\ 1 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  is equivalent to solving  $\left[ \begin{array}{cc|c} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 1 & 0 \end{array} \right]$  (by elementary matrix operations), which is not solvable.

(b) True.

(c) False.  $\dim(\mathbb{R}^2) = 2$ ; there can't be a linearly independent subset of  $\mathbb{R}^2$  of more than 2 vectors.

(d) False. Consider 1-dimensional vector space  $V = \text{span}(v)$ ; every vector is a multiple of the other.

(e) False. It is an "affine space" of  $\mathbb{R}^4$ , but definitely not a subspace of  $\mathbb{R}^4$ . For instance,

it doesn't contain zero vector  $\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ .

(f) True.

(g) False. The inequality should be reversed. Linear independent subset should always contain less (or equal number of) vectors than spanning set.

(h) True.

(i) False. Consider  $S = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ , since

$$1 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 1 \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix} + (-1) \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

it's linearly dependent. However, the subset  $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \subseteq S$  is easily the basis of  $\mathbb{R}^2$  and linearly independent.