Stationarized System with Spillover

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April 2018

$$y_{c,t} = \Gamma_{c,t} k_{i,1,t}^{\gamma} h_{1,t}^{1-a-b} k_{c,1,t}^{a} k_{i,1,t}^{b} \tag{1}$$

$$y_{i,t} = \Gamma_{i,t} k_{i,2,t}^{\gamma} h_{2,t}^{1-a-b} k_{c,2,t}^{a} k_{i,2,t}^{b}$$
(2)

$$k_{c,t+1} \exp(g_c) = (1 - \delta_c)k_{c,t} + i_{c,t}$$
 (3)

$$k_{i,t+1} \exp(g_i) = (1 - \delta_i)k_{i,t} + i_{i,t}$$
 (4)

$$y_{c,t} = c_t + i_{c,t} \tag{5}$$

$$y_{i,t} = i_{i,t} \tag{6}$$

$$w_t = \chi c_t \tag{7}$$

$$k_{c,t} = k_{c,1,t} + k_{c,2,t} (8)$$

$$k_{i,t} = k_{i,1,t} + k_{i,2,t} (9)$$

$$h_t = h_{1,t} + h_{2,t} (10)$$

$$1 = \beta \mathbb{E} \left[(\exp(g_c))^{-1} \frac{c_t}{c_{t+1}} \left(r_{c,t+1} + 1 - \delta_c \right) \right]$$
 (11)

$$1 = \beta \mathbb{E} \left[(\exp(g_i))^{-1} \frac{c_t}{c_{t+1}} \left(\frac{r_{i,t+1}}{p_t} + 1 - \delta_i \right) \right]$$
 (12)

$$w_t = (1 - a - b)\Gamma_{c,t}k_{i,t}^{\gamma}h_{1,t}^{-a-b}k_{c,1,t}^ak_{i,1,t}^b$$
(13)

$$r_{c,t} = a\Gamma_{c,t}k_{i,t}^{\gamma}h_{1,t}^{1-a-b}k_{c,1,t}^{a-1}k_{i,1,t}^{b}$$
(14)

$$r_{i,t} = b\Gamma_{c,t}k_{i,t}^{\gamma}h_{1,t}^{1-a-b}k_{c,1,t}^{a}k_{i,1,t}^{b-1}$$
(15)

$$\frac{w_t}{p_t} = (1 - a - b)\Gamma_{i,t}k_{i,t}^{\gamma}h_{2,t}^{-a-b}k_{c,2,t}^ak_{i,2,t}^b$$
(16)

$$\frac{r_{c,t}}{p_t} = a\Gamma_{i,t}k_{i,t}^{\gamma}h_{2,t}^{1-a-b}k_{c,2,t}^{a-1}k_{i,2,t}^b$$
(17)

$$\frac{r_{i,t}}{p_t} = b\Gamma_{i,t}k_{i,t}^{\gamma}h_{2,t}^{1-a-b}k_{c,2,t}^ak_{i,2,t}^{b-1}$$
(18)