Numerical Methods for New Keynesian ZLB Models

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What is covered

- Equilibrium with a simple Taylor rule
- Tauchen's (1986) method for approximating AR(1) process
- Equilibrium under the optimal discretionary policy (Adam and Billi, 2007)

Two-state shock process

- Exogenous shocks take only $N_s = 2$ values, $s_t \in \{s_H, s_L\}$. The stochastic process follows a Markov chain with the transition matrix:

$$\begin{bmatrix} 1 - p_H & p_H \\ 1 - p_L & p_L \end{bmatrix}.$$

- p_H is the frequency of crisis and p_L is the duration of crisis.

Equilibrium with Taylor rule

- Equilibrium conditions are

$$
\begin{aligned}
y_t &= E_t y_{t+1} - (i_t - E_t \pi_{t+1} - s_t), \\
\pi_t &= \kappa y_t + \beta E_t \pi_{t+1}, \\
i_t^* &= r^* + \phi_\pi E_t \pi_{t+1},
\end{aligned}
$$

  and the zero lower bound

$$
i_t = \{0, i_t^*\}.
$$

Analytical solution

- The solution has a form of (we omit time subscripts for the policy function)

$$y = y(s), \quad \pi = \pi(s), \quad i = i(s).$$

- We know that the functions have only two values, i.e.,

$$y = \begin{cases} y_H, \\ y_L, \end{cases} \qquad \pi = \begin{cases} \pi_H, \\ \pi_L, \end{cases} \qquad i = \begin{cases} i_H, \\ i_L. \end{cases}$$

Analytical solution, cont'd

- We assume that $i_H > 0$ and $i_L = 0$. Then we have

$$
\begin{aligned}
y_H &= (1-p_H)y_H + p_H y_L - (i_H - [(1-p_H)\pi_H + p_H \pi_L] - s_H)\,, \\
\pi_H &= \kappa y_H + \beta\left[(1-p_H)\pi_H + p_H \pi_L\right], \\
i_H &= r^* + \phi_\pi\left[(1-p_H)\pi_H + p_H \pi_L\right], \\
y_L &= (1-p_L)y_H + p_L y_L - (0 - [(1-p_L)\pi_H + p_L \pi_L] - s_L)\,, \\
\pi_L &= \kappa y_L + \beta\left[(1-p_L)\pi_H + p_L \pi_L\right], \\
i_L &= 0.
\end{aligned}
$$

- There are 6 equations and 6 unknowns, so we can solve for the unknowns.

Numerical solution: Policy function iteration

- Consider the general case of $N_s \geq 2$. A guess of the policy functions

$$y = y^{(0)}(s), \quad \pi = \pi^{(0)}(s), \quad i = i^{(0)}(s).$$

- We know the values of the functions only at each *grid point*, e.g.,

$$\begin{aligned} y^{(0)}(s) &= [y_1, y_2, ..., y_{N_s}]', \\ \pi^{(0)}(s) &= [\pi_1, \pi_2, ..., \pi_{N_s}]', \\ i^{(0)}(s) &= [i_1, i_2, ..., i_{N_s}]'. \end{aligned}$$

Policy function iteration

- At each grid point $k = 1, ..., N_s$, we solve

$$
\begin{aligned}
y_k &= y^e - (i_k - \pi^e - s_k), \\
\pi_k &= \kappa y_k + \beta \pi^e, \\
i_k &= \max\{0, r^* + \phi_\pi \pi^e\},
\end{aligned}
$$

for (y_k, π_k, i_k), where

$$
\begin{aligned}
y^e &= \sum_{l=1}^{N_s} p(k,l) y^{(0)}(s_l), \\
\pi^e &= \sum_{l=1}^{N_s} p(k,l) \pi^{(0)}(s_l).
\end{aligned}
$$

and $p(k,l)$ is the (k,l) element of the transition matrix.

Policy function iteration

- Once this is done for all the grid points, we update

$$y^{(1)}(s) = [y_1, y_2, ..., y_N]',$$
$$\pi^{(1)}(s) = [\pi_1, \pi_2, ..., \pi_N]',$$
$$i^{(1)}(s) = [i_1, i_2, ..., i_N]'.$$

- We repeat the procedure until the policy functions converge, i.e., $\left\| x^{(j)}(s) - x^{(j-1)}(s) \right\| < \epsilon$ for $x \in \{y, \pi, i\}$.

Tauchen's method

- Tauchen (1986) developed a method for approximating AR(1) process by using Markov chain.
- TBD

Optimal Discretionary Policy

- The policymaker chooses $\{\pi_t, y_t, i_t\}$ so as to maximize

$$V_0 \equiv -E_0 \sum_{t=0}^{\infty} \beta^t \left(\pi_t^2 + \lambda y_t^2\right)$$

subject to

$$\begin{aligned} y_t &= E_t y_{t+1} - (i_t - E_t \pi_{t+1}) + g_t, \\ \pi_t &= \kappa y_t + \beta E_t \pi_{t+1} + u_t, \\ i_t &\geq 0, \end{aligned}$$

taking $E_t y_{t+1}$ and $E_t \pi_{t+1}$ as given.

Optimal Discretionary Policy

- Exogenous shocks are given by

$$g_t = (1-\rho_g)g + \rho_g g_{t-1} + \varepsilon_{g,t},$$
$$u_t = \rho_u u_{t-1} + \varepsilon_{u,t},$$

  where $\varepsilon_{g,t} \sim N(0, \sigma_g^2)$ and $\varepsilon_{u,t} \sim N(0, \sigma_u^2)$.

- Note that $g = r^*$.

Optimal Discretionary Policy

- We know that Markov-perfect equilibrium has only natural state variables.
- Lagrangean is

$$\mathcal{L} \equiv E_0 \sum \beta^t \left(\pi_t^2 + \lambda y_t^2\right) + 2\phi_{PC,t}\left(-\pi_t + \kappa y_t + \beta E_t \pi_{t+1} + u_t\right)$$
$$+ 2\phi_{EE,t}\left(-y_t - i_t + E_t y_{t+1} + E_t \pi_{t+1} + g_t\right) + 2\phi_{ZLB,t} i_t.$$

- First-order necessary conditions are

$$\begin{aligned}
\partial \pi_t &: \pi_t - \phi_{PC,t} = 0, \\
\partial y_t &: \lambda y_t + \kappa \phi_{PC,t} - \phi_{EE,t} = 0, \\
\partial i_t &: -\phi_{EE,t} + \phi_{ZLB,t} = 0.
\end{aligned}$$

Optimal Discretionary Policy

- Complementary slackness condition:

$$\phi_{ZLB,t} > 0 \perp i_t > 0.$$

- When $i_t > 0$, $\phi_{ZLB,t} = 0$. Equilibrium conitions are

$$\begin{aligned} i_t &= -y_t + E_t y_{t+1} + E_t \pi_{t+1} + g_t, \\ \pi_t &= \kappa y_t + \beta E_t \pi_{t+1} + u_t, \\ 0 &= \lambda y_t + \kappa \pi_t. \end{aligned}$$

- When $i_t = 0$, $\phi_{ZLB,t} > 0$. Equilibrium conitions are

$$\begin{aligned} 0 &= -y_t + E_t y_{t+1} + E_t \pi_{t+1} + g_t, \\ \pi_t &= \kappa y_t + \beta E_t \pi_{t+1} + u_t, \\ \phi_{ZLB,t} &= \lambda y_t + \kappa \pi_t. \end{aligned}$$

Analytical solution

- The solution has a form of

$$y = y(g, u), \quad \pi = \pi(g, u), \quad i = i(g, u).$$

- Now consider the case in which there are only two-state g shocks. We know that the functions have only two values, i.e.,

$$y = \begin{cases} y_H, \\ y_L, \end{cases} \qquad \pi = \begin{cases} \pi_H, \\ \pi_L, \end{cases} \qquad i = \begin{cases} i_H, \\ i_L. \end{cases}$$

Analytical solution

- We assume that $i_H > 0$ and $i_L = 0$. Then we have

$$
\begin{aligned}
y_H &= (1-p_H)y_H + p_H y_L - (i_H - [(1-p_H)\pi_H + p_H \pi_L]) + g_H, \\
\pi_H &= \kappa y_H + \beta \left[(1-p_H)\pi_H + p_H \pi_L\right], \\
0 &= \lambda y_H + \kappa \pi_H, \\
y_L &= (1-p_L)y_H + p_L y_L - (0 - [(1-p_L)\pi_H + p_L \pi_L]) + g_L, \\
\pi_L &= \kappa y_L + \beta \left[(1-p_L)\pi_H + p_L \pi_L\right], \\
\phi_L &= \lambda y_L + \kappa \pi_L.
\end{aligned}
$$

- There are 6 equations and 6 unknowns, so we can solve for the unknowns.

Numerical solution: Joint shock process

- Let's get back to the general case. The shock processes are appoximated by Markov chains. That is,

$$g_m \in [g_1, g_2, ..., g_{N_g}],$$
$$u_n \in [u_1, u_2, ..., u_{N_u}],$$

and

$$P^g = \begin{bmatrix} p^g_{11} & \cdots & \cdots & p^g_{1N_g} \\ p^g_{21} & \ddots & & \vdots \\ \vdots & & \ddots & \vdots \\ p^g_{N_g 1} & \cdots & \cdots & p^g_{N_g N_g} \end{bmatrix}, \quad P^u = \begin{bmatrix} p^u_{11} & \cdots & \cdots & p^u_{1N_g} \\ p^u_{21} & \ddots & & \vdots \\ \vdots & & \ddots & \vdots \\ p^u_{N_g 1} & \cdots & \cdots & p^u_{N_g N_g} \end{bmatrix}.$$

Joint shock process

- A kronecker product $s = g \otimes u$ represents the joint shock process.
  - For example, when $N_g = N_u = 2$

$$
\begin{aligned}
s_1 &= (g_1, u_1), \\
s_2 &= (g_1, u_2), \\
s_3 &= (g_2, u_1), \\
s_4 &= (g_2, u_2).
\end{aligned}
$$

  - Note that each index points to a pair of shocks, $s_k = (g_{m(k)}, u_{n(k)})$.
- A kronecker product of the transition matrices $P^s = P^g \otimes P^u$ is the transition matrix of the joint shock process.

Numerical solution: Policy function iteration

- A guess of the policy functions

$$y = y^{(0)}(s), \quad \pi = \pi^{(0)}(s), \quad i = i^{(0)}(s).$$

- We know the values of the functions only at each *grid point*, e.g.,

$$\begin{aligned} y^{(0)}(s) &= [y_1, y_2, ..., y_N]', \\ \pi^{(0)}(s) &= [\pi_1, \pi_2, ..., \pi_N]', \\ i^{(0)}(s) &= [i_1, i_2, ..., i_N]'. \end{aligned}$$

Policy function iteration

- At each grid point $k = 1, ..., N$, we solve

$$
\begin{aligned}
i_k &= -y_k + y^e + \pi^e + g_{m(k)}, \\
\pi_k &= \kappa y_k + \beta \pi^e + u_{n(k)}, \\
0 &= \lambda y_k + \kappa \pi_k,
\end{aligned}
$$

for (y_k, π_k, i_k), where

$$
\begin{aligned}
y^e &= \sum_{l=1}^{N_s} P^s(k,l) y^{(0)}(s_l), \\
\pi^e &= \sum_{l=1}^{N_s} P^s(k,l) \pi^{(0)}(s_l).
\end{aligned}
$$

Policy function iteration

- Check $i_k \geq 0$. If not, we solve instead

$$0 = -y_k + y^e + \pi^e + g_{m(k)},$$
$$\pi_k = \kappa y_k + \beta \pi^e + u_{n(k)},$$

for (y_k, π_k), and set $i_k = 0$.

Policy function iteration

- Once this is done for all the grid points, we update

$$y^{(1)}(s) = [y_1, y_2, ..., y_N]',$$
$$\pi^{(1)}(s) = [\pi_1, \pi_2, ..., \pi_N]',$$
$$i^{(1)}(s) = [i_1, i_2, ..., i_N]'.$$

- We repeat the procedure until the policy functions converge, i.e., $\left\| x^{(j)}(s) - x^{(j-1)}(s) \right\| < \epsilon$ for $x \in \{y, \pi, i\}$.