

# ECOM027 – Research Methods

Methods and tools for Empirical Macroeconomics

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# Introduction

The goal of applied macroeconomics is to design models useful for policy analysis and forecasting.

The main methods are:

- Time series econometrics, e.g. Vector Autoregressions (VAR)
- Dynamic stochastic general equilibrium (DSGE) models, e.g. Real Business Cycles (RBC) and New Keynesian (NK) models

Today:

- Vector Autoregression (VAR) and Structural Vector Autoregression (SVAR) models
- VAR toolbox in MATLAB

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## Trend and cycles

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# Trend and cycles

Most macroeconomic time series exhibit a trend.

For instance, Gross Domestic Product (GDP):

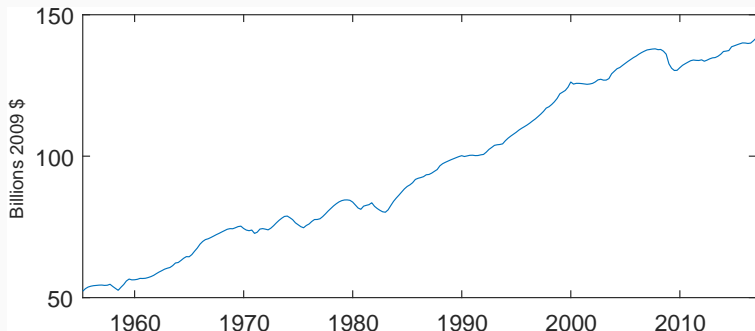


Figure 1: Real GDP per capita.

In applied macro, we are often interested in **cyclical fluctuations** of GDP.

To obtain the cyclical component of the time series we have two options:

- Estimate and remove the time trend.
- Filter out the lower frequency components.

We assume that the variable of interest grows linearly with time:

$$y_t = c + \delta t + \varepsilon_t$$

**Steps:**

1. Estimate the  $\delta$  coefficient to get the trend.
2. Remove the trend component to obtain the cycle.

# Log-linear trend

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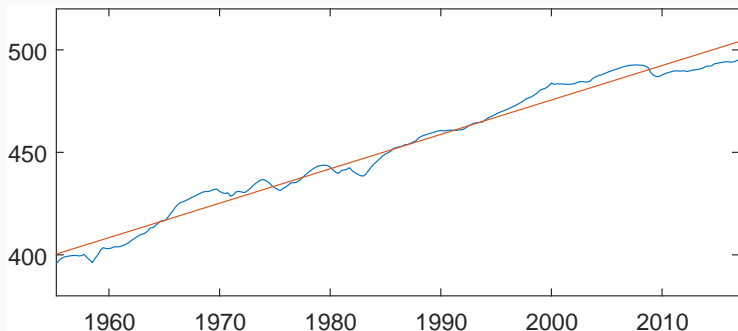


Figure 2: Log real GDP per capita with linear trend.



# Log-linear trend

2. Remove the trend component to obtain the cycle:

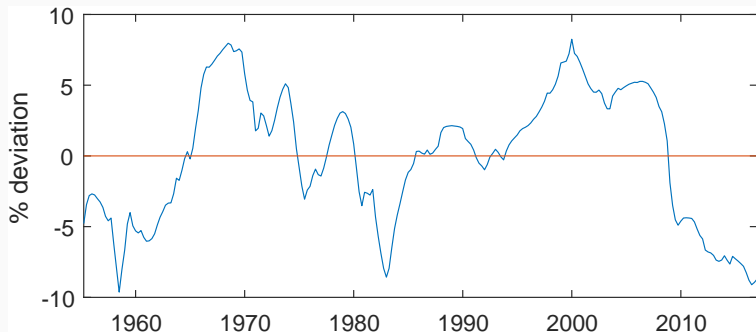


Figure 3: % deviations of GDP per capita around linear trend.

The time series moves at different frequencies, higher frequencies and lower frequencies.

We use the **Hodrick–Prescott** filter to separate the higher and lower frequencies of the time series

## Steps:

1. Use the Hodrick–Prescott filter to obtain the "slow moving" component.
2. Remove the lower frequency to get the cycle.

# Filtering

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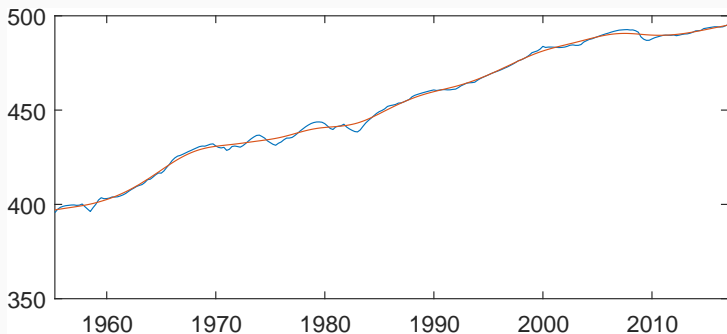


Figure 4: Log real GDP per capita with HP filtered trend.

2. Remove the lower frequency to get the cycle:

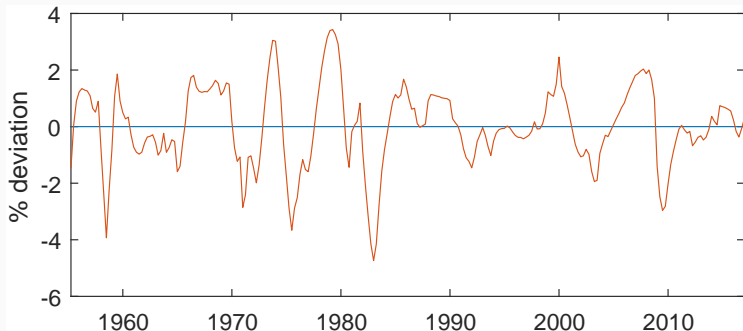


Figure 5: HP filtered real GDP per capita.

# Comparison: Linear trend vs HP filter

Both approaches can successfully identify recessions:

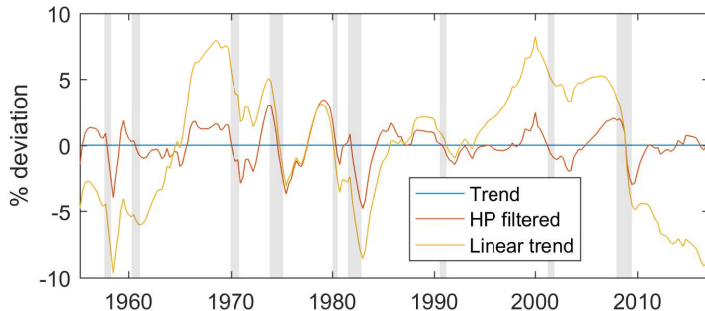


Figure 6: Linear de-trended vs HP filtered with NBER recessions.

# Vector Autoregression models

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Vector Autoregressions are the multivariate equivalent of an Autoregressive (AR) process.

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Recall an AR process of order one (AR1). This process is a sequence  $\{y_t\}_{t=0}^{\infty}$  defined by:

$$y_t = \rho y_{t-1} + e_t \tag{1}$$

where:

- Initial value  $y_0$  is known
- $e_t$  is an *i.i.d.* innovation that follows  $e_t \sim \mathcal{N}(0, \sigma_e^2)$



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**Stability condition:**  $|\rho| < 1$

# Vector Autoregressions (VARs)

A VAR is a model with  $n$  variables with  $k$  lags.

Example: **two** variables  $\{y_1, y_2\}$ , **one** lag

$$y_{1,t} = \phi_{11}y_{1,t-1} + \phi_{12}y_{2,t-1} + e_{1,t}$$

$$y_{2,t} = \phi_{21}y_{1,t-1} + \phi_{22}y_{2,t-1} + e_{2,t}$$

Group elements as follows

$$Y_t = \begin{pmatrix} y_{1,t} \\ y_{2,t} \end{pmatrix} \quad \Phi = \begin{pmatrix} \phi_{11} & \phi_{12} \\ \phi_{21} & \phi_{22} \end{pmatrix} \quad e_t = \begin{pmatrix} e_{1,t} \\ e_{2,t} \end{pmatrix}$$

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# Vector Autoregressions (VARs)

VAR models of this form

$$Y_t = \Phi Y_{t-1} + e_t \quad (3)$$

are often referred to as *reduced-form* models:

- Parameters  $\Phi$  do not have any intrinsic economic meaning.
- Innovations  $e_t$  do not have an economic or *structural* interpretation.

Reduced-form models are useful for forecasting:

- **One-period** ahead:  $\mathbb{E}_t[Y_{t+1}] = \Phi \mathbb{E}_t[Y_t] + \mathbb{E}_t[e_{t+1}] = \Phi Y_t$
- **Two-periods** ahead:  $\mathbb{E}_t[Y_{t+2}] = \Phi \mathbb{E}_t[Y_{t+1}] = \Phi \Phi Y_t$
- **$k$ -periods** ahead:  $\mathbb{E}_t[Y_{t+k}] = \Phi \cdots \Phi Y_t = \Phi^k Y_t$

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## Identification and causality

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VAR models are useful to predict the **dynamic** response of a set of macroeconomic variables to a **sudden** change in one of the variables.

Thus, we compute **Impulse Responses Functions** (IRFs):

1. The innovation  $e_{1,t}$  increases by one percent in period,  $t = 1$ .
2. The variable  $y_{1,t}$  immediately responds in the first period,  $t = 1$ .
3. Variables  $y_{1,t}$  and  $y_{2,t}$  respond in the subsequent periods,  $t > 1$ .



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This gives us a clear picture of the dynamic response of variables ...

... but what **caused** the innovation  $e_{1,t}$  to jump in the first place?

# Structural shocks and contemporaneous responses

If we want some economic insight on the response of variables, we need to identify **structural** shocks  $\varepsilon_{i,t}$ .

- A structural shock  $\varepsilon_{i,t}$  is likely to impact more than one variable  $y_{i,t}$  **contemporaneously!**
- The effect of the shock will show up in the residuals  $e_{i,t}$  but we cannot say if this is coming from  $\varepsilon_{1,t}$  or  $\varepsilon_{2,t}$

This is why movements in the residuals  $e_{i,t}$  are without economic meaning:

- A movement in  $e_{1,t}$  is not necessarily due to a shock to the  $y_{1,t}$  variable
- It might be the contemporaneous by-product of a shock to  $y_{2,t}$  or to both variables  $y_{1,t}$  and  $y_{2,t}$

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# Structural Vector Autoregressions (SVARs)

The standard VAR does not allow for contemporaneous interactions. SVARs augment VARs model by introducing them.

Model becomes:

$$\begin{aligned}y_{1,t} &= a_{12}y_{2,t} + b_{11}y_{1,t-1} + b_{12}y_{2,t-1} + c_1\varepsilon_{1,t} \\y_{2,t} &= a_{21}y_{1,t} + b_{21}y_{1,t-1} + b_{22}y_{2,t-1} + c_2\varepsilon_{2,t}\end{aligned}$$

which can be written as

$$AY_t = BY_{t-1} + C\varepsilon_t \quad (4)$$

where

$$A = \begin{pmatrix} 1 & -a_{12} \\ -a_{21} & 1 \end{pmatrix}, C = \begin{pmatrix} c_1 & 0 \\ 0 & c_2 \end{pmatrix}$$

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# SVARs: reduced form and identification problems

Note the SVAR can be written in reduced-form:

$$Y_t = \Phi Y_{t-1} + e_t \quad (5)$$

where

$$\Phi = A^{-1}B \quad (6)$$

$$e_t = A^{-1}C\varepsilon_t \quad (7)$$

No problem estimating  $\Phi$  from (5), but impossible to disentangle (6) and (7) to recover estimates *structural matrices*  $A$ ,  $B$  and  $C$ .

In words, you cannot tell if a movement in  $Y_t$  is caused by  $\varepsilon_{1,t}$  or  $\varepsilon_{2,t}$  because what you "observe" is only a movement in  $e_t$ .

Therefore, we must impose further structure to fully identify the model.



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# Identification of SVARs

Common (and easiest) approach is to assume a *recursive* structure:

- $y_{1,t}$  only affected by  $\varepsilon_{1,t}$ ,
- $y_{2,t}$  only affected by  $\varepsilon_{1,t}$  and  $\varepsilon_{2,t}$ ,
- $y_{3,t}$  only affected by  $\varepsilon_{1,t}$ ,  $\varepsilon_{2,t}$  and  $\varepsilon_{3,t}$ ,
- And so on.

This translates into saying that the **last** variable can be contemporaneously influenced by **all** variables, while the **first** one only by **itself**.

Usually this is justified by assuming that some variables move faster than others.

## Example

Structural VAR with three variables:

$$Y_t = \begin{pmatrix} \Pi_t \\ GDP_t \\ FFR_t \end{pmatrix} = \begin{pmatrix} inflation_t \\ output_t \\ policyrate_t \end{pmatrix} \quad (8)$$

and four lags. Thus model is:

$$AY_t = \sum_{s=1}^4 B_s Y_{t-s} + C\varepsilon_t \quad (9)$$

where the imposed form of the structural matrix  $A$  is:

$$A = \begin{bmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \quad (10)$$

## Example

The restrictions on the structural matrix  $A$  and the ordering of the variables

$$Y_t = \begin{pmatrix} \Pi_t \\ GDP_t \\ FFR_t \end{pmatrix}, \quad A = \begin{bmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \quad (8), (10)$$

imply that:

- The policy rate ( $FFR_t$ ) responds to contemporaneous changes to other variables
- Output ( $GDP_t$ ) responds current inflation but not interest rate
- Inflation ( $\Pi_t$ ) is **not** contemporaneously affected by  $GDP_t$  or  $FFR_t$  and only responds to these variables with a lag

## Example: practical implementation

We use a **VAR toolbox** designed by **Ambrogio Cesa-Bianchi**.

The Live Script `SVAR_demo.mlx`:

1. Downloads data from Federal Reserve data server (FRED)
2. Cleans raw data and creates final time-series for estimation
3. Estimates the model parameters of the reduced-form VAR
4. Applies a recursive identification scheme (short-run restriction) via a Cholesky decomposition
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You can have access to the material in many ways.

## Replication codes and slides:

1. Direct download ([zip version](#))
2. Github  repository ([view](#))
3. If you are a **git** user, clone the repository with

```
git clone --recurse-submodules https://github.com/LRondina/SVARs-Intro
```

Official version of the toolkit: [VAR Toolbox 2.0](#)

Data: <https://fred.stlouisfed.org/>

# Applications and Further Reading

Example questions:

- What is the response of output to monetary policy shock?
- What is the response of labour supply to a productivity shock?
- How do oil price shocks affect U.K. economy?

Some further reading:

- "Vector autoregressions" by Stock J. H., Watson M. W., *Journal of Economic Perspectives* (2001)
- "Macroeconomic Shocks and Their Propagation" by Ramey V. A., *Handbook of Macroeconomics Vol 2*, (2016)
- "Identification in Macroeconomics" by Nakamura E., Steinsson J., *Journal of Economic Perspectives* (2018)