# ECON 6130 - Problem Set # 2

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### December 1, 2017

### Part (a)

Note that the equations for the New Keynesian business cycle can be listed as follows

$$\pi_{t} - \beta \mathbb{E}_{t}(\pi_{t+1}) - \kappa \tilde{y}_{t} = 0$$

$$\tilde{y}_{t} - \mathbb{E}_{t}(\tilde{y}_{t+1}) + \frac{1}{\sigma}[(i_{t} - \rho) - \mathbb{E}_{t}(\pi_{t+1}) - (r_{t}^{n} - \rho)] = 0$$

$$(i_{t} - \rho) - \phi_{\pi}\pi_{t} - \phi_{y}\tilde{y}_{t} - \phi_{y}\psi_{ya}a_{t} - v_{t} = 0$$

$$(r_{t}^{n} - \rho) + \sigma(1 - \rho_{a})\psi_{ya}a_{t} - (1 - \rho_{z})z_{t} = 0$$

$$v_{t} = \rho_{v}v_{t-1} + \epsilon_{t}^{v}$$

$$a_{t} = \rho_{a}a_{t-1} + \epsilon_{t}^{a}$$

$$z_{t} = \rho_{z}z_{t-1} + \epsilon_{t}^{z}$$

$$\tilde{y}_{t} = \mathbb{E}_{t-1}(\tilde{y}_{t}) + \eta_{t}^{\tilde{y}_{t}}$$

$$\pi_{t} = \mathbb{E}_{t-1}(\pi_{t}) + \eta_{t}^{\tilde{n}}$$

where  $\eta_t$  are the forecast errors.

Thus, we define the following state space for our model

$$S_{t} = [\tilde{y}_{t}, \pi_{t}, r_{t}^{n} - \rho, i_{t} - \rho, v_{t}, a_{t}, z_{t}, \mathbb{E}_{t}(\tilde{y}_{t+1}), \mathbb{E}_{t}(\pi_{t+1})]$$

Note that the gensys.m code solves the following linear equation

$$\Gamma_0 S_t = \Gamma_1 S_{t-1} + B + \Psi \epsilon_t + \Pi \eta_t$$

where  $E(\epsilon_t \epsilon_t') = I$ .

Therefore, by rewriting the set of equations for the New Keynesian business cycle in

matrix form, we get

Then the gensys.m will out the coefficients of an VAR(1) process of the following form

$$S_t = AS_{t-1} + C\epsilon_t$$

where  $\epsilon_t \sim N(0, I)$ .

Given the parameters of set in the problem set, we have

# Part (b)

The impulse responses for inflation, output, output gap, interest rates and labor in responses to productivity, monetary policy and demand shocks are plotted in Fig.1, Fig.2 and Fig.3. Note that the impulses responses are consistent with the results shown in class.

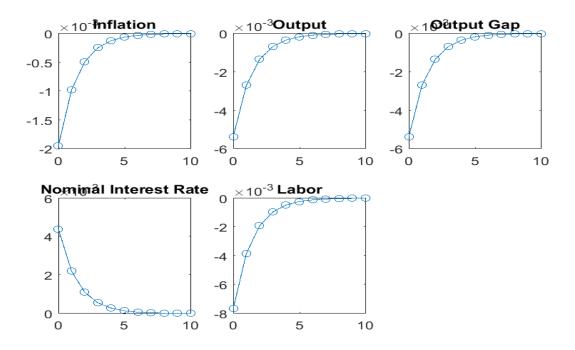


Figure 1: Impulse response to monetary shocks

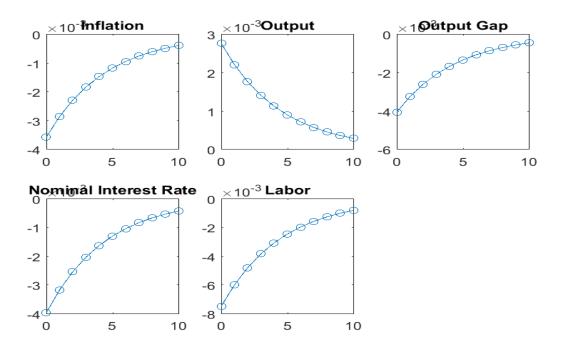


Figure 2: Impulse response to productivity shocks

Figure 3: Impulse response to demand shocks

# Part (c)

Note that the nominal interest rates and inflation are included in our states  $S_t$ . As for output, we need to compute it using the following formula

$$\hat{y}_t = y_t - y$$

$$= (y_t - y_t^n) + (y_t^n - y)$$

$$= \tilde{y}_t + \hat{y}_t^n$$

$$= \tilde{y}_t + \psi_{ya} a_t$$

where  $y^n$ , y,  $\psi_{ya}$  and  $a_t$  are defined as in Gali's book.

Then, we can write inflation, output and nominal interest rates in the following matrix form

$$Z(t) = DX(t)$$

where

$$D = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & \psi_{ya} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The simulated inflation, output and nominal interest rates are plotted in Fig.4. The standard deviations are reported in part (d) and Tab.1.

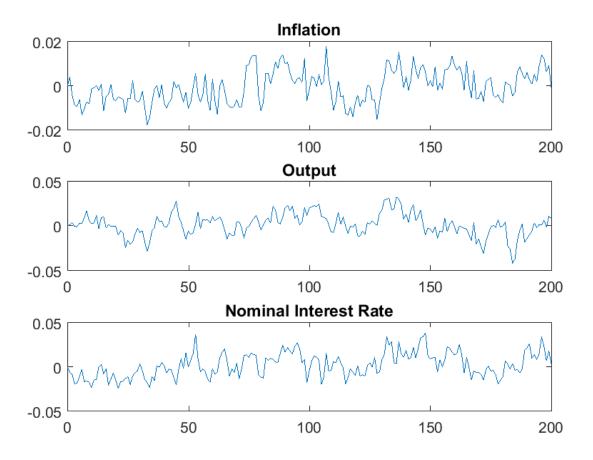


Figure 4: Simulation of New Keynesian business cycle model

# Part (d)

We use the following FRED series for our data:

- (i) Consumer Price Index of All Items in United States (USACPIALLQINMEI)
- (ii) Real Gross Domestic Product (GDPC1)
- (iii) Immediate Rates: Less than 24 Hours: Federal Funds Rate for the United States (IRSTFR01USQ156N)

Note that to compare the data to our model with need to log-linearized the series and detrend them using the Hodrick-Prescott filter. While the correspondence with the model states for GDP and the Federal Funds Rate is straightforward, it is important to note that the Consumer Price Index represents are price level. Therefore, after taking the log of the CPI, it is important to differentiate it before detrending it since

$$\pi_t = \log(P_t) - \log(P_{t-1})$$

where  $P_t$  is the price level (CPI) at time t.

The sample inflation, output and nominal interest rates are plotted in Fig.4. The standard deviations are reported in Tab.1.

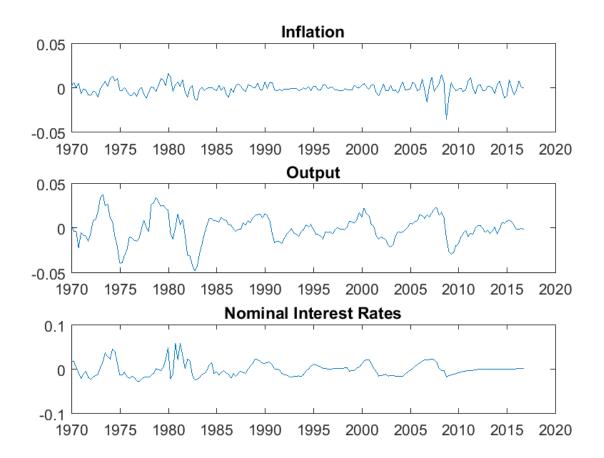


Figure 5: FRED Detrended Data

Note that the values for  $\sigma$  for our simulation somewhat matches the data. This might imply reasonable parameters values for our model.

	Simulation	Data
$\sigma_{\pi}$	0.0070	0.0060
$\sigma_y$	0.0113	0.0150
$\sigma_{i}$	0.0147	0.0154

Table 1: Standard deviation of inflation, output and interest rate

# Part (e)

Note that we can write our model in the following state space form

Then, we can write inflation, output and nominal interest rates in the following matrix form

$$S_t = AS_{t-1} + C\epsilon_t$$
$$Z(t) = DX(t)$$

where A and C are defined as previously,  $\epsilon_t \sim N(0, I)$ , and

$$D = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & \psi_{ya} & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Using the Kalman filter code from the last problem set we can compute  $S_t$ . In Fig.6, we report both the output and the output gap.

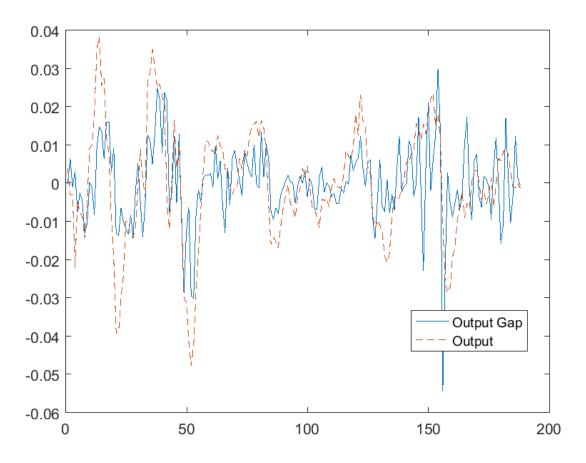


Figure 6: Kalman Filter estimate of output and output gap

As seen in Fig.6, the output gap follows output closely. This implies that  $y_t^n - y$  is fairly close to 0 for all t. Is it reasonable? It seems unlikely that the natural level of output should always be close to the trend as we expect shocks in productivity to push  $y_t^n$ .

### Code

```
1 % Housekeeping
2 close all;
  clear all;
  % Code based on Tilahun's code for NKBC model.
  %% Part (a)
  % Calibration
  sigma
             = 2; % CRRA parameter.
             = 0.99; % discount factor
  beta
             = 3; % inverse of elasticity of labor supply
  phi
             = 5; % elasticity of substitution between goods i and j
  eps
             = 1.5; % taylor rule parameter
  phi_pi
  phi_y
             = 0.5; % taylor rule parameter
  theta
             = 0.75; % degree of price stickiness
  alpha
             = 0.3; % production function parameter
15
  rho_a
             = 0.8; % persistence parameter
             = 0.5; % persistence parameter
  rho_v
             = 0.7; % persistence parameter
  rho_z
             = 0.008; % standard deviation
  sigma_a
19
             = 0.01; % standard deviation
  sigma_v
20
  sigma_z
             = 0.03; % standard deviation
21
22
  % Compute the coefficients
  rho = -log(beta);
  lambda = (1-theta)*(1-beta*theta)*(1-alpha)/(theta*(1-alpha+alpha*theta)
     eps));
  kappa = lambda*(sigma + (phi+alpha)/(1-alpha));
  psi_ya = (1+phi)/(sigma*(1-alpha)+phi+alpha);
28
  % State: 'y'; 'pi'; 'r^n'; 'i'; 'v'; 'a'; 'z'; 'E(y)'; 'E(pi)'
  Gamma0 = [-kappa \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ -beta;]
30
       1 \ 0 \ -1/sigma \ 1/sigma \ 0 \ 0 \ 0 \ -1 \ -1/sigma;
31
      -phi_y -phi_pi 0 1 -1 -phi_v*psi_va 0 0 0;
32
       0 \ 0 \ 1 \ 0 \ sigma*(1-rho_a)*psi_ya -(1-rho_z) \ 0 \ 0;
33
       0 0 0 0 1 0 0 0 0;
34
       0 0 0 0 0 1 0 0 0;
35
       0 0 0 0 0 0 1 0 0;
36
       1 0 0 0 0 0 0 0 0;
37
       0\ 1\ 0\ 0\ 0\ 0\ 0\ 0];
38
39
  Gamma1 = [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0];
40
       0 0 0 0 0 0 0 0 0;
41
```

```
0 0 0 0 0 0 0 0 0;
42
       0 0 0 0 0 0 0 0 0;
43
       0 0 0 0 rho_v 0 0 0 0;
44
       0 0 0 0 0 rho_a 0 0 0;
45
       0 0 0 0 0 0 rho_z 0 0;
       0 0 0 0 0 0 0 1 0;
47
       0 0 0 0 0 0 0 0 1];
48
49
  Psi
          = [0 \ 0 \ 0 \ 0 \ sigma_v \ 0 \ 0 \ 0;
50
       0 0 0 0 0 sigma_a 0 0 0;
51
       0 0 0 0 0 0 sigma_z 0 0;]';
52
53
          = [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 \ 0;
  Ρi
54
       0 0 0 0 0 0 0 0 1];
55
56
          = [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0];
  Cons
57
58
  % Solve New Keynesian Model
59
   [A, ~, C] = gensys (Gamma0, Gamma1, Cons, Psi, Pi);
60
  % Part (b)
62
  % Set up measurement matrix Z(t)=D*S(t)
  D = [0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0]; % inflation
64
       1 0 0 0 0 psi_ya 0 0 0; % output
       1\ 0\ 0\ 0\ 0\ 0\ 0\ 0;\ \%\ {\rm output\ gap}
66
       0 0 0 1 0 0 0 0; % nominal interest rate
67
       1/(1-alpha) 0 0 0 0 (psi_ya-1)/(1-alpha) 0 0 0]; % labor
68
69
  % Compute impulse responses
70
  time = 0:10;
                  % set time horizon
71
   col = C;
                % start impulse matrix
72
   for j=1:size (time, 2)
73
       resp(:,:,j)=D*col; % compute observations
74
       col=A*col; % compute next period states
75
  end
76
77
   for i = 1:3
78
       % Extract impulse responses for observations
79
       resp_pi(:, i) = squeeze(resp(1, i, :));
       resp_y(:, i) = squeeze(resp(2, i, :));
81
       resp_yg(:, i) = squeeze(resp(3, i, :));
       resp_i(:, i) = squeeze(resp(4, i, :));
83
       resp_n(:, i) = squeeze(resp(5, i, :));
85
       % Plot Impulse Responses
86
```

```
figure (i)
87
        subplot (2, 3, 1)
88
        plot (time, resp_pi(:,i), '-O')
89
         title ('Inflation')
90
        subplot (2, 3, 2)
91
        plot (time, resp_y (:, i), '-O')
92
         title ('Output')
93
        subplot (2, 3, 3)
94
        \operatorname{plot}\left(\operatorname{time},\operatorname{resp}_{-}\operatorname{yg}\left(:,i\right),'-O'\right)
95
         title ('Output Gap')
96
        subplot (2, 3, 4)
97
        plot (time, resp_i(:, i), '-O')
98
         title ('Nominal Interest Rate')
99
        subplot (2, 3, 5)
100
        plot (time, resp_n (:, i), '-O')
101
         title ('Labor')
102
   end
103
104
   % Print Impulse Responses - Monetary Shock
105
   figure (1)
   saveas(gcf, 'impulse_monetary.png')
107
   % Print Impulse Responses - Productivity Shock
   figure (2)
109
   saveas(gcf, 'impulse_prod.png')
   % Print Impulse Responses - Demand Shock
   figure (3)
112
   saveas(gcf, 'impulse_demand.png')
113
114
   % Part (c)
   % State space model:
   \% X(t) = A*X(t-1) + C*eps(t)
   \% Z(t) = D*X(t)
118
119
   % Set up measurement matrix Z(t) = D*X(t)
120
   D = [0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0;
        1 0 0 0 0 psi_ya 0 0 0;
122
        0 0 0 1 0 0 0 0 0];
123
124
                       % set time horizon
   time = 0:200;
   X(:,1) = zeros(9,1); % starting value for states
126
127
   error = randn(3, size(time, 2)); % generate epsilon
128
129
   % Compute state space model recursively
   for t=1: size (time, 2)-1
131
```

```
X(:,t+1)=A*X(:,t)+C*error(:,t+1); \% X(t+1) = A*X(t) + C*eps(t)
132
           +1)
                                 \% Z(t+1) = D*X(t+1)
       Z(:, t+1) = D*X(:, t+1);
133
   end
134
135
   % Compute model standard deviations
136
   sig_model = sqrt(var(Z'))
137
138
   % Plot simulated state space model
139
   figure (4)
140
   subplot (3,1,1)
141
   plot(time, Z(1,:))
142
   title ('Inflation')
143
   subplot (3,1,2)
144
   plot (time, Z(2,:))
145
   title ('Output')
   subplot (3,1,3)
147
   plot (time, Z(3,:))
148
   title ('Nominal Interest Rate')
149
   saveas (gcf, 'simulation.png')
150
151
   % Part (d)
152
   % Set handle for FRED data
153
   url = 'https://fred.stlouisfed.org/';
   c = fred(url);
155
156
   % Set dates for sample period
157
   startdate = '01/01/1970';
   enddate = '12/01/2016';
159
160
   CPI = fetch (c, 'USACPIALLQINMEI', '09/01/1969', enddate); % fetch CPI
161
       from FRED
   GDP = fetch(c, 'GDPC1', startdate, enddate); % fetch GDP from FRED
   INT = fetch (c, 'IRSTFR01USQ156N', startdate, enddate); % fetch rate
163
      from FRED
164
   pi_data = diff(log(CPI.Data(:,2))); \% log[price(t)] - log[price(t)]
165
      -1)
   gdp_data = log(GDP, Data(:,2)); \% log of GDP
166
   i_data = log(1+INT.Data(:,2)/100); \% log of nominal interest rate
167
168
   [~, pi_data] = hpfilter(pi_data,1600); % extract cyclical
169
      component of pi
   [~, gdp_data] = hpfilter(gdp_data,1600); % extract cyclical
      component of y
```

```
[~,i_data] = hpfilter(i_data,1600); % extract cyclical component
      of i
172
   % Combine data
173
   Z=[pi_data'; gdp_data'; i_data'];
175
   % Compute model standard deviations
176
   sig_data = sqrt(var(Z'))
177
178
   % Plot FRED detrended data
179
   figure (5)
180
   subplot (3,1,1)
181
   plot(INT.Data(:,1),Z(1,:))
   datetick ('x', 'yyyy')
183
   title ('Inflation')
184
   subplot (3,1,2)
185
   plot(INT.Data(:,1),Z(2,:))
186
   datetick ('x', 'yyyy')
187
   title ('Output')
188
   subplot (3,1,3)
   plot (INT. Data (:,1), Z(3,:))
190
   datetick ('x', 'yyyy')
   title ('Nominal Interest Rates')
192
   saveas (gcf, 'data.png')
194
   % Part (e)
195
   % State space model:
   \% X(t) = A*X(t-1) + C*eps(t)
   \% Z(t) = D*X(t)
198
199
   % Set up measurement matrix Z(t) = D*X(t)
200
   D = [0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0;
201
       1 0 0 0 0 psi_ya 0 0 0;
202
       0 0 0 1 0 0 0 0 0];
203
204
   % Set starting values
   X0 = zeros(9.1);
                         % set starting X
   P0 = dlyap(A,C*C'); % set starting for the variance
207
   % Compute the Kalman Filter
209
   [X_{post}, P_{post}, X_{prior}, P_{prior}, K] = kfilter(Z, A, C, D, 0, X0)
      , P0 );
211
  % Plot output and output gap
  figure (6)
213
```

```
\operatorname{plot}\left(\mathbf{X}_{\operatorname{-}}\operatorname{post}\left(1,:\right)\right)
   hold
215
   plot (Z(2,:), '---')
   legend('Output Gap', 'Output', 'Location', 'best')
   saveas (gcf, 'kalman.png')
   Kalman Filter (kfilter.m)
  function [X_{post}, P_{post}, X_{prior}, P_{prior}, K] = kfilter(Z, A, C, L)
        D, S<sub>vv</sub>, X0, P0
   %KFILTER Compute the Kalman Filter for a VAR(1) process
   %
              X[t+1] = AX[t] + Cu[t+1]
   %
         Z[t+1] = DX[t+1] + v[t+1]
 5
   % Get size of observations
   [\tilde{T}, T] = \operatorname{size}(Z);
   % Allocate space for estimates
   X_{\text{prior}} = \text{cell}(1,T);
   X_{post} = cell(1,T);
_{12} K = cell(1,T);
13
   % Set starting values
   X_{-post}\{1\} = X0;
   P_{-post} = P0;
17
    for t = 1:T-1
18
        % Compute X_{-}\{t+1|t\}
19
         X_{prior}\{t+1\} = A*X_{post}\{t\};
20
^{21}
        % Compute P_{t+1|t}
^{22}
         P_{prior} = A * P_{post} * A' + C * C';
23
24
        % Compute K_{-}\{t+1\}
25
        K\{t+1\} = P_prior*D'*(D*P_prior*D'+S_vv)^-1;
26
27
        \% Compute X_{-}\{t+1|t+1\}
28
         X_{post}\{t+1\} = A*X_{post}\{t\} + K\{t+1\} * (Z(:,t) - D*X_{prior}\{t\})
29
            +1});
30
        % Compute P_{-}\{t+1|t+1\}
31
         P_{post} = P_{prior} - K\{t+1\}*D*P_{prior};
32
33
   end
34
35
```

```
\% Convert post and prior estimates to matrices X_prior = cell2mat(X_prior); \\ X_post = cell2mat(X_post); \\ \end{subset}
```