	2.51	1 0		
Moments		1		Varobs
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	-	$[\psi_{\pi}\psi_{y}\rho_{I}]$		YGR
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y}\rho_{I}]$		INFL
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y}\rho_{I}]$		INT
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y} ho_{I}]$		y
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err err	$[\psi_{\pi}\psi_{y}\rho_{x}]$	$[\sigma_R]$	c
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	R] err	$[\psi_{\pi}\psi_{y}\rho_{I}]$	$[\sigma_R]$	R
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$_{R}]$ err	$ [\psi_{\pi}\psi_{y} ho]$	$[\sigma_R]$	$\pi$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	R] err	$[\psi_{\pi}\psi_{y} ho_{I}]$	$[\sigma_R]$	g
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	R] err	$[\psi_{\pi}\psi_{y} ho_{I}]$		z
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	R] err	$[\psi_{\pi}\psi_{y} ho_{I}]$	$[\sigma_R]$	ζ
<b>√</b> √	err	<b>√√</b>		YGR, INFL
<b>√</b> √	err	<b>//</b>		YGR, INT
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}]$	$o_R$	YGR, y
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y} ho_{I}]$		YGR, c
√ √	err		,	YGR,R
<b>//</b>	err	<b>//</b>		$YGR, \pi$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{L}]$		$[\psi_{\pi}\psi_{y}\rho_{I}]$	$\sigma_R$	YGR,g
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y}\rho_{I}]$		YGR, z
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y} ho_{1}]$		$YGR, \zeta$
$\frac{[\psi_\pi\psi_y\rho_R\sigma_I]}{[\psi_y]}$	err	$[\psi_{\eta}]^{[\psi_{\eta}\psi_{\eta}\rho_{I}]}$		INFL,INT
[\(\psi y\)]	err	$[\psi_{\pi}\psi_{y} ho_{1}]$		INFL, y
./	err	$[\varphi \pi \psi y \rho]$	$\frac{1 \vee K}{2 \times K}$	INFL, g $INFL, c$
[a/1 ]		$[\psi_{\pi}\psi_{y}\rho]$	$\frac{R^{O}R_{\parallel}}{2\sigma^{-1}}$	INFL, R
$[\psi_y]$	err	$[\psi_{\pi}\psi_{y}\rho_{I}]$		$INFL,\pi$ $INFL,\pi$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y}\rho_{x}]$	-	$INFL, \pi$ $INFL, g$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	_	$[\psi_{\pi}\psi_{y}\rho_{I}]$		INFL, g $INFL, z$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y}\rho_{I}]$		
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y}\rho_{I}]$		$INFL, \zeta$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{L}]$		$[\psi_{\pi}\psi_{y}\rho_{I}]$		INT, y
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y}\rho_{I}]$		INT, c
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	I	$[\psi_{\pi}\psi_{y}\rho_{I}]$		INT,R
$[\psi_y]$	err	$[\psi_{\pi}\psi_{y}\rho_{I}]$		$INT, \pi$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	-	$[\psi_{\pi}\psi_{y} ho_{I}]$		INT, g
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y} ho_{I}]$		INT, z
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$[\psi_{\pi}\psi_{y} ho]$		$INT, \zeta$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	R] err	$[\psi_{\pi}\psi_{y} ho_{I}]$	$[\sigma_R]$	y, c
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	R] err	$[\psi_{\pi}\psi_{y} ho_{I}]$	$[\sigma_R]$	y,R
✓	err	<b>√</b>		$y,\pi$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$_{R}]$ err	$[\psi_{\pi}\psi_{y} ho_{1}]$	$[\sigma_R]$	y,g
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	R] err	$[\psi_{\pi}\psi_{y} ho_{1}]$	$[\sigma_R]$	y, z
$[\psi_\pi \psi_y  ho_R \sigma_R]$	err	$  [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$	R]	$y,\zeta$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$  [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$	<sub>3</sub> ]	c, R
✓	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$		$c,\pi$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$	₹]	c, g
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$		c, z
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$		$c, \zeta$
$[\psi_y]$	err	$[\psi_y]$		$R,\pi$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$	2]	R, g
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	3	R, z
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$	3]	$R, \zeta$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$		$\pi, g$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$		$\pi, z$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$	_	$\pi, \zeta$
$\frac{[\psi_\pi\psi_y ho_R\sigma_R]}{[\psi_\pi\psi_y ho_R\sigma_R]}$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$		g, z
$[\psi_\pi\psi_y ho_R\sigma_R]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{I}]$	3]	$g, \zeta$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	3	$\frac{g, \zeta}{z, \zeta}$
$\frac{[\psi\pi\psi y \rho R \circ R]}{}$	err	$\sqrt{\checkmark}$	V	$\overline{GR, INFL, INT}$
	err			$\frac{GR,INFL,INI}{YGR,INFL,y}$
<b>√√</b>	err	<b>√√</b>		$\frac{IGR,INFL,g}{YGR,INFL,c}$
		\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \		$\frac{IGR,INFL,c}{YGR,INFL,R}$
	err	././	-	$\frac{IGR,INFL,\pi}{YGR,INFL,\pi}$
<b>√</b> √	err	V V		$\frac{YGR,INFL,\pi}{YGR,INFL,g}$
v v	err	_ <b>v</b> v		IGIL, INFL, g

<b>√√</b>	err	<b>√√</b>	YGR, INFL, z
<b>√√</b>	err	<b>/</b> /	$YGR, INFL, \zeta$
<b>√√</b>	err	<b>√√</b>	YGR, INT, y
<b>√√</b>	err	<b>√√</b>	YGR, INT, c
<b>√</b> √	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	YGR, INT, R
<b>√</b> √	err	<b>√√</b>	$YGR, INT, \pi$
<b>//</b>	err	<b>√</b> √	YGR, INT, g
<b>/</b> /	err	<b>√</b> √	YGR, INT, z
\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	err	$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	$YGR, INT, \zeta$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err		$\frac{YGR, y, c}{YGR, y, c}$
$\sqrt{}$		$\begin{array}{ c c c c c }\hline [\psi_\pi\psi_y\rho_R\sigma_R]\\\hline \checkmark\checkmark\\\hline \end{array}$	$\frac{YGR, y, c}{YGR, y, R}$
<b>√√</b>	err	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	
	err		$YGR, y, \pi$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	YGR, y, g
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	YGR, y, z
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$YGR, y, \zeta$
<b>√√</b>	err	<b>√</b> √	YGR, c, R
<b>√√</b>	err	<b>√</b> √	$YGR, c, \pi$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	YGR, c, g
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	YGR, c, z
<b>√√</b>	err	<b>√√</b>	$YGR, c, \zeta$
<b>√√</b>	err	<b>√</b> √	$YGR, R, \pi$
<b>√</b> √	err	<b>//</b>	YGR, R, g
<b>√√</b>	err	<b>//</b>	YGR, R, z
<b>√</b> √	err	<b>√√</b>	$YGR, R, \zeta$
<b>/</b> /	err	<b>/</b> /	$YGR, \pi, g$
			$\frac{YGR, \pi, g}{YGR, \pi, z}$
V V	err		
[-//]	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$YGR, \pi, \zeta$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	YGR, g, z
<b>√</b>	err	<b>√</b>	$YGR, g, \zeta$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$YGR, z, \zeta$
<b>√√</b>	err	<b>√√</b>	INFL, INT, y
<b>//</b>	err	<b>√√</b>	INFL, INT, c
$[\psi_y]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INFL, INT, R
$[\psi_y]$	$\operatorname{err}$	$[\psi_y]$	$INFL, INT, \pi$
<b>√√</b>	err	<b>√√</b>	INFL, INT, g
$[\psi_u]$	err	$[\psi_y]$	INFL, INT, z
<b>√√</b>	err	$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	$INFL, INT, \zeta$
$ \begin{array}{c c} [\psi_y] \\ \hline \checkmark \checkmark \\ \hline \checkmark \end{array} $	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INFL, y, c
<b>√√</b>	err	\( \sqrt{\psi} \)	INFL, y, R
<b>√</b>	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INFL, y, \pi$
			$\frac{INFL, y, x}{INFL, y, g}$
V	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INFL, y, y
<b>√</b>	err	$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	INFL, y, z
<b>√</b>	err	<b>V</b>	$INFL, y, \zeta$
<b>V V</b>	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INFL, c, R
<b>√</b>	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INFL, c, \pi$
<b>√</b>	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INFL, c, g
✓	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INFL, c, z
✓		$\begin{bmatrix} a/1 & a/2 & \alpha = \sigma \end{bmatrix}$	$INFL, c, \zeta$
$[\psi_y]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	
<b>√√</b>	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INFL, R, \pi$
$[\psi_y]$			
L / 91	err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$
√√	err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$
<b>√√</b>	err err err		$INFL, R, \pi$ $INFL, R, g$
$ \begin{array}{c} \checkmark \checkmark \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	err err err	$ \begin{aligned}                                   $	$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, g$
$ \begin{array}{c c} \checkmark \checkmark \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	err err err err err err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, g$ $INFL, \pi, g$ $INFL, \pi, z$
$ \begin{array}{c} \sqrt{\checkmark} \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	err err err err err err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, g$ $INFL, \pi, z$ $INFL, \pi, z$ $INFL, \pi, \zeta$
$ \begin{array}{c} \sqrt{\checkmark} \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	err err err err err err err err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, g$ $INFL, \pi, z$ $INFL, \pi, z$ $INFL, \pi, \zeta$ $INFL, \pi, \zeta$ $INFL, \pi, \zeta$
$ \begin{array}{c} \checkmark \checkmark \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	err err err err err err err err err	$ \begin{aligned}                                   $	$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, g$ $INFL, \pi, z$ $INFL, \pi, z$ $INFL, \pi, \zeta$ $INFL, \pi, \zeta$ $INFL, g, z$ $INFL, g, \zeta$
$ \begin{array}{c} \checkmark \checkmark \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, \zeta$ $INFL, \pi, z$ $INFL, \pi, \zeta$ $INFL, \pi, \zeta$ $INFL, \pi, \zeta$ $INFL, g, z$ $INFL, g, \zeta$ $INFL, z, \zeta$
$ \begin{array}{c} \sqrt{\checkmark} \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, g$ $INFL, \pi, z$ $INFL, \pi, \zeta$ $INFL, g, \zeta$ $INFL, g, \zeta$ $INFL, z, \zeta$ $INFL, z, \zeta$ $INFL, z, \zeta$ $INFL, z, \zeta$ $INT, y, c$
$ \begin{array}{c} \sqrt{\checkmark} \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ \checkmark \\ \checkmark$	err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, g$ $INFL, \pi, z$ $INFL, \pi, \zeta$ $INFL, \pi, \zeta$ $INFL, \pi, \zeta$ $INFL, g, \zeta$ $INFL, g, \zeta$ $INFL, z, \zeta$ $INFL, z, \zeta$ $INT, y, c$ $INT, y, R$
$ \begin{array}{c} \sqrt{\checkmark} \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	err		$INFL, R, \pi$ $INFL, R, g$ $INFL, R, z$ $INFL, R, \zeta$ $INFL, \pi, g$ $INFL, \pi, z$ $INFL, \pi, \zeta$ $INFL, g, \zeta$ $INFL, g, \zeta$ $INFL, z, \zeta$ $INFL, z, \zeta$ $INFL, z, \zeta$ $INFL, z, \zeta$ $INT, y, c$

.//	Orr	[a/2 a/2 0 - 5 - ]	INT a. ~
<b>√√</b>	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$\frac{INT, y, z}{INT, y, \zeta}$
<b>√</b> √ √	err		$\frac{INT, y, \zeta}{INT, c, R}$
	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	
<b>√</b> √	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INT, c, \pi$
<b>√ √</b>	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INT, c, g
<b>√√</b>	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INT, c, z
<b>√</b> √	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INT, c, \zeta$
$[\psi_y]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INT, R, \pi$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	INT, R, g
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$\left[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}\right]$	INT, R, z
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$\left[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}\right]$	$INT, R, \zeta$
<b>✓</b> ✓	err	$\left[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}\right]$	$INT,\pi,g$
$[\psi_y]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INT, \pi, z$
$[\psi_y]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INT, \pi, \zeta$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	INT, g, z
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$INT, g, \zeta$
$\frac{[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]}{[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]}$	err		$INT, z, \zeta$
\[ \sqrt{\gamma} \]	err	[	y, c, R
<u> </u>	err	<i></i>	$y, c, \pi$
$\frac{\mathbf{v}}{[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]}$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$y, c, \pi$ $y, c, g$
$\frac{[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]}{[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]}$	err	$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	
			y, c, z
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$y, c, \zeta$
<b>√</b> √	err	<b>√</b> √	$y, R, \pi$
<b>/</b> /	err	<b>/</b> /	y, R, g
<b>√</b> √	err	<b>√√</b>	y, R, z
<b>√</b> √	err	<b>/</b> /	$y, R, \zeta$
<b>√</b>	err	<b>√</b>	$y, \pi, g$
<b>√</b>	err	<b>√</b>	$y, \pi, z$
<b>√</b>	err	<b>√</b>	$y,\pi,\zeta$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	y, g, z
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$y, g, \zeta$
$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	err	$\left[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}\right]$	$y,z,\zeta$
<b>√</b> √	err	$\left[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}\right]$	$c, R, \pi$
<b>✓</b> ✓	err	$\left[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}\right]$	c, R, g
<b>√√</b>	err	<b>√√</b>	c, R, z
<b>√</b> √	err	<b>√√</b>	$c, R, \zeta$
<b>√</b>	err	$[\psi_{\pi}\psi_{u}\rho_{R}\sigma_{R}]$	$c,\pi,g$
<b>√</b>	err		$c,\pi,z$
$\checkmark$	err	<b>√</b>	$c,\pi,\zeta$
$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	err	$[\psi_{\pi}\psi_{y} ho_{R}\sigma_{R}]$	c, g, z
$\frac{[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]}{[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]}$	err		$c, g, z$ $c, g, \zeta$
$[y_1, y_1, z_2, \sigma_2]$	VII	$[ [ \forall \pi \forall y P \pi^{\vee} \pi] ]$	
1 107 - 107 - 11 15 15 15 15	err	$[\eta/_{-}\eta/_{2}, \alpha_{D}\sigma_{D}]$	$c \sim c$
$[\psi \pi \psi_y \rho_{R^0 R}]$	err	$[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]$	$c, z, \zeta$ $R \pi a$
$ \frac{[\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}]}{\checkmark\checkmark} $	err	$\begin{array}{c c} [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ \hline \checkmark\checkmark \end{array}$	$R, \pi, g$
$ \begin{array}{c c} [\psi_{\pi}\psi_{y}\rho_{R}o_{R}] \\ \hline \checkmark\checkmark \\ [\psi_{y}] \end{array} $	err	$ \begin{array}{c c} [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ \checkmark\checkmark \\ [\psi_{y}] \end{array} $	$R, \pi, g$ $R, \pi, z$
	err err err	$ \begin{array}{c c} [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ \hline \checkmark\checkmark \\ [\psi_{y}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	$R,\pi,g$ $R,\pi,z$ $R,\pi,\zeta$
$ \begin{array}{c c}                                    $	err err err	$ \begin{array}{c c} (\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}) \\ \checkmark\checkmark \\ [\psi_{y}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	$R, \pi, g$ $R, \pi, z$ $R, \pi, \zeta$ $R, g, z$
$ \begin{bmatrix} [\psi_y] \\ \checkmark \checkmark \\ [\psi_\pi \psi_y \rho_R \sigma_R] \\ [\psi_\pi \psi_y \rho_R \sigma_R] \end{bmatrix} $	err err err err	$ \begin{array}{c c} (\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}) \\ \hline \checkmark\checkmark \\ \hline [\psi_{y}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	$R, \pi, g$ $R, \pi, z$ $R, \pi, \zeta$ $R, g, z$ $R, g, \zeta$
$ \begin{bmatrix} [\psi_y] \\ \checkmark \checkmark \\ [\psi_\pi \psi_y \rho_R \sigma_R] \\ [\psi_\pi \psi_y \rho_R \sigma_R] \\ [\psi_\pi \psi_y \rho_R \sigma_R] \end{bmatrix} $	err err err	$ \begin{array}{c c} (\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}) \\ \hline \checkmark\checkmark \\ \hline [\psi_{y}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	$R, \pi, g$ $R, \pi, z$ $R, \pi, \zeta$ $R, g, z$ $R, g, \zeta$ $R, z, \zeta$
	err err err err		$R, \pi, g$ $R, \pi, z$ $R, \pi, \zeta$ $R, g, z$ $R, g, \zeta$ $R, z, \zeta$ $R, z, \zeta$
	err err err err err err	$ \begin{array}{c c} [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ \hline \checkmark\checkmark \\ \hline [\psi_{y}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	$R, \pi, g$ $R, \pi, z$ $R, \pi, \zeta$ $R, g, z$ $R, g, \zeta$ $R, z, \zeta$ $\pi, g, z$ $\pi, g, \zeta$
	err err err err err err err	$ \begin{array}{c c} (\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}) \\ \hline \checkmark\checkmark \\ \hline [\psi_{y}] \\ \hline [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ \hline [\psi_{y}] \end{array} $	$R, \pi, g$ $R, \pi, z$ $R, \pi, \zeta$ $R, g, z$ $R, g, \zeta$ $R, z, \zeta$ $R, z, \zeta$
	err	$ \begin{array}{c c} (\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}) \\ \hline \checkmark\checkmark \\ \hline [\psi_{y}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \\ [\psi_{y}] \\ [\psi_{\pi}\psi_{y}\rho_{R}\sigma_{R}] \end{array} $	$R, \pi, g$ $R, \pi, z$ $R, \pi, \zeta$ $R, g, z$ $R, g, \zeta$ $R, z, \zeta$ $\pi, g, z$ $\pi, g, \zeta$ $\pi, g, \zeta$ $\sigma, g, \zeta$

Table 1: PREFSHOCK MONPOL STEADYSTATE