

## Chapter 10: Building the regression model II: Diagnostics

Refined diagnostics for checking the adequacy of a regression model

- Improper functional form for a predictor variable
- Outliers
- Influential observations
- Multicollinearity

### 10.1 Model adequacy for a predictor variable – Added-variable plots

Review:

1. Extra sum of squares: Measurement of additional or extra reduction of the error sums of squares when an independent variable is added to the model given a set of independent variables are already in the model.  
For example,  $SSR(X_2|X_1) = SSE(X_1) - SSE(X_1, X_2)$ .
2. Residual plot of  $e_i$  vs.  $X_{ik}$  (residuals vs.  $k^{th}$  independent variable): Determine the appropriateness of the specified relationship between  $X_k$  and  $Y$ . For example, if there is a random scattering of points, the relationship between  $X_k$  and  $Y$  is specified correctly. If there is a relationship between the points of  $e_i$  vs.  $X_{ik}$  (for example, a quadratic relationship), this suggests  $X_{ik}$  is not specified correctly in the model.

The problem with #2 is that it does not necessarily give information about the marginal relationship between  $X_k$  and  $Y$  given all of the independent variables in the model.

Solution: Use **added-variable plots** (also called **partial regression plots** and **adjusted variable plots**). SAS calls these partial regression leverage plots.

Suppose there are only two independent variables  $X_1$  and  $X_2$ . The steps to create a partial regression plot for  $X_1$  are:

1. Fit the model using  $Y$  as the dependent variable and  $X_2$  as the independent variable. Obtain the residuals. Symbolically,  $\hat{Y}_i(X_2) = \hat{\beta}_0 + \hat{\beta}_1 X_{i2}$  and  $e_i(Y | X_2) = Y_i - \hat{Y}_i(X_2)$ .
2. Fit the model with  $X_1$  as the dependent variable and  $X_2$  as the independent variable. Obtain the residuals. Symbolically,  $\hat{X}_{i1}(X_2) = \hat{\beta}_0^* + \hat{\beta}_1^* X_{i2}$  and  $e_i(X_1 | X_2) = X_{i1} - \hat{X}_{i1}(X_2)$ .
3. Plot  $e_i(Y | X_2)$  vs.  $e_i(X_1 | X_2)$ .

If there are more than two independent variables in the model, then plot

$e_i(Y | X_2, X_3, \dots, X_{p-1})$  vs.  $e_i(X_1 | X_2, X_3, \dots, X_{p-1})$ . In addition, make the appropriate changes to do added-variable plots for  $X_2, X_3, \dots, X_{p-1}$ .

Interpretation:

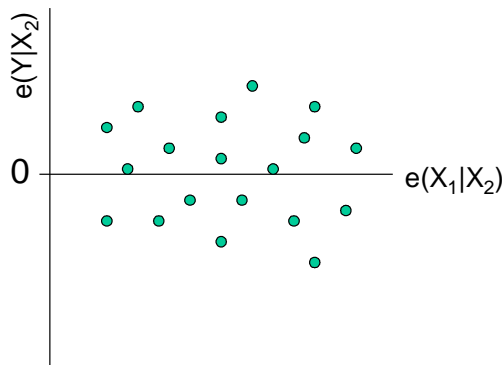
The added-variable plots

- (1) show the marginal importance of this variable in reducing the residual variability;
- (2) help to find the correct functional form of an independent variable in a multiple regression model;

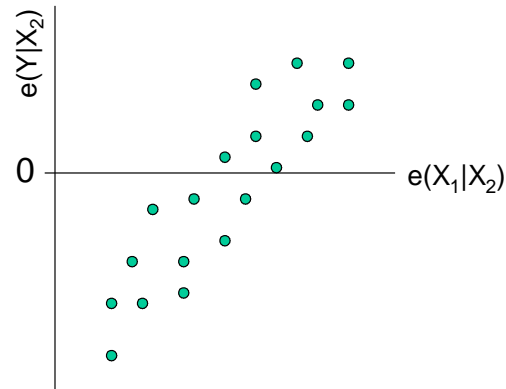
(3) provide information about the strength of this relationship (If the scatter of the points around the line through the origin is much less than the scatter around the horizontal line, inclusion of the variable in the regression model will provide a substantial further reduction in the error sum of squares).

Suppose the only independent variables are  $X_1$  and  $X_2$ . Below are example partial regression plots:

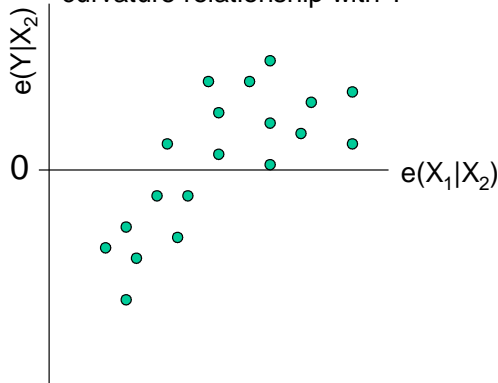
Given  $X_2$  in the model,  $X_1$  does not give any additional information about  $Y$



Given  $X_2$  in the model,  $X_1$  has a linear relationship with  $Y$



Given  $X_2$  in the model,  $X_1$  has a curvature relationship with  $Y$



#### Notes:

1. Remember what a t-test does – it tests the linear relationship between  $Y$  and  $X_k$  given all of the other variables in the model. Therefore, the partial regression plots and t-tests partially give the same information. With the added-variable plots, there is also information about the type of relationship between  $Y$  and  $X_k$ .
2. The added-variable plots are dependent on which independent variables are already included in a model.
3. See Figure 10.2 of KNN for an additional interpretation of added-variable plots. This further helps to relate added-variable plots to extra sum of squares.
4. Added-variable plots also help to identify outliers and “leverage” or influential points (more on this later).

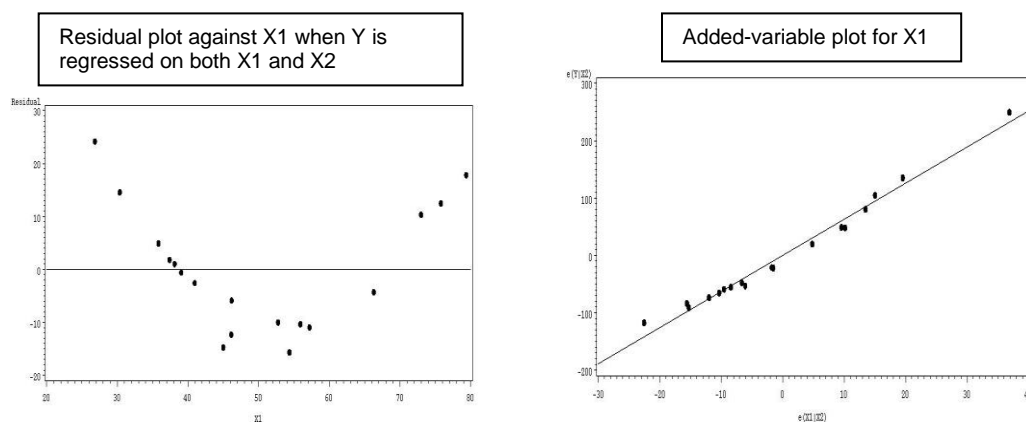
**Example 1:** Table 10.1 shows a portion of the data on average annual income ( $X_1$ ) of managers during the past two years, a score measuring each manager's risk aversion ( $X_2$ ), and the amount of life insurance carried ( $Y$ ) for a sample of 18 managers in the 30-39 age group.

See graphs below.

The residual plot suggests that a linear relationship for  $X_1$  is not appropriate.

The added-variable plot suggests that the curvilinear relationship between  $Y$  and  $X_1$  when  $X_2$  is already in the regression model is strongly positive.

Note that the scatter of the points around the least squares line through the origin with slope 6.2880 is much smaller than is the scatter around the horizontal axis, indicating that adding  $X_1$  to the model with a linear relation will substantially reduce the error of sum squares. In fact,  $R^2_{Y|2}=0.984$ , and the slope 6.2880 equals to the regression coefficient for  $X_1$  when is  $X_1$  added to the fitted model.



**Example 2** Consider the body fat example (Table 7.1) again. For demonstration purpose, we only consider the regression of body fat ( $Y$ ) on triceps thickness ( $X_1$ ) and thigh circumference( $X_2$ ).

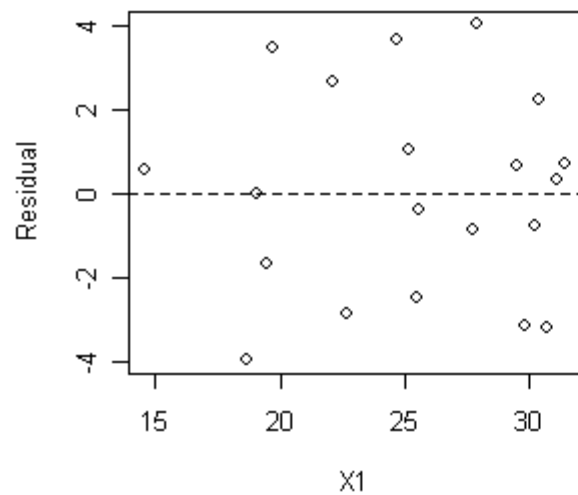
See the graphs below.

The two residual plots do not indicate any lack of fit for the linear terms or the existence of unequal variances of the error terms when the first-order model is used.

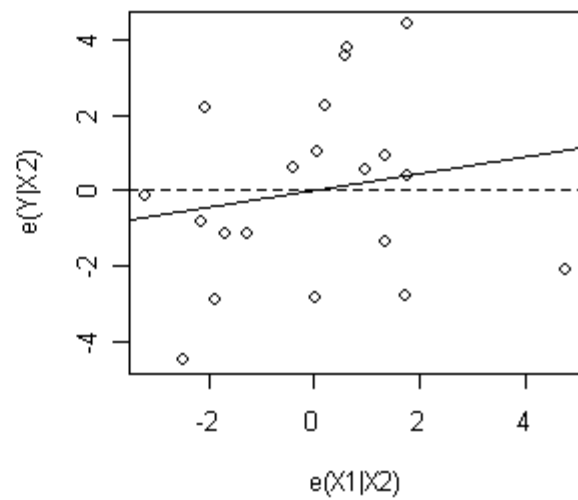
The added-variable plot for  $X_1$  suggests that  $X_1$  is of little help when  $X_2$  is already in the regression model. In fact  $R^2_{Y1|2}=0.031$ .

The added-variable plot for  $X_2$  suggests that a linear term in  $X_2$  may be helpful even when  $X_1$  is already in the regression model. In fact  $R^2_{Y2|1}=0.232$ . This plot also suggests the presence of one potentially influential case in the lower left corner.

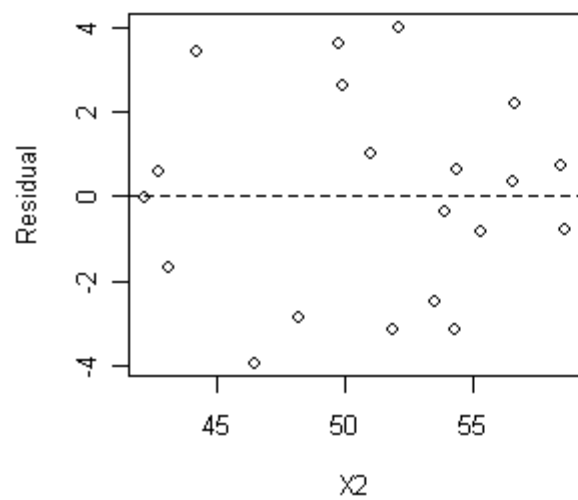
**Residual plot against X1**



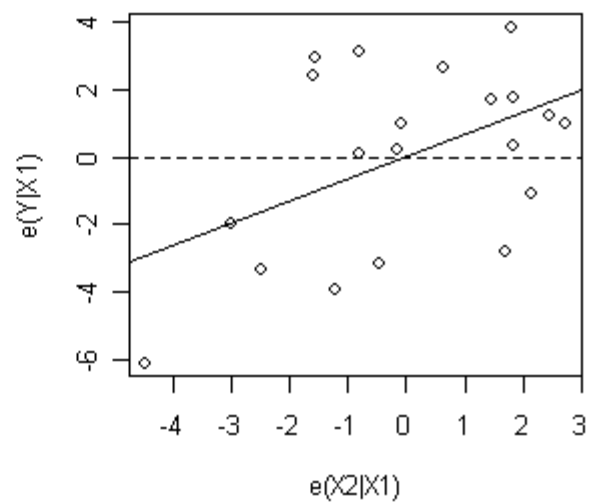
**Added-variable plot for X1**



**Residual plot against X2**



**Added-variable plot for X2**

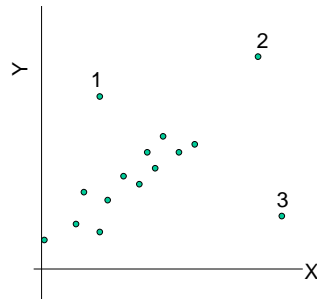


## 10.2 Identifying outlying Y observations – studentized deleted residuals

### Outlying cases

When there is only 1 independent variable, identifying outliers is not too difficult. Below is a partial reproduction of Figure 10.5 in KNN:

Scatter plot showing outliers



1. Outlying point with respect to its Y value. May not be very influential to the regression model fit since there are similar X values.
2. Outlying point with respect to its X and Y value. May not be very influential to the regression model fit since the Y value is consistent with the others.
3. Outlying point with respect to its X value. May be influential since the X value is outlying and not consistent with respect to the other X values.

In multiple regression, we generally can not look at plots as shown above (too many dimensions). Therefore, we need to look at numerical measures that give information about a particular observation being outlying or not.

### Residuals and semistudentized residuals (Chapters 1 and 3)

$$e_i = Y_i - \hat{Y}_i \text{ and } e_i^* = \frac{e_i}{\sqrt{MSE}}$$

Remember that  $\sqrt{MSE}$  is not quite the estimated variance of  $e_i$ . Thus,  $e_i^*$  is not quite a random variable with variance of 1.

Two refinements are made to the analysis of residuals more effective for identifying outlying Y observations. These refinements require the use of hat matrix.

### Hat matrix (Chapters 5 and 6)

Remember that:

$$\mathbf{H} = \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}', \quad \hat{\mathbf{Y}} = \mathbf{X}\hat{\boldsymbol{\beta}} = \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y} = \mathbf{H}\mathbf{Y},$$

The variance-covariance matrix for  $\mathbf{e}$  is  $\text{Cov}(\mathbf{e}) = \sigma^2(\mathbf{I} - \mathbf{H})$ , and its estimate is

$$\hat{\text{Cov}}(\mathbf{e}) = \text{MSE}(\mathbf{I} - \mathbf{H})$$

Note that  $\mathbf{H}$  is a  $n \times n$  matrix with elements of

$$\begin{bmatrix} h_{11} & h_{12} & \cdots & h_{1n} \\ h_{21} & h_{22} & \cdots & h_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ h_{n1} & h_{n2} & \cdots & h_{nn} \end{bmatrix}$$

And,  $\text{Cov}(\mathbf{e})$  is

$$\sigma^2 \left( \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix} - \begin{bmatrix} h_{11} & h_{12} & \cdots & h_{1n} \\ h_{21} & h_{22} & \cdots & h_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ h_{n1} & h_{n2} & \cdots & h_{nn} \end{bmatrix} \right) = \sigma^2 \begin{bmatrix} 1-h_{11} & -h_{12} & \cdots & -h_{1n} \\ -h_{21} & 1-h_{22} & \cdots & -h_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -h_{n1} & -h_{n2} & \cdots & 1-h_{nn} \end{bmatrix}$$

Thus,  $\text{Cov}(e_1, e_1) = \text{Var}(e_1) = \sigma^2(1-h_{11})$ ,  $\text{Var}(e_2) = \sigma^2(1-h_{22})$ , ...  $\text{Var}(e_n) = \sigma^2(1-h_{nn})$ . In general,  $\text{Var}(e_i) = \sigma^2(1-h_{ii})$

The estimated variance of the  $i^{\text{th}}$  residual is

$$\hat{\text{Var}}(e_i) = \text{MSE}(1-h_{ii})$$

The **studentized residual** is:

$$r_i = \frac{e_i}{\sqrt{\hat{\text{Var}}(e_i)}} = \frac{e_i}{\sqrt{\text{MSE}(1-h_{ii})}}$$

$$r_i \sim t(n-p)$$

### Deleted residuals

From Chapter 9, PRESS prediction error =  $Y_i - \hat{Y}_{i(i)}$

Example: Let  $i=3$ . Then the PRESS prediction error =  $Y_3 - \hat{Y}_{3(3)}$ . To obtain  $\hat{Y}_{3(3)}$ , a regression model is fit to the data where observation 3 is removed from the data set. For observation 3's  $X_1, \dots, X_{p-1}$ , the predicted  $Y$  value is obtained -  $\hat{Y}_{3(3)}$ .

**Deleted residual** for the  $i^{\text{th}}$  observation:  $d_i = Y_i - \hat{Y}_{i(i)}$

An algebraically equivalent expression without the recomputation of the fitted regression function omitting the  $i^{\text{th}}$  case is:

$$d_i = \frac{e_i}{(1-h_{ii})}$$

Notes:

1. Suppose  $X_i$  is very influential on the regression model fit (for example, point #3 on Figure 10.5). Then the regression line will be “pulled” toward  $(X_i, Y_i)$  resulting in a  $\hat{Y}_i$  “close” to  $Y_i$ . If this observation is deleted from the data set and a new

regression model is fit,  $\hat{Y}_{i(i)}$  will not be as “close” to  $Y_i$ . This will result in a  $d_i$  that is larger (in absolute value) than  $e_i$ .

- Suppose  $X_i$  is not very influential on the regression model fit (for example, a point within the main cluster of points). The regression line will not be heavily influenced by  $(X_i, Y_i)$ . Thus,  $d_i$  should be about the same as  $e_i$ .

From Section 6.7, the estimated variance of a “new” observation is

$$s^2_{\text{pred}} = MSE(1 + \mathbf{X}_h'(\mathbf{X}' - \mathbf{X})^{-1}\mathbf{X}_h)$$

for  $\mathbf{X}_h = (1, X_{h1}, X_{h2}, \dots, X_{h,p-1})'$ . This variance is used in calculating prediction intervals.

Since the  $i^{\text{th}}$  observation is removed from the data set in calculating  $d_i$ , the  $i^{\text{th}}$  observation can be thought of as a “new” observation and the estimated variance from Section 6.7 can be used for its variance. Thus,

$$s^2\{d_i\} = MSE_{(i)}(1 + \mathbf{X}_i'(\mathbf{X}'_{(i)} - \mathbf{X}_{(i)})^{-1}\mathbf{X}_i)$$

An algebraically equivalent expression is  $s^2\{d_i\} = \frac{MSE_{(i)}}{1 - h_{ii}}$

The **studentized deleted residual** is:

$$t_i = \frac{d_i}{s\{d_i\}} = \frac{e_i}{\sqrt{MSE_{(i)}(1 - h_{ii})}}$$

$$t_i \sim t(n-1-p),$$

where  $MSE_{(i)}$  is the MSE from the model where the  $i^{\text{th}}$  observation is deleted. Also,  $\mathbf{X}_{(i)}$  has the row of  $\mathbf{X}$  corresponding to the  $i^{\text{th}}$  observation deleted. Note that  $t_i \sim t(n-p-1)$  where the degrees of freedom comes from  $n-1$  observations and  $p$  parameters.

One more expression can be found for the studentized deleted residuals! Note that

$$(n-p)MSE = (n-p-1)MSE_{(i)} + \frac{e_i^2}{(1-h_{ii})}$$

Thus,

$$t_i = e_i \left[ \frac{n-p-1}{SSE(1-h_{ii}) - e_i^2} \right]^{1/2}$$

Therefore,  $n$  different regression models DO NOT need to be calculated!

## Test for outlying Y observations

KNN recommend doing the following (p.396) for studentized deleted residuals:

Use a Bonferroni critical value of  $t[1-\alpha/(2n); n-p-1]$  to determine if the observation is an outlier. In other words,  $H_0$ : Not outlier vs.  $H_a$ : outlier. If  $|t_i| < t(1-\alpha/(2n); n-p-1)$ , then there is not sufficient evidence that the  $i^{\text{th}}$  observation is an outlier. Otherwise, the  $i^{\text{th}}$  observation is an outlier.

Use the same method for studentized residuals, but use  $n-p$  degrees of freedom.

**Problem:**  $t[1-\alpha/(2n); n-p-1]$  typically is large since the number of tests being done is  $n$ . Therefore, this procedure will be VERY conservative.

**Example:** Consider the body fat example (Table 7.1) again. For demonstration purpose, we only consider the regression of body fat (Y) on triceps thickness ( $X_1$ ) and thigh circumference( $X_2$ ).

**Question:** Is case 13 which has the largest absolute studentized deleted residual an outlier?

When  $\alpha = 0.10$ , the appropriate Bonferroni critical value is:

$$t(1-\alpha/(2n); n-p-1) = t(0.9975; 16) = 3.252$$

```
> Data <- read.table(file="C://Hongmei/Teaching/stat350/DataSet/CH07TA01.txt", header=FALSE)
> colnames(Data) <- c("X1", "X2", "X3", "Y")
> fit <- lm(Y~X1+X2, data=Data)
> rstudent(fit) # studentized deleted residuals
```

	1	2	3	4	5	6	7
	-0.7299854027	1.5342541325	-1.6543295725	-1.3484842072	-0.0001269809	-0.1475490938	0.2981276214
	8	9	10	11	12	13	14
	1.7600924916	1.1176487404	-1.0337284208	0.1366610657	0.9231785040	-1.8259027246	1.5247630510
	15	16	17	18	19	20	
	0.2671500921	0.2581323416	-0.3445090997	-0.3344080836	-1.1761712768	0.4093564171	

```
> influence.measures(fit) # DFFITS, Cook's distance, DFBETAS
Influence measures of
      lm(formula = Y ~ X1 + X2, data = Data) :
```

	dfb.1	dfb.X1	dfb.X2	dffit	cov.r	cook.d	hat	inf
1	-3.05e-01	-1.31e-01	2.32e-01	-3.66e-01	1.361	4.60e-02	0.2010	
2	1.73e-01	1.15e-01	-1.43e-01	3.84e-01	0.844	4.55e-02	0.0589	
3	-8.47e-01	-1.18e+00	1.07e+00	-1.27e+00	1.189	4.90e-01	0.3719	*
4	-1.02e-01	-2.94e-01	1.96e-01	-4.76e-01	0.977	7.22e-02	0.1109	
5	-6.37e-05	-3.05e-05	5.02e-05	-7.29e-05	1.595	1.88e-09	0.2480	*
6	3.97e-02	4.01e-02	-4.43e-02	-5.67e-02	1.371	1.14e-03	0.1286	
7	-7.75e-02	-1.56e-02	5.43e-02	1.28e-01	1.397	5.76e-03	0.1555	
8	2.61e-01	3.91e-01	-3.32e-01	5.75e-01	0.780	9.79e-02	0.0963	
9	-1.51e-01	-2.95e-01	2.47e-01	4.02e-01	1.081	5.31e-02	0.1146	
10	2.38e-01	2.45e-01	-2.69e-01	-3.64e-01	1.110	4.40e-02	0.1102	
11	-9.02e-03	1.71e-02	-2.48e-03	5.05e-02	1.359	9.04e-04	0.1203	
12	-1.30e-01	2.25e-02	7.00e-02	3.23e-01	1.152	3.52e-02	0.1093	
13	1.19e-01	5.92e-01	-3.89e-01	-8.51e-01	0.827	2.12e-01	0.1784	
14	4.52e-01	1.13e-01	-2.98e-01	6.36e-01	0.937	1.25e-01	0.1480	
15	-3.00e-03	-1.25e-01	6.88e-02	1.89e-01	1.775	1.26e-02	0.3332	*
16	9.31e-03	4.31e-02	-2.51e-02	8.38e-02	1.309	2.47e-03	0.0953	
17	7.95e-02	5.50e-02	-7.61e-02	-1.18e-01	1.312	4.93e-03	0.1056	
18	1.32e-01	7.53e-02	-1.16e-01	-1.66e-01	1.462	9.64e-03	0.1968	
19	-1.30e-01	-4.07e-03	6.44e-02	-3.15e-01	1.002	3.24e-02	0.0670	
20	1.02e-02	2.29e-03	-3.31e-03	9.40e-02	1.224	3.10e-03	0.0501	

### 10.3 Identifying outlying X observations – hat matrix leverage values

The diagonal elements of the hat matrix,  $h_{ii}$ , are useful in detecting outlying X observations.

$h_{ii}$  measures distance of the  $i^{\text{th}}$  observation to the mean (center) of all observations. The farther away from the mean, the larger the  $h_{ii}$ . See Figure 10.6 of KNN.

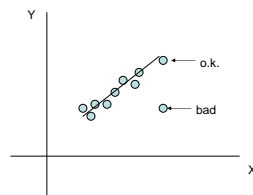
Notes:



- 1) Properties of  $h_{ii}$ 's:  $0 \leq h_{ii} \leq 1$  and  $\sum h_{ii} = p$
- 2)  $h_{ii}$  is often called the “leverage” (in terms of the X values) of the  $i^{\text{th}}$  observation.
- 3) If the  $i^{\text{th}}$  observation is outlying in terms of the X values, it has substantial leverage on determining the fitted value for  $\hat{Y}_i$ .
- 4) The larger is  $h_{ii}$ , the more important  $Y_i$  is to determining  $\hat{Y}_i$ . Remember that  $\hat{\mathbf{Y}} = \mathbf{H}\mathbf{Y}$ ; i.e.,  $\hat{Y}_i$  is a linear combination of  $h_{ii}$ 's.
- 5) The larger is  $h_{ii}$ , the smaller are the denominators of  $r_i$  and  $t_i$  (i.e., the estimated variances) since

$$r_i = \frac{e_i}{\sqrt{\text{MSE}(1-h_{ii})}} \quad \text{and} \quad t_i = e_i \left[ \frac{n-p-1}{\text{SSE}(1-h_{ii}) - e_i^2} \right]^{1/2}.$$

- 6) Since the estimated regression line is pulled toward observations with high leverage,  $e_i$  may not be large relative to the rest of the residuals.
- 7) Rule of thumb for determining if  $h_{ii}$  is “large”:
  - a)  $h_{ii} > 2p/n$  where  $p/n$  can be shown to be the mean of  $h_{ii}$
  - b)  $h_{ii} > 0.5$  indicates very high leverage,  $0.2 < h_{ii} \leq 0.5$  indicate moderate leverage. These rules apply only when the sample size is “large” relative to the number of parameters in the model.
- 8) Large  $h_{ii}$  are values are not necessarily bad!



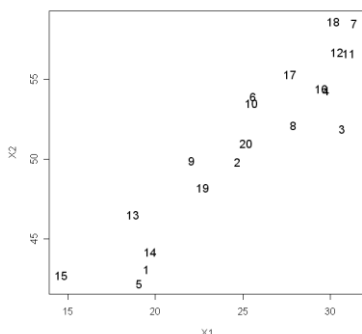
- 9) Use of hat matrix to identify hidden extrapolation

Let  $\mathbf{X}_{\text{new}}$  be the vector containing the X values for which an inference about a mean response or a new observation is to be made. Compute

$$h_{\text{new,new}} = \mathbf{X}'_{\text{new}} (\mathbf{X}'\mathbf{X})^{-1} \mathbf{X}_{\text{new}}$$

IF  $h_{\text{new,new}}$  is within the range of leverage values  $h_{ii}$  for the cases in the data set, no extrapolation is involved.

Example: Body fat example: Are there any outlying cases in terms of their X values? Look at previous SAS output, and notice  $2p/n = 2(3)/20 = 0.3$ . Check out the graph below



## 10.4 Identifying influential cases – DFFITS, Cook’s distance, and DFBETAS measures

Once outlying observations are identified, it needs to be determined if they are influential to the estimated regression function. An observation is considered to be **influential** if its exclusion causes major changes in the fitted regression function.

### Influence on single fitted value – DFFITS

The influence of observation  $i$  on  $\hat{Y}_i$  is measured by:

$$(\text{DFFITS})_i = \frac{\hat{Y}_i - \hat{Y}_{i(i)}}{\sqrt{\text{MSE}_{(i)} h_{ii}}}$$

The letters “DF” stands for the difference between the fitted values  $\hat{Y}_i$  for the  $i$ th case when all  $n$  cases are used in fitting the regression function and the predicted value  $\hat{Y}_{i(i)}$  for the  $i$ th case obtained when the  $i$ th case is omitted in fitting the regression function.

$(\text{DFFITS})_i \approx$  the number of standard deviations by which  $\hat{Y}_i$  changes when observation  $i$  is removed from the data set.

It can shown that DFFITS can be calculated in the following manner:

$$(\text{DFFITS})_i = e_i \left[ \frac{n-p-1}{\text{SSE}(1-h_{ii}) - e_i^2} \right]^{1/2} \left( \frac{h_{ii}}{1-h_{ii}} \right)^{1/2} = t_i \left( \frac{h_{ii}}{1-h_{ii}} \right)^{1/2}$$

Therefore, only one regression model needs to be fit.

Guideline for determining influential observations:

- $|(\text{DFFITS})_i| > 1$  for “small to medium” sized data sets
- $|(\text{DFFITS})_i| > 2\sqrt{p/n}$  for large data sets

### Influence on all fitted values – Cook’s Distance

Measures the influence of the  $i^{\text{th}}$  observation on ALL  $n$  fitted values.

Cook’s Distance is:

$$D_i = \frac{\sum_{j=1}^n (\hat{Y}_j - \hat{Y}_{j(i)})^2}{p\text{MSE}}$$

Notes:

1. The numerator is similar to  $(\text{DFFITS})_i$ . For Cook’s Distance, ALL of the fitted values are compared.
2. The denominator serves as a standardizing measure.

It can be shown that Cook’s Distance can be calculated in the following manner:

$$D_i = \frac{e_i^2}{pMSE} \left[ \frac{h_{ii}}{(1-h_{ii})^2} \right]$$

Therefore, only one regression model needs to be fit. From examining the above formula, note how  $D_i$  can be large (larger  $e_i$  or  $h_{ii}$  or both).

Guideline for determining influential observations:

Relate  $D_i$  to the  $F(p, n-p)$  distribution and ascertain the corresponding percentile value.

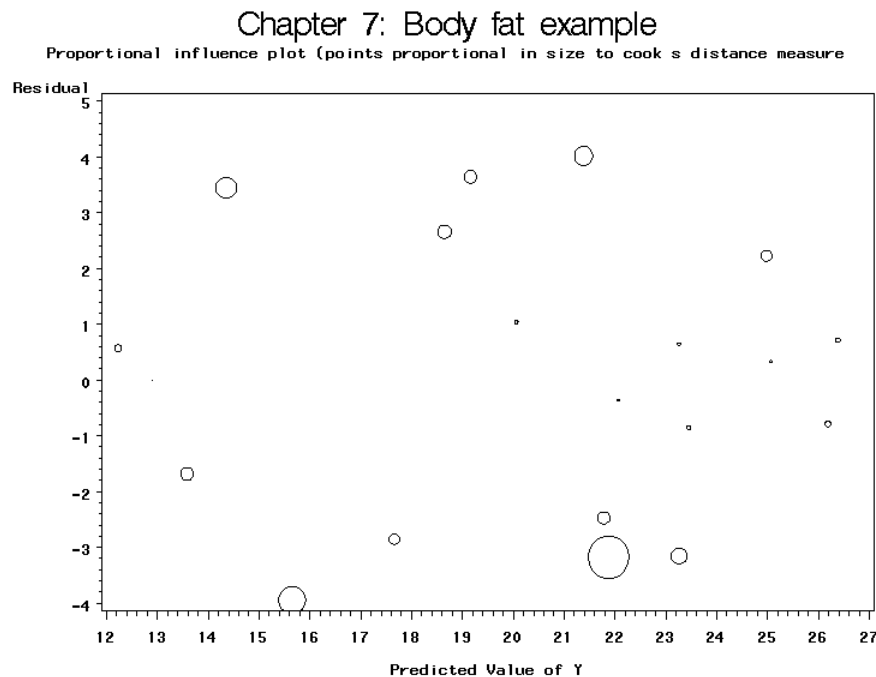
- If the percentile value is less than about 10% or 20%, little influence on the fitted values.
- If the percentile values is near 50% or more, the  $i$ th observation has a major influence on the fit of the regression function.

**Question:** For body fat example, is case an influential point?

For case 3,  $D_i=0.49$  is the 30.6<sup>th</sup> percentile using  $F(3,17)$  distribution. It does have influence on the regression fit. However it may not be large enough to call for consideration of remedial measures.

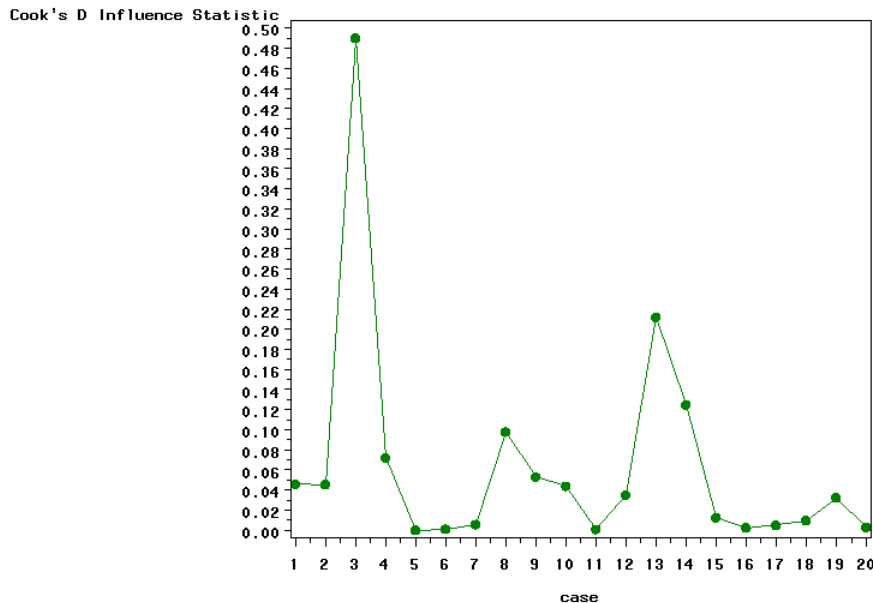
(If you specify model  $Y=X/r$  in the SAS proc reg procedure, Cook's distance will be printed out automatically.)

Look at **Figure 10.8**.



## Chapter 7: Body fat example

Index influence plot



### Influence on the regression coefficients - DFBETAS

Measures the influence of the  $i^{\text{th}}$  observation on each estimated regression coefficient,  $b_k$ .

Let  $b_{k(i)}$  be the estimate of  $\beta_k$  with the  $i^{\text{th}}$  observation removed from the data set, and  $c_{kk}$  be the  $k^{\text{th}}$  diagonal element of  $(\mathbf{X}'\mathbf{X})^{-1}$  (remember that  $\mathbf{X}$  is a  $n \times p$  matrix)

Then

$$(\text{DFBETAS})_{k(i)} = \frac{b_k - b_{k(i)}}{\sqrt{\text{MSE}_{(i)} c_{kk}}}$$

for  $k=1, \dots, p-1$

#### Notes:

1. Notice that DFBETAS is calculated for each  $\beta_k$  and each observation.
2. The variance of  $b_k$  is  $\sigma^2 c_{kk}$ . In this case,  $\sigma^2$  is estimated by  $\text{MSE}_{(i)}$ . Therefore, the denominator serves as a standardizing measure.

Guideline for determining influential observations:

- $|(\text{DFBETAS})_{k(i)}| > 1$  for “small to medium” sized data sets
- $|(\text{DFBETAS})_{k(i)}| > 2/\sqrt{n}$  for large data sets

## **Influence on inferences**

Examine the inferences from the estimated regression model with and without the observation(s) of concerned.

$$\text{Average absolute percent difference: } \frac{\sum_{j=1}^n \left| \frac{\hat{Y}_{j(i)} - \hat{Y}_j}{\hat{Y}_j} \right|}{n}$$

- If inferences are unchanged, remedial action is not necessary.
- If inferences are changed, remedial action is necessary.

### **R codes:**

```
Data <- read.table(file="C:// CH07TA01.txt", header=FALSE)
colnames(Data) <- c("X1", "X2", "X3", "Y")
fit <- lm(Y~X1+X2, data=Data)
rstudent(fit)                # studentized deleted residuals
influence.measures(fit)      # DFFITS, Cook's distance, DFBETAS
```

## **10.5 Multicollinearity diagnostics – variance inflation factor**

Chapter 7 discusses informal ways to detect multicollinearity and the results of multicollinearity. This section discusses a more formal measure of multicollinearity – the variance inflation factor (VIF).

**Problems** arise when predictor variables are highly correlated:

- 1) Adding or deleting a predictor variable changes the regression coefficients
- 2) The extra sum of squares associated with a predictor variable varies, depending upon which predictor variables are already included in the model
- 3) The estimated standard deviations of the regression coefficients become large
- 4) The estimated regression coefficients individually may not be statistically significant even though a definite statistical relation exists between the response variable and the set of predictor variables

**Informal Diagnostics:** indications of the presence of serious multicollinearity

- 1) Large changes in the estimated regression coefficients when a predictor variables is added or deleted
- 2) Nonsignificant results in individual tests on regression coefficients for important predictor variables
- 3) Estimated regression coefficients with an algebraic sign that is the opposite of that expected from theoretical considerations or prior experience
- 4) Large coefficients of simple correlation between pairs of predictor variables in the correlation matrix
- 5) Wide confidence intervals for the regression coefficients representing important predictor variables

## Variance Inflation factor

$$(VIF)_k = (1 - R_k^2)^{-1} \text{ for } k=1, \dots, p-1$$

Where  $R_k^2$  is the coefficient of multiple determination when  $X_k$  is regressed on the  $p-2$  other  $X$  variables in the model.

$R_k^2$  measures the relationship between  $X_k$  and the other independent variables.

If  $R_k^2$  is small (weak relationship) then  $(VIF)_k$  is small. For example, suppose  $R_k^2=0$ , then  $(VIF)_k=1$ . If  $R_k^2=0.5$ , then  $(VIF)_k=2$ .

If  $R_k^2$  is large (strong relationship) then  $(VIF)_k$  is large. For example, suppose  $R_k^2=0.9$ , then  $(VIF)_k=10$ . If  $R_k^2=0.99$ , then  $(VIF)_k=100$ .

A large  $(VIF)_k$  indicates the existence of multicollinearity.

$$(VIF)_k > 10$$

The mean of the VIF values: 
$$\overline{(VIF)} = \frac{\sum_{k=1}^{p-1} (VIF)_k}{p-1}.$$

Mean VIF values considerably larger than 10 are indicative of serious multicollinearity problems.

Example: Body fat example: The maximum of the VIF values is 708.84 and the mean value is 459.26. Thus the expected sum of the squared errors in the least squares standardized regression coefficients is nearly 460 times as large as it would be if the  $X$  variables are uncorrelated. These indicate there serious multicollinearity problems exist.

Variable	VIF
X1	708.84291
X2	564.34339
X3	104.60601

## 10.6 Surgical unit example

A hospital surgical unit was interested in predicting survival in patients undergoing a particular type of liver operation. A random selection of 108 patients was available for analysis. From each patient record, the following information was extracted from the pre-operation evaluation:

- $X_1$  blood clotting score
- $X_2$  prognostic index
- $X_3$  enzyme function test score
- $X_4$  liver function test score
- $X_5$  age in years
- $X_6$  indicator variable for gender (0=male, 1=female)
- $X_7$  and  $X_8$  indicator variable for history of alcohol use

Alcohol Use	$X_7$	$X_8$
None	0	0
Moderate	1	0
Severe	0	1

Use the first-order model with  $X_1$ ,  $X_2$ ,  $X_3$  and  $X_8$  based on Section 9.6.

R outputs and Figure 10.10

Questions:

- (1) Is there a multicollinearity among the four predictor variables?
- (2) Are there outlying Y observations?
- (3) Are there outlying X observations?
- (4) Are there influential cases? Check case 17.