Homework 2: Solving Eigenvalue

A. Rayleigh method

As one of the extensions of the Power method, the algorithm of Rayleigh method is based on the Power method. Here is the algorithm and pseudocode of the Power method.

```
Set eSheet = ThisWorkbook.Worksheets("Eigen")
Set eValep = eSheet.Range("B1") 'Convergence Criteria
Set eMatA = eSheet.Range("B2:K11") 'Matrix (Eigen values calculated)
Set eVecXD = eSheet.Range("M2:M11") 'Initial Vector
Set eVecXKD = eSheet.Range("M3:D22") 'Iteration Vector X(k)
Set eVecXkp = eSheet.Range("F13:F22") 'Iteration Vector X(k+1)
Set eValK = eSheet.Range("B13") 'Iteration count
Set eValJk = eSheet.Range("B13") 'Iteration count
Set eValK = eSheet.Range("B15") 'Value of maximum element in X(k)
Set eValRk = eSheet.Range("B16") 'Value of maximum element in X(k)
Set eValrkp = eSheet.Range("B16") 'Value of maximum element in X(k)
Set eValrkp = eSheet.Range("B16") 'Value of maximum element in X(k)

eValK.Value = 0
eValJk.Value = 0
eValJk.Value = eVecXO(eValJk.Value, 1) 'Get Elem No. of Maximun in XO
'Get its value
'Get its value
'Normalized XO -> X(k)

DO

eValRk.Value = eValrkp.Value
eValJk.Value = eValrkp.Value
eValJk.Value = eValrkp.Value
eValK.Value = eValrkp.Value 'r(k+1) -> r(k)
'A*X(k) -> X(k+1)
eValJk.Value = eValrkp.Value, 1).Value
eValK.Value = eValrkp.Value + 1
Call copyMatDivByValue(eVecXkp, eVecXk, eValrkp.Value)
'Counter Increment
'Axik' -> X(k)
'Check Convergence
```

```
Propose there are n independent eigenvector V and eigenvalue \lambda in matrix A Set |\lambda_1| > |\lambda_2| > \ldots > |\lambda_n| Loop X(k) = X(0)/\text{Max}[X(0)] X(k+1) = A * X(k) R(k) = \max[X(k+1)]/\max[X(k)] X(k+1) = X(k+1)/\max[X(k+1)] k = k+1 Until |R(k+1) - R(k)| < \epsilon * |R(k)| We obtain the eigenvector V(i) and eigenvalue X(i)
```

The difference between the Power method and the Rayleigh method is that the Rayleigh method replaces the maximum value of X(i) with its norm value.

$$R(X) = \frac{X^{T}AX}{X^{T}X}$$

$$Norm[X(i)] = ||X(i)||$$

Here is the algorithm and pseudocode of the Rayleigh method.

```
Sub Rayleigh()

Set eSheet = ThisWorkbook.Worksheets("Eigen")
Set eValep = eSheet.Range("B1") 'Convergence Criteria
Set eMatA = eSheet.Range("B2:K11") 'Matrix (Eigen values calculated)|
Set eVecXD = eSheet.Range("M2:M11") 'Initial Vector
Set eVecXk = eSheet.Range("F13:F22") 'Iteration Vector X(k)
Set eVexKp = eSheet.Range("F13:F22") 'Iteration Vector X(k+1)
Set eValK = eSheet.Range("F13") 'Iteration Vector X(k+1)
Set eValK = eSheet.Range("B13") 'Iteration Vector X(k+1)
Set eValK = eSheet.Range("B14") 'Element No. of maximum in X(k)
Set eValRk = eSheet.Range("B16") 'Value of Rayleigh in X(k)
Set eValrkp = eSheet.Range("B16") 'Value of Rayleigh in X(k+1)

'write codes here

eValK.Value = 0
eValRk.Value = GetEuclidNorm(eVecXO)
Call copyMatDivByValue(eVecXD, eVecXk, eValrkp.Value) 'Counter Initalize 'GetEucridNorm ||XD|| of XO 'Normalized XO -> X(k)

Do

eValRk.Value = eValrkp.Value 'r(k+1) -> r(k)
Call matVecMult(eMatA, eVecXk, eVecXkp) 'A*X(k) -> X(k+1)
eValK.Value = eValrk.Value + 1
Call copyMatDivByValue(eVecXp, eVecXk, GetEuclidNorm(eVecXp)) 'Avalue '(X(k),X(k+1)) -> r(k+1)
call copyMatDivByValue(eVecXkp, eVecXk, GetEuclidNorm(eVecXkp)) 'Normalized X(k+1) -> X(k)
diff = Abs(eValrp.Value + eValRk.Value)

Loop While diff > Abs(eValep.Value * eValRk.Value)
```

Propose there are n independent eigenvector V and eigenvalue λ in matrix ALoop $X(k) = X(0)/\mathrm{Norm}[X(0)] \\ X(k+1) = A*X(k) \\ R(k+1) = X(k)^T*X(k+1) \\ X(k+1) = X(k+1)/\mathrm{Norm}[X(k+1)] \\ k = k+1$ Until $|R(k+1) - R(k)| < \epsilon * |R(k)|$

B. Inverse iteration method

End Sub

As the stated above, the power method use the maximum value of X(i) to calculate the eigenvector V(i) and eigenvalue X(i). However, the inverse iteration method tries to use its non-zero minimum value instead of the maximum one.

We obtain the eigenvector V(i) and eigenvalue X(i)

So we can also use the algorithm of the power method but with $(A - \sigma I)^{-1}$ not A and what we get is $1/(\lambda - \sigma)$ not λ . As for the calculation of $(A - \sigma I)^{-1}$, the LU Decomposition method will be used.

According to calculation, we get 2.34×10^{-7} with $\sigma = 0$, 0.99 with $\sigma = 1$ and 2.56 with $\sigma = 2$.

Here is the algorithm and pseudocode of the Inverse iteration method.

```
Sub Rayleigh_Inverse()

Call LUDecomposition

Set eSheet = ThisWorkbook.Worksheets("Eigen")
Set eValep = eSheet.Range("B1") 'Convergence Criteria
Set eVecXD = eSheet.Range("M29:M38") 'Initial Vector
Set eVecXk = eSheet.Range("F52:D61") 'Iteration Vector X(k)
Set eVetXk = eSheet.Range("F52:F61") 'Iteration Count
Set eVetAlfK = eSheet.Range("B54") 'Iteration Count
Set eValfK = eSheet.Range("B54") 'Eucrid Norm of X(k)
Set eValfK = eSheet.Range("B54") 'Eucrid Norm of X(k)
Set eValfk = eSheet.Range("B54") 'Eucrid Norm of X(k)

Set eValfk.Value = 0 'Counter initalize

'write codes here

eValfk.Value = GetEuclidNorm(eVecXD)
Call copyMatDivByValue(eVecXO, eVecXk, eValfkp.Value) 'GetEucridNorm ||XO|| of XO
Normalized XO -> X(k)

Do

eValfk.Value = eValfkp.Value
Call ForwardSubstitution
Call BackwardSubstitution
eValfkp.Value = GetInnerProduct(eVecXk, eVecXkp)
eValfk.Value = eValfk.Value + 1
Call copyMatDivByValue(eVecXkp, eVecXk, GetEuclidNorm(eVecXkp))
diff = Abs(eValfkp.Value - eValfk.Value)

Loop While diff > Abs(eValep.Value * eValfk.Value)

End Sub
```

```
Propose there are n independent eigenvector V and eigenvalue \lambda in matrix A
Loop X(k) = X(0)/\text{Norm}[X(0)]
X(k) = A * X(k+1) \text{ with LU decomposition}
/Y(k+1) = L * X(k+1) /
/X(k) = U * Y(k+1) /
X(k+1) = A * X(k)
R(k+1) = X(k)^T * X(k+1)
X(k+1) = X(k+1)/\text{Norm}[X(k+1)]
k = k+1
Until |R(k+1) - R(k)| < \epsilon * |R(k)|
We obtain the eigenvector V(i) and eigenvalue X(i)
```

The advantage of inverse iteration combined with σ over the Rayleigh method is the ability to converge to any desired eigenvalue. By choosing a σ close to a desired eigenvalue, inverse iteration can converge very quickly. As the stated above, the inverse iteration method can traversal the different σ to search the eigenvalue one by one.

C. Jacobi method

The final method is the Jacobi method, which can calculate all the

eigenvector V(i) and eigenvalue X(i) simutanously. The basic idea of this method is to diagonal the matrix A with its congruence transformation and those elements located at the diagonal line is the eigenvalue X(i) in need.

$$A(k + 1) = Q^{T}(k) * A(k) * Q(k)$$

 $V = \{Q_{1}, Q_{2} ... Q_{n}\}$

Here is the algorithm and pseudocode of the Inverse Jacobi method.

```
Sub EigenJacobi()

        Set eSheet = ThisWorkbook.Worksheets("Jacobi")

        Set eValep = eSheet.Range("B1")
        'Conver,

        Set eMatA = eSheet.Range("B18:K27")
        'Matrix

        Set eMatAk = eSheet.Range("B18:K27")
        'Matrix

        Set eMatVk = eSheet.Range("B29:K38")
        'Eigen 'Set eValK = eSheet.Range("B13")
        'Iterat

        Set eValI = eSheet.Range("B14")
        'Row of

        Set eValJ = eSheet.Range("B15")
        'Column

                                                                                                            acobr)
'Convergence Criteria
'Matrix (Eigen values calculated)
'Matrix (for iteration)
'Eigen Vector Matrix
'Iteration count
                                                                                                            'Row of maximum element aij i<j
'Column no of aij
            Call copyMat(eMatA, eMatAk)
Call GenerateUnitMatrix(eMatVk)
eValK.Value = 0
                                                                                                           'initalize A(k)
                                                                                                           'initalize V(k)
'counter initalize
            'write codes here
            Dn
                                                                                                                                                                      'Find Posi of Maximun in A
'Remeber in J
'Remeber in I
'Check Convergence
                    Call FindAbsMaxMat(eMatAk, posi, posj)
                   eValJ.Value = posi
eValJ.Value = posi
If (Abs(eMatAk(eValI, eValJ)) < eValep) Then Exit Do
                   Call CalcQtAkQ(eMatAk, cos1, sin1, eValI, eValJ)
Call CalcVQ(eMatVk, cos1, sin1, eValI, eValJ)
                                                                                                                                                                        'QT * A * Q -> A
'QT * V -> V
            Loop
End Sub
```

Propose there are n independent eigenvector V and eigenvalue λ in matrix A

Loop
$$a(i,j) = Max[A(k,l)|k \neq l]$$

$$\tan 2\theta = -\frac{2a(i,j)}{a(i,i) - a(j,j)}$$

$$\cos 2\theta = \frac{1}{\sqrt{1 + (\tan 2\theta)^2}}$$

$$\sin 2\theta = \frac{\tan 2\theta}{\sqrt{1 + (\tan 2\theta)^2}}$$

$$\cos \theta = \sqrt{(1 + \cos 2\theta)/2}$$

$$\sin \theta = \cos \theta * \tan \theta$$

$$Q = \{I \mid [I(i,i) = \cos \theta][I(i,j) = \sin \theta][I(j,i) = -\sin \theta][I(j,j) = \cos \theta]\}$$

$$A(k+1) = Q^T(k) * A(k) * Q(k)$$

$$V(k+1) = V(k) * Q(k)$$

Until $|a(i,j)| < \epsilon$

We obtain the eigenvector V(i) and eigenvalue X(i)