

# Runge - Lenz vector (elementary knowledge).

①

## ① Classic Kepler problem

$$H = \frac{p^2}{2m} - \frac{k}{r}$$

obviously  $\dot{\vec{L}} = \dot{\vec{r}} \times \vec{p} + \vec{r} \times \dot{\vec{p}} = 0$  for central force fields.

$$\text{how about } \frac{d}{dt}(\vec{p} \times \vec{L}) = \dot{\vec{p}} \times \vec{L} + \vec{p} \times \dot{\vec{L}}$$

$$\dot{\vec{p}} \times \vec{L} = -\frac{k}{r^2} \hat{r} \times (\vec{r} \times m \dot{\vec{r}}) = -\frac{k}{r^2} m [\vec{r}(\hat{r} \cdot \dot{\vec{r}}) - \hat{r} \cdot \vec{r} \dot{\vec{r}}]$$

$$= -\frac{k}{r^3} m [\vec{r}(\vec{r} \cdot \dot{\vec{r}}) - r^2 \dot{\vec{r}}] \leftarrow \vec{r} \dot{\vec{r}} = r \dot{\vec{r}}$$

$$= -k m \left[ \frac{\vec{r} \dot{r}}{r^2} - \frac{\dot{\vec{r}}}{r} \right]$$

$$\Rightarrow \frac{d}{dt}(\vec{p} \times \vec{L}) = +km \left[ -\frac{\vec{r} \dot{r}}{r^2} + \frac{\dot{\vec{r}}}{r} \right] = km \frac{d}{dt} \left[ \frac{\vec{r}}{r} \right]$$

$$\text{define } \vec{A} = \vec{p} \times \vec{L} - mk \frac{\vec{r}}{r} \Rightarrow \frac{d}{dt} \vec{A} = 0. \quad \vec{A}: \text{Runge-Lenz vector.}$$

what's the direction of  $\vec{A}$ ?

$$\vec{A} \cdot \vec{L} = (\vec{p} \times \vec{L}) \cdot \vec{L} - mk \frac{\vec{r}}{r} \cdot (\vec{r} \times \vec{p}) = 0,$$

thus  $\vec{A}$  lies in the orbital plane.

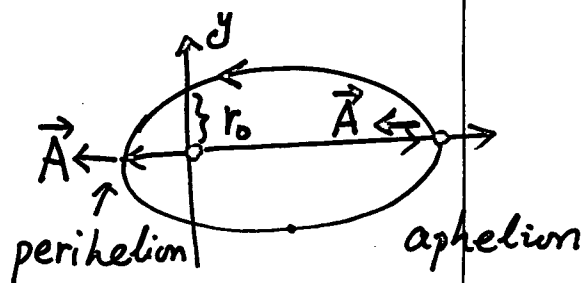
check at perihelion:

$$\vec{p} = -p \hat{y}, \quad \vec{L} = L \hat{z}$$

$$\vec{p} \times \vec{L} = -pL \hat{x}$$

$$\text{and } r = \frac{r_0}{1 - e \cos \theta}$$

Kepler's problem:



$$r_0 = \frac{L^2}{mk}$$

$$e = \sqrt{1 + \frac{2EL^2}{mk^2}} = \sqrt{1 + \frac{2E}{k/r_0}}$$

$$p \cdot \frac{r_0}{1+e} = l \Rightarrow p \cdot l = \frac{l^2(1+e)}{r_0} = mk(1+e)$$

$$\Rightarrow \vec{A} = -pl \hat{x} + \frac{\hat{x}}{mk} [-mk(1+e) + mk] \hat{x} = -mke \hat{x}$$

A's magnitude is  $\propto$  eccentricity; its direction points along to the perihelion.

Let's check  $\vec{A} \cdot \vec{r} = -A \cos \theta = \vec{r} \cdot (\vec{\omega} \times \vec{L}) - mkr$

$$\vec{r} \cdot (\vec{\omega} \times \vec{L}) = \vec{L} \cdot (\vec{r} \times \vec{p}) = l^2$$

$$\Rightarrow -A \cos \theta = l^2 - mkr \Rightarrow r = \frac{l^2}{mk - A \cos \theta} = \frac{l^2/mk}{1 - \frac{A}{mk} \cos \theta}$$

Solution to Kepler problem using R-L vector

Compare  $e = \sqrt{1 + \frac{2El^2}{mk^2}} = \frac{A}{mk} \Rightarrow \frac{A^2}{m^2 k^2} = 1 + \frac{2El^2}{m^2 k^2}$

once  $E, \vec{L}$  are determined,  $|A|$ , and  $\vec{A} \perp \vec{L}$  are decided, there's only one more angle to determine the direction of  $\vec{A}$ . Once this is determined, the orbit is determined.

Count degree of freedom:  $E, \vec{L} : 4$

direction of  $\vec{A} : 1 \leftarrow \begin{cases} \vec{A} \cdot \vec{L} = 0 \\ A^2 = m^2 k^2 + 2El^2 \end{cases}$

initial condition: 1

6 (complete!)

## 2. 2D Quantum mechanics Kepler problem

$$\vec{A} = \frac{1}{2mk} (\vec{p} \times \vec{r} - \vec{r} \times \vec{p}) - \hat{e}_r \quad (\text{a different normalization})$$

$$\text{in 2D: } A_x = \frac{1}{2mk} (p_y l_z + l_z p_y) - \hat{e}_{rx}, \quad A_y = \frac{1}{2mk} (p_x l_z + l_z p_x) - \hat{e}_{ry}$$

$$\Rightarrow A_x = \frac{1}{mk} l_z p_y + \frac{i\hbar}{2mk} p_x - \frac{x}{r}; \quad A_y = -\frac{1}{mk} l_z p_x + \frac{i\hbar}{2mk} p_y - \frac{y}{r}$$

$A_x, y$  are Hermitian, but  $l_z p_y$  and  $l_z p_x$  are not. Thus  $\frac{i\hbar}{2mk} \vec{p}$  comes to compensate.

\* Check  $[l_z, A_x] = i\hbar A_y$  and  $[l_z, A_y] = -i\hbar A_x$

$$\begin{aligned} [l_z, A_x] &= \frac{1}{mk} [l_z, l_z p_y] + \frac{i\hbar}{2mk} [l_z, p_x] - [l_z, \frac{x}{r}] \\ &= \frac{1}{mk} l_z (-i\hbar p_x) + \frac{i\hbar}{2mk} (i\hbar p_y) - i\hbar \frac{y}{r} = i\hbar A_y \end{aligned}$$

the other one can be proved similarly.

\* Check  $[A_x, A_y] = -\frac{2\hbar}{mk^2} i\hbar l_z$

$$\begin{aligned} [A_x, A_y] &= -\frac{1}{(mk)^2} [l_z p_y, l_z p_x] + \frac{i\hbar}{2(mk)^2} \{ [l_z p_y, p_y] + [l_z p_x, p_x] \} \\ &\quad - \frac{i\hbar}{2mk} \{ [p_x, \frac{y}{r}] - [p_y, \frac{x}{r}] \} - \frac{1}{mk} \{ [l_z p_y, \frac{y}{r}] + [l_z p_x, \frac{x}{r}] \} \end{aligned}$$

$$\begin{aligned} [l_z p_y, l_z p_x] &= l_z [p_y, l_z p_x] + [l_z, l_z p_x] p_y = l_z [p_y, l_z] p_x + l_z [l_z, p_x] p_y \\ &= l_z (i\hbar) p_x^2 + i\hbar l_z p_y^2 = i\hbar l_z p^2 \end{aligned}$$

$$[l_z p_y, p_y] = p_y [l_z, p_y] = -i\hbar p_y p_x, \quad [l_z p_x, p_x] = p_x [l_z, p_x] = i\hbar p_x p_y \xrightarrow{\text{add together.}} 0$$

$$[p_x, \frac{y}{r}] = -i\hbar y \partial_x \frac{1}{r} = i\hbar \frac{xy}{r^3}, \quad [p_y, \frac{x}{r}] = -i\hbar x \partial_y \frac{1}{r} = -i\hbar \frac{xy}{r^3}$$

add together  $\rightarrow 0$

$$[L_z P_y, \frac{y}{r}] = L_z [P_y, \frac{y}{r}] + [L_z, \frac{y}{r}] P_y = L_z (-i\hbar) P_y \frac{y}{r} - i\hbar \frac{x}{r} P_y$$

$$P_y \frac{y}{r} = \frac{1}{r} - \frac{y^2}{r^3} \rightarrow = (-i\hbar) L_z \left( \frac{1}{r} - \frac{y^2}{r^3} \right) - i\hbar \frac{x}{r} P_y$$

$$[L_z P_x, \frac{x}{r}] = -i\hbar L_z \left( \frac{1}{r} - \frac{x^2}{r^3} \right) - i\hbar \frac{y}{r} P_x$$

$$\text{add together} \Rightarrow -i\hbar L_z \left( \frac{2}{r} - \frac{1}{r} \right) - i\hbar \frac{1}{r} L_z = -2i\hbar L_z \frac{1}{r}$$

$$\begin{aligned} \text{organize everything} \Rightarrow [A_x, A_y] &= -\frac{1}{(mk)^2} i\hbar L_z p^2 + \frac{1}{mk} i\hbar L_z \frac{2}{r} \\ &= \frac{-2}{mk^2} \left[ \frac{p^2}{2m} - \frac{\hbar}{r} \right] L_z i\hbar = -\frac{2\hbar}{mk^2} i\hbar L_z \end{aligned}$$

\* Next prove  $[A_x, H] = [A_y, H] = 0.$

$$[A_x, H] = \frac{1}{2m} [A_x, p^2] - \hbar [A_x, \frac{1}{r}]$$

$$\text{we need } [\vec{p}, \frac{1}{r}] = -i\hbar \nabla \frac{1}{r} = +i\hbar \frac{\vec{r}}{r^3},$$

$$\nabla \cdot \left( \frac{\vec{r}}{r^3} \right) = \frac{1}{r^3} \nabla \cdot \vec{r} + \nabla \left( \frac{1}{r^3} \right) \cdot \vec{r} = \frac{2}{r^3} + \frac{-3\vec{r} \cdot \vec{r}}{r^5} = -\frac{1}{r^3}$$

$$[A_x, p^2] = \frac{1}{mk} [L_z P_y, p^2] - \left[ \frac{x}{r}, p^2 \right] = [p^2, \frac{x}{r}]$$

$$[p^2, \frac{x}{r}] = \overset{\uparrow}{0} x [p^2, \frac{1}{r}] + [p^2, x] \frac{1}{r} = x \vec{p} [\vec{p}, \frac{1}{r}] + x [\vec{p}, \frac{1}{r}] \vec{p} + \vec{p} [\vec{p} x] \frac{1}{r} + [\vec{p}, x] \vec{p} \frac{1}{r}$$

$$= x i\hbar \left[ \frac{\vec{p} \cdot \vec{r}}{r^3} + \frac{\vec{r}}{r^3} \cdot \vec{p} \right] - 2i\hbar P_x \frac{1}{r}$$

$$= 2i\hbar x \frac{\vec{r}}{r^3} \cdot \vec{p} + x i\hbar (-i\hbar) \left( \frac{-1}{r^3} \right) - 2i\hbar (-i\hbar) \frac{-x}{r^3} - 2i\hbar \frac{1}{r} P_x$$

$$= 2i\hbar x \left[ -\frac{1}{r} P_x + \frac{x}{r^3} \vec{r} \cdot \vec{p} \right] + \frac{\hbar^2 x}{r^3} = [A_x, p^2]$$

(5)

$$[A_x, \frac{k}{r}] = \frac{1}{m} [l_z p_y, \frac{1}{r}] + \frac{i\hbar}{2m} [p_x, \frac{1}{r}]$$

$$= \frac{1}{m} l_z [p_y, \frac{1}{r}] + \frac{i\hbar}{2m} [p_x, \frac{1}{r}] = \frac{1}{m} l_z (-i\hbar) \partial_y \frac{1}{r} + \frac{i\hbar}{2m} (-i\hbar) \partial_x \frac{1}{r}$$

$$= \frac{1}{m} l_z (-i\hbar) \frac{-y}{r^3} - \frac{\hbar^2}{2m} \frac{x}{r^3} = +\frac{i\hbar}{m} \left( \frac{y}{r^3} l_z + [l_z, y] \right) - \frac{\hbar^2}{2m} \frac{x}{r^3}$$

||  
-i\hbar x

$$= \frac{i\hbar}{m} \frac{1}{r^3} [y(x p_y - y p_x)] + \frac{\hbar^2}{2m} \frac{x}{r^3}$$

$$= \frac{\hbar^2}{m} \frac{x}{r^3} (x \partial_x + y \partial_y) - \frac{\hbar^2}{m} \frac{1}{r^3} (x^2 + y^2) \partial_x + \frac{\hbar^2}{2m} \frac{x}{r^3}$$

$$[A_x, \frac{k}{r}] = \frac{i\hbar^2}{m} \left[ \frac{x}{r^3} (\vec{r} \cdot \vec{p}) - \frac{1}{r} p_x \right] + \frac{\hbar^2}{2m} \frac{x}{r^3}$$

add together  $\Rightarrow [A_x, H] = 0$ , and similarly  $[A_y, H] = 0$ .

$\left\{ \sqrt{\frac{-mk^2}{2E}} A_x, \sqrt{\frac{-mk^2}{2E}} A_y, l_z \right\}$  form an  $SU(2)$  algebra.

⊛ Calculate Casimir

$$A_x^2 + A_y^2 = \left( \frac{1}{mk} l_z p_y + \frac{i\hbar}{2mk} p_x - \frac{x}{r} \right)^2 + \left( \frac{-1}{mk} l_z p_x + \frac{i\hbar}{2mk} p_y - \frac{y}{r} \right)^2$$

$$= \frac{1}{m^2 k^2} l_z^2 p^2 - \frac{\hbar^2}{4mk^2} p^2 + 1 + \frac{i\hbar}{2(mk)^2} [l_z p_y p_x + p_x l_z p_y - l_z p_x p_y - p_y l_z p_x]$$

$$- \frac{1}{mk} \left( l_z p_y \frac{x}{r} - l_z p_x \frac{y}{r} + \frac{x}{r} l_z p_y - \frac{y}{r} l_z p_x \right)$$

$$- \frac{i\hbar}{2mk} \left( p_x \frac{x}{r} + p_y \frac{y}{r} + \frac{x}{r} p_x + \frac{y}{r} p_y \right)$$

$$l_z p_y l_z p_y + l_z p_x l_z p_x = l_z^2 (p_y^2 + p_x^2) + \underbrace{l_z [p_y l_z] p_y + l_z [p_x l_z] p_x}_{\text{add to 0}} = l_z^2 p^2$$

add to 0.

(6)

$$P_x L_z P_y - P_y L_z P_x = L_z P_x P_y - L_z P_y P_x + [P_x L_z] P_y - [P_y L_z] P_x$$

$$= 0 - i\hbar P_y^2 - i\hbar P_x^2 = -i\hbar P^2$$

$$\therefore P^2 \text{ related terms } \frac{P^2}{m} \left[ \frac{1}{mk^2} \right] \left( L_z^2 - \frac{\hbar^2}{4} + \frac{\hbar^2}{2} \right) = \frac{P^2}{m} \frac{1}{mk^2} \left( L_z^2 + \frac{\hbar^2}{4} \right)$$

$$L_z P_y \frac{x}{r} - L_z P_x \frac{y}{r} + \frac{x}{r} L_z P_y - \frac{y}{r} L_z P_x$$

$$= L_z [x P_y - y P_x] \frac{1}{r} + \frac{1}{r} L_z [x P_y - y P_x] + \frac{1}{r} [x L_z] P_y - \frac{1}{r} [y L_z] P_x$$

$$= \frac{2}{r} L_z^2 + \frac{1}{r} (-i\hbar) y P_y + \frac{1}{r} (i\hbar) x P_x = \frac{2}{r} L_z^2 - i\hbar \frac{1}{r} \vec{r} \cdot \vec{p}$$

$$P_x \left( \frac{x}{r} \right) + P_y \left( \frac{y}{r} \right) + \frac{x}{r} P_x + \frac{y}{r} P_y = 2 \frac{1}{r} \vec{r} \cdot \vec{p} - i\hbar \partial_x \left( \frac{x}{r} \right) - i\hbar \partial_y \left( \frac{y}{r} \right)$$

$$\partial_x \left( \frac{x}{r} \right) = \frac{1}{r} + \frac{x(-x)}{r^3} \Rightarrow -i\hbar \partial_x \left( \frac{x}{r} \right) - i\hbar \partial_y \left( \frac{y}{r} \right) = -i\hbar \left( \frac{2}{r} - \frac{1}{r} \right) = -\frac{i\hbar}{r}$$

put together  $\frac{1}{r}$  - related terms are

$$- \frac{1}{mk} \left[ \frac{2}{r} L_z^2 - i\hbar \frac{1}{r} \vec{r} \cdot \vec{p} \right] - \frac{i\hbar}{2mk} \left[ 2 \frac{1}{r} \vec{r} \cdot \vec{p} - \frac{i\hbar}{r} \right]$$

$$= \frac{2}{mk^2} \frac{(-\hbar)}{r} \left[ L_z^2 + \frac{\hbar^2}{4} \right]$$

$$\Rightarrow \boxed{A_x^2 + A_y^2 = \frac{2H}{mk^2} \left( L_z^2 + \frac{\hbar^2}{4} \right) + 1}$$

The normalized Casimir is: (replace H with eigenvalue E).

$$\left( \sqrt{\frac{-mk^2}{2E}} \right)^2 A_x^2 + \left( \sqrt{\frac{-mk^2}{2E}} \right)^2 A_y^2 + L_z^2 = \frac{-mk^2}{2E} - \frac{\hbar^2}{4} \quad (L_z^2 \text{ term cancels})$$

because  $L_z$  is orbital

angular momentum  $\Rightarrow L$  can only be integer

$$= \underset{\substack{\uparrow \\ \text{SU(2) quantum number}}}{L(L+1)} \hbar^2 \quad (L=0, 1, 2, \dots)$$

$$\Rightarrow \frac{-mk^2}{2E} = \hbar^2 \left(L + \frac{1}{2}\right)^2 \Rightarrow E = \frac{\hbar^2 k^2}{2(L + \frac{1}{2})^2} \quad (L=0,1,2,\dots)$$

The corresponding  $J_{\pm}$  operator

$$J_{\pm} = \sqrt{\frac{-mk^2}{2E}} (A_x \pm iA_y) = \hbar(L + \frac{1}{2}) (A_x \pm iA_y)$$

$$J_{\pm} |E, m\rangle = \hbar \sqrt{(L \mp m)(L \pm m + 1)} |E, m \pm 1\rangle$$

$$\Rightarrow (A_x \pm iA_y) |E(L), m\rangle = \frac{1}{L + \frac{1}{2}} \sqrt{(L \mp m)(L \pm m + 1)} |E, m \pm 1\rangle$$

$$L_z |E, m\rangle = m\hbar |E, m\rangle$$

3. 3D case  $H = \frac{p^2}{2m} - \frac{k}{r}$

①  $\vec{A} = \frac{1}{2mk} (\vec{p} \times \vec{L} - \vec{L} \times \vec{p}) - \hat{e}_r$

$$A_x = \frac{1}{2mk} (p_y L_z - p_x L_y + L_z p_y - L_y p_x) - \hat{e}_{r,x} = \frac{1}{mk} p_y L_z - \frac{i\hbar}{mk} p_x - \frac{x}{r}$$

$$\Rightarrow \vec{A} = \frac{1}{mk} (\vec{p} \times \vec{L} - i\hbar \vec{p}) - \hat{e}_r$$

$$\begin{aligned} \vec{p} \times \vec{L} &= \vec{p} \times (\vec{r} \times \vec{p}) = p_x \vec{r} p_x + p_y \vec{r} p_y + p_z \vec{r} p_z - (\vec{p} \cdot \vec{r}) \vec{p} \\ &= p_x (p_x \vec{r} + i\hbar \hat{x}) + \dots - (\vec{p} \cdot \vec{r}) \vec{p} \\ &= p^2 \vec{r} + i\hbar \vec{p} - (\vec{p} \cdot \vec{r}) \vec{p} \end{aligned}$$

$$\Rightarrow \boxed{\vec{A} = \frac{1}{mk} (p^2 \vec{r} - (\vec{p} \cdot \vec{r}) \vec{p}) - \vec{r}/r}$$

② Prove  $\vec{A} \times \vec{A} = -\frac{2i\hbar}{mk^2} H \vec{L}$

$$mk^2 \vec{A} \times \vec{A} = (p^2 \vec{r} - (\vec{p} \cdot \vec{r}) \vec{p} - mk \vec{r}/r) \times (p^2 \vec{r} - (\vec{p} \cdot \vec{r}) \vec{p} - mk \vec{r}/r)$$

The trick is to move the second expression:  $p^2 \vec{r} \rightarrow \vec{r} p^2$  and so on.

$$\begin{aligned} p^2 \vec{r} &= p_i \vec{r} p_i + p_i [p_i \vec{r}] = p_i \vec{r} p_i + \vec{r} (-i\hbar) = \vec{r} p^2 + [p_i \vec{r}] p_i - (i\hbar) \vec{p} \\ &= \vec{r} p^2 - 2i\hbar \vec{p} \end{aligned}$$

$$(\vec{p} \cdot \vec{r}) \vec{p} = p_i r_i p_j = p_i p_j r_i + p_i [r_i p_j] = p_i p_j r_i + i\hbar p_j = \vec{p} (\vec{p} \cdot \vec{r}) + i\hbar \vec{p}$$

$$\Rightarrow \vec{A} \times \vec{A} mk^2 = (p^2 \vec{r} - (\vec{p} \cdot \vec{r}) \vec{p} - mk \vec{r}/r) \times (\vec{r} p^2 - 3i\hbar \vec{p} - \vec{p} (\vec{p} \cdot \vec{r}) - mk \vec{r}/r)$$

$$p^2 \vec{r} \times \vec{r} p^2 = (\vec{p} \cdot \vec{r}) \vec{p} \times \vec{p} (\vec{p} \cdot \vec{r}) = mk \frac{\vec{r}}{r} \times \frac{\vec{r}}{r} = 0$$



$$\Rightarrow m^2 k^2 \vec{A} \times \vec{A} = p^2 (-3i\hbar) \vec{r} \times \vec{p} - p^2 (\vec{r} \times \vec{p}) (\vec{p} \cdot \vec{r})$$

$$- (\vec{p} \cdot \vec{r}) (\vec{p} \times \vec{r}) p^2 + (\vec{p} \cdot \vec{r}) (\vec{p} \times \vec{r}/r) (mk) - mk \frac{\vec{r}}{r} \times (-3i\hbar \vec{p})$$

$$+ mk (\frac{\vec{r}}{r} \times \vec{p}) (\vec{p} \cdot \vec{r})$$

$$= -3i\hbar p^2 \vec{L} - p^2 (\vec{p} \cdot \vec{r}) \vec{L} + (\vec{p} \cdot \vec{r}) \vec{L} p^2 - mk (\vec{p} \cdot \vec{r}) \frac{1}{r} \vec{L} + 3i\hbar mk \frac{1}{r} \vec{L}$$

$$+ mk \frac{1}{r} (\vec{p} \cdot \vec{r}) \vec{L}$$

$$= (-3i\hbar p^2 + [\vec{p} \cdot \vec{r}, p^2] - mk [\vec{p} \cdot \vec{r}, \frac{1}{r}] + \frac{3i\hbar mk}{r}) \vec{L}$$

( $\vec{L}$  commutes with all rotation invariant operators)

$$[\vec{p} \cdot \vec{r}, p^2] = [p_i r_i, p_j p_j] = p_i [r_i p_j p_j] = p_i p_j [r_i p_j] + p_i [r_i p_j] p_j$$

$$= +i\hbar 2 p^2$$

$$[\vec{p} \cdot \vec{r}, \frac{1}{r}] = [p_i r_i, \frac{1}{r}] = [p_i \frac{1}{r}] r_i = -i\hbar \frac{-\vec{r} \cdot \vec{r}}{r^3} = i\hbar \frac{1}{r}$$

$$\Rightarrow m^2 k^2 \vec{A} \times \vec{A} = (-3i\hbar p^2 + 2i\hbar p^2 - i\hbar \frac{mk}{r} + \frac{3i\hbar mk}{r}) \vec{L}$$

$$= -i\hbar \left[ \frac{p^2}{2m} - \frac{k}{r} \right] \cdot 2m \vec{L} = -2i\hbar m H \vec{L}$$

$$\Rightarrow \boxed{\vec{A} \times \vec{A} = -\frac{2i\hbar}{mk^2} H \vec{L}}$$

③ Prove  $\boxed{[L_i, A_j] = i\epsilon_{ijk} A_k \hbar}$

This is obvious because  $A$  is defined in a 3-vector form,

under spatial rotation  $A$  transforms like a vector.

form  $SO(4)$  algebra.

This means  $L_{12} = L_z, L_{23} = L_x, L_{31} = L_y$  and

$$\boxed{L_{14} = \sqrt{\frac{-mk^2}{2E}} A_x, L_{24} = \sqrt{\frac{-mk^2}{2E}} A_y, L_{34} = \sqrt{\frac{-mk^2}{2E}} A_z}$$

④ prove  $[\vec{A}, H] = 0$

$$\vec{A} = \frac{1}{mk} (\vec{p} \times \vec{L} - i\hbar \vec{p}) - \frac{\vec{r}}{r}$$

$$[\vec{A}, p^2] = \frac{1}{2mk} [\vec{p} \times \vec{L} - \vec{L} \times \vec{p}, p^2] - [\frac{\vec{r}}{r}, p^2]$$

This first term is 0 because  $[\vec{L}, p^2] = 0$ .

$$[p^2, \frac{\vec{r}}{r}] = \vec{r} [p^2, \frac{1}{r}] + [p^2, \vec{r}] \frac{1}{r}$$

$$[p^2, \frac{1}{r}] = 2i\hbar \frac{\vec{r} \cdot \vec{p}}{r^3} + \hbar^2 \nabla \cdot (\frac{\vec{r}}{r^3}) = 2i\hbar \frac{\vec{r} \cdot \vec{p}}{r^3} + 4\pi\hbar^2 \delta^{(3)}(\vec{r})$$

$$\Rightarrow \vec{r} [p^2, \frac{1}{r}] = 2i\hbar \frac{\vec{r}}{r^3} \vec{r} \cdot \vec{p} + 4\pi\hbar^2 \vec{r} \delta^{(3)}(\vec{r}) \rightarrow 0$$

$$[p^2, \vec{r}] = -2i\hbar \vec{p}, \quad [p^2, \vec{r}] \frac{1}{r} = -\frac{2i\hbar}{r} \vec{p} + 2\hbar^2 \frac{\vec{r}}{r^3}$$

$$\Rightarrow [p^2, \frac{\vec{r}}{r}] = 2i\hbar [-\frac{1}{r} \vec{p} + \frac{\vec{r}}{r^3} \vec{r} \cdot \vec{p}] + 2\hbar^2 \frac{\vec{r}}{r^3} = [\vec{A}, p^2]$$

\*\*

$$[\vec{A}, \frac{1}{r}] = \frac{1}{mk} [\vec{p} \times \vec{L} - i\hbar \vec{p}, \frac{1}{r}]$$

$$[\vec{p} \times \vec{L}, \frac{1}{r}] = \vec{p} \times [\vec{L}, \frac{1}{r}] + [\vec{p}, \frac{1}{r}] \times \vec{L} = [\vec{p}, \frac{1}{r}] \times \vec{L}$$

$$[\vec{p}, \frac{1}{r}] = i\hbar \frac{\vec{r}}{r^3}$$

$$\Rightarrow [\vec{A}, \frac{1}{r}] = \frac{1}{mk} i\hbar \frac{1}{r^3} \vec{r} \times (\vec{r} \times \vec{p}) - \frac{i\hbar}{mk} (i\hbar) \frac{\vec{r}}{r^3}$$

$$\begin{aligned} \vec{r} \times (\vec{r} \times \vec{p}) &= r_x \vec{r} p_x + r_y \vec{r} p_y + r_z \vec{r} p_z - (\vec{r} \cdot \vec{r}) \vec{p} \\ &= \vec{r} (\vec{r} \cdot \vec{p}) - r^2 \vec{p} \end{aligned}$$

$$\Rightarrow [\vec{A}, \frac{1}{r}] = \frac{i\hbar}{m} \left[ \frac{\vec{r}}{r^3} (\vec{r} \cdot \vec{p}) - \frac{\vec{p}}{r} \right] + \frac{\hbar^2}{m} \frac{\vec{r}}{r^3}$$

$$\Rightarrow [\vec{A}, \frac{p^2}{2m} - \frac{k}{r}] = 0!$$

⑤ Prove  $A^2 = \frac{2H}{mk^2} (\vec{L}^2 + \hbar^2) + 1$

$$m^2 k^2 A^2 = (\vec{p} \times \vec{L} - i\hbar \vec{p} - mk \vec{r}/r) \cdot (\vec{p} \times \vec{L} - i\hbar \vec{p} - mk \vec{r}/r)$$

$$= (\vec{p} \times \vec{L}) \cdot (\vec{p} \times \vec{L}) - \hbar^2 p^2 + (mk)^2 \\ - i\hbar [(\vec{p} \times \vec{L}) \cdot \vec{p} + \vec{p} \cdot (\vec{p} \times \vec{L})] - mk [(\vec{p} \times \vec{L}) \cdot \vec{r}/r + \vec{r}/r \cdot (\vec{p} \times \vec{L})] \\ + im\hbar k [\vec{p} \cdot \vec{r}/r + \vec{r}/r \cdot \vec{p}]$$

$$(\vec{p} \times \vec{L}) \cdot (\vec{p} \times \vec{L}) = p_i L_j p_i L_j - \quad = p_i p_i L_j L_j + p_i [L_j p_i] L_j - p_i L_i L_j p_j$$

$$= p^2 L^2 - \epsilon_{ijk} i\hbar p_i p_k L_j - p_i L_i p_j L_j = \boxed{p^2 L^2 - (\vec{p} \cdot \vec{L})^2 = (\vec{p} \times \vec{L}) \cdot (\vec{p} \times \vec{L})}$$

*( $L_j p_i$  is rotation scalar)*

$$(\vec{p} \times \vec{L} + \vec{L} \times \vec{p})_i = \epsilon_{ijk} [p_j L_k] = \epsilon_{ijk} \epsilon_{kji} (-i\hbar) p_i$$

$$= \epsilon_{ijk} \epsilon_{kji} (-i\hbar) p_i = (\delta_{ij} \delta_{ji} - \delta_{ii} \delta_{jj}) (-i\hbar) p_i = -i\hbar (p_i - 3p_i) = 2i\hbar p_i$$

$$\Rightarrow \boxed{\vec{p} \times \vec{L} = -\vec{L} \times \vec{p} + 2i\hbar \vec{p}}$$

$$\boxed{(\vec{p} \times \vec{L}) \cdot \vec{p} = 2i\hbar p^2}, \quad \vec{p} \cdot (\vec{p} \times \vec{L}) = 0$$

$$(\vec{p} \times \vec{L}) \cdot \vec{r} = [-(\vec{L} \times \vec{p}) + 2i\hbar \vec{p}] \cdot \vec{r} = -(\vec{L} \times \vec{p}) \cdot \vec{r} + 2i\hbar \vec{p} \cdot \vec{r} = L^2 + 2i\hbar \vec{p} \cdot \vec{r}$$

$$\vec{r} \cdot (\vec{p} \times \vec{L}) = L^2$$

$$\frac{\vec{r}}{r} \cdot \vec{p} = \vec{p} \cdot \left( \frac{\vec{r}}{r} + i\hbar \nabla \cdot \left( \frac{\vec{r}}{r} \right) \right) = \vec{p} \cdot \vec{r}/r + i\hbar \left( \frac{3}{r} - \frac{\vec{r} \cdot \vec{r}}{r^3} \right) = \vec{p} \cdot \vec{r}/r + 2i\hbar \frac{1}{r}$$

$$\Rightarrow m^2 k^2 A^2 = p^2 L^2 - (\vec{p} \cdot \vec{L})^2 - \hbar^2 p^2 + (mk)^2 + 2\hbar p^2 - mk \left[ \frac{2L^2}{r} + 2i\hbar \vec{p} \cdot \vec{r}/r \right] \\ + 2im\hbar k \left[ \frac{\vec{p} \cdot \vec{r}}{r} + i\hbar \frac{1}{r} \right]$$

$$\vec{p} \cdot \vec{L} = \vec{p} \cdot (\vec{r} \times \vec{p}) = \epsilon_{ijk} p_i r_j p_k = \epsilon_{ijk} [r_j p_i p_k + (-i\hbar \delta_{ij}) p_k] = 0$$

$$\Rightarrow m^2 k^2 A^2 = p^2 [L^2 + \hbar^2] - 2m \frac{k}{r} [L^2 + \hbar^2] + (mk)^2$$

$$\Rightarrow A^2 = \frac{2m}{m^2 k^2} \left( \frac{p^2}{2m} - \frac{\kappa}{r} \right) (\ell^2 + \hbar^2) + 1 = \frac{2H}{m k^2} (\vec{\ell}^2 + \hbar^2) + 1$$

⑥

$$\vec{A} \cdot \vec{\ell} = \vec{\ell} \cdot \vec{A} = 0$$

$$\textcircled{1} \quad \vec{A} = \frac{1}{m k} (\vec{p} \times \vec{\ell} - i \hbar \vec{p}) - \frac{\vec{r}}{r}$$

$$\vec{A} \cdot \vec{\ell} = \frac{1}{m k} (\vec{p} \times \vec{\ell}) \cdot \vec{\ell} - \frac{i \hbar}{m k} \vec{p} \cdot \vec{\ell} - \frac{\vec{r}}{r} \cdot \vec{\ell}$$

$$= 0 + 0 + 0 = 0$$

$$\vec{A} = \frac{1}{m k} (-\vec{\ell} \times \vec{p} + i \hbar \vec{p}) - \frac{\vec{r}}{r}$$

$$\vec{\ell} \cdot \vec{A} = \frac{1}{m k} [-\vec{\ell} \cdot (\vec{\ell} \times \vec{p}) + i \hbar \vec{\ell} \cdot \vec{p}] - \vec{\ell} \cdot \frac{\vec{r}}{r}$$

$$= 0 + 0 + 0 = 0$$

$$\vec{r} \cdot \vec{\ell} = \vec{r} \cdot (\vec{r} \times \vec{p}) = 0$$

$$\vec{\ell} \cdot \vec{p} = (\vec{r} \times \vec{p}) \cdot \vec{p} = 0$$

$$\vec{\ell} \cdot \vec{r} = (\vec{r} \times \vec{p}) \cdot \vec{r} = -(\vec{p} \times \vec{r}) \cdot \vec{r} = 0$$

⑦

$$\text{Define } \vec{I} = \frac{1}{2} \left[ \vec{L} + \sqrt{\frac{-m k}{2 E}} \vec{A} \right]$$

$$\vec{K} = \frac{1}{2} \left[ \vec{L} - \sqrt{\frac{-m k}{2 E}} \vec{A} \right]$$

pay attention to the coefficient  $\frac{1}{2}$

$SO(4)$  decompose into a pair of  $SO(3)$ .

$$\text{due to } \vec{L} \cdot \vec{A} = \vec{A} \cdot \vec{L} = 0 \Rightarrow \vec{I} \cdot \vec{I} = \vec{K} \cdot \vec{K} = \frac{1}{4} \left[ \vec{L}^2 + \left( \frac{-m k}{2 E} \right) \vec{A}^2 \right]$$

we can only realize a special class of  $SO(4)$  Rep.  $I = K$ .

due to coefficients  $\frac{1}{2}$ ,  $I = K$  can take both integer/half integers.

$$\vec{L} = \vec{I} + \vec{K}$$

$$\vec{A} = \vec{I} - \vec{K}$$

thus  $\vec{L}$  is still an angular momentum, but  $\vec{A}$  is not! Because  $I = K$ ,  $L$  can only be integer-valued!

⑧ Figure out the spectrum

$$\left( \sqrt{\frac{-mk^2}{2E}} \vec{A} \right)^2 + \vec{L}^2 = -(\vec{L}^2 + \hbar^2) + \frac{mk^2}{-2E} + \vec{L}^2$$
$$= -\frac{m^2 k^2}{2E} - \hbar^2$$

↓ twice of

the SO(4) Casimir  $2[I(I+1)\hbar^2 + K(K+1)\hbar^2] = 4I(I+1)\hbar^2$   
define in Page 12.

$I = K$  ↑

$$\Rightarrow -\frac{mk^2}{2E} = (2I+1)^2 \hbar^2 \Rightarrow E = \frac{-mk^2/\hbar^2}{2(2I+1)^2} \quad \text{where } I = \frac{1}{2}, \frac{3}{2}, \dots$$

$2I+1 = 1, 2, 3, \dots$

$$mk^2/\hbar^2 = \frac{me^4}{\hbar^2} = \frac{e^2}{\hbar^2/me^2} = \frac{e^2}{a} = \text{Rydberg}$$