

Runge - Lenz vector (elementary knowledge).

① Classic Kepler problem

$$H = \frac{P^2}{2m} - \frac{k}{r}$$

obviously $\dot{\vec{L}} = \ddot{\vec{r}} \times \vec{P} + \vec{r} \times \ddot{\vec{P}} = 0$ for central force fields.

$$\text{how about } \frac{d}{dt}(\vec{P} \times \vec{L}) = \dot{\vec{P}} \times \vec{L} + \vec{P} \times \dot{\vec{L}}$$

$$\dot{\vec{P}} \times \vec{L} = -\frac{k}{r^2} \hat{r} \times (\vec{r} \times m \dot{\vec{r}}) = -\frac{k}{r^2} m [\vec{r}(\hat{r} \cdot \dot{\vec{r}}) - \hat{r} \cdot \vec{r} \dot{\vec{r}}]$$

$$= -\frac{k}{r^3} m [\vec{r}[\vec{r} \cdot \dot{\vec{r}}] - r^2 \dot{\vec{r}}] \leftarrow \vec{r} \cdot \dot{\vec{r}} = r \dot{r}$$

$$= -\frac{k}{r^3} m \left[\frac{\vec{r} \cdot \dot{\vec{r}}}{r^2} - \frac{\dot{\vec{r}}}{r} \right]$$

$$\Rightarrow \frac{d}{dt}(\vec{P} \times \vec{L}) = +km \left[-\frac{\vec{r} \cdot \dot{\vec{r}}}{r^2} + \frac{\dot{\vec{r}}}{r} \right] = km \frac{d}{dt} \left[\frac{\vec{r}}{r} \right]$$

define $\vec{A} = \vec{P} \times \vec{L} - mk \frac{\vec{r}}{r}$ $\Rightarrow \frac{d}{dt} \vec{A} = 0$. \vec{A} : Runge-Lenz vector.

what's the direction of \vec{A} ?

$$\vec{A} \cdot \vec{L} = (\vec{P} \times \vec{L}) \cdot \vec{L} - mk \frac{\vec{r}}{r} \cdot (\vec{r} \times \vec{P}) = 0,$$

thus \vec{A} lies in the orbital plane.

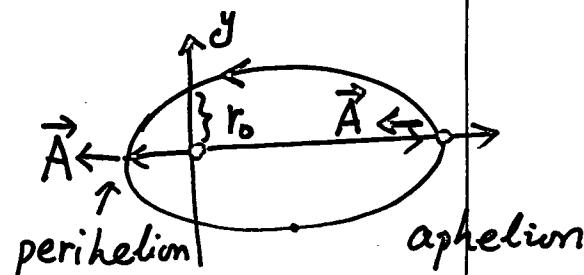
check at perihelion:

$$\vec{P} = -p \hat{y}, \quad \vec{L} = l \hat{z}$$

$$\vec{P} \times \vec{L} = -pl \hat{x}$$

$$\text{and } r = \frac{r_0}{1 - e \cos \theta}$$

Kepler's problem:



$$\begin{cases} r_0 = \frac{l^2}{mk} \\ e = \sqrt{1 + \frac{2El^2}{mk^2}} = \sqrt{1 + \frac{2E}{k/r_0}} \end{cases}$$

$$P \cdot \frac{r_0}{1+e} = l \Rightarrow P \cdot l = \frac{l^2(1+e)}{r_0} = mk(1+e)$$

$$\Rightarrow \vec{A} = -pl \hat{x} + \frac{\hat{x}}{mk} = \left[-mk(1+e) + mk \right] \hat{x} = -mke \hat{x}$$

A's magnitude is ∞ eccentricity; its direction points along to the perihelion.

Let's check $\vec{A} \cdot \vec{r} = -A r \omega \theta = \vec{r} \cdot (\vec{p} \times \vec{L}) - mkr$

$$\vec{r} \cdot (\vec{p} \times \vec{L}) = \vec{L} \cdot (\vec{r} \times \vec{p}) = l^2$$

$$\Rightarrow -A r \omega \theta = l^2 - mkr \Rightarrow r = \frac{l^2}{mk - A \cos \theta} = \frac{l^2/mk}{1 - \frac{A}{mk} \cos \theta}$$

Solution to Kepler problem using R-L vector

compare $e = \sqrt{1 + \frac{2El^2}{mk^2}} = \frac{A}{mk} \Rightarrow \frac{A^2}{m^2 k^2} = 1 + \frac{2El^2}{m^2 k^2}$

Once E, \vec{L} are determined,

$|A|$, and $\vec{A} \perp \vec{L}$ are decided, there's only one more angle to determine the direction of \vec{A} . Once this is determined, the orbit is determined.

Connt degree of freedom: $E, \vec{L} : 4$

$$\text{direction of } \vec{A} : 1 \leftarrow \begin{cases} \vec{A} \cdot \vec{L} = 0 \\ A^2 = m^2 k^2 + 2El^2 \end{cases}$$

initial condition: 1

6 (complete!)

2. 2D Quantum mechanics Kepler problem

$$\vec{A} = \frac{1}{2mk} (\vec{p} \times \vec{l} - \vec{l} \times \vec{p}) - \hat{\mathbf{e}}_r \quad (\text{a different normalization})$$

in 2D: $A_x = \frac{1}{2mk} (P_y l_z + l_z P_y) - \hat{\mathbf{e}}_{r,x}$, $A_y = \frac{1}{2mk} (P_x l_z + l_z P_x) - \hat{\mathbf{e}}_{r,y}$

$$\Rightarrow A_x = \frac{1}{mk} l_z P_y + \frac{i\hbar}{2mk} P_x - \frac{x}{r}; \quad A_y = -\frac{1}{mk} l_z P_x + \frac{i\hbar}{2mk} P_y - \frac{y}{r}$$

A_x, y are Hermitian, but $l_z P_y$ and $l_z P_x$ are not. Thus $\frac{i\hbar}{2mk} \vec{p}$ comes to compensate.

④ Check $[l_z, A_x] = i\hbar A_y$ and $[l_z, A_y] = -i\hbar A_x$

$$\begin{aligned} [l_z, A_x] &= \frac{1}{mk} [l_z, l_z P_y] + \frac{i\hbar}{2mk} [l_z, P_x] - [l_z, \frac{x}{r}] \\ &= \frac{1}{mk} l_z (-i\hbar P_x) + \frac{i\hbar}{2mk} (i\hbar P_y) - i\hbar \frac{y}{r} = i\hbar A_y \end{aligned}$$

the other one can be proved similarly.

⑤ Check $[A_x, A_y] = -\frac{2\hbar}{mk^2} i\hbar l_z$

$$\begin{aligned} [A_x, A_y] &= -\frac{1}{(mk)^2} [l_z P_y, l_z P_x] + \frac{i\hbar}{2(mk)^2} \left\{ [l_z P_y, P_y] + [l_z P_x, P_x] \right\} \\ &\quad - \frac{i\hbar}{2mk} \left\{ [P_x, \frac{y}{r}] - [P_y, \frac{x}{r}] \right\} - \frac{1}{mk} \left\{ [l_z P_y, \frac{y}{r}] + [l_z P_x, \frac{x}{r}] \right\} \end{aligned}$$

$$\begin{aligned} [l_z P_y, l_z P_x] &= l_z [P_y, l_z P_x] + [l_z, l_z P_x] P_y = l_z [P_y, l_z] P_x + l_z [l_z, P_x] P_y \\ &= l_z (i\hbar) P_x^2 + i\hbar l_z P_y^2 = i\hbar l_z P^2 \end{aligned}$$

add together.

$$[l_z P_y, P_y] = P_y [l_z, P_y] = -i\hbar P_y P_x, \quad [l_z P_x, P_x] = P_x [l_z, P_x] = i\hbar P_x P_y \rightarrow 0$$

$$[P_x, \frac{y}{r}] = -i\hbar y \partial_x \frac{1}{r} = i\hbar \frac{xy}{r^3}, \quad [P_y, \frac{x}{r}] = -i\hbar x \partial_y \frac{1}{r} = -i\hbar \frac{xy}{r^3}$$

add together 0

$$[\ell_2 P_y, \frac{y}{r}] = \ell_2 [P_y, \frac{y}{r}] + [\ell_2, \frac{y}{r}] P_y = \ell_2 (-i\hbar) \frac{\partial y}{r} - i\hbar \frac{x}{r} P_y$$

$$\frac{\partial y}{r} = \frac{1}{r} - \frac{y^2}{r^3} \rightarrow = (-i\hbar) \ell_2 \left(\frac{1}{r} - \frac{y^2}{r^3} \right) - i\hbar \frac{1}{r} x P_y$$

$$[\ell_2 P_x, \frac{x}{r}] = -i\hbar \ell_2 \left(\frac{1}{r} - \frac{x^2}{r^3} \right) - i\hbar \frac{y}{r} P_x$$

$$\text{add together} \Rightarrow -i\hbar \ell_2 \left(\frac{2}{r} - \frac{1}{r} \right) - i\hbar \frac{1}{r} \ell_2 = -2i\hbar \ell_2 \frac{1}{r}$$

$$\text{organize everything} \Rightarrow [A_x, A_y] = -\frac{1}{(mk)^2} i\hbar \ell_2 P^2 + \frac{1}{mk} i\hbar \ell_2 \frac{2}{r}$$

$$= \frac{-2}{mk^2} \left[\frac{P^2}{2m} - \frac{k}{r} \right] \ell_2 i\hbar = -\frac{2H}{mk^2} i\hbar \ell_2$$

④ Next prove $[A_x, H] = [A_y, H] = 0.$

$$[A_x, H] = \frac{1}{2m} [A_x, P^2] - \frac{1}{k} [A_x, \frac{1}{r}]$$

$$\text{we need } [\vec{P}, \frac{1}{r}] = -i\hbar \nabla \frac{1}{r} = +i\hbar \frac{\vec{r}}{r^3},$$

$$\nabla \cdot \left(\frac{\vec{r}}{r^3} \right) = \frac{1}{r^3} \nabla \cdot \vec{r} + \nabla \left(\frac{1}{r^3} \right) \vec{r} = \frac{2}{r^3} + \frac{-3\vec{r} \cdot \vec{r}}{r^5} = -\frac{1}{r^3}$$

$$[A_x, P^2] = \frac{1}{mk} [\ell_2 P_y, P^2] - [\frac{x}{r}, P^2] = [P^2, \frac{x}{r}]$$

$$[\vec{P}, \frac{x}{r}] = x [\vec{P}, \frac{1}{r}] + [\vec{P}, x] \frac{1}{r} = x \vec{P} [\vec{P}, \frac{1}{r}] + x [\vec{P}, \frac{1}{r}] \vec{P} + \vec{P} [\vec{P}, x] \frac{1}{r} + [\vec{P}, x] \vec{P} \frac{1}{r}$$

$$= x i\hbar \left[\vec{P} \cdot \vec{r} / r^3 + \frac{\vec{r} \cdot \vec{P}}{r^3} \right] - 2i\hbar P_x \frac{1}{r}$$

$$= 2i\hbar x \frac{\vec{r}}{r^3} \cdot \vec{P} + x i\hbar (-i\hbar) \left(-\frac{1}{r^3} \right) - 2i\hbar (-i\hbar) \underbrace{\frac{-x}{r^3}}_{-\frac{x}{r^3}} - 2i\hbar \frac{1}{r} P_x$$

$$= \boxed{2i\hbar x \left[-\frac{1}{r} P_x + \frac{x}{r^3} \vec{r} \cdot \vec{P} \right] + \frac{i^2 x}{r^3}} = [A_x, P^2]$$

(5)

$$\begin{aligned}
 [A_x, \frac{k}{r}] &= \frac{1}{m} [l_z P_y, \frac{1}{r}] + \frac{i\hbar}{2m} [P_x, \frac{1}{r}] \\
 &= \frac{1}{m} l_z [P_y, \frac{1}{r}] + \frac{i\hbar}{2m} [P_x, \frac{1}{r}] = -\frac{1}{m} l_z (-i\hbar) \partial_y \frac{1}{r} + \frac{i\hbar}{2m} (-i\hbar) \partial_x \frac{1}{r} \\
 &= \frac{1}{m} l_z (-i\hbar) \frac{-y}{r^3} - \frac{\hbar^2}{2m} \frac{x}{r^3} = \frac{i\hbar}{m} \left(\frac{y}{r^3} l_z + [l_z, y] \right) - \frac{\hbar^2}{2m} \frac{x}{r^3} \\
 &= \frac{i\hbar}{m} \frac{1}{r^3} (y(xP_y - yP_x)) + \frac{\hbar^2}{2m} \frac{x}{r^3} \\
 &= \frac{\hbar^2}{m} \frac{x}{r^3} (x\partial_x + y\partial_y) - \frac{\hbar^2}{m} \frac{1}{r^3} (x^2 + y^2) \partial_x + \frac{\hbar^2}{2m} \frac{x}{r^3}
 \end{aligned}$$

$$[A_x, \frac{k}{r}] = \frac{i\hbar^2}{m} \left(\frac{x}{r^3} (\vec{r} \cdot \vec{p}) - \frac{1}{r} P_x \right) + \frac{\hbar^2}{2m} \frac{x}{r^3}$$

add together $\Rightarrow [A_x, H] = 0$, and similarly $[A_y, H] = 0$.

$\left\{ \sqrt{\frac{-mk^2}{2E}} A_x, \sqrt{\frac{-mk^2}{2E}} A_y, l_z \right\}$ form an $SU(2)$ algebra.

* Calculate Casimir

$$\begin{aligned}
 A_x^2 + A_y^2 &= \left(\frac{1}{mk} l_z P_y + \frac{i\hbar}{2mk} P_x - \frac{x}{r} \right)^2 + \left(\frac{-1}{mk} l_z P_x + \frac{i\hbar}{2mk} P_y - \frac{y}{r} \right)^2 \\
 &= \frac{1}{m^2 k^2} l_z^2 P_y^2 - \frac{\hbar^2}{4mk^2} P_x^2 + 1 + \frac{i\hbar}{2(mk)^2} [l_z P_y P_x + P_x l_z P_y - l_z^2 P_y^2 - P_y l_z P_x] \\
 &\quad - \frac{1}{mk} (l_z P_y \frac{x}{r} - l_z P_x \frac{y}{r} + \frac{x}{r} l_z P_y - \frac{y}{r} l_z P_x) \\
 &\quad - \frac{i\hbar}{2mk} (P_x \frac{x}{r} + P_y \frac{y}{r} + \frac{x}{r} P_x + \frac{y}{r} P_y)
 \end{aligned}$$

$$\begin{aligned}
 l_z P_y l_z P_y + l_z P_x l_z P_x &= l_z^2 (P_y^2 + P_x^2) + l_z \underbrace{[P_y l_z] P_y}_{l_z [P_x l_z] P_x} + l_z [P_x l_z] P_x = l_z^2 P^2 \\
 &\text{add to } 0.
 \end{aligned}$$

$$P_x l_z P_y - P_y l_z P_x = l_z P_x P_y - l_z P_y P_x + [P_x l_z] P_y - [P_y l_z] P_x$$

$$= 0 - i\hbar P_y^2 - i\hbar P_x^2 = -i\hbar P^2$$

$$\therefore P^2 \text{ related terms } \frac{P^2}{m} \left[\frac{1}{m k^2} \right] \left[l_z^2 - \frac{\hbar^2}{4} + \frac{\hbar^2}{2} \right] = \frac{P^2}{m} \frac{1}{m k^2} \left[l_z^2 + \frac{\hbar^2}{4} \right]$$

$$l_z P_y \frac{x}{r} - l_z P_x \frac{y}{r} + \frac{x}{r} l_z P_y - \frac{y}{r} l_z P_x$$

$$= l_z [x P_y - y P_x] \frac{1}{r} + \frac{1}{r} l_z [x P_y - y P_x] + \frac{1}{r} [x l_z] P_y - \frac{1}{r} [y l_z] P_x$$

$$= \frac{2}{r} l_z^2 + \frac{1}{r} (-i\hbar) y P_y + \frac{1}{r} (i\hbar) x P_x = \frac{2}{r} l_z^2 - i\hbar \frac{1}{r} \vec{r} \cdot \vec{p}$$

$$P_x \left(\frac{x}{r} \right) + P_y \left(\frac{y}{r} \right) + \frac{x}{r} P_x + \frac{y}{r} P_y = 2 \frac{1}{r} \vec{r} \cdot \vec{p} - i\hbar \partial_x \left(\frac{x}{r} \right) - i\hbar \partial_y \left(\frac{y}{r} \right)$$

$$\partial_x \left(\frac{x}{r} \right) = \frac{1}{r} + \frac{x(-x)}{r^3} \Rightarrow -i\hbar \partial_x \left(\frac{x}{r} \right) - i\hbar \partial_y \left(\frac{y}{r} \right) = -i\hbar \left(\frac{2}{r} - \frac{1}{r} \right) = -\frac{i\hbar}{r}$$

Put together $\frac{1}{r}$ - related terms are

$$- \frac{1}{m k} \left[\frac{2}{r} l_z^2 - i\hbar \frac{1}{r} \vec{r} \cdot \vec{p} \right] - \frac{i\hbar}{2mk} \left[2 \frac{1}{r} \vec{r} \cdot \vec{p} - \frac{i\hbar}{r} \right]$$

$$= \frac{2}{m k^2} \frac{(-k)}{r} \left[l_z^2 + \frac{\hbar^2}{4} \right]$$

$$\Rightarrow \boxed{A_x^2 + A_y^2 = \frac{2H}{m k^2} \left(l_z^2 + \frac{\hbar^2}{4} \right) + 1}$$

The normalized Casimir is : (replace H with eigenvalue E).

$$\left(\sqrt{\frac{-mk^2}{2E}} \right)^2 A_x^2 + \left(\sqrt{\frac{-mk^2}{2E}} \right)^2 A_y^2 + l_z^2 = - \frac{-mk^2}{2E} - \frac{\hbar^2}{4} \quad \begin{matrix} (l_z^2 \text{ term} \\ \text{cancels}) \end{matrix}$$

because l_z is orbital

$$= L(L+1) \hbar^2 \quad (L=0, 1, 2, \dots)$$

angular momentum $\Rightarrow L$ can
only be integer

\uparrow
SU(2) quantum number

$$\Rightarrow \frac{-mk^2}{2E} = \hbar^2 \left(L + \frac{1}{2}\right)^2 \Rightarrow E = \frac{-mk^2}{2\left(L + \frac{1}{2}\right)^2} \quad (L=0, 1, 2, \dots)$$

The corresponding J_{\pm} operator

$$J_{\pm} = \sqrt{\frac{-mk^2}{2E}} (A_x \pm iA_y) = \hbar(L + \frac{1}{2}) (A_x \pm iA_y)$$

$$J_{\pm} |E, m\rangle = \hbar \sqrt{(L \mp m)(L \pm m + 1)} |E, m \pm 1\rangle$$

$$\Rightarrow (A_x \pm iA_y) |E(L), m\rangle = \frac{1}{L + \frac{1}{2}} \sqrt{(L \mp m)(L \pm m + 1)} |E, m \pm 1\rangle.$$

$$\ell_2 |E, m\rangle = m\hbar |E, m\rangle$$

$$3: \text{3D case} \quad H = \frac{\vec{P}^2}{2m} - \frac{\vec{k}}{r}$$

$$\vec{A} = \frac{1}{2mk} (\vec{P} \times \vec{l} - \vec{l} \times \vec{P}) - \hat{e}_r$$

$$A_x = \frac{1}{2mk} (P_y l_z - P_z l_y + l_z P_y - l_y P_z) - \hat{e}_{r,x} = \frac{1}{mk} P_y l_z - \frac{i\hbar}{mk} P_x - \frac{x}{r}$$

$$\Rightarrow \vec{A} = \frac{1}{mk} (-\vec{P} \times \vec{l} - i\hbar \vec{P}) - \hat{e}_r$$

$$\begin{aligned} \vec{P} \times \vec{l} &= \vec{P} \times (\vec{r} \times \vec{P}) = P_x \vec{r} P_x + P_y \vec{r} P_y + P_z \vec{r} P_z - (\vec{P} \cdot \vec{r}) \vec{P} \\ &= P_x (P_x \vec{r} + i\hbar \hat{x}) + \dots - (\vec{P} \cdot \vec{r}) \vec{P} \\ &= \vec{P}^2 \vec{r} + i\hbar \vec{P} - (\vec{P} \cdot \vec{r}) \vec{P} \end{aligned}$$

$$\Rightarrow \boxed{\vec{A} = \frac{1}{mk} (\vec{P}^2 \vec{r} - (\vec{P} \cdot \vec{r}) \vec{P}) - \vec{r}/r}$$

$$3: \text{Prove } \vec{A} \times \vec{A} = -\frac{2i\hbar}{mk^2} H \vec{l}$$

$$m^2 k^2 \vec{A} \times \vec{A} = (\vec{P}^2 \vec{r} - (\vec{P} \cdot \vec{r}) \vec{P} - mk \vec{r}/r) \times (\vec{P}^2 \vec{r} - (\vec{P} \cdot \vec{r}) \vec{P} - mk \vec{r}/r)$$

The trick is to move the second expression: $\vec{P}^2 \vec{r} \rightarrow \vec{r} \vec{P}^2$ and so on.

$$\begin{aligned} \vec{P}^2 \vec{r} &= P_i \vec{r} P_i + P_i [P_i \vec{r}] = P_i \vec{r} P_i + \vec{P} (-i\hbar) = \vec{r} \vec{P}^2 + [P_i \vec{r}] P_i - (i\hbar) \vec{P} \\ &= \vec{r} \vec{P}^2 - 2i\hbar \vec{P} \end{aligned}$$

$$(\vec{P} \cdot \vec{r}) \vec{P} = P_i r_i P_j = P_i P_j r_i + P_i [r_i P_j] = P_i P_j r_i + i\hbar P_j = \vec{P} (\vec{P} \cdot \vec{r}) + i\hbar \vec{P}$$

$$\begin{aligned} \Rightarrow \vec{A} \times \vec{A} m^2 k^2 &= (\vec{P}^2 \vec{r} - (\vec{P} \cdot \vec{r}) \vec{P} - mk \vec{r}/r) \times (\vec{r} \vec{P}^2 - 3i\hbar \vec{P} - \vec{P} (\vec{P} \cdot \vec{r}) - mk \vec{r}/r) \\ &= \vec{P}^2 \vec{r} \times \vec{r} \vec{P}^2 - (\vec{P} \cdot \vec{r}) \vec{P} \times \vec{P} (\vec{P} \cdot \vec{r}) = mk \frac{\vec{r}}{r} \times \frac{\vec{r}}{r} = 0 \end{aligned}$$

$$m^2 k^2 \vec{A} \times \vec{A} = p^2 (-3i\hbar) \vec{r} \times \vec{p} - p (\vec{r} \times \vec{p}) (\vec{p} \cdot \vec{r})$$

$$- (\vec{p} \cdot \vec{r}) (\vec{p} \times \vec{r}) p^2 + (\vec{p} \cdot \vec{r}) (\vec{p} \times \vec{r}/r) (mk) - mk \frac{\vec{r}}{r} \times (-3i\hbar \vec{p})$$

$$+ mk \left(\frac{\vec{r}}{r} \times \vec{p} \right) (\vec{p} \cdot \vec{r})$$

$$= -3i\hbar p^2 \vec{l} - p^2 (\vec{p} \cdot \vec{r}) \vec{l} + (\vec{p} \cdot \vec{r}) \vec{l} p^2 - mk (\vec{p} \cdot \vec{r}) \frac{1}{r} \vec{l} + 3i\hbar mk \frac{1}{r} \vec{l}$$

$$+ mk \frac{1}{r} (\vec{p} \cdot \vec{r}) \vec{l}$$

$$= (-3i\hbar p^2 + [\vec{p} \cdot \vec{r}, p^2] - mk [\vec{p} \cdot \vec{r}, \frac{1}{r}] + \frac{3i\hbar mk}{r}) \vec{l}$$

(\vec{l} commutes with all rotation invariant operators)

$$[\vec{p} \cdot \vec{r}, p^2] = [P_i r_i, P_j P_j] = P_i [r_i P_j P_j] = P_i P_j [r_i P_j] + P_i [r_i, P_j] P_j$$

$$= +i\hbar 2 P^2$$

$$[\vec{p} \cdot \vec{r}, \frac{1}{r}] = [P_i r_i, \frac{1}{r}] = [P_i \frac{1}{r}] r_i = -i\hbar \frac{-\vec{r} \cdot \vec{r}}{r^3} = i\hbar \frac{1}{r}$$

$$\Rightarrow m^2 k^2 \vec{A} \times \vec{A} = (-3i\hbar p^2 + 2i\hbar p^2 - i\hbar \frac{mk}{r} + 3i\hbar \frac{mk}{r}) \vec{l}$$

$$= -i\hbar \left[\frac{p^2}{2m} - \frac{k}{r} \right] \cdot 2m \vec{l} = -2i\hbar m H \vec{l}$$

\Rightarrow

$$\boxed{\vec{A} \times \vec{A} = -\frac{2i\hbar}{mk^2} H \vec{l}}$$

③

$$\text{Prove } [L_i A_j] = i \epsilon_{ijk} A_k \hbar$$

This is obvious because A is defined in a 3-vector form,

under spatial rotation A transforms like a vector.

This means $L_{12} = L_z, L_{23} = L_x, L_{31} = L_y$ and

form $SO(4)$

algebra.

$$\boxed{L_{14} = \sqrt{-\frac{mk^2}{2E}} A_x, L_{24} = \sqrt{-\frac{mk^2}{2E}} A_y, L_{34} = \sqrt{-\frac{mk^2}{2E}} A_z}$$

④ prove $[\vec{A}, \vec{p}^2] = 0$

$$\vec{A} = \frac{1}{mk} (\vec{p} \times \vec{l} - i\hbar \vec{p}) - \frac{\vec{r}}{r}$$

$$[\vec{A}, \vec{p}^2] = \frac{1}{2mk} [\vec{p} \times \vec{l} - \vec{l} \times \vec{p}, \vec{p}^2] - [\frac{\vec{r}}{r}, \vec{p}^2]$$

This first term is 0 because $[\vec{l}, \vec{p}^2] = 0$.

$$[\vec{p}^2, \frac{\vec{r}}{r}] = \vec{r} [\vec{p}^2, \frac{1}{r}] + [\vec{p}^2, \vec{r}] \frac{1}{r}$$

$$[\vec{p}^2, \frac{1}{r}] = 2i\hbar \frac{\vec{r} \cdot \vec{p}}{r^3} + \hbar^2 \nabla \cdot \left(\frac{\vec{r}}{r^3} \right) = 2i\hbar \frac{\vec{r} \cdot \vec{p}}{r^3} + 4\pi \hbar^2 \delta^{(3)}(\vec{r})$$

$$\Rightarrow \vec{r} [\vec{p}^2, \frac{1}{r}] = 2i\hbar \frac{\vec{r}}{r^3} \vec{r} \cdot \vec{p} + 4\pi \hbar^2 \vec{r} \delta^{(3)}(\vec{r}) \rightarrow 0$$

$$[\vec{p}^2, \vec{r}] = -2i\hbar \vec{p}, \quad [\vec{p}^2, \vec{r}] \frac{1}{r} = -\frac{2i\hbar}{r} \vec{p} + 2\hbar^2 \frac{\vec{r}}{r^3}$$

$$\Rightarrow [\vec{p}^2, \frac{\vec{r}}{r}] = \boxed{2i\hbar \left[-\frac{1}{r} \vec{p} + \frac{\vec{r}}{r^3} \vec{r} \cdot \vec{p} \right] + 2\hbar^2 \frac{\vec{r}}{r^3}} = [\vec{A}, \vec{p}^2]$$

**

$$[\vec{A}, \frac{1}{r}] = \frac{1}{mk} [\vec{p} \times \vec{l} - i\hbar \vec{p}, \frac{1}{r}]$$

$$[\vec{p} \times \vec{l}, \frac{1}{r}] = \vec{p} \times [\vec{l}, \frac{1}{r}] + [\vec{p}, \frac{1}{r}] \times \vec{l} = [\vec{p}, \frac{1}{r}] \times \vec{l}$$

$$[\vec{p}, \frac{1}{r}] = i\hbar \frac{\vec{r}}{r^3}$$

$$\Rightarrow [\vec{A}, \frac{1}{r}] = \frac{1}{mk} i\hbar \frac{1}{r^3} \vec{r} \times (\vec{r} \times \vec{p}) - \frac{i\hbar}{mk} (i\hbar) \frac{\vec{r}}{r^3}$$

$$\vec{r} \times (\vec{r} \times \vec{p}) = r_x \vec{r} p_x + r_y \vec{r} p_y + r_z \vec{r} p_z - (\vec{r} \cdot \vec{r}) \vec{p}$$

$$= \vec{r} (\vec{r} \cdot \vec{p}) - r^2 \vec{p}$$

$$\Rightarrow [\vec{A}, \frac{1}{r}] = \frac{i\hbar}{m} \left[\frac{\vec{r}}{r^3} (\vec{r} \cdot \vec{p}) - \frac{\vec{p}}{r} \right] + \frac{\hbar^2}{m} \frac{\vec{r}}{r^3}$$

$$\Rightarrow [\vec{A}, \frac{\vec{p}^2}{2m} - \frac{k}{r}] = 0 !$$

(1) Prove $A^2 = \frac{2H}{mk^2} (\vec{l}^2 + \vec{t}^2) + 1$

$$m^2 k^2 A^2 = (\vec{p} \times \vec{l} - i\hbar \vec{p} - mk \vec{r}/r) \cdot (\vec{p} \times \vec{l} - i\hbar \vec{p} - mk \vec{r}/r)$$

$$= (\vec{p} \times \vec{l}) \cdot (\vec{p} \times \vec{l}) - \vec{t}^2 p^2 + (mk)^2$$

$$- i\hbar [(\vec{p} \times \vec{l}) \cdot \vec{p} + \vec{p} \cdot (\vec{p} \times \vec{l})] - mk [(\vec{p} \times \vec{l}) \cdot \vec{r}/r + \vec{r}/r \cdot (\vec{p} \times \vec{l})]$$

$$+ im\hbar k [\vec{p} \cdot \vec{r}/r + \vec{r}/r \cdot \vec{p}]$$

$$(\vec{p} \times \vec{l}) \cdot (\vec{p} \times \vec{l}) = P_i l_j P_i l_j - = P_i P_i l_j l_j + P_i [L_j P_i] l_j - P_i l_i l_j P_j$$

$P_i l_j P_j l_i$ ($L_j P_j$ is rotation scalar)

$$= P^2 l^2 - \epsilon_{ijk} i\hbar P_i P_k l_j - P_i l_i P_j l_j = P^2 l^2 - (\vec{p} \cdot \vec{l})^2 = (\vec{p} \times \vec{l}) \cdot (\vec{p} \times \vec{l})$$

$$(\vec{p} \times \vec{l} + \vec{l} \times \vec{p})_i = \epsilon_{ijk} [P_j l_k] = \epsilon_{ijk} \epsilon_{kji'} (-i\hbar) P_{i'}$$

$$= \epsilon_{ijk} \epsilon_{j'i'k} (-i\hbar) P_{i'} = (\delta_{ij} \delta_{j'i'} - \delta_{ii'} \delta_{jj'}) (-i\hbar) P_{i'} = -i\hbar (P_i - 3P_i) = 2i\hbar P_i$$

$$\Rightarrow \vec{p} \times \vec{l} = -\vec{l} \times \vec{p} + 2i\hbar \vec{p}$$

$$(\vec{p} \times \vec{l}) \cdot \vec{p} = 2i\hbar p^2, \quad \vec{p} \cdot (\vec{p} \times \vec{l}) = 0$$

$$(\vec{p} \times \vec{l}) \cdot \vec{r} = [-(\vec{l} \times \vec{p}) + 2i\hbar \vec{p}] \cdot \vec{r} = -(\vec{l} \times \vec{p}) \cdot \vec{r} + 2i\hbar \vec{p} \cdot \vec{r} = l^2 + 2i\hbar \vec{p} \cdot \vec{r}$$

$$\vec{r} \cdot (\vec{p} \times \vec{l}) = l^2$$

$$\vec{r} \cdot \vec{p} = \vec{p} \cdot \left(\frac{\vec{r}}{r} \right) + i\hbar \nabla \cdot \left(\frac{\vec{r}}{r} \right) = \vec{p} \cdot \vec{r}/r + i\hbar \left(\frac{3}{r} - \frac{\vec{r} \cdot \vec{r}}{r^3} \right) = \vec{p} \cdot \vec{r}/r + 2i\hbar \frac{1}{r}$$

$$\Rightarrow m^2 k^2 A^2 = P^2 l^2 - (\vec{p} \cdot \vec{l})^2 - \vec{t}^2 p^2 + (mk)^2 + 2i\hbar p^2 - mk \left[\frac{2l^2}{r} + 2i\hbar \frac{\vec{p} \cdot \vec{r}}{r} \right] + 2im\hbar k \left[\frac{\vec{p} \cdot \vec{r}}{r} + i\hbar \frac{1}{r} \right]$$

$$\vec{p} \cdot \vec{l} = \vec{p} \cdot (\vec{r} \times \vec{p}) = \epsilon_{ijk} P_i r_j P_k = \epsilon_{ijk} [r_j P_i P_k + (-i\hbar \delta_{ij}) P_k] = 0$$

$$\Rightarrow m^2 k^2 A^2 = P^2 [l^2 + \vec{t}^2] - 2m \frac{k}{r} [l^2 + \vec{t}^2] + (mk)^2$$

$$\Rightarrow A^2 = \frac{2m}{m^2 k^2} \left(\frac{p^2}{2m} - \frac{x}{r} \right) (\ell^2 + \vec{k}^2) + 1 = \frac{2H}{mk^2} (\vec{\ell}^2 + \vec{k}^2) + 1$$

⑥ $\vec{A} \cdot \vec{\ell} = \vec{\ell} \cdot \vec{A} = 0$

$$\vec{r} \cdot \vec{\ell} = \vec{r} \cdot (\vec{r} \times \vec{p}) = 0$$

$$\textcircled{1} \quad \vec{A} = \frac{1}{mk} (\vec{p} \times \vec{\ell} - i\hbar \vec{p}) - \vec{r}/r$$

$$\vec{A} \cdot \vec{\ell} = \frac{1}{mk} (\vec{p} \times \vec{\ell}) \cdot \vec{\ell} - \frac{i\hbar}{mk} \vec{p} \cdot \vec{\ell} - \frac{\vec{r}}{r} \cdot \vec{\ell}$$

$$= 0 + 0 + 0 = 0$$

$$\vec{A} = \frac{1}{mk} (-\vec{\ell} \times \vec{p} + i\hbar \vec{p}) - \vec{r}/r$$

$$\vec{\ell} \cdot \vec{A} = \frac{1}{mk} [-\vec{\ell}(\vec{\ell} \times \vec{p}) + i\hbar \vec{\ell} \cdot \vec{p}] - \vec{\ell} \cdot \vec{r}$$

$$= 0 + 0 + 0 = 0$$

$$\vec{\ell} \cdot \vec{p} = (\vec{r} \times \vec{p}) \cdot \vec{p} = 0$$

$$\vec{\ell} \cdot \vec{r} = (\vec{r} \times \vec{p}) \cdot \vec{r} \\ = -(\vec{p} \times \vec{r}) \cdot \vec{r} = 0$$

⑦ Define

$$\vec{I} = \frac{1}{2} [\vec{\ell} + \sqrt{\frac{-mk}{2E}} \vec{A}]$$

$$\vec{K} = \frac{1}{2} [\vec{\ell} - \sqrt{\frac{-mk}{2E}} \vec{A}]$$

$SO(4)$ decompose into a pair of $SO(3)$.

pay attention to the coefficient $\frac{1}{2}$

$$\text{due to } \vec{\ell} \cdot \vec{A} = \vec{A} \cdot \vec{\ell} = 0 \Rightarrow \vec{I} \cdot \vec{I} = \vec{K} \cdot \vec{K} = \frac{1}{4} [\vec{\ell}^2 + \left(\frac{-mk}{2E}\right) \vec{A}^2]$$

we can only realize a special class of $SO(4)$ Rep. $I = K$.

due to coefficients $\frac{1}{2}$, $I = K$ can take both integer/half integers.

$\vec{\ell} = \vec{I} + \vec{K}$ thus \vec{I} is still an angular momentum, but \vec{A} is not! Because $I = K$, \vec{L} can only be integer-valued!

⑧ Figure out the spectrum

$$\left(\sqrt{\frac{-mk^2}{2E}} \vec{A} \right)^2 + \vec{L}^2 = -(\vec{L}^2 + \hbar^2) + \frac{mk^2}{-2E} + \vec{L}^2 \\ = -\frac{m^2 k^2}{2E} - \hbar^2$$

↓ twice of

the SO(4) Casimir $2 \left[I(I+1)\hbar^2 + K(K+1)\hbar^2 \right] = 4 I(I+1)\hbar^2$
define in Page 12.

$$I = K$$

$$\Rightarrow -\frac{mk^2}{2E} = (2I+1)^2 \hbar^2 \Rightarrow E = \frac{-mk^2/\hbar^2}{2(2I+1)^2} \quad \text{where } I = \frac{1}{2}, \frac{3}{2}, \dots \\ 2I+1 = 1, 2, 3, \dots$$

$$\frac{mk^2}{\hbar^2} = \frac{me^4}{\hbar^2} = \frac{e^2}{\hbar^2 me^2} = \frac{e^2}{a} = \text{Ryderberg}$$