

Empirical Analysis of Brute-Force and Divide-and-Conquer Algorithms for the 2-D Closest-Pair Problem

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Analysis of Algorithm (COT 6405-001)

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Problem Definition

Problem Name: Closest Pair of Points

Problem Statement:

Given n distinct points P_1, P_2, \dots, P_n in a 2D plane, find the pair of points (P_i, P_j) with the minimum Euclidean distance between them.

Input:

A set of n points where each point $P_i = (x_i, y_i)$ with integer coordinates.

Output:

Indices i, j such that distance between P_i and P_j is minimized.

Real-world Applications:

- Pattern recognition
- Geographic information systems (GIS)
- Robotics and navigation
- Clustering and data mining

Algorithms & Running Time Analysis

Algorithm 1: Brute-Force (ALG1)

BruteForceClosestPoints(P)

// P is a list of n points, $n \geq 2$, $P_1 = (x_1, y_1), \dots, P_n = (x_n, y_n)$

// Returns the index1 and index2 of the closest pair of points

$d_{\min} = \infty$

for $i = 1$ to $n - 1$

 for $j = i + 1$ to n

$d = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$

 if $d < d_{\min}$

$d_{\min} = d$

 index1 = i

 index2 = j

return index1, index2

Time Complexity:

- The outer loop runs $n-1$ times
- The inner loop runs from $i+1$ to n , giving roughly $n(n-1)/2$ iterations

Worst-case runtime: $\Theta(n^2)$

Best-case runtime: Also $\Theta(n^2)$ - always checks all pairs

Algorithm 2: Divide-and-Conquer (ALG2)

DivideAndConquerClosestPoints(P)

// Input: P is a list of n points in 2D

// Returns the closest pair of points

1. Sort the points P by x-coordinate $\rightarrow P_x$
2. Sort the points P by y-coordinate $\rightarrow P_y$
3. return ClosestPair(P_x , P_y)

Function ClosestPair(P_x , P_y)

if $|P_x| \leq 3$ then

 return BruteForceClosestPoints(P_x)

Let Q_x and R_x be the left and right halves of P_x

Let midpoint = $P_x[n/2].x$

Let Q_y = points in P_y with $x \leq \text{midpoint}$

Let R_y = points in P_y with $x > \text{midpoint}$

$(p1, q1) = \text{ClosestPair}(Q_x, Q_y)$

$(p2, q2) = \text{ClosestPair}(R_x, R_y)$

$\delta = \min(\text{distance}(p1, q1), \text{distance}(p2, q2))$

$(p_3, q_3) = \text{ClosestSplitPair}(P_x, P_y, \delta)$

return the pair among (p_1, q_1) , (p_2, q_2) , (p_3, q_3) with the smallest distance

Function $\text{ClosestSplitPair}(P_x, P_y, \delta)$

Let $S_y =$ points within δ of the midpoint line (sorted by y)

for $i = 1$ to $\text{length}(S_y)$

 for $j = i+1$ to $i+7$

 if $j \leq \text{length}(S_y)$

 compute distance and update minimum if needed

return closest split pair

Time Complexity:

Let $T(n)$ be the time to compute the closest pair for n points.

- Dividing the points into two halves: $O(n)$
- Two recursive calls: $2T(n/2)$
- Merging and split pair check: $O(n)$

Worst-case runtime: $\Theta(n \log n)$

Best-case runtime: Still $\Theta(n \log n)$ - since it always recurses

Experimental Results

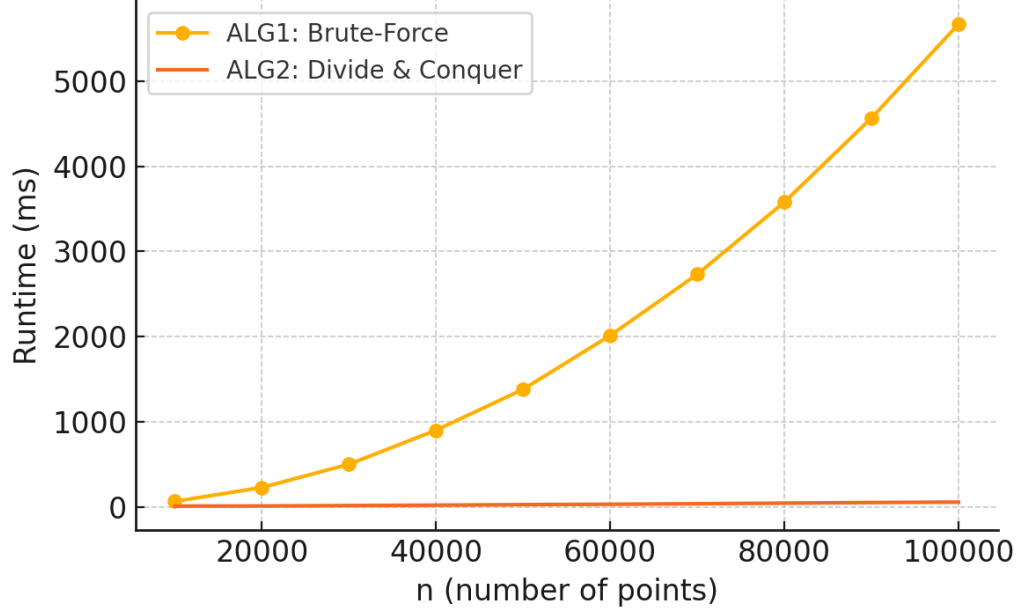
Table ALG1 – Computing constant c_1 for Brute Force

n	TheoreticalRT n^2	EmpiricalRT (msec)	Ratio	Predicted RT
1×10^4	1×10^8	63.52	63.52×10^{-8}	63.52
2×10^4	4×10^8	227.12	56.78×10^{-8}	254.08
3×10^4	9×10^8	500.08	55.56×10^{-8}	571.69
4×10^4	16×10^8	900.15	56.26×10^{-8}	1016.33
5×10^4	25×10^8	1380.44	55.22×10^{-8}	1588.02
6×10^4	36×10^8	2012.45	55.90×10^{-8}	2286.75
7×10^4	49×10^8	2731.82	55.75×10^{-8}	3112.52
8×10^4	64×10^8	3579.47	55.93×10^{-8}	4065.33
9×10^4	81×10^8	4566.79	56.38×10^{-8}	5145.19
10×10^4	100×10^8	5670.44	56.70×10^{-8}	6352.08

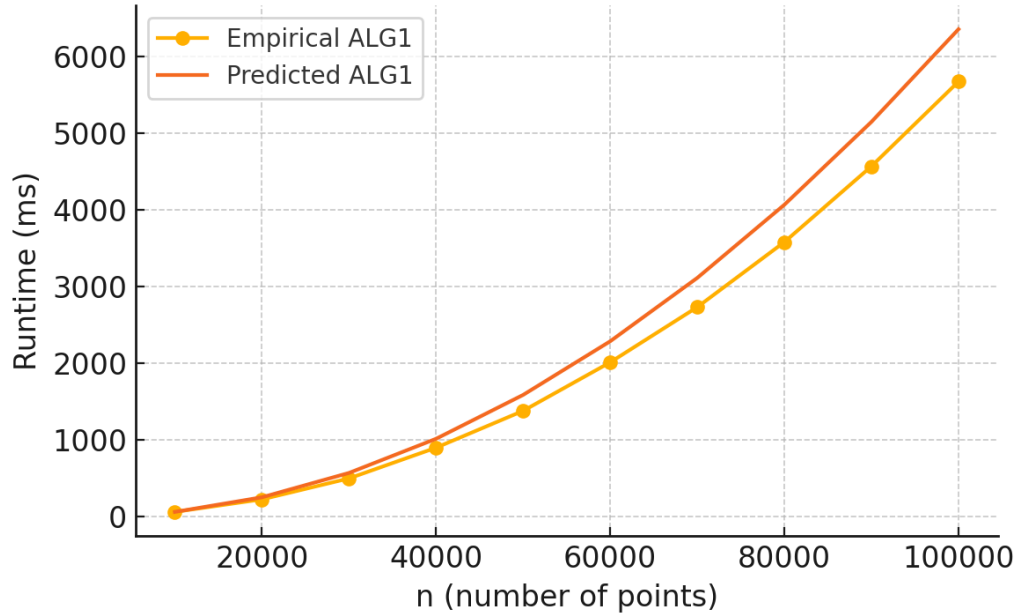
Table ALG2 – Computing constant c_2 for Divide and Conquer

n	TheoreticalRT $n \cdot \log_2(n)$	EmpiricalRT (msec)	Ratio	Predicted RT
1×10^4	132877	8.31	6.25×10^{-5}	8.31
2×10^4	285754	9.60	3.36×10^{-5}	17.87
3×10^4	446180	14.53	3.26×10^{-5}	27.90
4×10^4	611508	19.15	3.13×10^{-5}	38.24
5×10^4	780482	25.48	3.26×10^{-5}	48.80
6×10^4	952360	30.04	3.15×10^{-5}	59.55
7×10^4	1126655	35.96	3.19×10^{-5}	70.45
8×10^4	1303017	42.91	3.29×10^{-5}	81.48
9×10^4	1481187	50.07	3.38×10^{-5}	92.62
10×10^4	1660964	55.23	3.33×10^{-5}	103.86

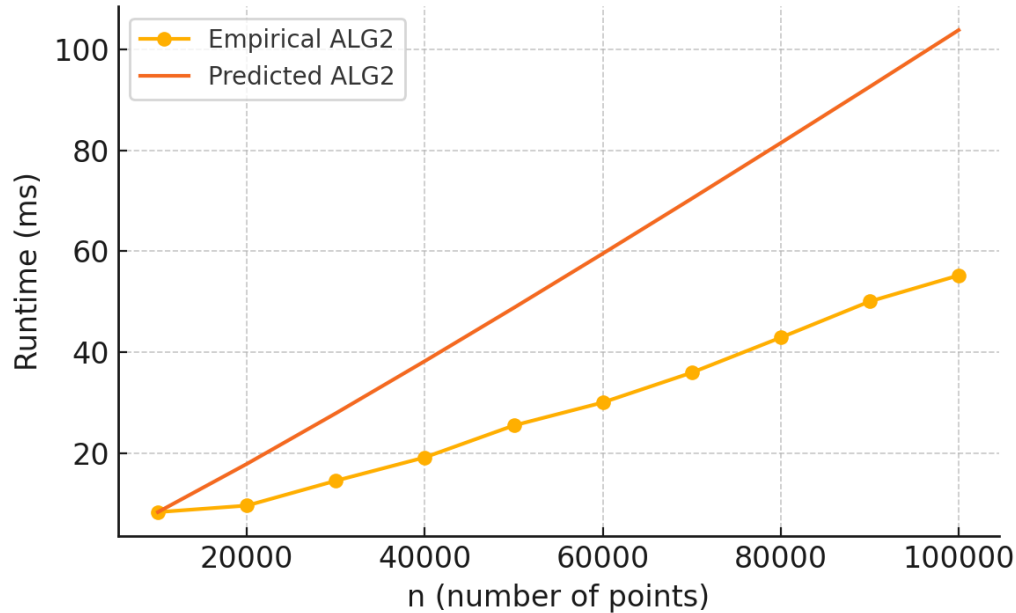
Graph 1: Empirical Running Time Comparison



Graph 2: Brute-Force – Empirical vs Predicted RT



Graph 3: Divide-and-Conquer – Empirical vs Predicted



Conclusions

The experimental results strongly support the theoretical analysis of the two algorithms:

ALG1 – Brute-Force Approach ($\Theta(n^2)$):

- This algorithm performs an exhaustive pairwise comparison of all points, resulting in a quadratic growth in runtime.
- The empirical results confirmed this: as n doubled, the runtime roughly quadrupled.
- It becomes inefficient for larger inputs (e.g., $n > 30,000$), where runtimes exceeded several seconds.
- This aligns precisely with the expected theoretical performance of $\Theta(n^2)$.

ALG2 – Divide-and-Conquer Approach ($\Theta(n \log n)$):

- This algorithm leverages recursive spatial partitioning and only compares relevant candidate pairs near the partition boundary.
- Empirical results show a much more scalable growth pattern, consistent with the logarithmic multiplier.
- ALG2 significantly outperforms ALG1 for all values of n , particularly when n exceeds 20,000.
- The predicted runtime curve based on theoretical complexity closely follows the actual measurements, confirming its asymptotic efficiency.

Constants and Variability:

- Hidden constants c_1 and c_2 were extracted from the ratio of empirical to theoretical runtime.
- Minor fluctuations were observed due to system noise and Java execution overhead, but the trends were stable.
- Graphs show a consistent and expected gap between the performance of ALG1 and ALG2.

Final Verdict:

- For small n , both algorithms are feasible, though ALG1 is simpler to implement.
- For moderate to large n , ALG2 is clearly preferable due to its significantly faster execution time and better scalability.
- This experiment validates both theoretical complexity analysis and practical performance expectations.

Project Demo

Demo: https://youtu.be/8ac1KTX9_9g

Source Code: <https://github.com/JigarPurohit12/Programming-Project>

References

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