

Answer2

December 11, 2024

```
[1]: import torch
      from torchvision.transforms import ToTensor
      from torch.utils.data import DataLoader, Subset
      from torchvision import datasets
      import torch.nn as nn
      import matplotlib.pyplot as plt
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[2]: usps_train = datasets.USPS(root="./data", train=True, transform=ToTensor(),
      ↪download=True)
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[3]: device = 'cuda'
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[4]: class_indices = {i: [] for i in range(10)}
      for idx, (_, label) in enumerate(usps_train):
          if len(class_indices[label]) < 500:
              class_indices[label].append(idx)

      # Collect indices for the final dataset
      final_indices = []
      for indices in class_indices.values():
          final_indices.extend(indices)

      # Subset the dataset
      train_dataset = Subset(usps_train, final_indices)

      # DataLoader
      minibatches = DataLoader(train_dataset, batch_size=500, shuffle=True)

      print(f"Number of samples in training dataset: {len(train_dataset)}")
```

Number of samples in training dataset: 5000

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[5]: class Discriminator(nn.Module):
      def __init__(self):
          super().__init__()
          self.conv1 = nn.Conv2d(in_channels=1, out_channels=8, kernel_size=4,
          ↪stride=2)
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        self.conv2 = nn.Conv2d(in_channels=8, out_channels=16, kernel_size=3,
↪stride=2)
        self.conv3 = nn.Conv2d(in_channels=16, out_channels=1, kernel_size=3,
↪stride=2)
        self.a = nn.Tanh()
        self.s = nn.Sigmoid()

    def forward(self, X):
        X = self.a(self.conv1(X))
        X = self.a(self.conv2(X))
        return self.s(self.conv3(X))[:, :, 0, 0]

class Generator(nn.Module):
    def __init__(self):
        super().__init__()
        self.deconv1 = nn.ConvTranspose2d(in_channels=10, out_channels=16,
↪kernel_size=3, stride=1)
        self.bn1 = nn.BatchNorm2d(16)
        self.deconv2 = nn.ConvTranspose2d(in_channels=16, out_channels=8,
↪kernel_size=3, stride=2)
        self.bn2 = nn.BatchNorm2d(8)
        self.deconv3 = nn.ConvTranspose2d(in_channels=8, out_channels=1,
↪kernel_size=4, stride=2)
        self.a = nn.Tanh()
        self.s = nn.Sigmoid()

    def forward(self, X):
        X = self.a(self.bn1(self.deconv1(X)))
        X = self.a(self.bn2(self.deconv2(X)))
        X = self.s(self.deconv3(X))
        return X

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[6]: G = Generator().to(device)
    D = Discriminator().to(device)

    loss_fn = nn.BCELoss()
    optimizerG = torch.optim.SGD(G.parameters(), lr=0.15)
    optimizerD = torch.optim.SGD(D.parameters(), lr=0.15)

    epochs = 300
    CE_D = torch.zeros(epochs)
    CE_G = torch.zeros(epochs)

    CE_D = torch.zeros(epochs)
    CE_G = torch.zeros(epochs)

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for epoch in range(epochs): # Fixed 'epochs' variable conflict
    for X, _ in minibatches:
        # Loss accumulation for real images
        D.zero_grad()
        X_real = X.to(device)
        Y_real = torch.ones(500).to(device) # Match size of discriminator
        ↪output
        outD_real = D(X_real).squeeze() # Ensure the output is [500]
        loss_real = loss_fn(outD_real, Y_real)

        # Loss accumulation for fake images
        z = torch.randn(500, 10, 1, 1).to(device)
        X_fake = G(z)
        Y_fake = torch.zeros(500).to(device) # Match size of discriminator
        ↪output
        outD_fake = D(X_fake).squeeze() # Ensure the output is [500]
        loss_fake = loss_fn(outD_fake, Y_fake)

        # Gradient descent part for Discriminator
        lossD = loss_real + loss_fake
        lossD.backward()
        optimizerD.step()

        # Training of the Generator
        G.zero_grad()
        z = torch.randn(500, 10, 1, 1).to(device)
        Y = torch.ones(500).to(device) # Generator tries to fool the
        ↪discriminator
        outG = G(z)
        outD_fake_for_G = D(outG).squeeze() # Ensure the output is [500]
        lossG = loss_fn(outD_fake_for_G, Y)
        lossG.backward()
        optimizerG.step()

        # Log the losses
        CE_D[epoch] = lossD.item()
        CE_G[epoch] = lossG.item()
        #print(f"Epoch {epoch + 1}/5, Loss_D: {CE_D[epoch]:.4f}, Loss_G:
        ↪{CE_G[epoch]:.4f}")

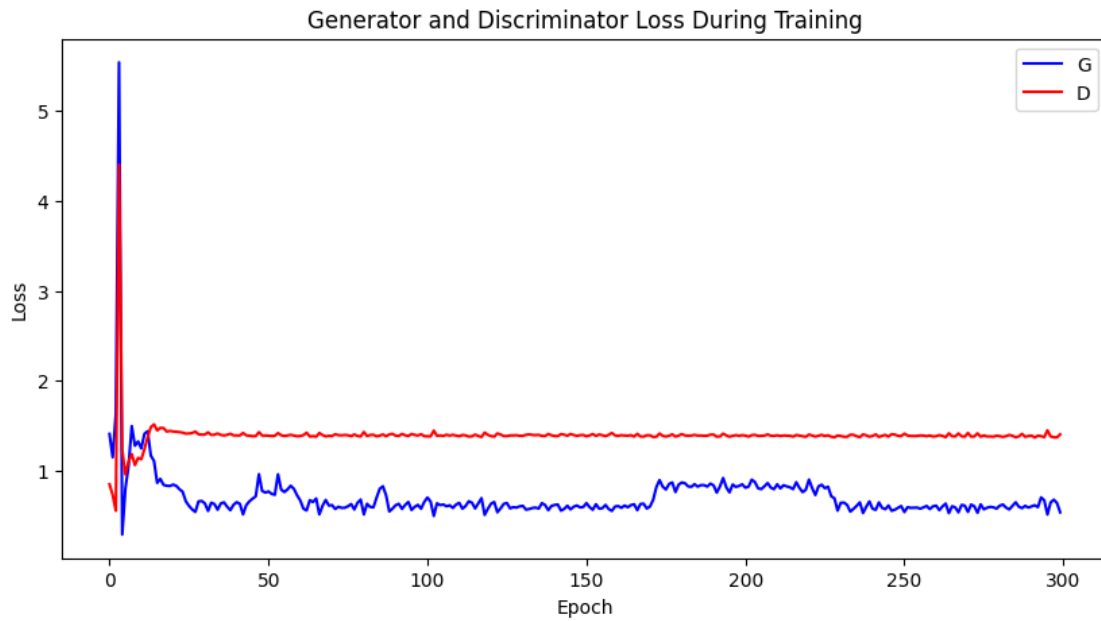
```

```

[7]: plt.figure(figsize=(10,5))
plt.title("Generator and Discriminator Loss During Training")
plt.plot(CE_G.numpy(), label="G", color='blue')
plt.plot(CE_D.numpy(), label="D", color='red')
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.legend()

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plt.show()
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```
[8]: G.eval() # Set the generator to evaluation mode
generated = G(torch.randn(10, 10, 1, 1).to(device))

plt.figure(figsize=(10, 5))
for i in range(10):
    plt.subplot(1, 10, i + 1)
    # Remove channel dimension by indexing [0]
    plt.imshow(generated[i, 0].cpu().detach().numpy(), cmap='gray')
    plt.axis('off') # Hide axes for better visualization
plt.show()
```

