Answer1

December 8, 2024

```
[1]: import torch
     from torchvision.transforms import ToTensor
     from torch.utils.data import DataLoader, Subset
     from torchvision import datasets
     import torch.nn as nn
     import matplotlib.pyplot as plt
[2]: usps_train = datasets.USPS(root="./data", train=True, transform=ToTensor(),_

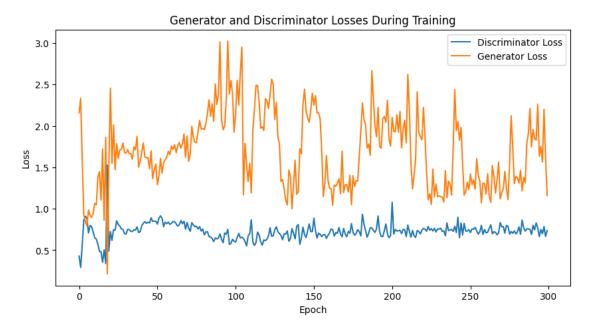
download=True)
[3]: device = 'cuda'
[4]: class_indices = {i: [] for i in range(10)}
     for idx, (_, label) in enumerate(usps_train):
         if len(class_indices[label]) < 500:</pre>
             class_indices[label].append(idx)
     # Collect indices for the final dataset
     final_indices = []
     for indices in class_indices.values():
         final_indices.extend(indices)
     # Subset the dataset
     train_dataset = Subset(usps_train, final_indices)
     # DataLoader
     minibatches = DataLoader(train_dataset, batch_size=500, shuffle=True)
     print(f"Number of samples in training dataset: {len(train_dataset)}")
    Number of samples in training dataset: 5000
[5]: class Generator(nn.Module):
         def __init__(self):
             super().__init__()
             self.l1 = nn.Linear(10, 128)
             self.12 = nn.Linear(128, 16*16)
             self.a = nn.ReLU()
```

```
self.s = nn.Sigmoid()
    def forward(self, X):
        X = self.a(self.l1(X))
        X = self.s(self.12(X))
        return X
class Discriminator(nn.Module):
    def __init__(self):
        super().__init__()
        self.l1 = nn.Linear(16*16, 128)
        self.12 = nn.Linear(128, 1)
        self.a = nn.ReLU()
        self.s = nn.Sigmoid()
    def forward(self, X):
        X = self.a(self.l1(X))
        X = self.s(self.12(X))
        return X
```

```
[6]: G = Generator().to(device)
     D = Discriminator().to(device)
     loss fn = nn.BCELoss()
     lr = 0.15
     optimizerG = torch.optim.SGD(G.parameters(), lr=lr)
     optimizerD = torch.optim.SGD(D.parameters(), lr=lr)
     epochs = 300
     CE_D = torch.zeros(epochs)
     CE_G = torch.zeros(epochs)
     for start in range(epochs):
         for X, Y in minibatches:
             #loss acumalation for real images
             D.zero_grad()
             X_real, Y_real = nn.Flatten()(X), torch.ones((500, 1))
             X_real, Y_real = X_real.to(device), Y_real.to(device)
             outD = D(X_real)
             loss_real = loss_fn(outD, Y_real)
             #loss acumlation for fake images
             z = torch.randn(500, 10).to(device)
             X_{fake}, Y_{fake} = G(z), torch.zeros((500, 1))
             X_fake, Y_fake = X_fake.to(device), Y_fake.to(device)
             outD = D(X fake)
             loss_fake = loss_fn(outD, Y_fake)
             #Gradient descent part for Discriminator
             lossD = loss_real + loss_fake
             lossD.backward()
             optimizerD.step()
```

```
#Training of the Generator
G.zero_grad()
z = torch.randn(500, 10).to(device)
Y = torch.ones((500, 1)).to(device)
outG = G(z)
outD = D(outG)
lossG = loss_fn(outD, Y)
lossG.backward()
optimizerG.step()
CE_D[start] = lossD
CE_G[start] = lossG
```

```
[7]: plt.figure(figsize=(10, 5))
   plt.plot(CE_D.detach().cpu().numpy(), label="Discriminator Loss")
   plt.plot(CE_G.detach().cpu().numpy(), label="Generator Loss")
   plt.xlabel("Epoch")
   plt.ylabel("Loss")
   plt.title("Generator and Discriminator Losses During Training")
   plt.legend()
   plt.show()
```



```
[8]: generated = G(torch.randn(10, 10).to(device))
generated = generated.view(10, 16, 16)

plt.figure(figsize=(15, 3)) # Adjusted figure size for better visualization
for i in range(10):
```

```
plt.subplot(1, 10, i + 1)
  plt.imshow(generated[i].cpu().detach().numpy(), cmap="gray")
  plt.axis("off") # Turn off axis for cleaner display
plt.tight_layout()
plt.show()
```



Answer2

December 11, 2024

```
[1]: import torch
     from torchvision.transforms import ToTensor
     from torch.utils.data import DataLoader, Subset
     from torchvision import datasets
     import torch.nn as nn
     import matplotlib.pyplot as plt
[2]: usps_train = datasets.USPS(root="./data", train=True, transform=ToTensor(),__

download=True)
[3]: device = 'cuda'
[4]: class_indices = {i: [] for i in range(10)}
     for idx, (_, label) in enumerate(usps_train):
         if len(class_indices[label]) < 500:</pre>
             class_indices[label].append(idx)
     # Collect indices for the final dataset
     final_indices = []
     for indices in class_indices.values():
         final_indices.extend(indices)
     # Subset the dataset
     train_dataset = Subset(usps_train, final_indices)
     # DataLoader
     minibatches = DataLoader(train_dataset, batch_size=500, shuffle=True)
     print(f"Number of samples in training dataset: {len(train_dataset)}")
    Number of samples in training dataset: 5000
[5]: class Discriminator(nn.Module):
         def __init__(self):
             super().__init__()
             self.conv1 = nn.Conv2d(in_channels=1, out_channels=8, kernel_size=4,_
      ⇔stride=2)
```

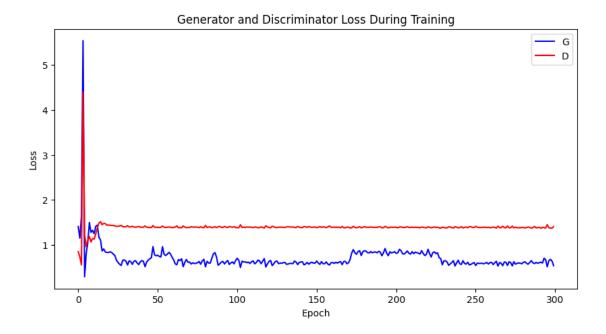
```
self.conv2 = nn.Conv2d(in_channels=8, out_channels=16, kernel_size=3,_u
      ⇔stride=2)
             self.conv3 = nn.Conv2d(in_channels=16, out_channels=1, kernel_size=3,__
      ⇔stride=2)
             self.a = nn.Tanh()
             self.s = nn.Sigmoid()
         def forward(self, X):
             X = self.a(self.conv1(X))
             X = self.a(self.conv2(X))
             return self.s(self.conv3(X))[:, :, 0, 0]
     class Generator(nn.Module):
         def __init__(self):
             super().__init__()
             self.deconv1 = nn.ConvTranspose2d(in_channels=10, out_channels=16,__
      →kernel_size=3, stride=1)
             self.bn1 = nn.BatchNorm2d(16)
             self.deconv2 = nn.ConvTranspose2d(in_channels=16, out_channels=8,_u
      →kernel_size=3, stride=2)
             self.bn2 = nn.BatchNorm2d(8)
             self.deconv3 = nn.ConvTranspose2d(in channels=8, out channels=1,,,
      →kernel_size=4, stride=2)
             self.a = nn.Tanh()
             self.s = nn.Sigmoid()
         def forward(self, X):
             X = self.a(self.bn1(self.deconv1(X)))
             X = self.a(self.bn2(self.deconv2(X)))
             X = self.s(self.deconv3(X))
             return X
[6]: G = Generator().to(device)
     D = Discriminator().to(device)
     loss_fn = nn.BCELoss()
     optimizerG = torch.optim.SGD(G.parameters(), lr=0.15)
     optimizerD = torch.optim.SGD(D.parameters(), lr=0.15)
     epochs = 300
     CE_D = torch.zeros(epochs)
     CE_G = torch.zeros(epochs)
```

CE_D = torch.zeros(epochs)
CE_G = torch.zeros(epochs)

```
for epoch in range(epochs): # Fixed 'epochs' variable conflict
    for X, _ in minibatches:
        # Loss accumulation for real images
        D.zero_grad()
        X_real = X.to(device)
        Y_real = torch.ones(500).to(device) # Match size of discriminator_
 \hookrightarrow output
        outD_real = D(X_real).squeeze() # Ensure the output is [500]
        loss_real = loss_fn(outD_real, Y_real)
        # Loss accumulation for fake images
        z = torch.randn(500, 10, 1, 1).to(device)
        X fake = G(z)
        Y_fake = torch.zeros(500).to(device) # Match size of discriminator_
 \hookrightarrow output
        outD_fake = D(X_fake).squeeze() # Ensure the output is [500]
        loss_fake = loss_fn(outD_fake, Y_fake)
        # Gradient descent part for Discriminator
        lossD = loss_real + loss_fake
        lossD.backward()
        optimizerD.step()
        # Training of the Generator
        G.zero_grad()
        z = torch.randn(500, 10, 1, 1).to(device)
        Y = torch.ones(500).to(device) # Generator tries to fool the
 \hookrightarrow discriminator
        outG = G(z)
        outD_fake_for_G = D(outG).squeeze() # Ensure the output is [500]
        lossG = loss_fn(outD_fake_for_G, Y)
        lossG.backward()
        optimizerG.step()
    # Log the losses
    CE_D[epoch] = lossD.item()
    CE_G[epoch] = lossG.item()
    #print(f"Epoch {epoch + 1}/5, Loss_D: {CE_D[epoch]:.4f}, Loss_G:\Box
 \hookrightarrow {CE_G[epoch]:.4f}")
```

```
[7]: plt.figure(figsize=(10,5))
    plt.title("Generator and Discriminator Loss During Training")
    plt.plot(CE_G.numpy(), label="G", color='blue')
    plt.plot(CE_D.numpy(), label="D", color='red')
    plt.xlabel("Epoch")
    plt.ylabel("Loss")
    plt.legend()
```





```
[8]: G.eval() # Set the generator to evaluation mode
generated = G(torch.randn(10, 10, 1, 1).to(device))

plt.figure(figsize=(10, 5))
for i in range(10):
    plt.subplot(1, 10, i + 1)
    # Remove channel dimension by indexing [0]
    plt.imshow(generated[i, 0].cpu().detach().numpy(), cmap='gray')
    plt.axis('off') # Hide axes for better visualization
plt.show()
```

