

Assignment 4

*Course: EE708, Fundamentals of Data
Science and Machine Intelligence*

Nikhil Jain

Dept: Electrical Engineering

Roll No: 220709

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Step 1: Compute Gini Index Before Splitting

The Gini index is given by:

$$G = 1 - \sum p_i^2 \quad (1)$$

where p_i is the proportion of each class.

For the original dataset:

- Positive samples = 120
- Negative samples = 80
- Total samples = 200

Class probabilities:

$$p_{\text{positive}} = \frac{120}{200} = 0.6, \quad p_{\text{negative}} = \frac{80}{200} = 0.4 \quad (2)$$

Gini index before splitting:

$$G_{\text{before}} = 1 - (0.6^2 + 0.4^2) \quad (3)$$

$$G_{\text{before}} = 1 - (0.36 + 0.16) = 1 - 0.52 = 0.48 \quad (4)$$

Step 2: Compute Weighted Gini Index After Splitting

For the **left subset**:

- Positive samples = 50
- Negative samples = 10
- Total = 60

$$p_{\text{positive}} = \frac{50}{60} \approx 0.833, \quad p_{\text{negative}} = \frac{10}{60} \approx 0.167 \quad (5)$$

$$G_{\text{left}} = 1 - (0.833^2 + 0.167^2) \quad (6)$$

$$G_{\text{left}} = 1 - (0.694 + 0.028) = 1 - 0.722 = 0.278 \quad (7)$$

For the **right subset**:

- Positive samples = 70
- Negative samples = 70
- Total = 140

$$p_{\text{positive}} = \frac{70}{140} = 0.5, \quad p_{\text{negative}} = \frac{70}{140} = 0.5 \quad (8)$$

$$G_{\text{right}} = 1 - (0.5^2 + 0.5^2) \quad (9)$$

$$G_{\text{right}} = 1 - (0.25 + 0.25) = 1 - 0.5 = 0.5 \quad (10)$$

Step 3: Compute Weighted Gini Index

The weighted Gini index after splitting is:

$$G_{\text{after}} = \frac{60}{200}G_{\text{left}} + \frac{140}{200}G_{\text{right}} \quad (11)$$

$$G_{\text{after}} = \frac{60}{200} \times 0.278 + \frac{140}{200} \times 0.5 \quad (12)$$

$$G_{\text{after}} = 0.0834 + 0.35 = 0.4334 \quad (13)$$

Step 4: Check if Purity Improves

Since the Gini index decreased:

$$G_{\text{after}} = 0.4334 < G_{\text{before}} = 0.48 \quad (14)$$

The split improves purity as it reduces impurity.

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Solution:

Given the dataset with two independent variables (x_1, x_2) and one dependent variable (y), we aim to determine the best splitting point for x_1 using the sum of squared errors (SSE) and construct the first split of a regression tree.

Step 1: Compute SSE for Different Splits on x_1

For each possible split s on x_1 , we divide the dataset into two groups:

- **Left group:** $x_1 \leq s$
- **Right group:** $x_1 > s$

For each group, we compute:

1. The mean of y in that group.
2. The SSE for the group:

$$SSE = \sum (y_i - \bar{y})^2 \quad (15)$$

where \bar{y} is the mean of y in that group.

Total SSE for the split is the sum of SSEs for both groups. The split with the lowest SSE is the best.

Step 2: Compute the Best Split

The possible split points for x_1 are:

$$s = \{1.5, 2.5, 3.5, 4.5, 5.5, 6.5, 7.5\}$$

Computing SSE for each split, we find that the best split occurs at $x_1 = 4.5$, resulting in the minimum SSE of:

$$SSE_{\min} = 82.75$$

Step 3: Constructing the First Split

Using $x_1 = 4.5$ as the split:

- **Left node** ($x_1 \leq 4.5$): Data points $(1, 10), (2, 12), (3, 15), (4, 18)$

$$\bar{y}_{\text{left}} = \frac{10 + 12 + 15 + 18}{4} = 13.75$$

- **Right node** ($x_1 > 4.5$): Data points $(5, 21), (6, 25), (7, 28), (8, 30)$

$$\bar{y}_{\text{right}} = \frac{21 + 25 + 28 + 30}{4} = 26$$

Thus, the regression tree's first split is:

$$\text{If } x_1 \leq 4.5, \text{ predict } y = 13.75$$

$$\text{If } x_1 > 4.5, \text{ predict } y = 26$$

This minimizes the total sum of squared errors (SSE).

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Solution:

Step 1: Compute Squared Euclidean Distance

The squared Euclidean distance between a point (x, y) and a centroid (c_x, c_y) is given by:

$$d^2 = (x - c_x)^2 + (y - c_y)^2$$

Given initial centroids:

$$C_1 = (2, 3), \quad C_2 = (5, 8), \quad C_3 = (9, 4)$$

Data points:

$$(1, 2), \quad (3, 4), \quad (6, 7), \quad (8, 3), \quad (5, 5)$$

For each point, we compute:

$$\begin{aligned}
d^2((1,2), C_1) &= (1-2)^2 + (2-3)^2 = 1 + 1 = 2 \\
d^2((1,2), C_2) &= (1-5)^2 + (2-8)^2 = 16 + 36 = 52 \\
d^2((1,2), C_3) &= (1-9)^2 + (2-4)^2 = 64 + 4 = 68 \\
d^2((3,4), C_1) &= (3-2)^2 + (4-3)^2 = 1 + 1 = 2 \\
d^2((3,4), C_2) &= (3-5)^2 + (4-8)^2 = 4 + 16 = 20 \\
d^2((3,4), C_3) &= (3-9)^2 + (4-4)^2 = 36 + 0 = 36 \\
d^2((6,7), C_1) &= (6-2)^2 + (7-3)^2 = 16 + 16 = 32 \\
d^2((6,7), C_2) &= (6-5)^2 + (7-8)^2 = 1 + 1 = 2 \\
d^2((6,7), C_3) &= (6-9)^2 + (7-4)^2 = 9 + 9 = 18 \\
d^2((8,3), C_1) &= (8-2)^2 + (3-3)^2 = 36 + 0 = 36 \\
d^2((8,3), C_2) &= (8-5)^2 + (3-8)^2 = 9 + 25 = 34 \\
d^2((8,3), C_3) &= (8-9)^2 + (3-4)^2 = 1 + 1 = 2 \\
d^2((5,5), C_1) &= (5-2)^2 + (5-3)^2 = 9 + 4 = 13 \\
d^2((5,5), C_2) &= (5-5)^2 + (5-8)^2 = 0 + 9 = 9 \\
d^2((5,5), C_3) &= (5-9)^2 + (5-4)^2 = 16 + 1 = 17
\end{aligned}$$

| Point | $d^2(C_1)$ | $d^2(C_2)$ | $d^2(C_3)$ | Assigned Cluster |
|-------|------------|------------|------------|------------------|
| (1,2) | 2 | 52 | 68 | C_1 |
| (3,4) | 2 | 20 | 36 | C_1 |
| (6,7) | 32 | 2 | 18 | C_2 |
| (8,3) | 36 | 34 | 2 | C_3 |
| (5,5) | 13 | 9 | 17 | C_2 |

Step 2: Compute New Centroids

$$\begin{aligned}
C'_1 &= \left(\frac{1+3}{2}, \frac{2+4}{2} \right) = (2, 3) \\
C'_2 &= \left(\frac{6+5}{2}, \frac{7+5}{2} \right) = (5.5, 6) \\
C'_3 &= (8, 3)
\end{aligned}$$

| Cluster | Assigned Points | New Centroid |
|---------|-----------------|--------------|
| C_1 | (1,2), (3,4) | (2, 3) |
| C_2 | (6,7), (5,5) | (5.5, 6) |
| C_3 | (8,3) | (8, 3) |

Step 3: Compute Distortion

$$D_{\text{initial}} = 2 + 2 + 2 + 9 + 2 + 2 + 9 = 28$$

New distortion:

$$D_{\text{new}} = 2 + 2 + 1.25 + 1.25 + 0 = 6.5$$

Since $D_{\text{new}} = 6.5$ is less than $D_{\text{initial}} = 28$, the distortion has decreased, indicating improved clustering.

Final Answer:

- New centroids after one iteration: $C'_1 = (2, 3)$, $C'_2 = (5.5, 6)$, $C'_3 = (8, 3)$.
- The distortion decreases from 28 to 6.5, confirming an improved clustering arrangement.

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Solution:

We need to maximize the expectation of the complete log-likelihood function with respect to Σ_k and π_k , while keeping the responsibilities $\gamma(z_{nk})$ fixed.

Expected Log-Likelihood Function

The expectation of the complete log-likelihood function is given by:

$$E_Z[\ln p(X, Z|\mu, \Sigma, \pi)] = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) (\ln \pi_k + \ln \mathcal{N}(x_n|\mu_k, \Sigma_k)). \quad (16)$$

Here, $\gamma(z_{nk})$ represents the posterior responsibility for data point x_n belonging to cluster k .

Maximization with respect to π_k

The constraint on mixing coefficients π_k is:

$$\sum_{k=1}^K \pi_k = 1. \quad (17)$$

Using a Lagrange multiplier λ , we maximize:

$$\sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \ln \pi_k + \lambda \left(1 - \sum_{k=1}^K \pi_k \right). \quad (18)$$

Differentiating w.r.t. π_k :

$$\sum_{n=1}^N \frac{\gamma(z_{nk})}{\pi_k} - \lambda = 0. \quad (19)$$

Solving for π_k :

$$\pi_k = \frac{N_k}{N}, \quad \text{where } N_k = \sum_{n=1}^N \gamma(z_{nk}). \quad (20)$$

Maximization with respect to Σ_k

The normal distribution term in the log-likelihood:

$$\ln \mathcal{N}(x_n | \mu_k, \Sigma_k) = -\frac{1}{2} \left(d \ln(2\pi) + \ln |\Sigma_k| + (x_n - \mu_k)^T \Sigma_k^{-1} (x_n - \mu_k) \right). \quad (21)$$

Differentiating w.r.t. Σ_k :

$$\frac{\partial}{\partial \Sigma_k} \sum_{n=1}^N \gamma(z_{nk}) \left(-\frac{1}{2} \ln |\Sigma_k| - \frac{1}{2} (x_n - \mu_k)^T \Sigma_k^{-1} (x_n - \mu_k) \right) = 0. \quad (22)$$

Solving for Σ_k :

$$\Sigma_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) (x_n - \mu_k)(x_n - \mu_k)^T. \quad (23)$$

Final Solutions

Thus, the closed-form solutions are:

$$\pi_k = \frac{N_k}{N}, \quad \Sigma_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) (x_n - \mu_k)(x_n - \mu_k)^T. \quad (24)$$

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Solution:

Consider the given mixture model:

$$p(x) = \sum_{k=1}^K \pi_k p(x | k) \quad (25)$$

where:

- x is the full data vector.
- π_k are the mixing coefficients with $\sum_{k=1}^K \pi_k = 1$.
- $p(x | k)$ are the component densities.
- The sum is taken over K mixture components.

Partitioning the Vector

We partition x into two parts: $x = (x_a, x_b)$. Then, each component density can be written as:

$$p(x | k) = p(x_a, x_b | k) = p(x_b | x_a, k) p(x_a | k). \quad (26)$$

Finding $p(x_b \mid x_a)$

Using the law of total probability:

$$p(x_b \mid x_a) = \frac{p(x_a, x_b)}{p(x_a)}. \quad (27)$$

Substituting the mixture model:

$$p(x_a, x_b) = \sum_{k=1}^K \pi_k p(x_a, x_b \mid k), \quad (28)$$

and marginalizing over x_b :

$$p(x_a) = \sum_{k=1}^K \pi_k p(x_a \mid k). \quad (29)$$

Thus, we obtain:

$$p(x_b \mid x_a) = \frac{\sum_{k=1}^K \pi_k p(x_a \mid k) p(x_b \mid x_a, k)}{\sum_{k=1}^K \pi_k p(x_a \mid k)}. \quad (30)$$

Identifying the Mixture Structure

The above equation is in the form:

$$p(x_b \mid x_a) = \sum_{k=1}^K \tilde{\pi}_k p(x_b \mid x_a, k), \quad (31)$$

where:

- The new mixing coefficients are given by:

$$\tilde{\pi}_k = \frac{\pi_k p(x_a \mid k)}{\sum_{j=1}^K \pi_j p(x_a \mid j)}. \quad (32)$$

- The new component densities remain:

$$p(x_b \mid x_a, k). \quad (33)$$

Conclusion

Thus, the conditional density $p(x_b \mid x_a)$ is itself a mixture distribution with updated mixing coefficients $\tilde{\pi}_k$ and component densities $p(x_b \mid x_a, k)$.

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Solution:

(a) Log-Likelihood Function

Given a dataset $\{x_1, x_2, \dots, x_N\}$ where each x_i is independently drawn from the Gaussian Mixture Model (GMM):

$$p(x|\Theta) = \sum_{k=1}^K \pi_k \mathcal{N}(x|\mu_k, \Sigma_k) \quad (34)$$

The likelihood of the dataset is:

$$L(\Theta) = \prod_{i=1}^N p(x_i|\Theta) = \prod_{i=1}^N \sum_{k=1}^K \pi_k \mathcal{N}(x_i|\mu_k, \Sigma_k) \quad (35)$$

Taking the logarithm:

$$\log L(\Theta) = \sum_{i=1}^N \log \left(\sum_{k=1}^K \pi_k \mathcal{N}(x_i|\mu_k, \Sigma_k) \right) \quad (36)$$

This is the complete log-likelihood function.

(b) Maximum Likelihood Estimation (MLE) Update Rules

If the component $z_i \in \{1, \dots, K\}$ generating each data point is known (i.e., we know which Gaussian component each data point belongs to), we define an indicator variable:

$$z_{ik} = \begin{cases} 1, & \text{if } x_i \text{ is generated by component } k \\ 0, & \text{otherwise} \end{cases} \quad (37)$$

The complete-data log-likelihood (assuming known z_i) is:

$$\log L(\Theta) = \sum_{i=1}^N \sum_{k=1}^K z_{ik} (\log \pi_k + \log \mathcal{N}(x_i|\mu_k, \Sigma_k)) \quad (38)$$

Maximizing with respect to the parameters:

1. Mixing Coefficients π_k

$$\pi_k = \frac{\sum_{i=1}^N z_{ik}}{N} \quad (39)$$

2. Mean μ_k

$$\mu_k = \frac{\sum_{i=1}^N z_{ik} x_i}{\sum_{i=1}^N z_{ik}} \quad (40)$$

3. Covariance Matrix Σ_k

$$\Sigma_k = \frac{\sum_{i=1}^N z_{ik} (x_i - \mu_k)(x_i - \mu_k)^T}{\sum_{i=1}^N z_{ik}} \quad (41)$$

These are the MLE update rules for a Gaussian Mixture Model when the component generating each data point is known.

7 .

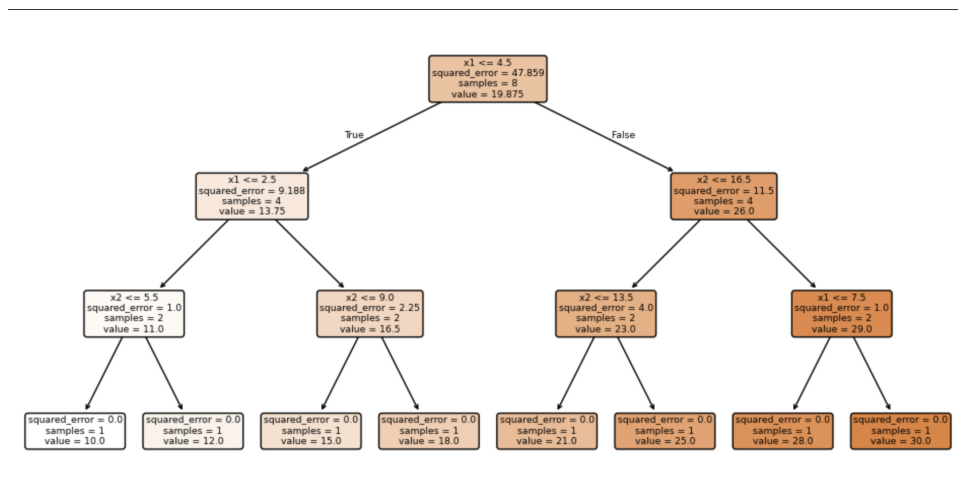


Figure 1: Regression plot

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a.

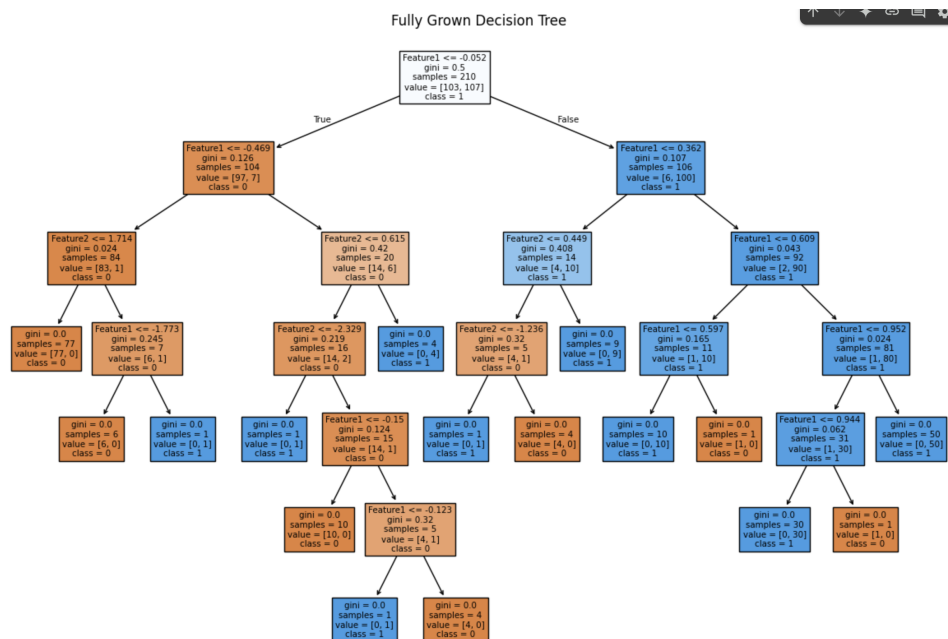


Figure 2: DT

b.

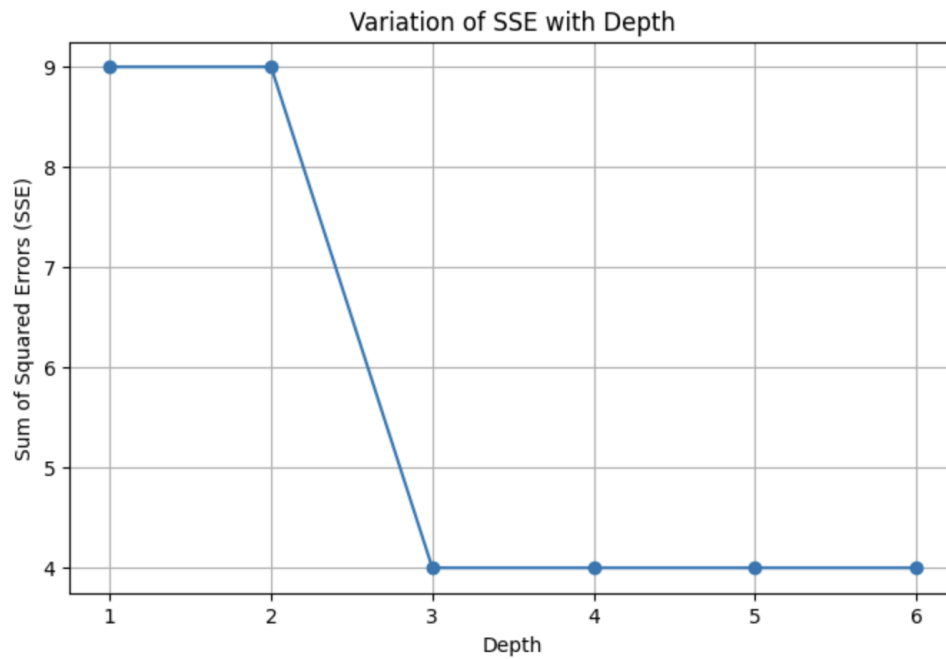


Figure 3: Variatoin plot

- c. Optimal Pruning depth = 1
d.

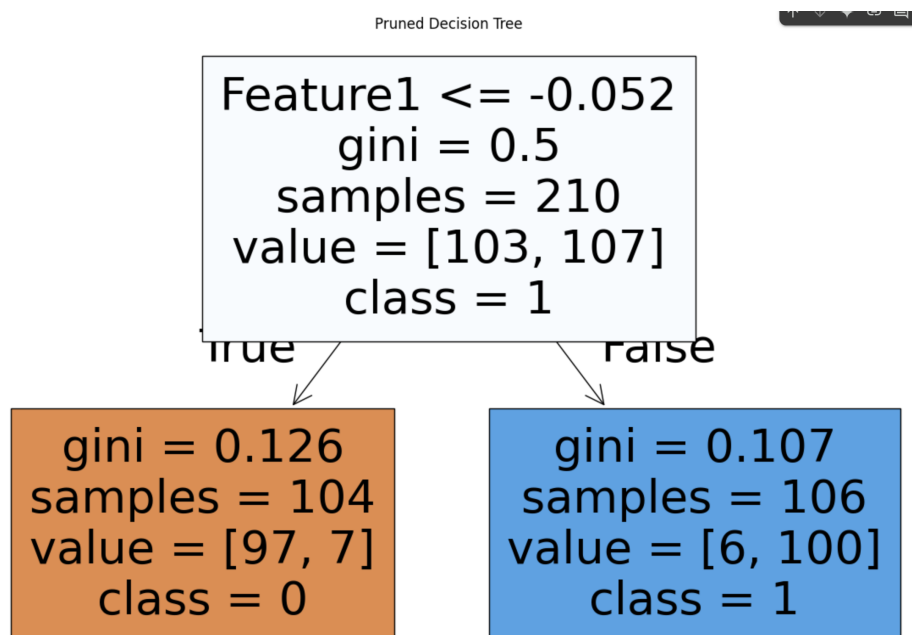


Figure 4: Pruned DT