



**KTH Computer Science
and Communication**

Implementation of “The Train” problem

Statistical Methods in Applied Computer Science, DD2447
Final Project

JIM HOLMSTRÖM JIMHO@KTH.SE
JOHAN GARDELL JGAR@KTH.SE

Teacher: Jens Lagergren

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Chapter 1

The Problem

1.1 Problem formulation ¹

G is undirected and all vertices has degree 3. At each vertex the edges are labeled 0, L, and R (an edge can have different labels at different vertices). So a vertex is a switch. Start positions and switch settings have uniform priors.

A switch setting is a function $\sigma : V(G) \rightarrow \{L, R\}$, which has the natural interpretation. By a position we mean a pair (v, e) , where $v \in V(G)$ and $e \in E(G)$, with the interpretation that the train has passed v and exited through e .

Below we give a DP algorithm for $p(s, O, G | \sigma)$. We will estimate $p(\sigma | G, O)$ using MCMC and then $p(s | G, O)$ using:

$$p(s | G, O) = \sum_{\sigma} p(s, \sigma | G, O) = \sum_{\sigma} p(s | \sigma, G, O) p(\sigma | G, O) = \sum_{\sigma} \frac{p(s, G, O | \sigma) p(\sigma | G, O)}{p(G, O | \sigma)} \quad (1.1)$$

The probability p is 0.05. Given $G, \sigma, s \in V(G)$ (s is a stop position), $O \in \{L, R, 0\}^T$ (observed switch signals), we can compute $p(s, G, O | \sigma)$ using DP and in each step compute the probability of going from some position s' to s in t steps and observing $O_{1:t} = \{o_i\}_{i=1}^t$ when the switch settings are σ . By doing this for all stop positions s and then summing out the stop position, we obtain $p(O | G, \sigma)$ in time $\mathcal{O}(N^2 T)$, where $N = |V(G)|$.

The states in our HMM are positions. The transition probabilities are always 1, i.e., given how we enter a vertex it is uniquely determined how we exit (since switches are fixed). Also, when passing a switch the correct direction of the label of the position is emitted with probability $1 - p$ and any different direction is emitted with probability $p/2$.

Let $c(s, t)$ be computed as below (we want $c(s, t)$ to be the probability of going from some position s' to $s = (v, e)$ in t steps and observing $O_{1:t}$). Let $f = (u, v)$ and $g = (w, v)$ be the two edges that are incident with v but different from e .

¹ This formulation has some minor differences but it should still be equivalent with the original one.

$$c(s, t) = \begin{cases} 1/N, & t = 0 \\ [c((u, f), t - 1) + c((w, g), t - 1)] (1 - p) & e = 0 \wedge o_t = 0 \\ [c((u, f), t - 1) + c((w, g), t - 1)] p & e = 0 \wedge o_t \neq 0 \\ [c((u, f), t - 1)] (1 - p) & e = L \wedge o_t = L \wedge f = 0 \\ [c((u, f), t - 1)] p & e = L \wedge o_t \neq L \wedge f = 0 \\ [c((u, f), t - 1)] (1 - p) & e = R \wedge o_t = R \wedge f = 0 \\ [c((u, f), t - 1)] p & e = R \wedge o_t \neq R \wedge f = 0 \end{cases} \quad (1.2)$$

Chapter 2

Implementation

*The ignoring of G. email Jens bout it

*MCMC *basic basic MCMC abstract theory *MCMC used for estimating $E[f(\sigma)]$ without going through all σ which is intractable. *why is $E[f(\sigma)] = \sum f(\sigma) p(\sigma) = \sum_{\sigma \text{ sampled}} f(\sigma)$ *how it relates to our problem *sigma graph with the weights $Q(\sigma, \sigma')$ which 2^N states (devil) *different algorithms for implementing MCMC *compare the different ones shortly (what they assume) *explain why we chose it *how we chose Q what are the requirements for it *hamming distance measure and pick why hamming? a more natural distance for switch settings than say euclidean or such. *abstractly relate to the graph (what is this type of graph called?) *describe the marginalization over states in $p(\sigma_i)$

Chapter 3

Results & Discussion