

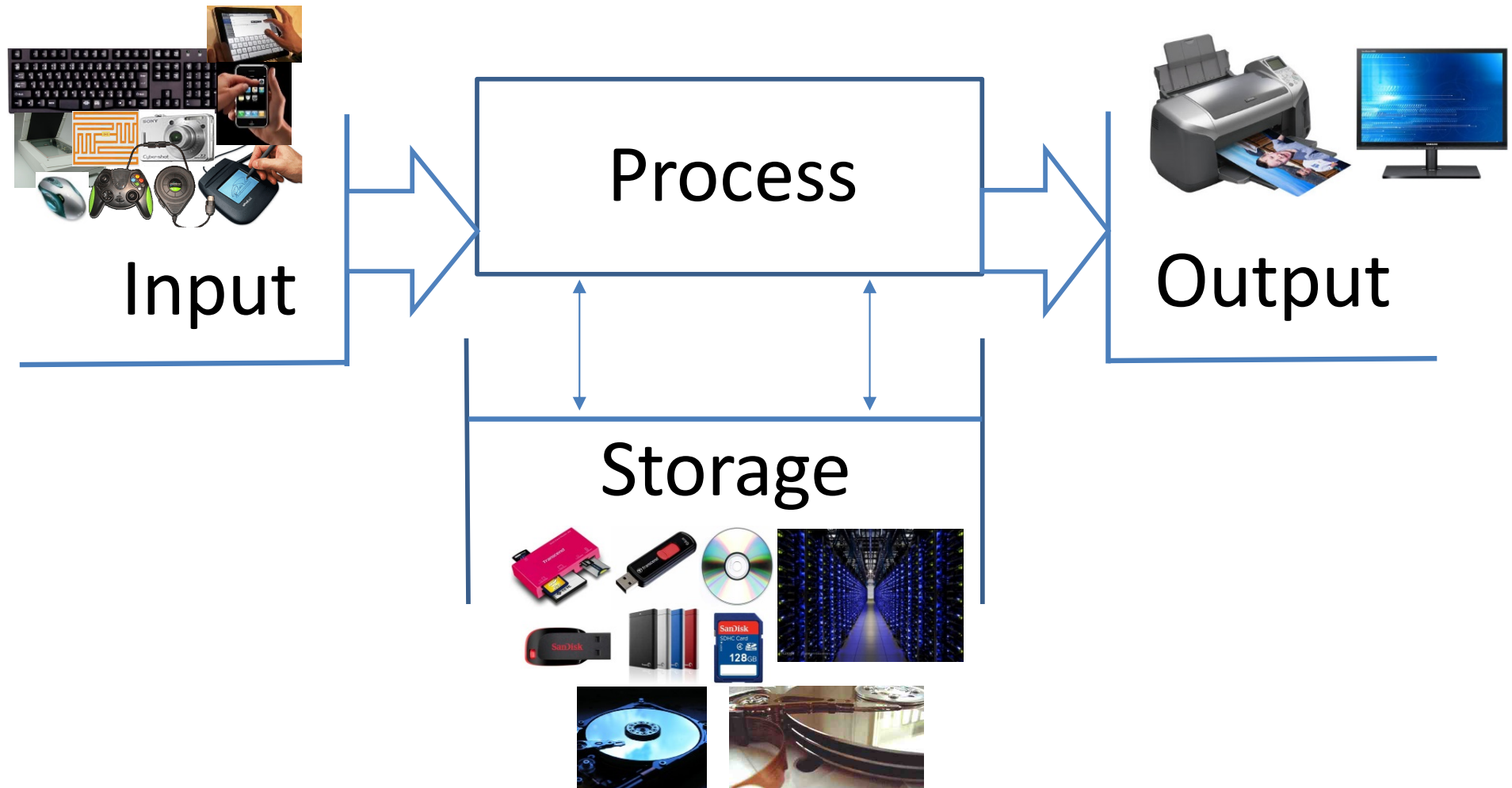
# CT1100: Computer Systems

## Computer Hardware: An Overview

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# Computer Hardware

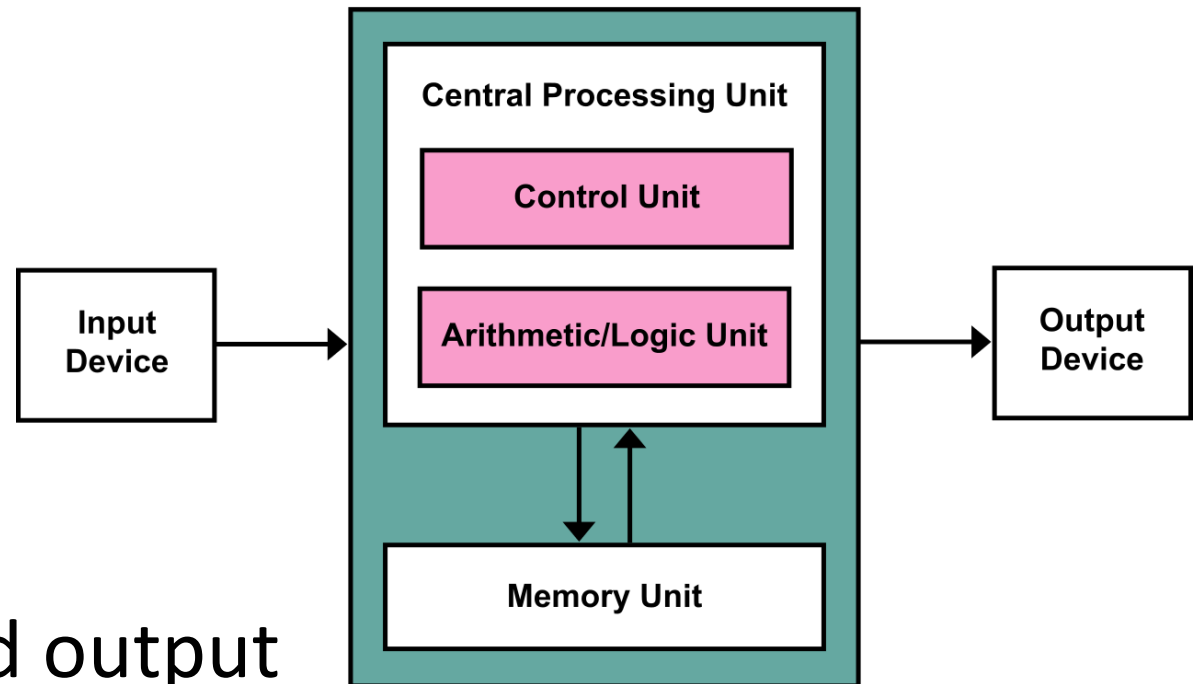


# Computer Architecture

- Computers process the data we input in order to achieve a required output
  - Input data is recognised by the computer as a series of binary numbers (electronic signals)
  - The chip circuitry manipulates these data following the instructions coded in programs
- The computer memory is used to store both data and the program
  - From there, the processor can easily extract the instructions and execute them
  - The program is stored as a series of bit patterns and can be easily altered

# The Processing Cycle

- The CPU
  - ALU
  - Control unit
  - Bus
- Computer memory
- Processing input and output
- Running a computer program
  - Fetch-decode-execute cycle



# Memory

- Memory is a collection of cells, each with a unique physical address; both addresses and contents are in binary
- Contents of a cell may be a value (e.g. number, text, image) or a program instruction

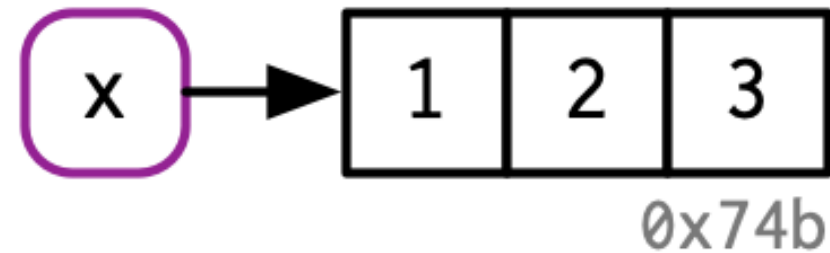
Address	Contents
00000000	11100011
00000001	10101001
:	:
.	.
11111100	00000000
11111101	11111111
11111110	10101010
11111111	00110011

# Memory

- RAM: Random Access Memory (Main memory)
  - Primary storage area
  - On-line, fast, small, directly accessible, volatile, expensive
  - Accessed by address for read and write
- ROM: Read Only Memory
  - Written during manufacture: can only be read by user
- PROM and EPROM
- Extended memory
  - Use of secondary storage as virtual memory

# In R

```
x <- c(1, 2, 3)
```



```
1 library(lobstr)
2
3 x <- c(1, 2, 3)
4
5 obj_addr(x)
```

```
> x
[1] 1 2 3
>
> obj_addr(x)
[1] "0x7f804be9edb8"
```

# Size of objects in memory

```
> y <- rnorm(100,72,10)
```

```
> obj_size(y)
```

```
848 B
```

```
> y <- rnorm(1000000,72,10)
```

```
> obj_size(y)
```

```
8,000,048 B
```

```
> y <- rnorm(1000000000000,72,10)
```

```
Error: vector memory exhausted (limit reached?)
```

```
> y <- rnorm(10000000000,72,10)
```

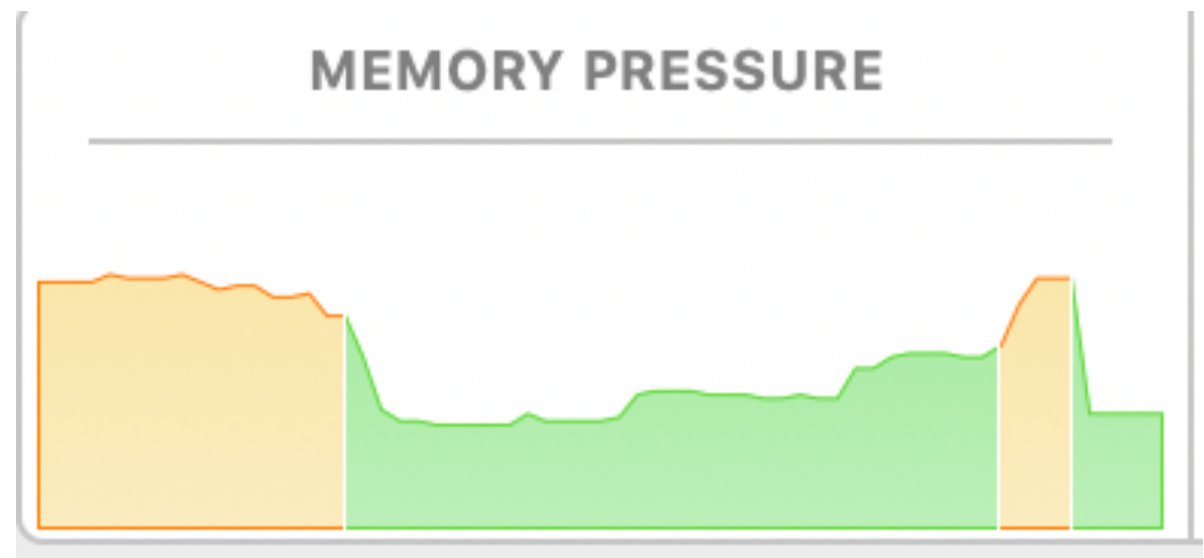
```
> obj_size(y)
```

```
8,000,000,048 B
```



# The impact on System Memory

```
> y <- rnorm(100000000,72,10)
> x <- rnorm(100000000,72,10)
> z <- rnorm(100000000,72,10)
> obj_sizes(x,y,z)
* 800,000,048 B
* 800,000,048 B
* 800,000,048 B
```



# Memory Used

```
> mem_used()
```

```
63,572,952 B
```

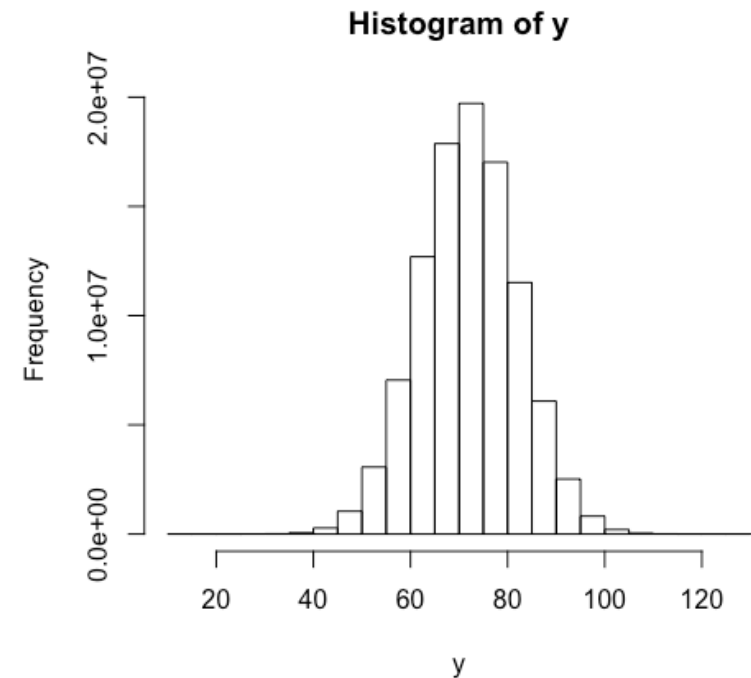
```
>
```

```
> y <- rnorm(100000000, 72, 10)
```

```
>
```

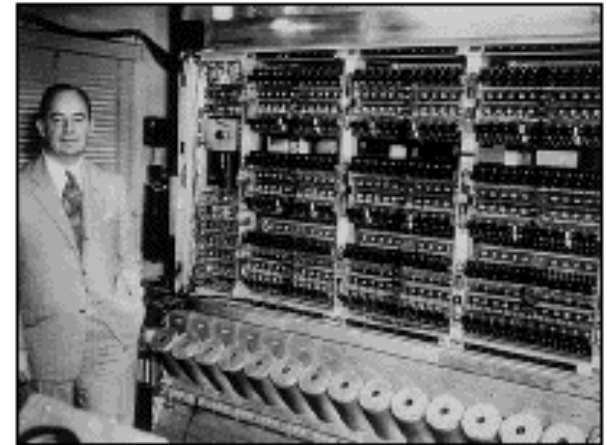
```
> mem_used()
```

```
863,573,152 B
```



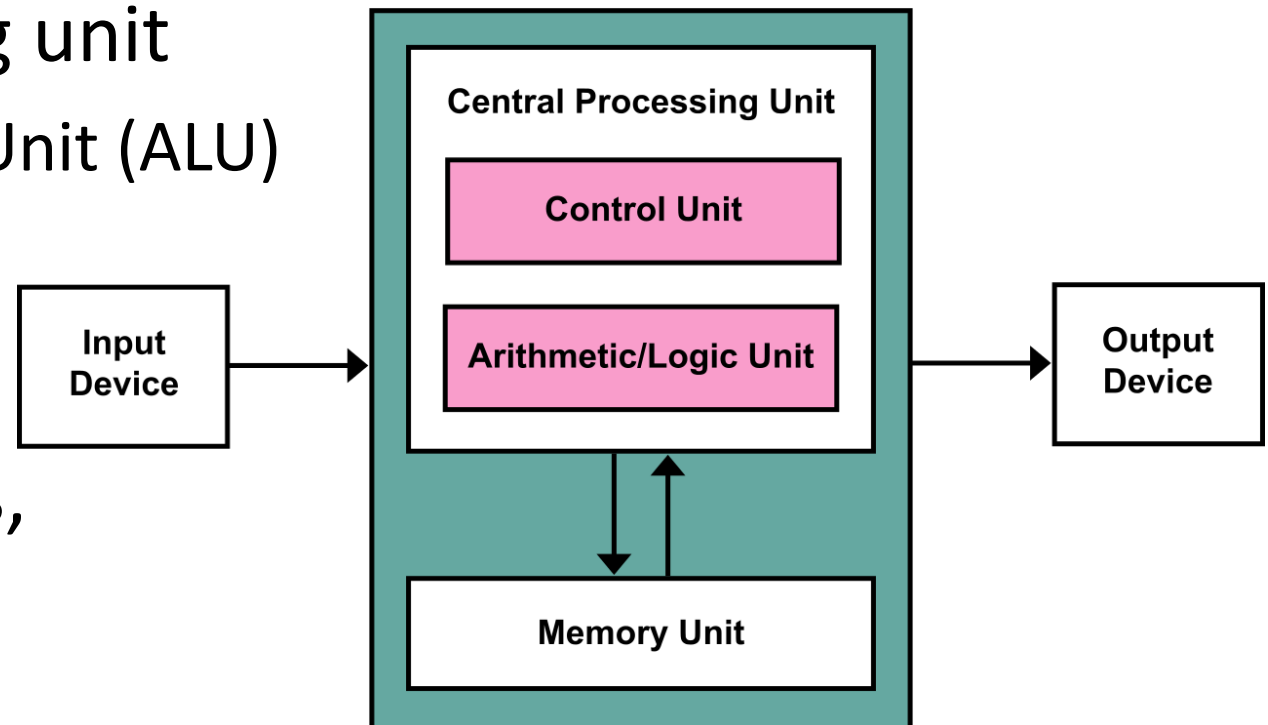
# John von Neumann 1903 - 1957

- 1946 Stored program concept (von Neumann architecture)
  - Program stored in same memory as data
  - Instructions comprise opcode and operand(s)
  - Instructions executed sequentially by Central Processing Unit (CPU)
- Worked on EDVAC, an early computer

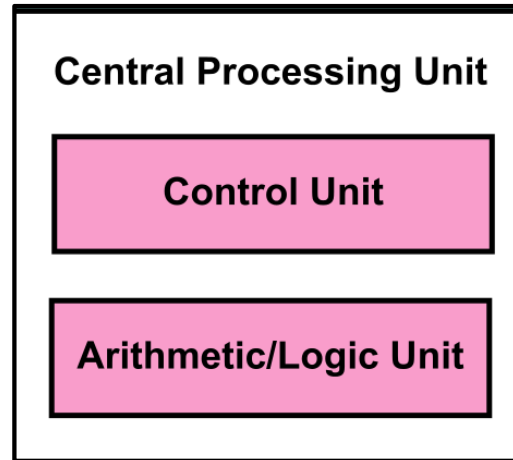


# von Neumann architecture

- Input and output devices
- Central processing unit
  - Arithmetic Logic Unit (ALU)
  - Control Unit
- Memory Unit
- Bus: data, address, control

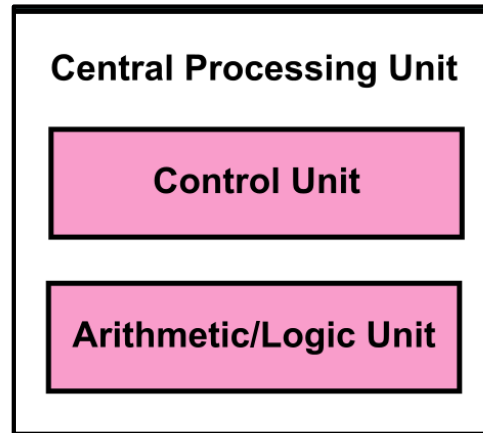


# Central Processing Unit (CPU)



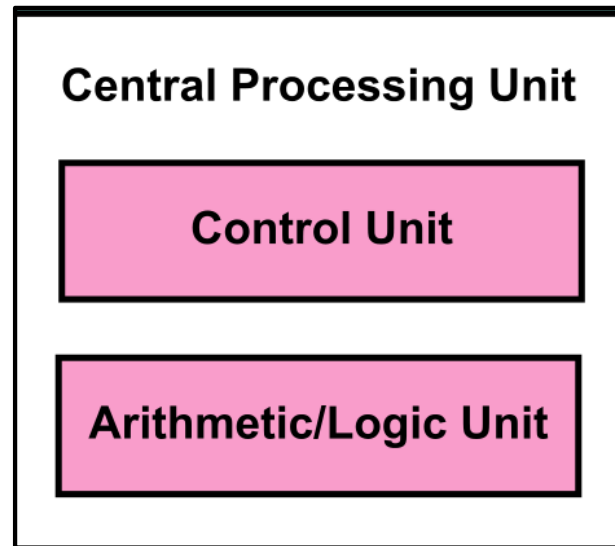
- Manages the *fetching* and *decoding* of programming instructions in sequence
- Causes the processing by the ALU of the arithmetic and logic operations required by the instruction
- Sends out command signals to control the operation of the other elements of the system

# CPU: Arithmetic Logic Unit



- Carries out arithmetic and performs logic operations
- Has available limited number of internal *registers*
  - General purpose registers for temporary storage while doing operations (*accumulators*)
  - Special purpose registers: program counter, instruction register, processor status etc.
- Is directed by the Control unit

# CPU: Control Unit



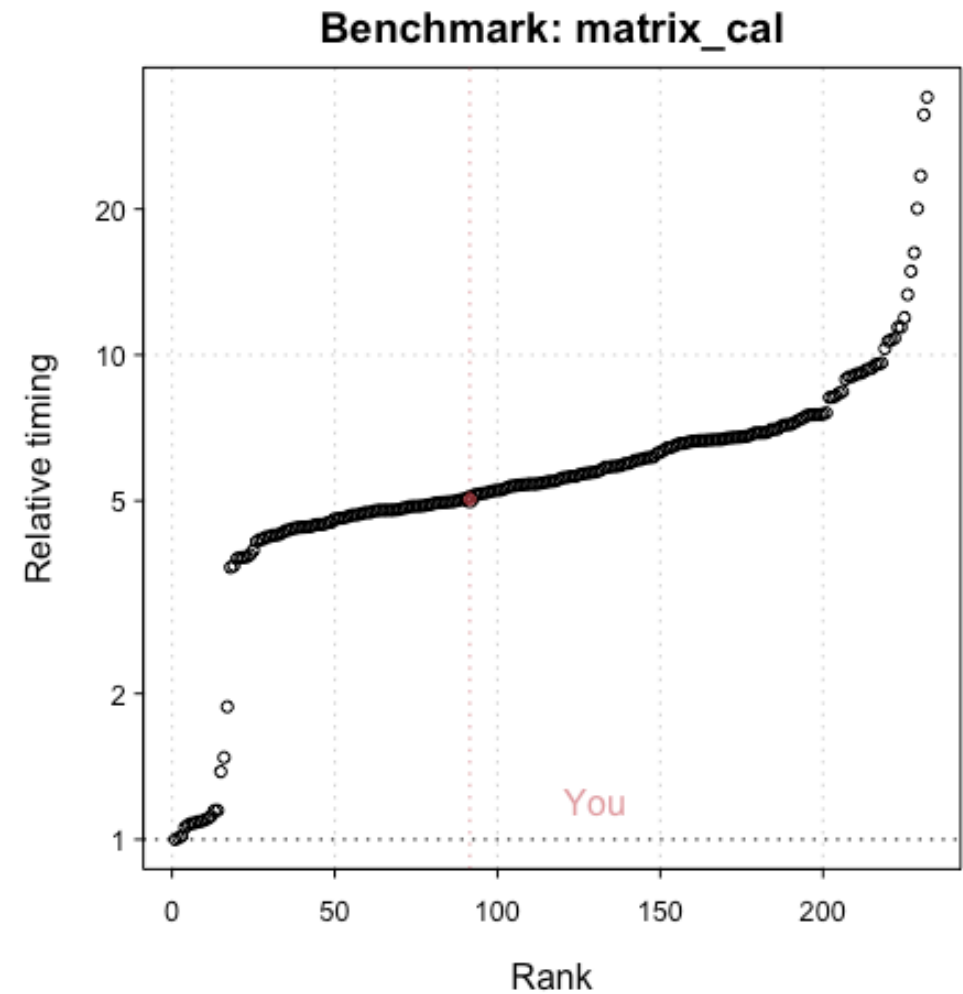
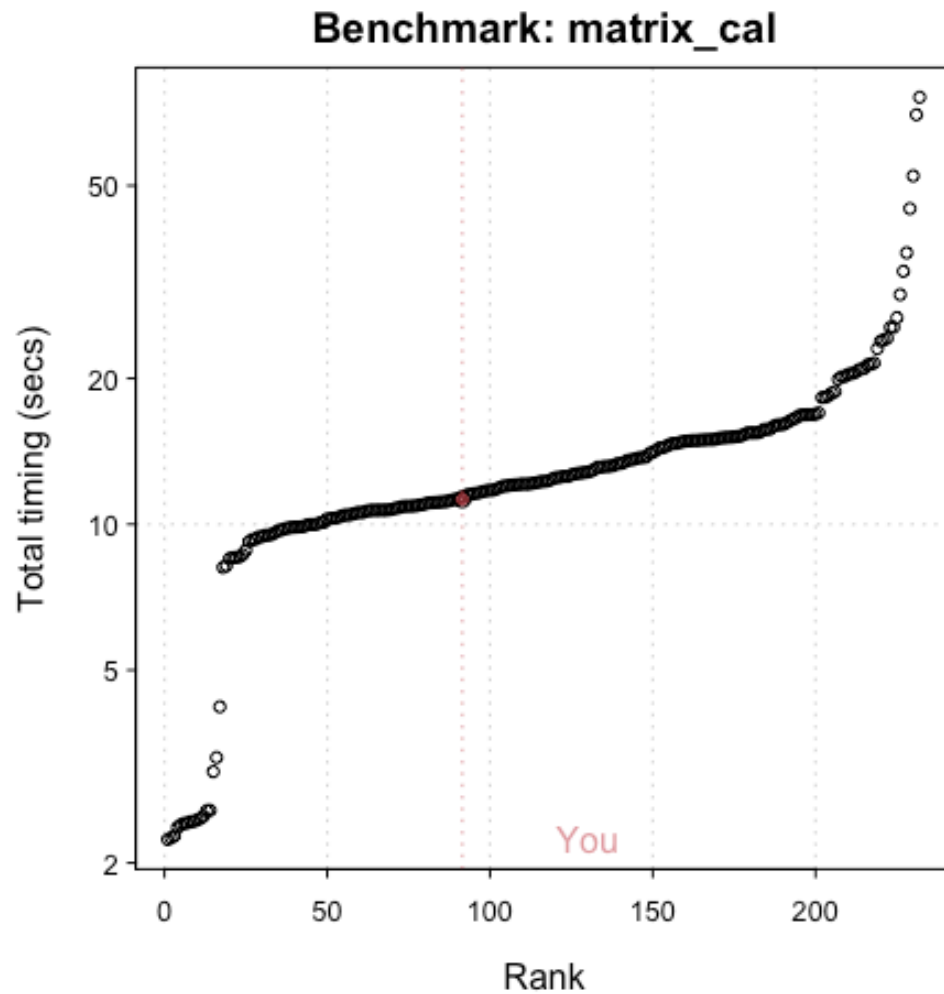
- Controls all activity in the microprocessor
  - Communicates with input and output devices to initiate transfer of instructions and data from memory
  - Fetches instructions from memory, interprets them, and decodes them to produce microinstructions
  - Dictates the correct sequence of operations
- Does not process or store data, just directs

# Benchmarks - Laptop

```
> library(benchmarkme)
> res = benchmark_std()
# Programming benchmarks (5 tests):
  3,500,000 Fibonacci numbers calculation (vector calc): 0.195 (sec).
  Grand common divisors of 1,000,000 pairs (recursion): 0.505 (sec).
  Creation of a 3,500 x 3,500 Hilbert matrix (matrix calc): 0.215 (sec).
  Creation of a 3,000 x 3,000 Toeplitz matrix (loops): 1.12 (sec).
  Escoufier's method on a 60 x 60 matrix (mixed): 1.04 (sec).
# Matrix calculation benchmarks (5 tests):
  Creation, transp., deformation of a 5,000 x 5,000 matrix: 0.481 (sec).
  2,500 x 2,500 normal distributed random matrix^1,000: 0.151 (sec).
  Sorting of 7,000,000 random values: 0.643 (sec).
  2,500 x 2,500 cross-product matrix (b = a' * a): 9.16 (sec).
  Linear regr. over a 5,000 x 500 matrix (c = a \ b'): 0.817 (sec).
# Matrix function benchmarks (5 tests):
  Cholesky decomposition of a 3,000 x 3,000 matrix: 5.25 (sec).
  Determinant of a 2,500 x 2,500 random matrix: 3.46 (sec).
  Eigenvalues of a 640 x 640 random matrix: 0.712 (sec).
  FFT over 2,500,000 random values: 0.233 (sec).
  Inverse of a 1,600 x 1,600 random matrix: 2.87 (sec).
```



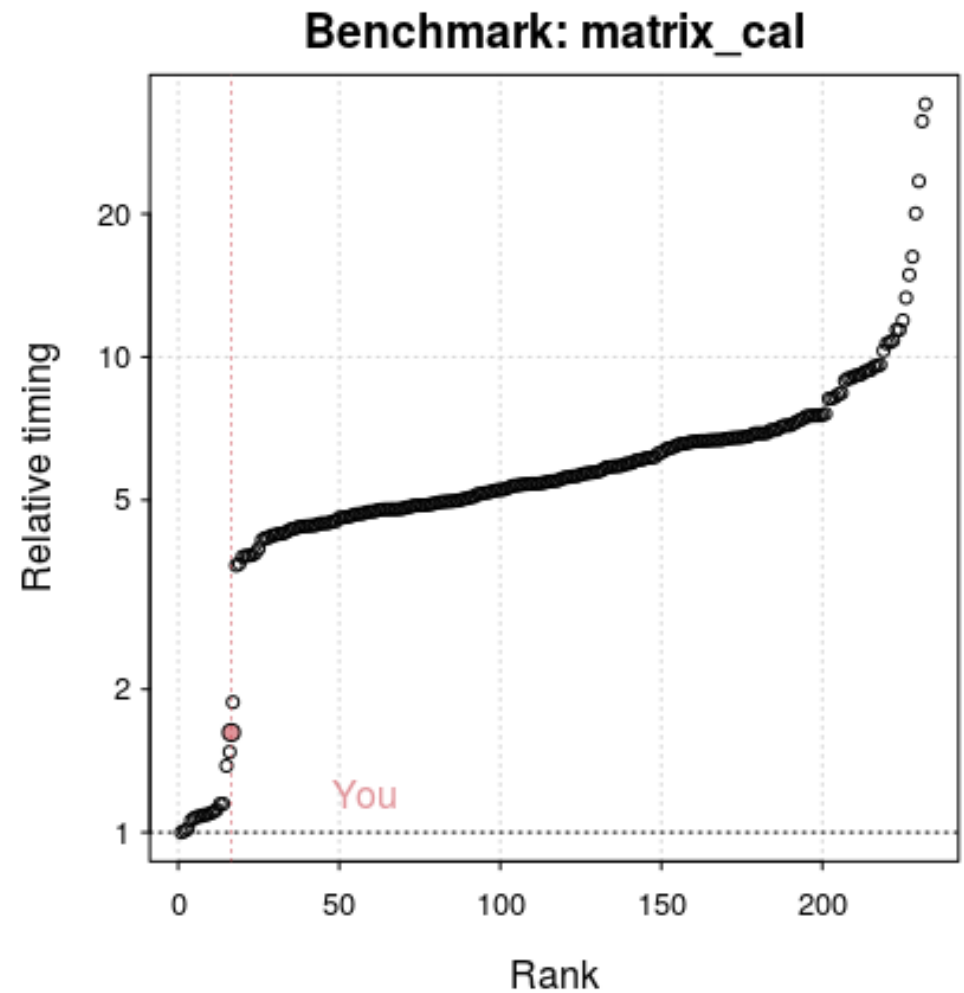
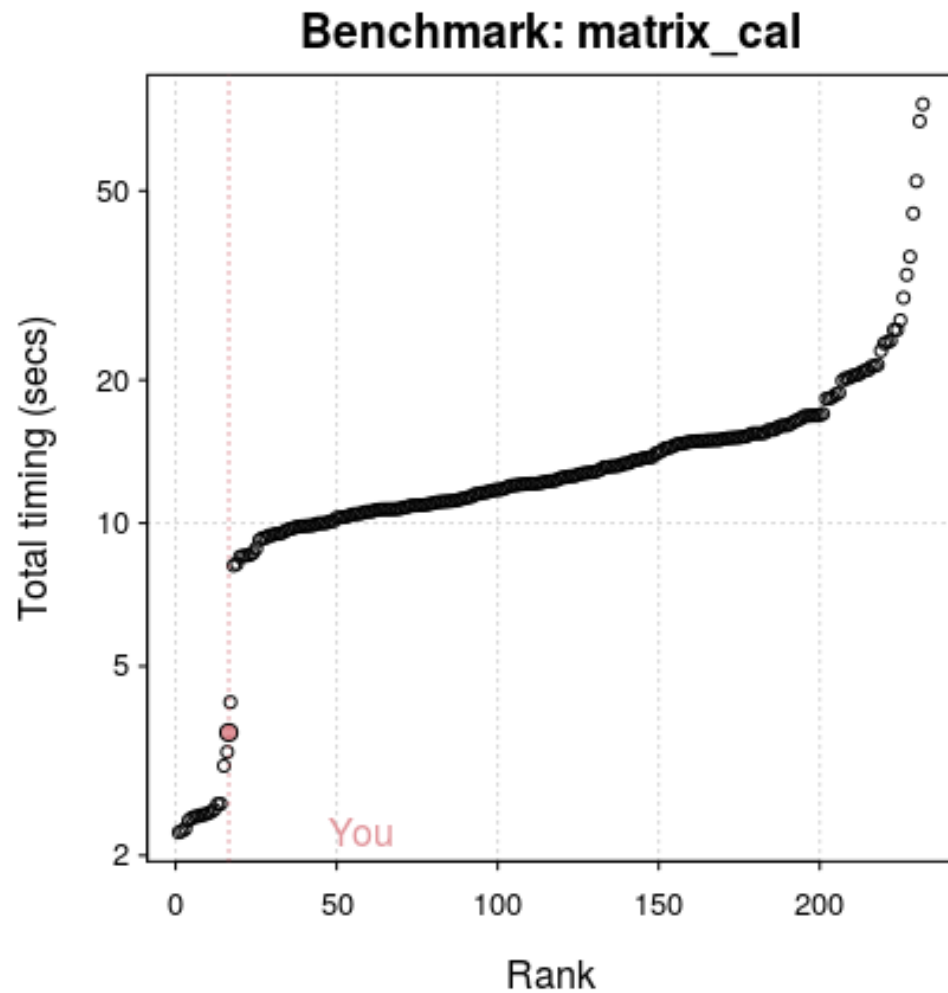
# Comparisons - Laptop



# Benchmarks – Rstudio Cloud

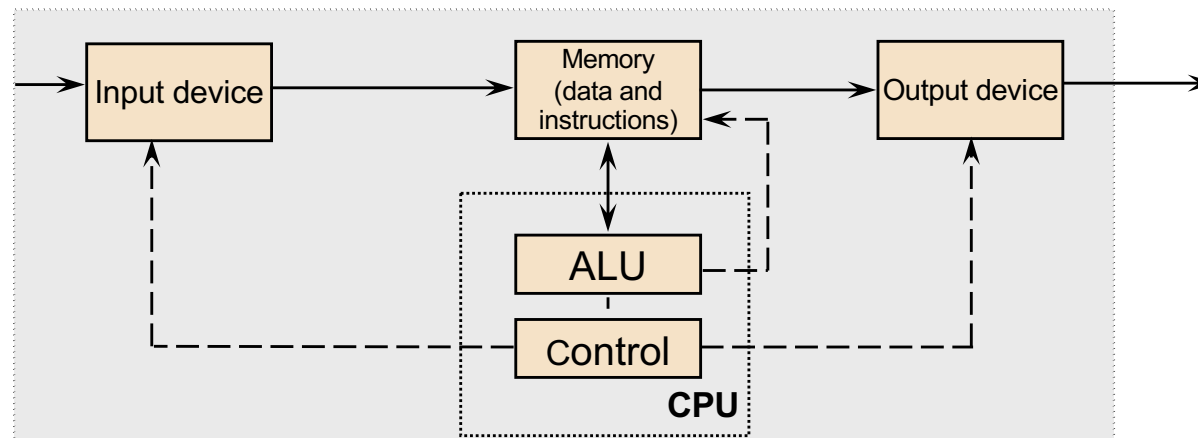
```
> library(benchmarkme)
> res = benchmark_std()
# Programming benchmarks (5 tests):
  3,500,000 Fibonacci numbers calculation (vector calc): 0.605 (sec).
  Grand common divisors of 1,000,000 pairs (recursion): 0.811 (sec).
  Creation of a 3,500 x 3,500 Hilbert matrix (matrix calc): 0.415 (sec).
  Creation of a 3,000 x 3,000 Toeplitz matrix (loops): 1.21 (sec).
  Escoufier's method on a 60 x 60 matrix (mixed): 0.862 (sec).
# Matrix calculation benchmarks (5 tests):
  Creation, transp., deformation of a 5,000 x 5,000 matrix: 0.801 (sec).
  2,500 x 2,500 normal distributed random matrix^1,000: 0.538 (sec).
  Sorting of 7,000,000 random values: 0.84 (sec).
  2,500 x 2,500 cross-product matrix (b = a' * a): 1.32 (sec).
  Linear regr. over a 5,000 x 500 matrix (c = a \ b'): 0.129 (sec).
# Matrix function benchmarks (5 tests):
  Cholesky decomposition of a 3,000 x 3,000 matrix: 0.94 (sec).
  Determinant of a 2,500 x 2,500 random matrix: 0.955 (sec).
  Eigenvalues of a 640 x 640 random matrix: 0.483 (sec).
  FFT over 2,500,000 random values: 0.343 (sec).
  Inverse of a 1,600 x 1,600 random matrix: 0.818 (sec).
```

# Comparisons - RStudio



# Bus

- The bus is a common route way along which the bits travel inside the machine
- Can have 8,16,32 or 64 bit bus (the number of bits travelling in parallel)
- Data bits travelling on the bus are available to any component attached to bus
- Three separate bus pathways: data, address and control



# Computer Bus

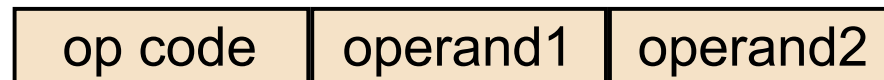
- Data Bus
  - Bus for moving **data** between different units
  - Bi-directional: direction governed by additional signal lines
- Address Bus
  - An address identifies memory locations
  - This is a unidirectional bus carrying **addresses** between microprocessor to memory and I-O
- Control Bus
  - Used to send **control signals** which control access to and use of data and address buses

# Running a Computer Program

- Program instructions are stored in memory in the form:



what is to be done . . . . . with what data

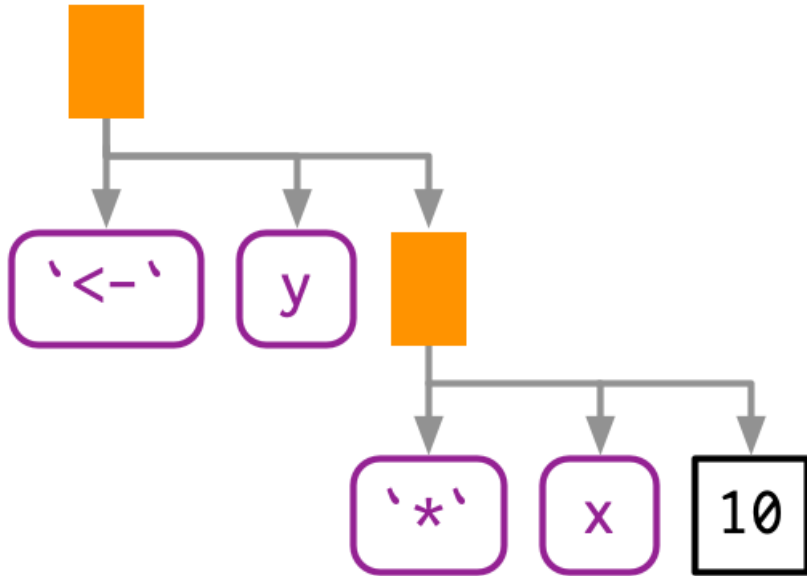


- Processing comprises:
  - **Fetch** the next instruction from memory
  - Determine the type of instruction just fetched (**decode**)
  - If the instruction uses data in memory, determine what they are and fetch them
  - **Execute** the instruction
  - Store the results in the proper place (in memory)

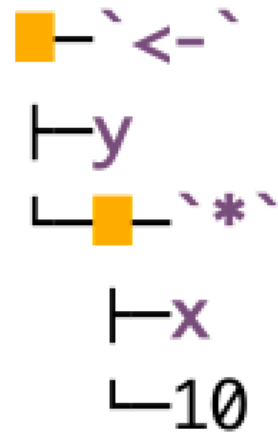
# Fetch-Decode-Execute

- **Fetch:** the address of the next instruction in the program is held in the *program counter register*
  - This address is sent on the address bus to memory with read signal
  - The value is put on the data bus and then stored in the *instruction register*
  - The program counter register is updated to point to the next instruction
- **Decode:** the instruction to be executed is decoded into low-level machine microinstructions
- **Execute:** the decoded instructions are carried out in the ALU

# Computation Idea



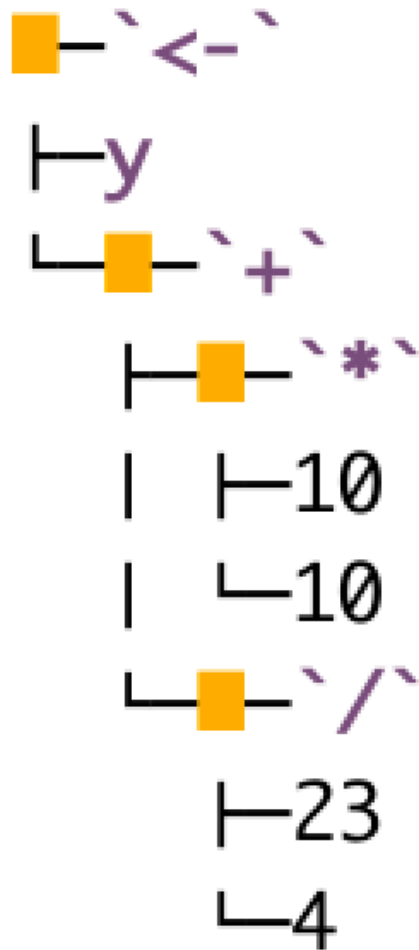
```
> lobster::ast(y <- x * 10)
```





# More complicated equation

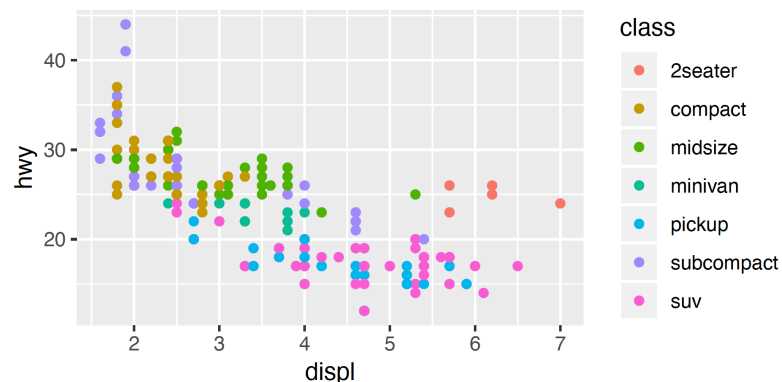
```
> lobstr::ast(y <- 10 * 10 + 23/4)
```



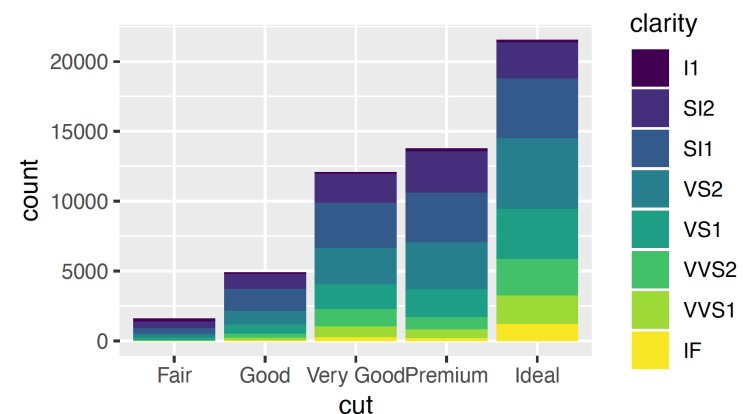
# Course Summary

Lecture(s)	Topic
1	Course Introduction
2	The Processing Cycle and Binary Data
3	Data in R with Atomic Vectors
4	The CRAN Library and Calling Functions in R
5	Tidy Data and Data Frames
6-7	<b>ggplot2</b> - A Grammar of Graphics
8-10	<b>dplyr</b> - A Grammar of Data Manipulation
11-12	Introduction to Hardware

```
ggplot(data=d)+  
  geom_point(aes(x=displ,y=hwy,colour=class))
```



```
ggplot(data=diamonds)+  
  geom_bar(aes(x=cut,fill=clarity))
```



# R Summary

