#### CSCI 5451: Introduction to Parallel Computing

**Lecture 17: Advanced Analytical Modeling** 



#### **Lecture Overview**

- $\square$  Review of Asymptotic Function Growth Rates (Big-O,  $\Omega$ ,  $\Theta$ )
- Scalability and the Definition of Work (W)
- Isoefficiency
- Optimal Computation Time
- Comparing Different Algorithms with Parallel Metrics



#### **Lecture Overview**

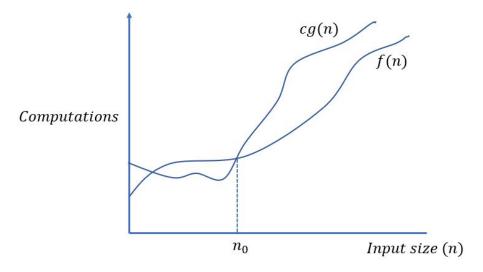
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- Big O (O)
  - o Upper bound on function of interest, *f*
  - o  $f(n) = O(g(n)) \Rightarrow c \cdot g(n)$  is an upper bound for f(n),  $n > n_0$  for some c,  $n_0$
- lacksquare Big  $\Omega$  (Omega)
  - o Lower bound on function of interest, *f*
  - o  $f(n) = \Omega(g(n)) \Rightarrow c \cdot g(n)$  is a lower bound for f(n),  $n > n_0$  for some c,  $n_0$
- □ Big **②** (Theta)
  - o Tight bound on function of interest, *f*
  - o  $f(n) = \Theta(g(n)) \Rightarrow c_1 g(n)$  is a lower bound for f(n),  $c_2 g(n)$  an upper bound for f(n),  $n > n_0$  some  $c_1$ ,  $c_2$ ,  $n_0$

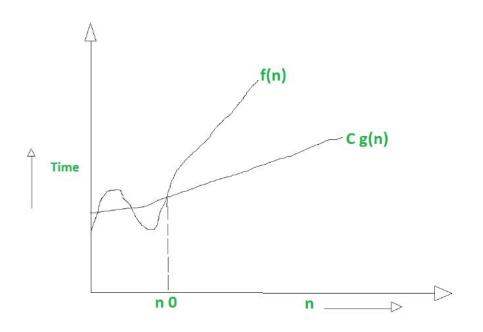


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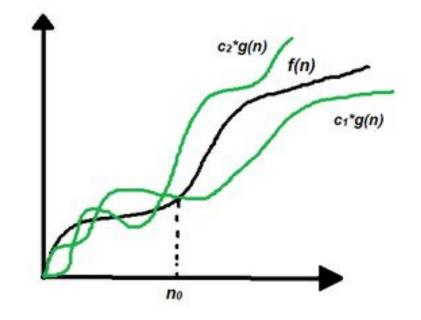


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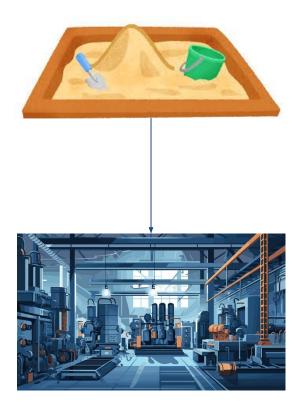
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# Scalability

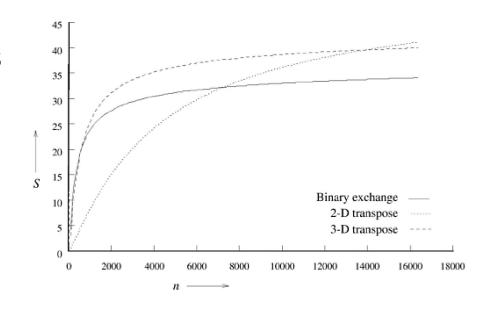
- □ Ultimately, we want to figure out how to go from programs that complete in minutes on dozens of processes to programs which take weeks on thousands of processes
- To do this, we must estimate how efficient our programs will be, as we will not be able to empirically determine their runtimes at such enormous scale





# Scalability

- We have to consider how the efficiency, parallel runtime & speedups of our program change as we vary the size of the input problem and the number of processing elements
- ☐ [Right] Speedup comparison of several different parallel algorithms for Fast Fourier Transform





# Revisiting Efficiency

We can rewrite efficiency in several different ways terms of  $T_o$  and  $T_s$ 

$$egin{aligned} E &= rac{S}{P} \ E &= rac{T_s}{p \, T_p} \ &= rac{1}{1 + \left(rac{T_o}{T_s}
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# Revisiting Efficiency

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#### Increasing the number of processors

- $T_{o}$  is an increasing function of p.
- Every program will have some serial portion taking up time t<sub>serial</sub>
- All other *p-1* processes will idle in this time
- Thus, in the best case,  $T_o = \Omega(p)$
- Other costs (communication, excess computation) can further increase T<sub>o</sub>
- If we fix the problem size, then  $T_s$  will remain constant
- Increasing p will decrease efficiency E



# Revisiting Efficiency

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$$E = rac{S}{P}$$

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#### Increasing the problem size

- Increasing the problem size will increase the size of T<sub>s</sub>
- Increasing the problem size can increase the overhead T<sub>0</sub>
- A good parallel algorithm should have an efficiency that increases as the problem size grows.
- If your algorithm does not exhibit this, it will not scale to larger problems



Let's find some non-asymptotic metrics when summing *N* numbers

- ☐ Sum *n* numbers on *p* processors
- ☐ Assume each addition takes 1 unit time
- Each communication takes 1 unit time
- What are the values of
  - $\circ$  T<sub>s</sub> = ?
  - $\circ$  T<sub>p</sub> = ?
  - $\circ$  T<sub>o</sub> = ?
  - S = ?
  - $\circ$  E = ?

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$$T_s = n$$

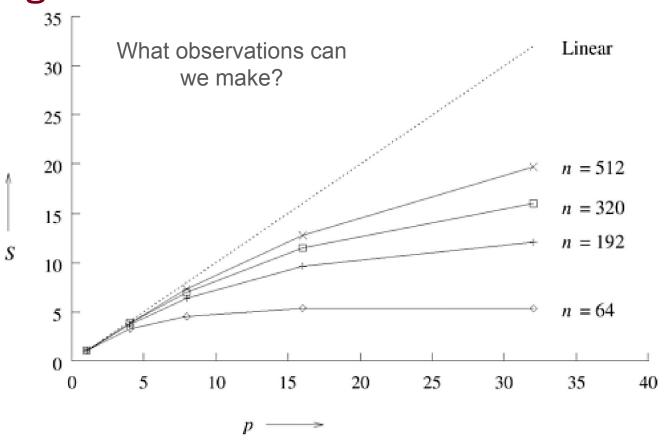
$$T_p = rac{n}{p} + 2\log p$$

$$T_o = 2p \log p$$

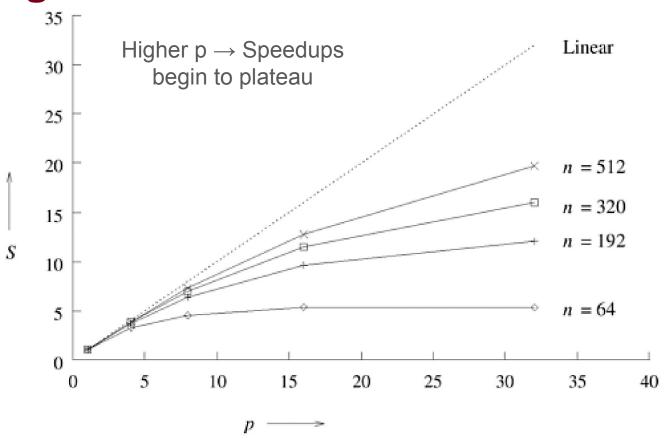
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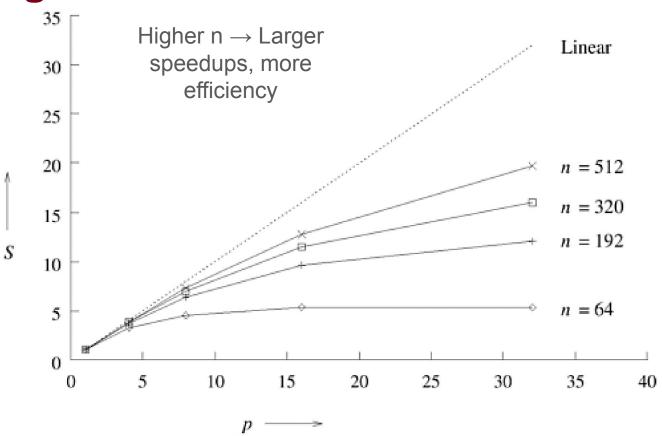














n	p = 1	p = 4	p = 8	p = 16	p = 32
64	1.0	0.80	0.57	0.33	0.17
192	1.0	0.92	0.80	0.60	0.38
320	1.0	0.95	0.87	0.71	0.50
512	1.0	0.97	0.91	0.80	0.62



For a given number of processors, p, and efficiency, E, we can determine the problem size needed (in this case n)

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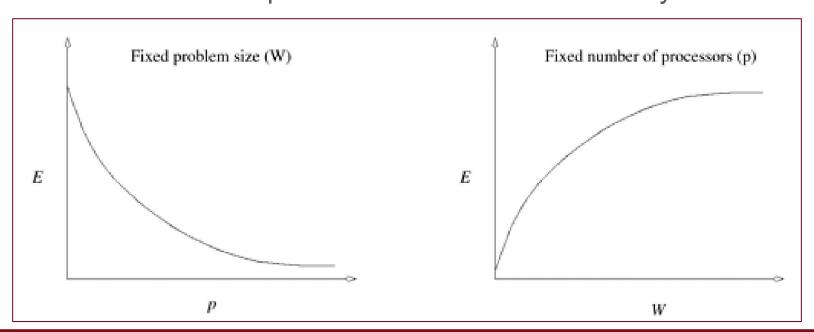
#### IsoEfficiency

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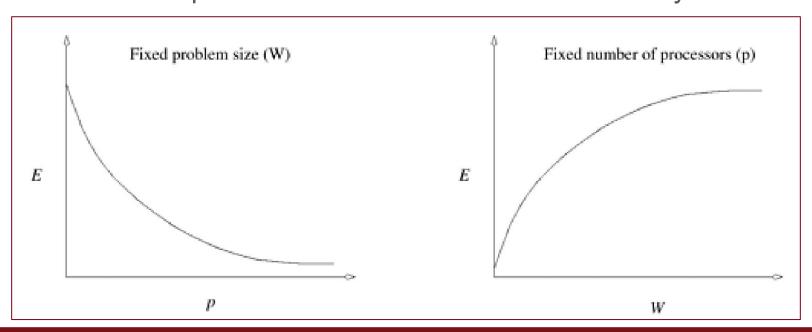
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General Observation #1:
With a fixed problem size, increasing the amount of processors **decreases** efficiency

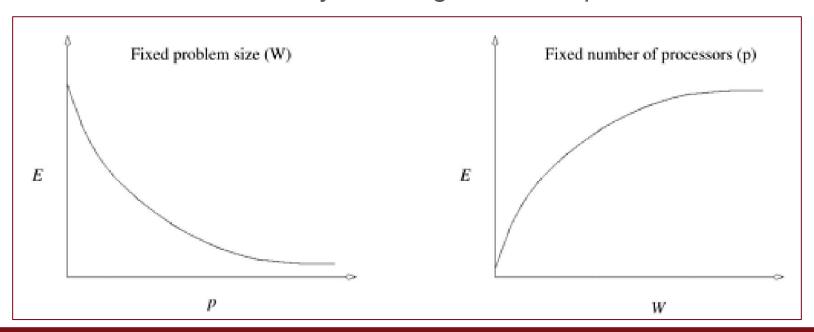


General Observation #2: With a fixed number of processors, increasing the problem size **often increases** efficiency



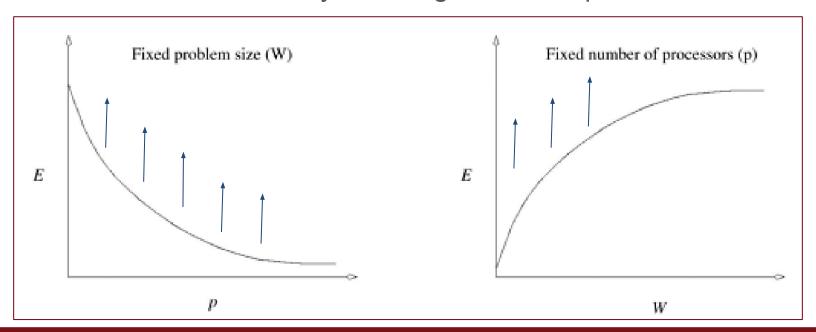


What would be more ideal versions of the below curves? In other words, how would we want efficiency to change w.r. to *W,p?* 





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# Formally Defining Work W

- ☐ Up to this point, we have defined problem sizes & work in informal terms
- Naive way to define this → amount of input data n
- Problem with this?



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- Problem with this?
  - Doesn't reflect runtime
  - Consider multiplying two nxn input matrices
  - o Input is n<sup>2</sup>, runtime is n<sup>3</sup>
- Problem Size (or Work) should reflect the serial execution complexity



# Formally Defining Work W

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  - o Input is n<sup>2</sup>, runtime is n<sup>3</sup>
- → Problem Size (or Work) should reflect the serial execution complexity

Precise definition:
The problem size *W* is defined as the number of computation steps in the *best* sequential algorithm to solve the problem on a single processing element



## Redefining Metrics in Terms of W

$$T_P = rac{W + T_o(W,p)}{p}$$

$$S = rac{W}{T_P} = rac{Wp}{W + T_o(W,p)}$$

$$E=rac{S}{p}=rac{W}{W+T_o(W,p)}=rac{1}{1+rac{T_o(W,p)}{W}}$$



# Deriving W as a function of p, $T_{o'}$ E

$$E \; = \; rac{1}{1+rac{T_o(W,p)}{W}},$$

$$rac{T_o(W,p)}{W} \;=\; rac{1-E}{E},$$

$$oxed{W} \; = \; rac{E}{1-E} \, T_o(W,p) \, ,$$

$$W = K T_o(W, p)$$



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For a constant efficiency, E, we can define the Work, W, as a function of the overhead  $T_o$ 

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IsoEfficiency

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# Isoefficiency

- □ This tells us f we change the number of processors, by what amount must we change the work to keep efficiency constant
- Usefulness → Understanding how well your program will scale when going from smaller problems to bigger ones

 $W = K T_o(W, p)$ 

# Comparing Isoefficiency Functions

For each of the two overhead functions at right

What are their isoefficiency functions?

Which has a better isoefficiency function and why?

(A) 
$$T_o = \log p$$

(B) 
$$T_o = p$$



# Comparing Isoefficiency Functions

For each of the two overhead functions at right

■ What are their isoefficiency functions?

(A) 
$$W = K \log p$$

(B) 
$$W = Kp$$

- Which has a better isoefficiency function and why?
  - A has better scaling. If we increase p from 2 to 64, then maintaining efficiency on (A), requires increasing the work by 6x, whereas on (B) we must increase work by 32x

(A) 
$$T_o = \log p$$

(B) 
$$T_o = p$$



## Isoefficiency (Adding n numbers)

The overhead function for adding n numbers is

$$T_o = 2p \log p$$

The isoefficiency function is

$$W = 2kp\log p$$

- Asymptotically this is ⊕(plogp)
- □ In other words, if we increase the number of processors from p to p', how much will we need to increase the amount of work by to maintain constant efficiency?



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$$rac{p'\log p'}{p\log p}$$

- In the simple example of adding n numbers, the overhead function is simple & only a function of p
- Most overhead functions will be a function of both p and W
- It can be more difficult to define a closed form expression of W
- As such, we instead compute the isoefficiency function for each separate component only considering the function that grows largest as a function of p

$$T_o = p^{3/2} + p^{3/4} W^{3/4}$$



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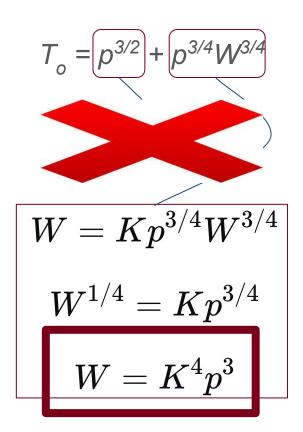
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$$T_{o} = p^{3/2} + p^{3/4}W^{3/4}$$
 $W = Kp^{3/2}$ 
 $W = Kp^{3/4}W^{3/4}$ 
 $W^{1/4} = Kp^{3/4}$ 
 $W = Kp^{3/4}$ 



#### **Take largest**

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#### **Optimal Computation Time**

- □ A common question we may ask is what the minimum parallel runtime (T<sub>p</sub>) is and what the minimum number of processors are needed to achieve this minimum runtime?
- ☐ How can we achieve this?



## **Optimal Computation Time**

- □ A common question we may ask is what the minimum parallel runtime (T<sub>p</sub>) is and what the minimum number of processors are needed to achieve this minimum runtime?
- How can we achieve this?
  - Take the derivative of T<sub>p</sub> with respect to p
  - $\circ$  Find  $p_o$  where this derivative is 0
  - $\circ$  Use this *p* as the input to  $T_p$

$$rac{d}{dp}T_P=0$$

## Optimal Computation Time (Adding n numbers)

$$T_p = rac{n}{p} + 2\log p$$

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$$rac{d}{dp}T_P = -rac{n}{p_0^2} + rac{2}{p_0} = 0,$$
  $-n + 2p_0 = 0,$   $p_0 = rac{n}{2},$   $T_P^{min} = n \log n - n \log 2 + 2$ 

$$oxed{T_P = rac{W}{p} + p^{1/2} + rac{W^{3/4}}{p^{1/4}}}$$

$$rac{d}{dp}T_P = -rac{W}{p_0^2} + rac{1}{2p_0^{1/2}} - rac{W^{3/4}}{4p_0^{5/4}} = 0,$$

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$$T_P = rac{W}{p} + p^{1/2} + rac{W^{3/4}}{p^{1/4}}$$

$$\begin{split} \frac{d}{dp}T_P &= -\frac{W}{p_0^2} + \frac{1}{2p_0^{1/2}} - \frac{W^{3/4}}{4p_0^{5/4}} = 0, \\ -W &+ \frac{1}{2}p_0^{3/2} - \frac{1}{4}W^{3/4}p_0^{3/4} = 0, \\ p_0^{3/4} &= \frac{1}{4}W^{3/4} \pm \left(\frac{1}{16}W^{3/2} + 2W\right)^{1/2} \\ &= \Theta(W^{3/4}), \end{split}$$



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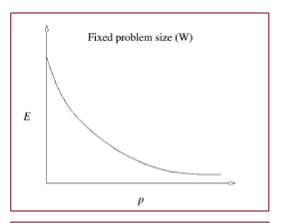
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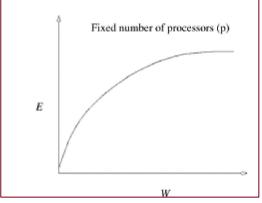


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- These metrics (E, S, isoefficiency, T<sub>o</sub>, etc.) are useful tools for comparing different parallel approaches we can determine which approaches are more scalable
- □ They expand on runtime analysis to show which algorithms will make better use of the processors we utilize, rather than just how much faster the algorithm itself will run







# Consider the below set of algorithms

Algorithm	A1	A2	А3	A4
p	$n^2$	log n	n	$\sqrt{n}$
$T_P$	1	n	$\sqrt{n}$	$\sqrt{n} \log n$
S	n log n	log n	$\sqrt{n} \log n$	$\sqrt{n}$
E	$\frac{\log n}{n}$	1	$\frac{\log n}{\sqrt{n}}$	1
$pT_P$	$n^2$	n log n	$n^{1.5}$	n log n



#### Which is fastest?

Algorithm	A1	A2	А3	A4
p	n <sup>2</sup>	log n	n	$\sqrt{n}$
$T_P$	1	n	$\sqrt{n}$	$\sqrt{n} \log n$
S	n log n	log <i>n</i>	$\sqrt{n} \log n$	$\sqrt{n}$
E	$\frac{\log n}{n}$	1	$\frac{\log n}{\sqrt{n}}$	1
$pT_P$	$n^2$	n log n	$n^{1.5}$	n log n



Which is fastest? (A1)

Algorithm	A1	A2	А3	A4
p	$n^2$	log n	n	$\sqrt{n}$
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S	n log n	log <i>n</i>	$\sqrt{n} \log n$	$\sqrt{n}$
E	$\frac{\log n}{n}$	1	$\frac{\log n}{\sqrt{n}}$	1
$pT_P$	$n^2$	n log n	$n^{1.5}$	n log n



#### Should we use A1?

Algorithm	A1	A2	А3	A4
p	$n^2$	log n	n	$\sqrt{n}$
$T_P$	1	n	$\sqrt{n}$	$\sqrt{n} \log n$
S	n log n	log <i>n</i>	$\sqrt{n} \log n$	$\sqrt{n}$
E	$\frac{\log n}{n}$	1	$\frac{\log n}{\sqrt{n}}$	1
$pT_P$	$n^2$	n log n	$n^{1.5}$	n log n



Should we use A1? No - requiring *p* processors is not practical

Algorithm	<b>A1</b>	A2	А3	A4
p	$n^2$	log n	n	$\sqrt{n}$
$T_P$	1	n	$\sqrt{n}$	$\sqrt{n} \log n$
S	n log n	log <i>n</i>	$\sqrt{n} \log n$	$\sqrt{n}$
E	$\frac{\log n}{n}$	1	$\frac{\log n}{\sqrt{n}}$	1
$pT_P$	$n^2$	n log n	$n^{1.5}$	n log n



Which are cost optimal?

Algorithm	A1	A2	А3	A4
p	$n^2$	log n	n	$\sqrt{n}$
$T_P$	1	n	$\sqrt{n}$	$\sqrt{n} \log n$
S	n log n	log n	$\sqrt{n} \log n$	$\sqrt{n}$
E	$\frac{\log n}{n}$	1	$\frac{\log n}{\sqrt{n}}$	1
$pT_P$	$n^2$	n log n	$n^{1.5}$	n log n



Which are cost optimal? (A2, A4)

Algorithm	A1	A2	А3	A4
p	$n^2$	log n	n	$\sqrt{n}$
$T_P$	1	n	$\sqrt{n}$	$\sqrt{n} \log n$
S	n log n	log n	$\sqrt{n} \log n$	$\sqrt{n}$
E	$\frac{\log n}{n}$	1	$\frac{\log n}{\sqrt{n}}$	1
$pT_P$	$n^2$	n log n	$n^{1.5}$	n log n



What should we use and why?

Algorithm	A1	A2	А3	A4
p	$n^2$	log n	n	$\sqrt{n}$
$T_P$	1	n	$\sqrt{n}$	$\sqrt{n} \log n$
S	n log n	log n	$\sqrt{n} \log n$	$\sqrt{n}$
E	$\frac{\log n}{n}$	1	$\frac{\log n}{\sqrt{n}}$	1
$pT_P$	$n^2$	n log n	$n^{1.5}$	n log n

