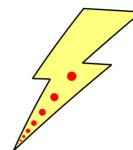
Jim's yucky talk wowee

#### This talk is based on...



# Solving Laplace Problems with Corner Singularities via Rational Functions

- ...A paper written by Gopal and Trefethen, published in SIAM Journal on Numerical Analysis September 2019
- The Lightning Laplace code, based on the paper, yields accurate approximations quickly (on nice problems)
- https://epubs.siam.org/doi/pdf/10.1137/19M125947X
- https://people.maths.ox.ac.uk/trefethen/lightning.html

# Here's the problem

We wish to find a (real) function u over a domain  $\Omega$  (the complex 2-D plane) which satisfies

$$\Delta u(z) = 0, \quad z \in \Omega$$
  $u(z) = h(z), \quad z \in \Gamma.$ 

In particular, we want to be able to handle a domain with sharp corners, curves etc.

We will find r, and approximation of u ( $u \approx \text{Re}[r]$ ).

$$r(z) = \sum_{j=1}^{N_1} \frac{a_j}{z - z_j} + \sum_{j=0}^{N_2} b_j (z - z_*)^j$$

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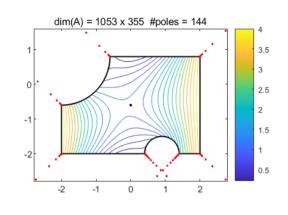
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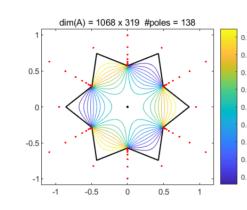
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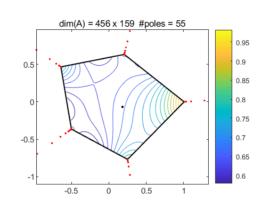
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# Why this problem?

- $\bullet$  Problems involving the Laplace operator  $\Delta = \nabla^2$  frequently appear in physical equations:
  - Heat Equation  $\alpha \nabla^2 u = \partial_t u$
  - Schrodinger Equation  $\left[\frac{-\hbar^2}{2m}\nabla^2 + V\right]\Psi = i\hbar\,\partial_t\Psi$
  - Wave Equation  $c^2 \nabla^2 u = \partial_t^2 u$
  - And more...
- Functions which satisfy Laplace's Equation have very nice properties, and are called harmonic.

# Some nice properties of functions of interest

- $\bullet$  The real and imaginary parts of a holomorphic (and thus also an analytic) function f=u+iv are harmonic;
- ullet f is also smooth (infinitely differentiable); by extension this applies to u and v as well.
- Maximum Principle: a harmonic function on a compact domain attains a max. (and min.) on the boundary.

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On a simply connected domain we can construct a holomorphic function from a harmonic one: given u, define g=u-iu. The theory will work with harmonic functions, which will trickle down to our problem.

If r approximates f, having real part u, the worst we'll do over the whole domain in approximating u is  $||u(z) - \operatorname{Re}[r(z)]||$ ,  $z \in \Gamma$ .

# Back to the problem

$$r(z) = \underbrace{\sum_{j=1}^{N_1} \frac{a_j}{z-z_j}}_{\text{"Newman"}} + \underbrace{\sum_{j=0}^{N_2} b_j (z-z_*)^j}_{\text{"Runge"}}$$

• Using the scheme in the paper, we can have root exponentially good approximations for u. The task at hand is finding the coefficients  $a_j$ ,  $b_j$ .

$$||f - r_n||_{\Omega} = O(e^{-C\sqrt{n}})$$

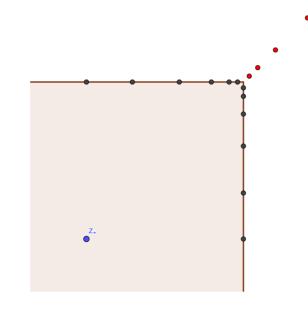
- The theorems in the paper are based on interpolation, showing existence.
- In the code, the problem is solved via a least squares approach using QR factorization. Code is written in MATLAB.

# Describing r

$$r(z) = \sum_{j=1}^{N_1} \frac{a_j}{z - z_j} + \sum_{j=0}^{N_2} b_j (z - z_*)^j$$

The Newman Part: built to handle corners.

- The terms  $z_j$  are poles, exponentially clustered near a corner on the exterior of  $\Omega$  (works for spacing scaled at least  $O(n^{-1/2})$ ).
- "Rational functions are more powerful than polynomials for approximating functions near singularities..."<sup>a</sup>



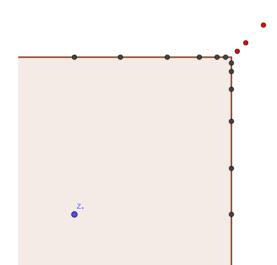
<sup>&</sup>lt;sup>a</sup>Lloyd N. Trefethen. 2013. Approximation theory and approximation practice, Society for Industrial and Applied Mathematics.

# Describing r

$$r(z) = \sum_{j=1}^{N_1} \frac{a_j}{z - z_j} + \sum_{j=0}^{N_2} b_j (z - z_*)^j$$

The Runge part: built to handle the interior.

- The term  $z_*$  is an expansion point, near the middle of  $\Omega$ .
- Polynomials can approximate root exponentially well on a nice domain (going back to Runge).



### The function r is harmonic

$$r(z) = \sum_{j=1}^{N_1} \frac{a_j}{z - z_j} + \sum_{j=0}^{N_2} b_j (z - z_*)^j$$

To prove r is harmonic, consider f(z)=1/z and  $g(z)=z^k$ . The function f can be decomposed as f=u+iv, where

$$u(x,y) = \frac{x}{x^2 + y^2}$$
  $v(x,y) = \frac{-y}{x^2 + y^2}$ .

Taking derivatives will show that u and v satisfy the Cauchy-Riemann equations,  $\partial_x u = \partial_y v$ ,  $\partial_y u = -\partial_x v$ .

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Taking derivatives will show that u and v satisfy the Cauchy-Riemann equations,  $\partial_x u = \partial_y v$ ,  $\partial_y u = -\partial_x v$ , meaning f is (holomorphic, and thus) harmonic.

Writing g in polar form, then in terms of sines and cosines is enough to see g is harmonic:

$$g(z) = \rho e^{ik\theta} = \rho[\cos(k\theta) + i\sin(k\theta)].$$

Adding these templates, applying translations and scaling as necessary give us our result.

## An important lemma

Hermite integral formula for rational interpolation.

Let  $\Omega$  be a simply connected domain in  $\mathbb C$  bounded by a closed curve  $\Gamma$ , and let f be analytic in that domain and extend continuously to the boundary. Let interpolation points  $\alpha_0,\ldots,\alpha_{n-1}\in\Omega$  and poles  $\beta_0,\ldots,\beta_{n-1}$  anywhere in the complex plane be given. Let r be the unique type (n-1,n) rational function with simple poles at  $\{\beta_j\}$  that interpolate f at  $\{\alpha_j\}$ . Then for any  $z\in\Omega$ ,

$$f(z) - r(z) = \frac{1}{2\pi i} \int_{\Gamma} \frac{\phi(z)}{\phi(t)} \frac{f(t)}{t - z} dt,$$

$$\phi(z) = \prod_{j=0}^{n-1} (z - \alpha_j) / \prod_{j=0}^{n-1} (z - \beta_j).$$

### First Theorem

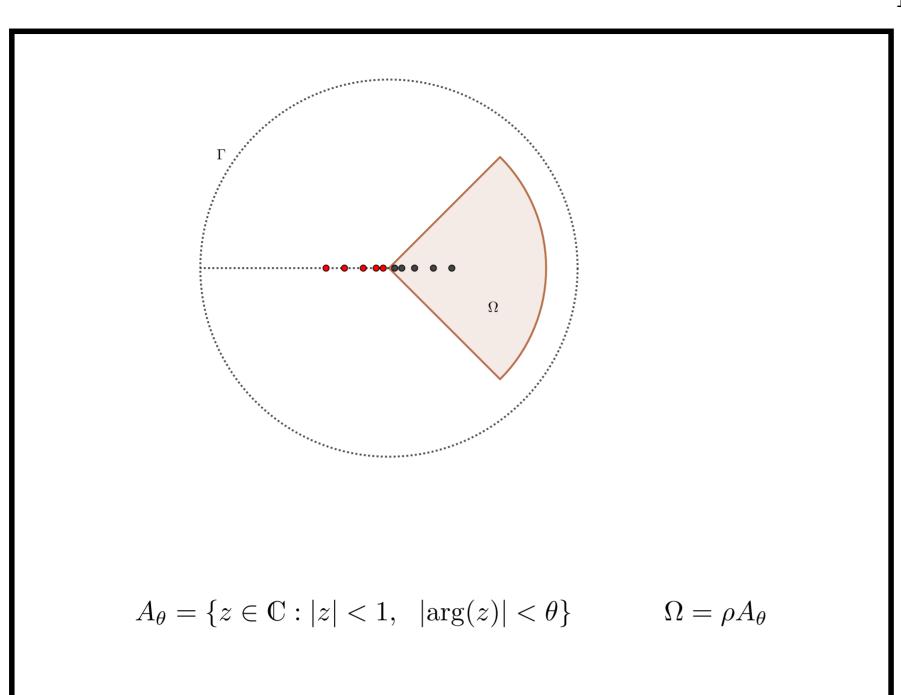
Let f be a bounded analytic function in the slit disk  $A_\pi$  that satisfies  $f(z)=O(|z|^\delta)$  as  $z\to 0$  for some  $\delta>0$ , and let  $\theta\in(0,\pi/2)$  be fixed. Then for some  $0<\rho<1$  depending on  $\theta$  but not on f, there exist type (n-1,n) rational functions  $\{r_n\}$ ,  $1\le n<\infty$ , such that

$$||f - r_n||_{\Omega} = O(e^{-C\sqrt{n}})$$

as  $n\to\infty$  for some C>0, where  $\Omega=\rho A_\theta$ . Moreover, each  $r_n$  can be taken to have simple poles only at

$$\beta_j = -e^{-\sigma j/\sqrt{n}}, \quad 0 \le j \le n - 1,$$

where  $\sigma > 0$  is arbitrary.



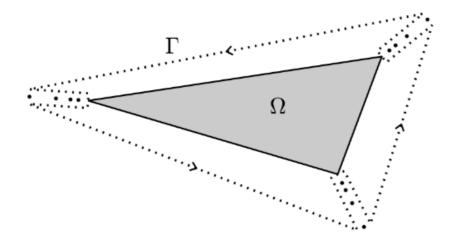
#### Second Theorem

Let  $\Omega$  be a convex polygon with corners  $w_1,\ldots,w_m$ , and let f be an analytic function in  $\Omega$  that is analytic on the interior of each side segment and can be analytically continued to a disk near each  $w_k$  with a slit along the exterior bisector there. Assume f satisfies  $f(z)-f(w_k)=O(|z-w_k|^\delta)$  as  $z\to w_k$  for each k for some  $\delta>0$ . There exist degree n rational functions  $\{r_n\},\ 1\le n<\infty$  such that

$$||f - r_n||_{\Omega} = O(e^{-C\sqrt{n}})$$

as  $n\to\infty$  for some C>0. Moreover, each  $r_n$  can be taken to have finite poles only at points exponentially clustered along the exterior bisectors at the corners, with arbitrary clustering parameter  $\sigma$ , as long as the number of poles near each  $w_k$  grows at least in proportion to n as  $n\to\infty$ .

## Second Theorem: the idea<sup>a</sup>



Split f into 2m terms, a "Newman" part and a "Runge" part:

$$f = \sum_{k=1}^{m} f_k + \sum_{k=1}^{m} g_k.$$

The Runge part can be handled by previously established results, and the Newman part can be handled by applying the first theorem to each corner.

<sup>a</sup>Image from Gopal, A., & Trefethen, L. N. (2019). Solving Laplace Problems with Corner Singularities via Rational Functions. SIAM Journal on Numerical Analysis.

#### Some extensions

Numerical experiments show that:

- We can get root exponentially good approximations on non-convex domains;
- We're not limited to sectors and convex polygons, we can have curvy edges.

These theorems apply to an analytic function f, but our problem involves a harmonic u.

If we assume u satisfies the corner behavior needed and  $\Omega$  is simply connected, then so will a v, where we can have an f=u+iv.

#### The Algorithm

- 1. Define boundary  $\Gamma$ , corners  $w_1, \ldots, w_m$ , boundary function h, tolerance  $\varepsilon$ .
- 2. For increasing values of n with  $\sqrt{n}$  approximately evenly spaced;
- 2a. fix  $N_1=O(mn)$  poles  $1/(z-z_k)$  clustered outside the corners;
- 2b. fix  $N_2+1=O(n)$  monomials  $1,(z-z_*),\dots,(z-z_*)^{N_2}$  and set  $N=N_1+N_2+1$ ;
- 2c. choose  $M \approx 3N$  sample points on a boundary, also clustered near corners;
- 2d. evaluate at sample points to obtain an  $M \times N$  matrix A and M-vector b;
- 2e. solve the least-squares problem  $Ax \approx b$  for the coefficient vector x;
- 2f. exit loop if  $||Ax b||_{\infty} < \varepsilon$  or if N is too large or the error is growing
- 3. Confirm accuracy by checking the error on a finer boundary mesh.
- 4. Construct a function to evaluate r(z) based on computed coefficients x.

### The code

Code is branded "Lightning Laplace." We enter:

- $\bullet$  Corners of a polygonal-ish domain in  $\mathbb C;$
- boundary data in the form of a (real) function handle(s), or scalar values, corresponding to the edges.

Errors are computed by comparing the procedure with a finer sampling (so not a true error).

