





## Remember... Sorting - the main problem

- Assume we have n comparable objects in an array and we want to rearrange them to be in increasing order
- Input:
  - An array A of n comparable objects
  - A **key value** in each data object
  - A comparison function (consistent and total)
- Output:
  - **Reorganize** the objects of A such that:

 $\forall$  i,j (if i < j then A[i]  $\leq$  A[j])

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## **Classification of Sorting Algorithms**



Comparison based sorting algorithms may be classified as follows:

- **Elementary** sorting algorithms:
  - Insertion
  - □ Selection
  - □ Shell Sort
- **Divide and Conquer** sorting algorithms:
  - □ Merge-Sort
  - □ Quick-Sort
- Priority queues based sorting algorithm:
  - □ Heap-Sort



## Shell Sort (also called - "Gap" sort).



- Created in 1959 by Donald Shell\*\*
- Motivation:
  - □ **Shell sort** is a generalization of **insertion sort**, with two observations in mind:
    - 1. Insertion sort is **efficient** if the input is "almost sorted".
    - 2. Insertion sort is **inefficient**, on average, because it moves values just one position at a time.



### segmented insertion sort.

- □ **Shell sort** is easy to develop an intuitive sense of how this algorithm works, but is <u>very difficult to analyze its running time complexity</u>.
- \*\***Donald Shell**: "A High-Speed Sorting Procedure", Communications of the ACM Vol 2, No. 7, 1959, pp. 30-32.

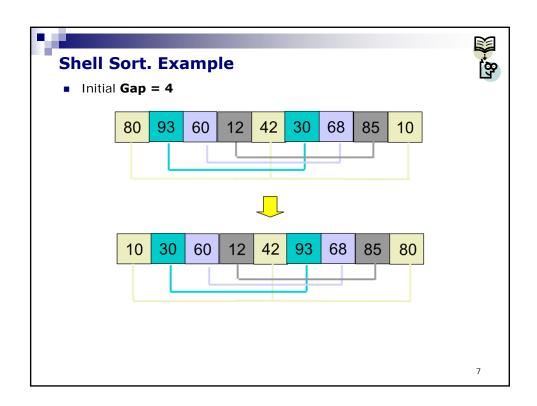
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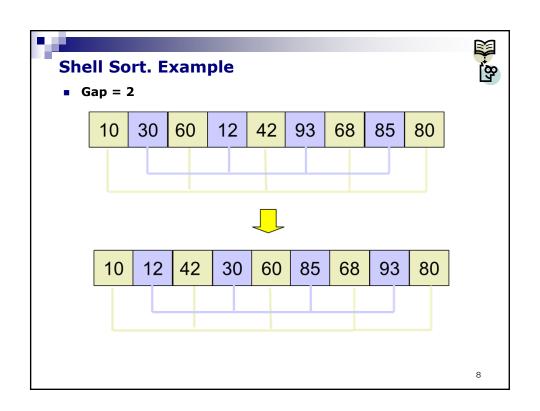


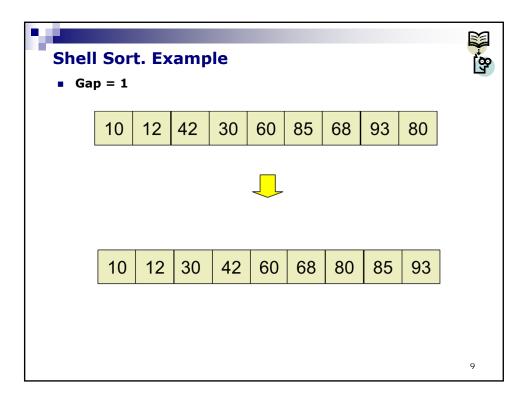
### Shell Sort.



- Algorithm. Main ideas:
  - Divides an array into several smaller non-contiguous segments.
  - ☐ The **distance** between successive elements in one segment is called a **gap**.
  - ☐ Each segment is sorted within itself using **Insertion sort**.
  - □ Then re-segment into larger segments (**smaller gaps**) and repeat (insert) sort.
  - $\Box$  Continue until only one segment (**gap = 1**).
  - □ When the gap = 1 ⇒ Shell Sort ≡ Insertion Sort,
    - It will be able to work very fast, since **Insertion Sort** is fast when the array is almost in order.







## Shell Sort. Gap sequence



- Important points:
  - □ The sequence  $h_1$ ,  $h_2$ ,  $h_3$ ,...,  $h_t$  is a sequence of increasing integer values which will be used as a sequence (from right to left) of **gap values**.
  - Any sequence will work as long as it is increasing and h<sub>1</sub>=1.
  - For any gap value  $h_k$  we have  $A[i] \le A[i + h_k]$
  - Best practical results are obtained when all values in the gap sequence are relatively prime (sequence does not share any divisors).



### **Shell Sort. Practical Gap sequence**



- Important points (cont...):
  - ☐ Three Methods (for the **gap sequence**):
    - 1) **Shell's suggestion** first gap is n/2 successive gaps are previous value divided by 2.
    - 2) **Odd gaps only** like **Shell** method except if division produces an even number add 1.
    - **3) 2.2 method** like Odd gaps method (add 1 to even division result) but use a divisor of 2.2 and truncate. Best performance of all most nearly a relatively prime sequence.

### **Visualization:**

https://www.youtube.com/watch?v=CmPA7zE8mx0

http://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html

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## **Shell Sort. Analysis and Java Code**



- Running Time:
  - □ Worst case:  $O(n^{1.5})$  sub-quadratic!
  - □ Best case: *O(nlogn)*
  - □ Average:  $O(n^{1.25})$  conjectured!
- Java code for Shell Sort

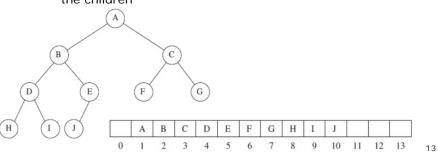
## HeapSort



 Heap sort is a comparison based sorting technique based on Binary Heap data structure.

### Remember that...

- A binary min-heap has:
  - **Structure property:** A complete binary tree binary tree that is completely filled, with the possible exception of the bottom level, which is filled from left to right.
  - **(min) Heap property**: the key of a node ≤ the keys of the children



## HeapSort. The algorithm.



- Input:
  - □ Unsorted array A[1..*n*]
- Algorithm:
  - □ BuildHeap

for (i=0; i < A.length; i++) B[i]=insert(A[i])

Sort procedure

for (i=0; i <B.length; i++)
A[i]=deleteMin()</pre>

- Output:
  - □ Sorted array A[1..*n*]
- Algorithm Analysis:
  - □ insert() and deleteMin() are O(logn) then the overall running time of HeapSort is O(nlogn)

# HeapSort



Java implementation (Author: Mark Weiss)

https://users.cs.fiu.edu/~weiss/dsj2/code/Sort.java

Visualization (in-place version)

https://www.cs.usfca.edu/~galles/visualization/HeapSort.html

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## **Summary and preliminary results:**



algorithm	¿stable?	best time	average time	worst time	extra memory
selectionsort	no	0(n <sup>2</sup> )	0(n <sup>2</sup> )	0(n <sup>2</sup> )	0(1)
insertionsort	yes	0(n)	0(n <sup>2</sup> )	0(n <sup>2</sup> )	0(1)
shellsort	no	O(n*log(n))	$0(n^{1.25})^{\dagger}$	$0(n^{1.5})$	0(1) Non-trivial
heapsort	no	0(n)	0(n*log(n))	0(n*log(n))(	0(1)

■ **Stable sorting algorithm** – mean that the algorithm preserves the <u>input order of equal elements in the sorted output</u>.

