# Artificial Intelligence Algorithms and Mathematics

**CSCN 8000** 



# Unsupervised

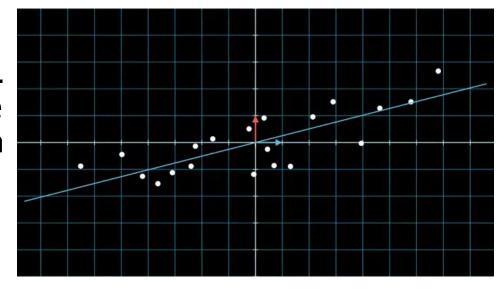
- FDA/LDA
- K-Means
- Hierarchical Clustering



### Recall: Dimensionality Reduction



- The efficiency of ML methods depends crucially on the choice of features that are used to characterize data points.
- Target → have a small number of highly relevant features to characterize data points.
- Dimensionality Reduction techniques reduce the number of input variables or features in a dataset <u>while retaining its essential</u> <u>characteristics</u>
- Benefits of dimensionality reduction:
  - Reduce excessive resource requirements
  - Reduce the probability of overfitting
  - Make data visualizations easier



### Principal Component Analysis (PCA)

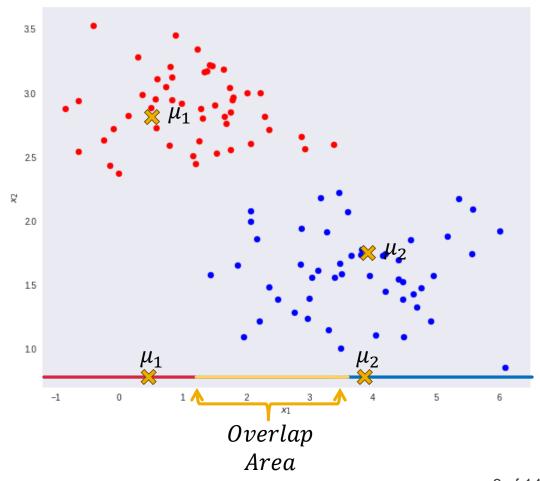


$$Su = \lambda u$$

- To project original data  $X \in \mathbb{R}^{D*N}$  to P features, where  $P \leq D$ :
  - Calculate the Covariance Matrix  $S = \frac{1}{N}(X \bar{X})(X \bar{X})^T$
  - Get all the possible eigenvalues and eigenvectors of S.
  - Sort the eigenvalues in descending order:
    - The Largest eigenvalue corresponds to the (eigenvector) axis with highest variance of data projected on that axis.
    - Lower eigenvalues correspond to axes that are worse in preserving the characteristics of the data.
  - Get the highest P eigenvalues and their eigenvectors.
  - Construct full matrix  $U \in R^{P*D}$  by stacking all chosen eigenvectors vertically (row-wise)
  - Get the final full projected dataset  $Z \in \mathbb{R}^{P*N} \rightarrow Z = UX^T$

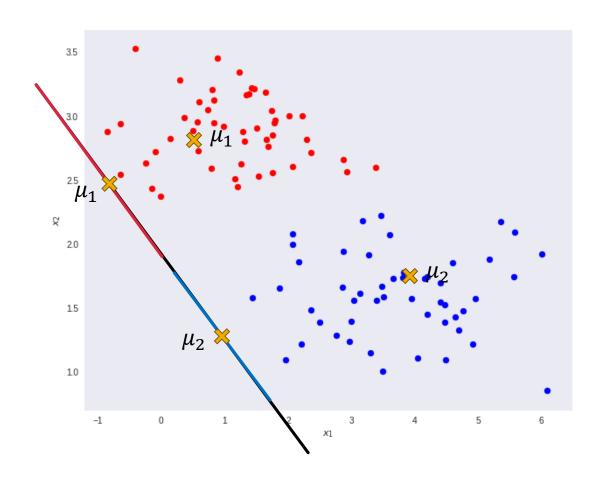


- Assume we want to project our features to fewer dimensions while maintaining the separability of our classes.
- A possible approach would be to maximize the distance between the centers (means) of the projected classes.
- In the following example, does the proposed axis maintain the best separability between the classes?

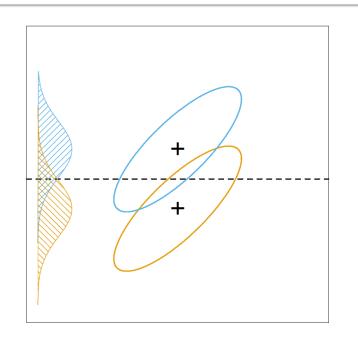


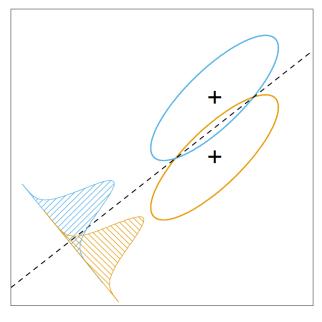


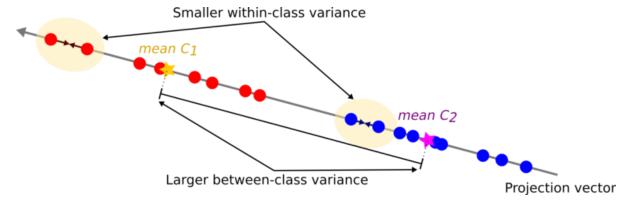
- It looks like maximizing the distance between means of projected classes is not enough if the classes are widespread with high variance.
- An additional constraint could be imposed by <u>minimizing the within-</u> class variance of the projected data.
- Combining the two constraints leads to a new axis (dimensionality) that maintains the separability of the original data with minimum or no overlap.













- Fisher's Linear Discriminant Analysis (FDA) is a linear dimensionality reduction technique that aims to project highdimensional data into a lower-dimensional space while maximizing the separation between classes.
- This is achieved through two targets:
  - T1: Maximizing Inter-Class Variance (Distance between class means)
  - T2: Minimizing the Intra-Class Variance (Within-class variance).



- Assume that we have two classes to be projected.
- We will apply a linear transformation  $u \in R^{D*1}$  on each original data point  $x_{\{0,1\}} \in R^{D*1}$  belonging to classes 0 and 1, such that the value z of the projected point at the new axis is formulated as,

$$z = u^T X$$

The means of the points in each class are formulated as,

$$\mu_0 = \frac{1}{N_0} \sum_{i=0}^{N_0} x_0^i, \qquad \mu_1 = \frac{1}{N_1} \sum_{i=0}^{N_1} x_1^i$$



$$\mu_0 = \frac{1}{N_0} \sum_{i=0}^{N_0} x_0^i, \qquad \mu_1 = \frac{1}{N_1} \sum_{i=0}^{N_1} x_1^i$$

For Target 1: Distance between the projected means is formulated as:

$$(u^T \mu_0 - u^T \mu_1)^2 = (u^T \mu_0 - u^T \mu_1)^T (u^T \mu_0 - u^T \mu_1)$$

$$(u^T \mu_0 - u^T \mu_1)^2 = (\mu_0 - \mu_1)^T u u^T (\mu_0 - \mu_1)$$

$$(u^T \mu_0 - u^T \mu_1)^2 = u^T (\mu_0 - \mu_1) (\mu_0 - \mu_1)^T u$$

• 
$$(u^T \mu_0 - u^T \mu_1)^2 = u^T S_B u$$
,  $S_B = (\mu_0 - \mu_1)(\mu_0 - \mu_1)^T$ 

• Where  $S_B$  represents the distance between class means before projection.



- Recall from PCA  $\rightarrow Cov(Z) = u^T Su$ , where S = Cov(X)
- For Target 2: Within class-variance for the two classes can be formulated as:
  - $Cov(Z_0 + Z_1) = Cov(Z_0) + Cov(Z_1)$
  - $Cov(Z_0 + Z_1) = u^T S_0 u + u^T S_1 u$ , where  $S_0 = Cov(X_0)$ ,  $S_1 = Cov(X_1)$
  - $Cov(Z_0 + Z_1) = u^T(S_0 + S_1)u = u^TS_Wu$ ,  $S_W = S_0 + S_1$
  - Where  $S_W$  represents the within-class variance of the two classes altogether.



To Achieve both Target 1 and Target 2, our target could be formulated as follows:

$$maximize \frac{u^T S_B u}{u^T S_W u}$$

Recall that our new axis needs to be unit vector (from PCA), to enforce it we can formulate the target as follows:

maximize 
$$u^T S_B u$$
, s.t.  $u^T S_W u = 1$ 

To formulate it as a loss function, we will borrow the concepts from Lagrangian Multipliers:

$$L(u,\lambda) = -\left(u^T S_B u - \lambda \left(u^T S_W u - 1\right)\right)$$

The negative sign is added to minimize rather than maximize

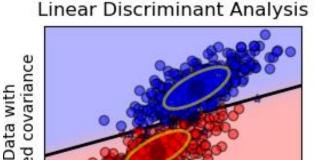


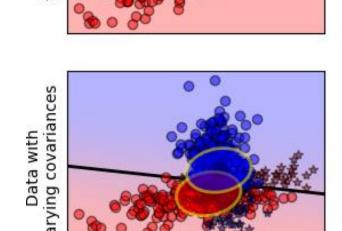
$$L(u,\lambda) = -\left(u^T S_B u - \lambda \left(u^T S_W u - 1\right)\right)$$

- To minimize the loss with respect to  $u \rightarrow \text{Solve} \frac{dL}{du} = 0$
- $S_B u = \lambda S_W u \to [S_W^{-1} S_B] u = \lambda u$
- We reach a formulation exactly similar to the one of <u>eigenvalues and</u> <u>eigenvectors</u>.
- In other words, u is considered an eigenvector of the matrix  $S_W^{-1}S_B$  calculated from the original data and  $\lambda$  is the associated eigenvalue.
- To transform the full dataset, follow the same steps as PCA, but with calculating  $S_W^{-1}S_B$  in the first step instead.

#### LDA vs FDA

- Both Linear Discriminant Analysis (LDA) and FDA refer to the same technique which aims to project the data to lower dimensions while maximizing the class separability.
- LDA is the direct extension of FDA to work with two or more classes.
- LDA is not only doing dimensionality reduction, but also computes the <u>linear decision boundary</u> between the classes in the projected space.
- LDA makes important assumptions about the shape of the data:
  - All classes follow a gaussian (normal) distribution
  - All classes have equal (identical) covariance matrices.
- If any of those assumptions doesn't hold, LDA won't perform well in classification or dimensionality reduction.



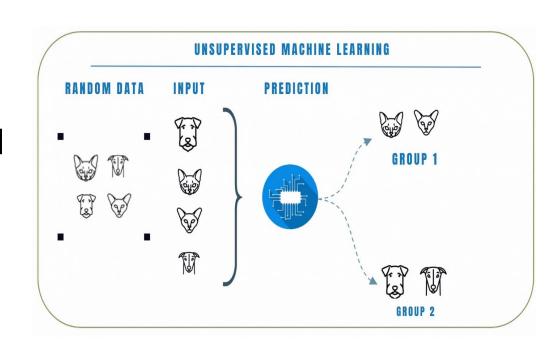


# **Unsupervised Learning**

### **Unsupervised Learning**

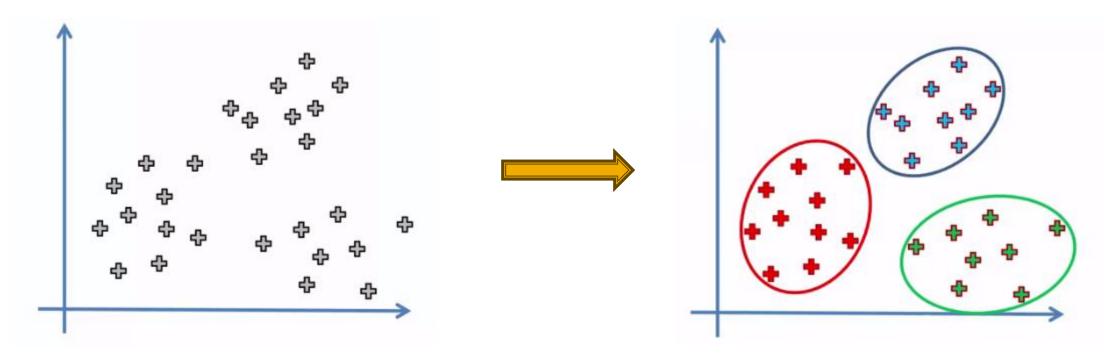


- Unsupervised learning is a type of machine learning where the algorithm is given data without explicit instructions on what to do with it.
- The system tries to learn the patterns and the structure of the data without any labeled responses to guide the learning process.
- Benefits:
  - Uncover hidden patterns and structures
  - Adaptable to various types of data without the need for labeled examples
  - Valuable tool for exploratory data analysis



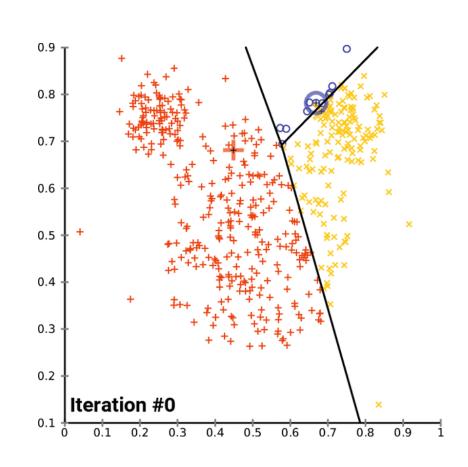


Given the following dataset, can we group the points into 3 meaningful clusters that are sufficiently far from each other?



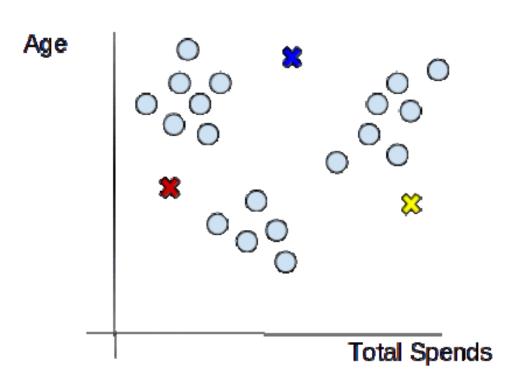


- K-Means is a popular unsupervised machine learning algorithm used for clustering data into groups or clusters based on similarity.
- The primary goal of K-Means is to partition data points into K clusters, where each point belongs to the cluster with the <u>nearest mean</u>.
- K is a hyperparameter manually set to determine the number of clusters.





- Assume we want to cluster the following dataset into 3 clusters where K=3.
- Step 1: Initialize Clusters:
  - Choose a strategy to initialize the means (centers) of the 3 clusters.
    - A popular strategy is just to choose 3 random points to define the cluster means.
    - Other methods include: Naiive Shardin and K-Means++



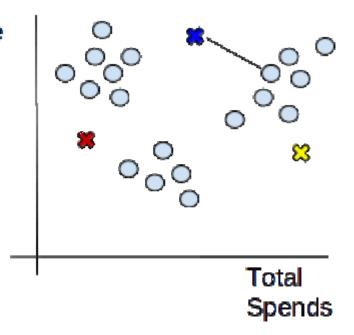


#### Step 2: Assign Points to Clusters:

 For each point in the dataset, calculate the distance between the points and the K-Cluster means (centers).

• 
$$d(x_i, \mu_k) = \sqrt{\sum_{d=1}^{D} (x_i^d - \mu_k^d)^2}$$

- Assign the point to the cluster closest to it (smallest distance).
- Repeat this step until all points in the dataset are assigned successfully to a cluster.

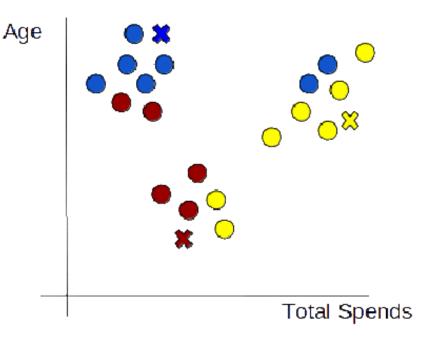




- Step 3: Re-calculate Cluster Means:
  - Now since different points belong to each cluster, we need to recalculate the cluster means (centers), such that:

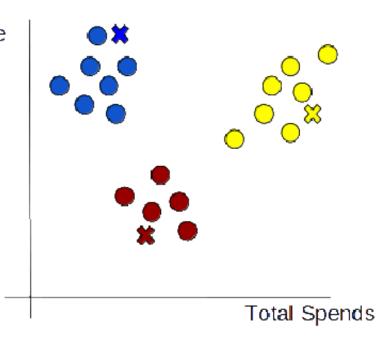
$$\mu_k = \frac{1}{n_k} \sum_{i=0}^{n_k} x_i$$

- Where  $\mu_k$  represents the mean of cluster k as the mean of the points belonging to the cluster.
- $n_k$  represents the number of points belonging to cluster k.





- Step 4: Repeat steps 2 and 3:
  - Repeat steps 2 and 3 until the assignment of points to clusters is not changing anymore (saturation).
  - The final assignment of points to clusters will define the optimal K for the current dataset.

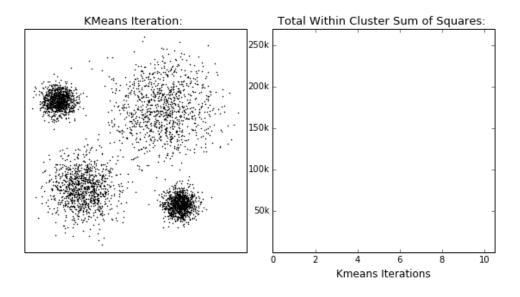


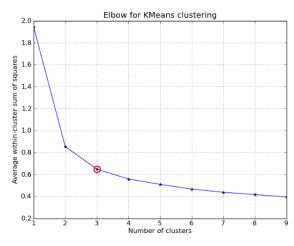


- How to choose optimal K?
  - One method is called the *Elbow Plot:* 
    - Calculate the Within-Cluster-Sum-of-Squares (WCSS) for different values of K:

$$WCSS_K = \sum_{i=1}^{K} \sum_{j=1}^{n_i} (x_j - \mu_i)^2$$

- Where  $n_i$  represents the number of points in cluster i.
- The WCSS tells us how spread the points in each cluster are. Lower WCSS means better clusters (more compact).
- Plot the WCSS for different K values and choose the K value where an inflection point (elbow) occurs.

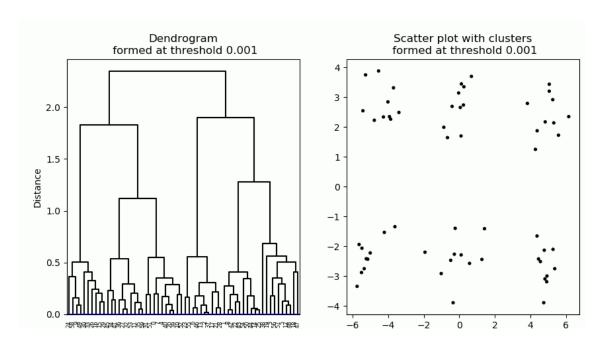




### Hierarchical Clustering

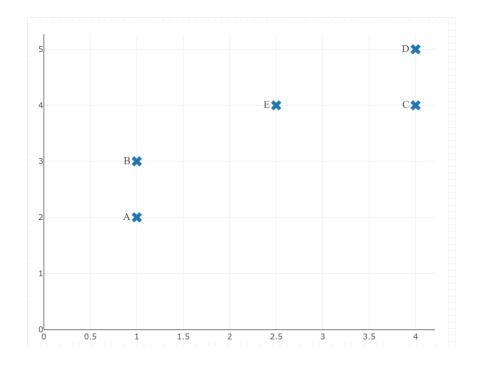


- Hierarchical clustering is a method of cluster analysis which seeks to build a hierarchy of clusters.
- There are two main types of hierarchical clustering:
   Agglomerative and Divisive.





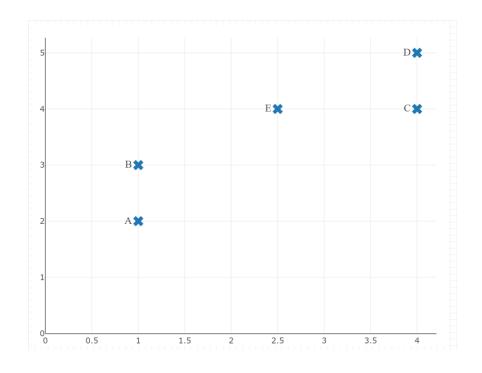
- This method is "bottom-up," meaning it starts with each data point as a separate cluster and iteratively merges them into larger clusters.
- Assume that we have the example dataset with 5 points, we will use Agglomerative clustering to combine them into clusters.





#### Step 1: Initialization:

- All points are treated as their own clusters. So we start with N clusters.
- In our example, we start with 5 clusters.



### **Linkage Criterions**



- They determine how the distance between clusters is measured, which directly influences how the clusters are formed. The types are:
  - Single Linkage (Nearest Neighbor): Uses the minimum distance between members of the two clusters.

$$d(A,B) = \min_{\{a \in A, b \in B\}} d(a,b)$$

 Complete Linkage: Uses the maximum distance between members of the two clusters.

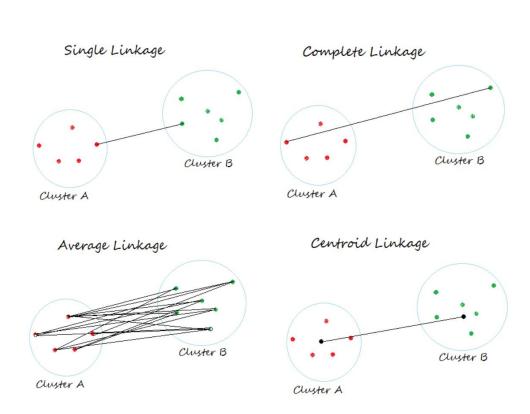
$$d(A,B) = \max_{\{a \in A, b \in B\}} d(a,b)$$

 Average Linkage: Uses the average distance between all pairs of members in the two clusters.

$$d(A,B) = \frac{1}{N_A N_B} \sum_{a \in A} \sum_{b \in B} d(a,b)$$

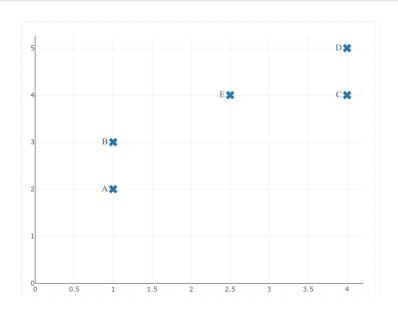
Centroid Linkage: Uses the distance between cluster means.

• 
$$d(A,B) = \|\mu_A - \mu_B\|^2$$





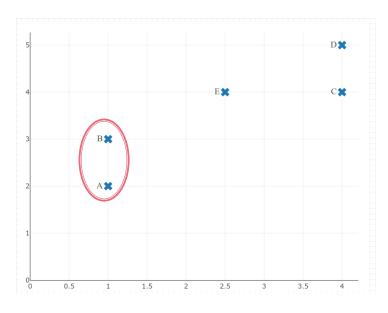
- Step 2: Distance Matrix Computation:
  - Calculate a similarity or distance matrix that measures the distances between all pairs of data points. This matrix is N \* N size.
  - You could use any distance metric discussed in class
    - Euclidean is the most famous
    - We will use Manhattan in this example
  - Any of the linkage criterion could also be used, we will use Complete Linkage in this example.



	Α	В	С	D	Е
Α					
В	1				
C	5	4			
D	6	5	1		
Е	3.5	2.5	1.5	2.5	



- Step 3: Merge Closest Cluster:
  - Find the pair of clusters that are closest to each other based on the chosen <u>distance</u> <u>metric</u> and <u>linkage criterion</u>.
  - In our example, A-B and C-D show the minimum distances, we could choose any of them to be merged. We'll go with A-B

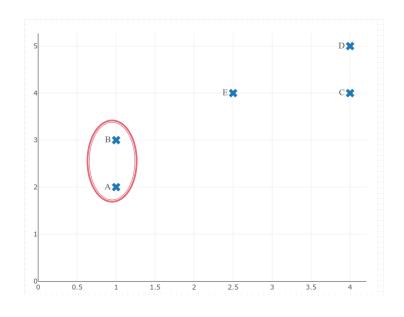


	Α	В	C	D	Е
Α					
В	1				
C	5	4			
D	6	5	1		
Ε	3.5	2.5	1.5	2.5	

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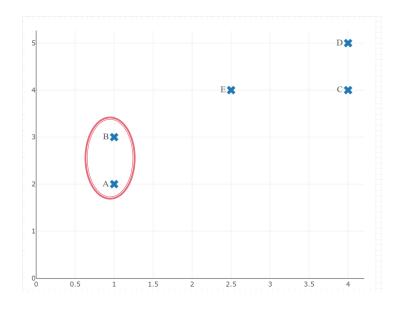
- Step 4: Recalculate Distance Metric:
  - Recalculate the distance matrix with the new cluster.
  - Recall that we're using complete linkage and Manhattan distance.



	A-B	C	D	Е
A-B				
С	5			
D	6	1		
Е	3.5	1.5	2.5	

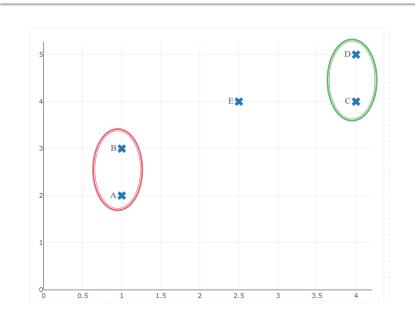


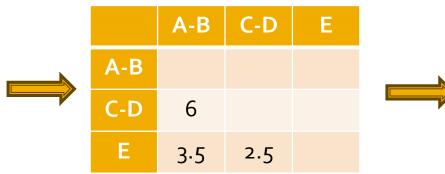
- Step 5: Repeat Steps 3 and 4:
  - Repeat steps 3 and 4 until all points are merged into one cluster.

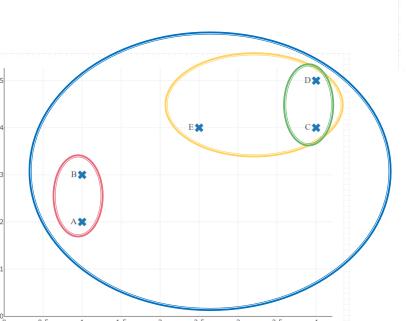


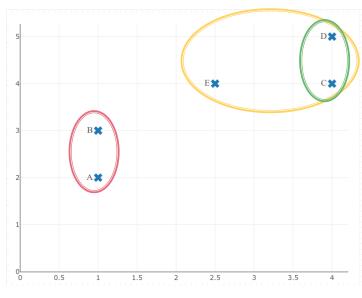
	A-B	C	D	E
A-B				
C	5			
D	6	1		
Е	3.5	1.5	2.5	





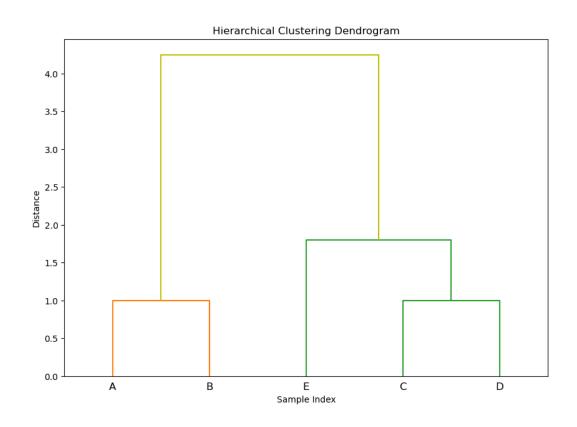


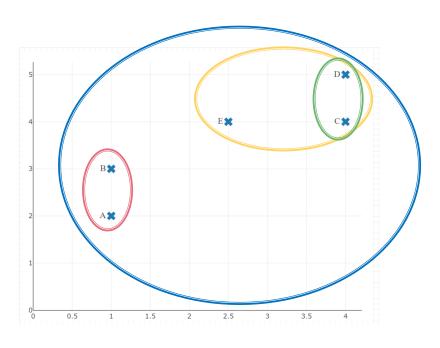








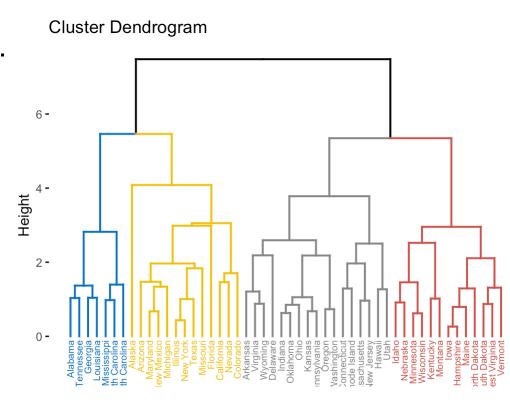




### Divisive Hierarchical Clustering



- This method is a "top-down" approach to cluster analysis. It begins with all data points in a single cluster and iteratively splits them into smaller clusters.
- Steps:
  - Initialization:
    - Start with one large cluster that includes all data points.
  - Cluster Splitting:
    - At each step, split a cluster into smaller clusters.
    - The splitting is typically based on a criterion that identifies the <u>'least</u> <u>similar'</u> members of the cluster.
  - Iterative Division:
    - Continue the process of splitting clusters at each step.
    - This process is repeated recursively until each data point forms its own cluster or a specified number of clusters is reached.
  - Result:
    - The result is often visualized as a dendrogram, which shows the hierarchical relationship between clusters and the order in which splits occurred.



### Thank you!

Any questions?



#### Disclaimer



Due to nature of the course, various materials have compiled from different open source resources with some moderation. I sincerely acknowledge their hard work and contribution





Thank You
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