# Artificial Intelligence Algorithms and Mathematics

**CSCN 8000** 



#### Classification

- Solutions for Overfitting
- PCA
- FDA/LDA



#### Ways to reduce overfitting



- Overfitting occurs when a model learns not only the underlying patterns in the training data but also the noise and random fluctuations
- To reduce the overfitting, a general rule of thumb is to try to decrease the model complexity, but not too much to avoid underfitting.
- Specifically, techniques that can be used include:
  - Cross-Validation: Assess the model's performance on multiple subsets of the data to ensure good generalization to different portions of the dataset.
  - Increase Dataset size: A larger dataset can provide more diverse examples and help the model generalize better.
  - Early Stopping: Stop training once the performance on the validation set starts to degrade, preventing the model from overfitting the training data.
  - Dropout: random neurons are "dropped out" (ignored) during each training iteration.
     This helps prevent co-adaptation of neurons and reduces overfitting.
  - Data Augmentation: Increase the size of the training dataset by applying various transformations to the existing data
  - Regularization?

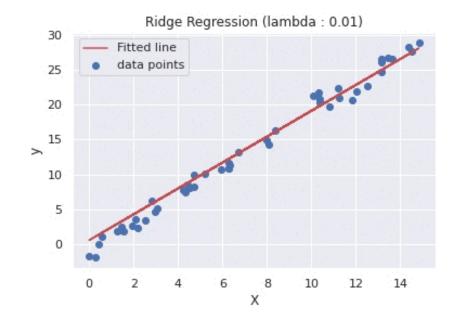
#### Regularization



- The intuition is that one way to decrease the overall model complexity is to reduce the magnitude of the learned weights w. This way we won't be assigning very high weights to certain features over the others → Simpler model
- This could be achieved by adding a <u>regularization term</u> to the loss function of any machine learning algorithm, such that,

$$L_{reg}(\overrightarrow{\boldsymbol{w}}, \boldsymbol{b}) = L(\overrightarrow{\boldsymbol{w}}, \boldsymbol{b}) + [\boldsymbol{\beta} * Regularization Term]$$

- This will allow the model to not only prioritize minimizing the cost term, but also minimizing the magnitude of the weights (controlled by the hyperparameter  $\beta$ )
- There are different types of regularization terms that could be used.



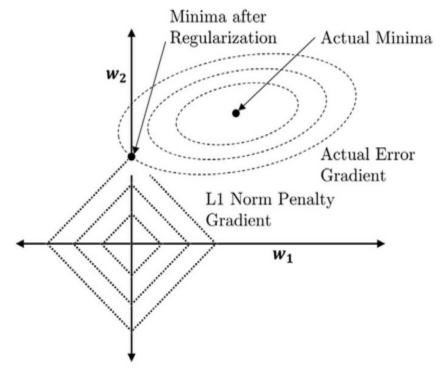
#### L1 Regularization (Lasso)



- L1 regularization introduces a penalty term proportional to the absolute values of the model parameters.
- Mathematically,

$$L_{reg}(\overrightarrow{\boldsymbol{w}}, \boldsymbol{b}) = L(\overrightarrow{\boldsymbol{w}}, \boldsymbol{b}) + \left[\boldsymbol{\beta} * \sum_{p} |\overrightarrow{\boldsymbol{w}_p}|\right]$$

- This encourages the model to prefer a sparse set of features, effectively driving some of them to exactly zero.
- Not only does it help prevent overfitting but also performs feature selection by excluding less relevant features.



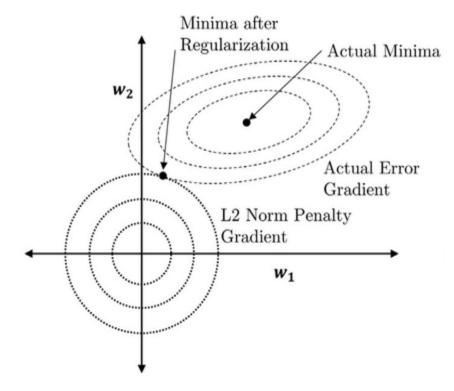
## L2 Regularization (Ridge)



- L2 regularization introduces a penalty term proportional to the square of the model parameters.
- Mathematically,

$$L_{reg}(\overrightarrow{\boldsymbol{w}}, \boldsymbol{b}) = L(\overrightarrow{\boldsymbol{w}}, \boldsymbol{b}) + \left[\boldsymbol{\beta} * \sum_{p} (\overrightarrow{\boldsymbol{w}_p})^2\right]$$

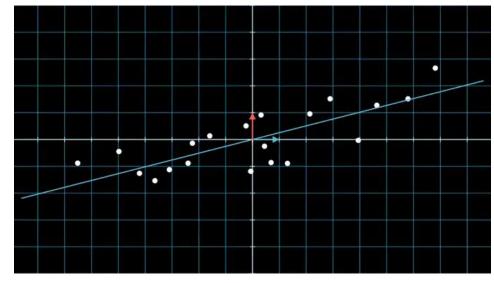
- This discourages the weights from becoming too large, preventing individual features from dominating the model.
- It distributes the importance of features more evenly, leading to a smoother model.



#### Dimensionality Reduction

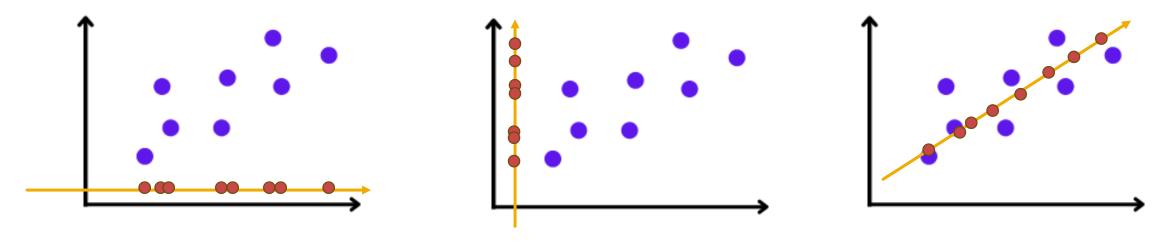


- The efficiency of ML methods depends crucially on the choice of features that are used to characterize data points.
- Target → have a small number of highly relevant features to characterize data points.
- Dimensionality Reduction techniques reduce the number of input variables or features in a dataset <u>while retaining its essential</u> <u>characteristics</u>
- Benefits of dimensionality reduction:
  - Reduce excessive resource requirements
  - Reduce the probability of overfitting
  - Make data visualizations easier





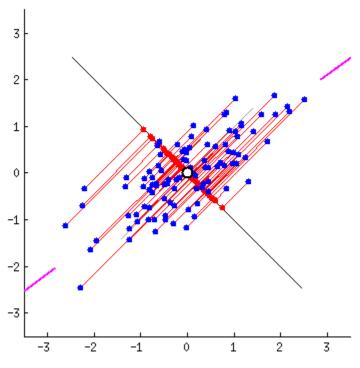
Intuitively, if we want to project the following 2D points to only one dimension, which one of the following best preserves the shape of the dataset?



 Generally, it looks like in the best dimension, the projected data points have the <u>largest possible variance</u>.



- The <u>PCA</u> is a dimensionality reduction technique that transforms high-dimensional data into a new coordinate system (principal components/axes).
- Target → Maximize the variance of projected data.
- Doesn't need any class labels (unsupervised)
- The projected data must obey certain properties:
  - Each new feature (principal component/axis) is a <u>linear</u> combination of the original features (axes)
  - Each principal component (axis) must be perpendicular to all other principal components (axes).
  - Each principal component (axis) must be a unit vector (magnitude = 1)





- Covariance Matrix: provides important information about the relationships between pairs of variables in a dataset.
- Given a dataset  $X \in R^{D*N}$  with D features and N rows, the covariance matrix will have size D\*D can be computed as follows:

$$C(X) = \frac{1}{N} (X - \bar{X}) (X - \bar{X})^{T}$$

- ullet  $\overline{X}$  represents the mean of each feature in X.
- Cell  $C_{ij}$  represents the co-variance between feature i and feature j.
- If one feature increases/decreases and the other feature increases/decreases at the same time  $\rightarrow C_{ij} \neq 0$ .
- If the features are not correlated  $\rightarrow C_{ij} = 0$ .

#### Eigen Vectors and Eigen Values



• Given a vector v, apply linear transformation with square matrix A.

$$A. v = ?$$
  
 $A. v = \lambda v \rightarrow [Special Case]$ 

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} = -1 \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\lambda_1 = 3$$
,  $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$   $\lambda_2 = -1$ ,  $v_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ 



- Given the initial dataset with D features, we want to get the first axis
  of the new coordinate space.
- We will apply a linear transformation  $u \in R^{D*1}$  on each original data point  $x \in R^{D*1}$ , such that the value z of the projected point at the new axis is formulated as,

$$z = u^T x$$

- Applying the same equation on the full dataset  $X \in \mathbb{R}^{D*N}$ , such that,  $Z = u^T X$
- Target → Maximize the variance of projected data (1D) → Maximize the covariance matrix of projected data (Multi-Dimensional)



- Target 

   Maximize the covariance matrix of projected data
- $\text{Cov}(Z) = \frac{1}{N} (Z \bar{Z}) (Z \bar{Z})^T$
- $Cov(Z) = \frac{1}{N} (u^T X u^T \overline{X}) (u^T X u^T \overline{X})^T$
- $Cov(Z) = \frac{1}{N} \left( u^T (X \bar{X}) \right) \left( u^T (X \bar{X}) \right)^T \rightarrow \text{Expand 2}^{\text{nd}} \text{ Transpose}$
- $Cov(Z) = \frac{1}{N}u^T(X \bar{X})(X \bar{X})^T u = u^T \left[\frac{1}{N}(X \bar{X})(X \bar{X})^T\right] u$
- $Cov(Z) = u^T Su$ , where S = Cov(X)



$$maximize u^{T}Su$$
,  $such that u^{T}u = 1$ 

- The constraint guarantees that the axis  $oldsymbol{u}$  is a unit vector.
- By borrowing the concept of Lagrangian Multipliers, we will translate the equation to a loss function to be *minimized*, such that,

$$L(u,\lambda) = -(u^T S u - \lambda (u^T u - 1))$$

■ To minimize the loss with respect to  $u \rightarrow \operatorname{Solve} \frac{dL}{du} = 0$ 

#### Matrix/Vector Rules and Derivatives



Rule	Comments		
$(\mathbf{A}\mathbf{B})^T = \mathbf{B}^T \mathbf{A}^T$	order is reversed, everything is transposed		
$(\mathbf{a}^T \mathbf{B} \mathbf{c})^T = \mathbf{c}^T \mathbf{B}^T \mathbf{a}$	as above		
$\mathbf{a}^T\mathbf{b}=\mathbf{b}^T\mathbf{a}$	(the result is a scalar, and the transpose of a scalar is itself)		
$(\mathbf{A} + \mathbf{B})\mathbf{C} = \mathbf{AC} + \mathbf{BC}$	multiplication is distributive		
$(\mathbf{a} + \mathbf{b})^T \mathbf{C} = \mathbf{a}^T \mathbf{C} + \mathbf{b}^T \mathbf{C}$	as above, with vectors		
$\mathbf{AB} \neq \mathbf{BA}$	multiplication is <b>not</b> commutative		

Scalar derivative		Vector derivative			
f(x)	$\rightarrow$	$\frac{\mathrm{d}f}{\mathrm{d}x}$	$f(\mathbf{x})$	$\rightarrow$	$\frac{\mathrm{d}f}{\mathrm{d}\mathbf{x}}$
bx	$\rightarrow$	b	$\mathbf{x}^T\mathbf{B}$	$\rightarrow$	В
bx	$\rightarrow$	b	$\mathbf{x}^T\mathbf{b}$	$\rightarrow$	b
$x^2$	$\rightarrow$	2x	$\mathbf{x}^T\mathbf{x}$	$\rightarrow$	$2\mathbf{x}$
$bx^2$	$\rightarrow$	2bx	$\mathbf{x}^T \mathbf{B} \mathbf{x}$	$\rightarrow$	$2\mathbf{B}\mathbf{x}$



$$L(u,\lambda) = -(u^T S u - \lambda (u^T u - 1))$$

- To minimize the loss with respect to  $u \rightarrow \operatorname{Solve} \frac{dL}{du} = 0$
- $\frac{dL}{du} = -(2Su 2\lambda u) = 0$

$$\mathbf{S}\mathbf{u} = \lambda \mathbf{u} \to Result \ of \frac{dl}{du} = 0$$

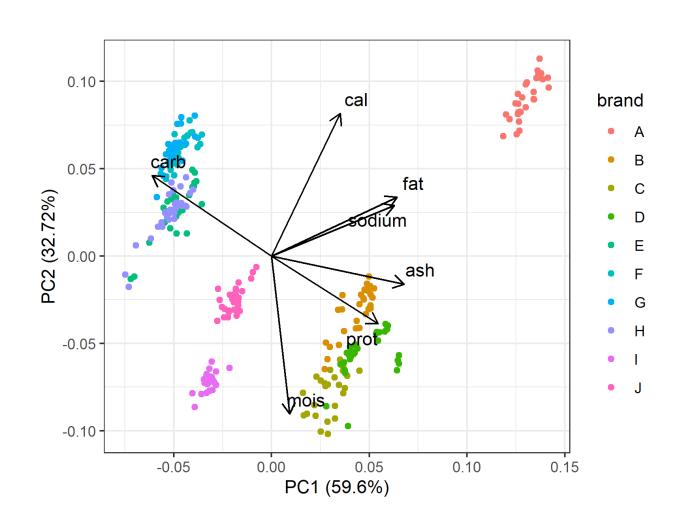
- We reach a formulation exactly similar to the one of <u>eigenvalues</u> and <u>eigenvectors</u>.
- In other words, u is considered an eigenvector of the covariance matrix S of the original data and  $\lambda$  is the associated eigenvalue.

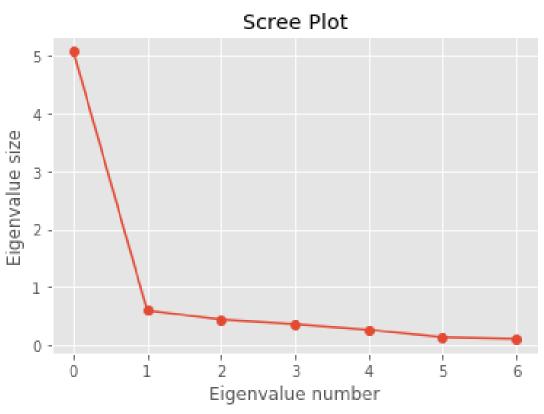


$$Su = \lambda u$$

- To project original data  $X \in \mathbb{R}^{D*N}$  to P features, where  $P \leq D$ :
  - Calculate the Covariance Matrix  $S = \frac{1}{N}(X \bar{X})(X \bar{X})^T$
  - Get all the possible eigenvalues and eigenvectors of S.
  - Sort the eigenvalues in descending order:
    - The Largest eigenvalue corresponds to the (eigenvector) axis with highest variance of data projected on that axis.
    - Lower eigenvalues correspond to axes that are worse in preserving the characteristics of the data.
  - Get the highest P eigenvalues and their eigenvectors.
  - Construct full matrix  $U \in R^{P*D}$  by stacking all chosen eigenvectors vertically (row-wise)
  - Get the final full projected dataset  $Z \in \mathbb{R}^{P*N} \rightarrow Z = UX^T$

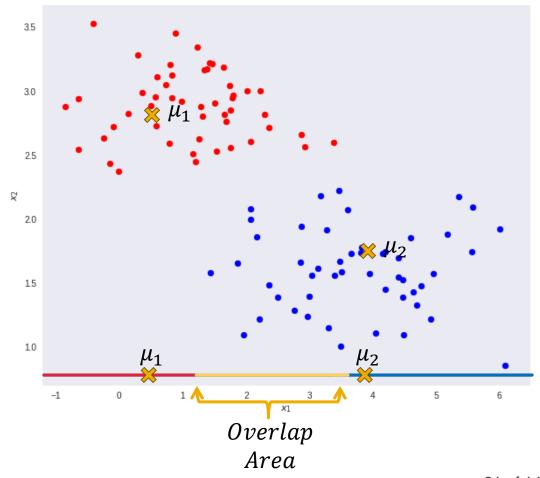






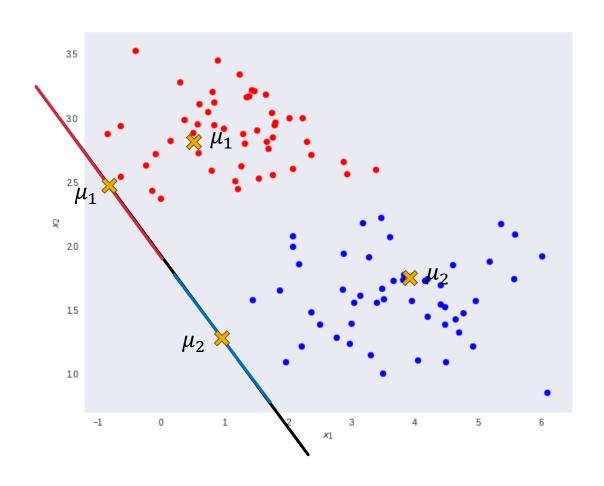


- Assume we want to project our features to fewer dimensions while maintaining the separability of our classes.
- A possible approach would be to maximize the distance between the centers (means) of the projected classes.
- In the following example, does the proposed axis maintain the best separability between the classes?

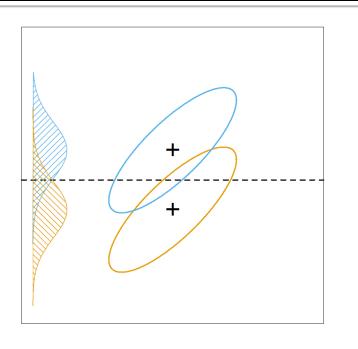


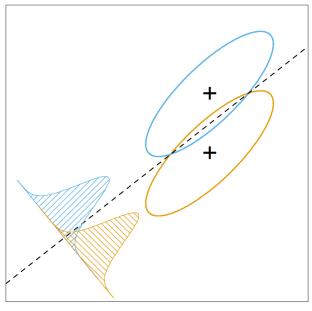


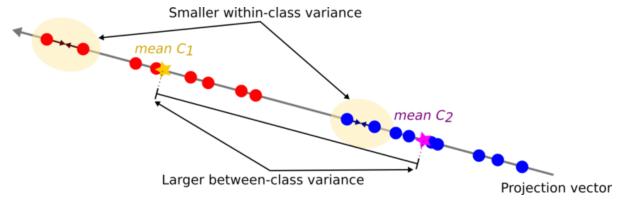
- It looks like maximizing the distance between means of projected classes is not enough if the classes are widespread with high variance.
- An additional constraint could be imposed by <u>minimizing the within-</u> class variance of the projected data.
- Combining the two constraints leads to a new axis (dimensionality) that maintains the separability of the original data with minimum or no overlap.













- Fisher's Linear Discriminant Analysis (FDA) is a linear dimensionality reduction technique that aims to project highdimensional data into a lower-dimensional space while maximizing the separation between classes.
- This is achieved through two targets:
  - T1: Maximizing Inter-Class Variance (Distance between class means)
  - T2: Minimizing the Intra-Class Variance (Within-class variance).



- Assume that we have two classes to be projected.
- We will apply a linear transformation  $u \in R^{D*1}$  on each original data point  $x_{\{0,1\}} \in R^{D*1}$  belonging to classes 0 and 1, such that the value z of the projected point at the new axis is formulated as,

$$z = u^T X$$

The means of the points in each class are formulated as,

$$\mu_0 = \frac{1}{N_0} \sum_{i=0}^{N_0} x_0^i, \qquad \mu_1 = \frac{1}{N_1} \sum_{i=0}^{N_1} x_1^i$$



$$\mu_0 = \frac{1}{N_0} \sum_{i=0}^{N_0} x_0^i, \qquad \mu_1 = \frac{1}{N_1} \sum_{i=0}^{N_1} x_1^i$$

• For Target 1: Distance between the projected means is formulated as:

$$(u^T \mu_0 - u^T \mu_1)^2 = (u^T \mu_0 - u^T \mu_1)^T (u^T \mu_0 - u^T \mu_1)$$

$$(u^T \mu_0 - u^T \mu_1)^2 = (\mu_0 - \mu_1)^T u u^T (\mu_0 - \mu_1)$$

$$(u^T \mu_0 - u^T \mu_1)^2 = u^T (\mu_0 - \mu_1) (\mu_0 - \mu_1)^T u$$

• 
$$(u^T \mu_0 - u^T \mu_1)^2 = u^T S_B u$$
,  $S_B = (\mu_0 - \mu_1)(\mu_0 - \mu_1)^T$ 

• Where  $S_B$  represents the distance between class means before projection.



- Recall from PCA  $\rightarrow Cov(Z) = u^T Su$ , where S = Cov(X)
- For Target 2: Within class-variance for the two classes can be formulated as:
  - $Cov(Z_0 + Z_1) = Cov(Z_0) + Cov(Z_1)$
  - $Cov(Z_0 + Z_1) = u^T S_0 u + u^T S_1 u$ , where  $S_0 = Cov(X_0)$ ,  $S_1 = Cov(X_1)$
  - $Cov(Z_0 + Z_1) = u^T(S_0 + S_1)u = u^TS_Wu$ ,  $S_W = S_0 + S_1$
  - Where  $S_W$  represents the within-class variance of the two classes altogether.



To Achieve both Target 1 and Target 2, our target could be formulated as follows:

$$maximize \frac{u^T S_B u}{u^T S_W u}$$

Recall that our new axis needs to be unit vector (from PCA), to enforce it we can formulate the target as follows:

maximize 
$$u^T S_B u$$
, s.t.  $u^T S_W u = 1$ 

To formulate it as a loss function, we will borrow the concepts from Lagrangian Multipliers:

$$L(u,\lambda) = -\left(u^T S_B u - \lambda \left(u^T S_W u - 1\right)\right)$$

The negative sign is added to minimize rather than maximize

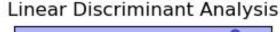


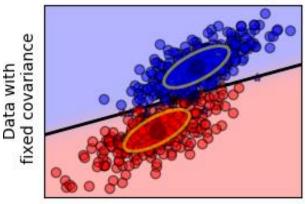
$$L(u,\lambda) = -\left(u^T S_B u - \lambda \left(u^T S_W u - 1\right)\right)$$

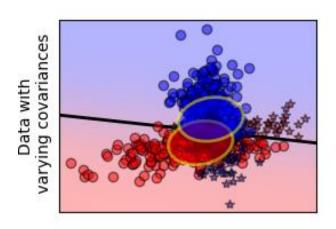
- To minimize the loss with respect to  $u \rightarrow \text{Solve} \frac{dL}{du} = 0$
- $S_B u = \lambda S_W u \to [S_W^{-1} S_B] u = \lambda u$
- We reach a formulation exactly similar to the one of <u>eigenvalues and</u> <u>eigenvectors</u>.
- In other words, u is considered an eigenvector of the matrix  $S_W^{-1}S_B$  calculated from the original data and  $\lambda$  is the associated eigenvalue.
- To transform the full dataset, follow the same steps as PCA, but with calculating  $S_W^{-1}S_B$  in the first step instead.

#### LDA vs FDA

- Both Linear Discriminant Analysis (LDA) and FDA refer to the same technique which aims to project the data to lower dimensions while maximizing the class separability.
- LDA is the direct extension of FDA to work with two or more classes.
- LDA is not only doing dimensionality reduction, but also computes the <u>linear decision boundary</u> between the classes in the projected space.
- LDA makes important assumptions about the shape of the data:
  - All classes follow a gaussian (normal) distribution
  - All classes have equal (identical) covariance matrices.
- If any of those assumptions doesn't hold, LDA won't perform well in classification or dimensionality reduction.







#### Extra Resources



- More information regarding the Matrix/Vector Derivatives:
  - https://www.math.uwaterloo.ca/~hwolkowi/matrixcookbook.pdf

## Thank you!

Any questions?



#### Disclaimer



Due to nature of the course, various materials have compiled from different open source resources with some moderation. I sincerely acknowledge their hard work and contribution





Thank You
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