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time/		
fps	36	
iterations	51	
time_elapsed	1448	
total_timesteps	52224	
train/		
approx_kl	0.037390806	
clip_fraction	0.117	
clip_range	0.2	
clip_range_vf	0.2	
entropy_loss	-0.663	
explained_variance	0.582	
learning_rate	0.0001	
loss	66.2	
n_updates	498	
policy_gradient_loss	-0.00514	
value_loss	142	
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成功到达目标！ 剩余距离：1.98m