

Importance sampling (not a sampling method  
→ it used as an extension  
to MC for approximate  
intractable integral)

Recall Monte-Carlo:

$$\mathbb{E}_{x \sim p(x)} [f(x)] = \int f(x) p(x) dx \approx \frac{1}{n} \sum_{i=1}^n f(x_i), \quad x_i \stackrel{\text{i.i.d}}{\sim} p(x)$$

•  $f(x) = x$  : expectation of  $x$

•  $f(x) = (x - \mathbb{E}(x))^2$  : variance of  $x$

Setup: Assume  $p(x)$  is a density, i.e.  $\int p(x) dx = 1$ . Then:

$$\mathbb{E}_{x \sim p(x)} [f(x)] = \int f(x) p(x) dx = \int \left[ f(x) \frac{p(x)}{q(x)} \right] q(x) dx$$

$$= \mathbb{E}_{x \sim q(x)} \left[ f(x) \frac{p(x)}{q(x)} \right] \approx \frac{1}{n} \sum_{i=1}^n f(x_i) \frac{p(x_i)}{q(x_i)}, \quad x_i \stackrel{\text{i.i.d}}{\sim}$$

$$\approx \frac{1}{n} \sum_{i=1}^n f(x_i) w(x_i), \quad w(x) := \frac{p(x)}{q(x)} \quad \text{Importance weights.}$$

$q(x)$ : proposal distribution

↳  $\begin{cases} 1. \text{ Easy to sample from} \\ 2. \text{ Easy to evaluate for a given } x. \end{cases}$

$p(x)$ :  $\begin{cases} 1. \text{ May not be easy to sample} \\ 2. \text{ Should be easy to evaluate} \end{cases}$

⊕  $\forall$  density  $q(x)$  s.t.  $q(x) > 0 \Rightarrow p(x) > 0$

Remarks:

$$1.) \quad \mathbb{E}_{x \sim q(x)} \left[ \hat{\mu}_n^{\text{IS}} \right] = \frac{1}{n} \sum_{i=1}^n \mathbb{E}_{x \sim q(x)} \left[ f(x_i) \frac{p(x_i)}{q(x_i)} \right]$$

$$= \frac{1}{n} \sum_{i=1}^n \int f(x_i) \frac{p(x_i)}{q(x_i)} q(x_i) dx =$$

$$= \frac{1}{n} \sum_{i=1}^n \mathbb{E}_{x \sim p(x)} [f(x_i)] \xrightarrow{n \rightarrow \infty} \mathbb{E}_{x \sim p(x)} [f(x)]$$

⇒ Hence, <sup>the</sup> IS estimator is unbiased, consistent.

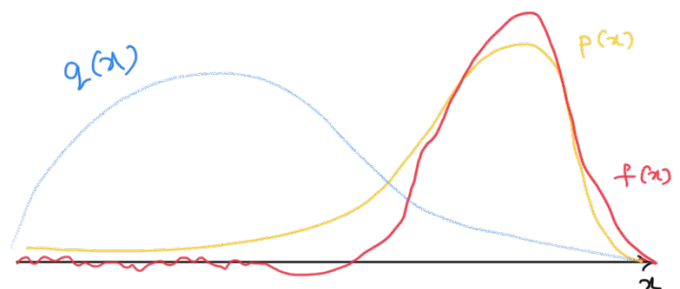
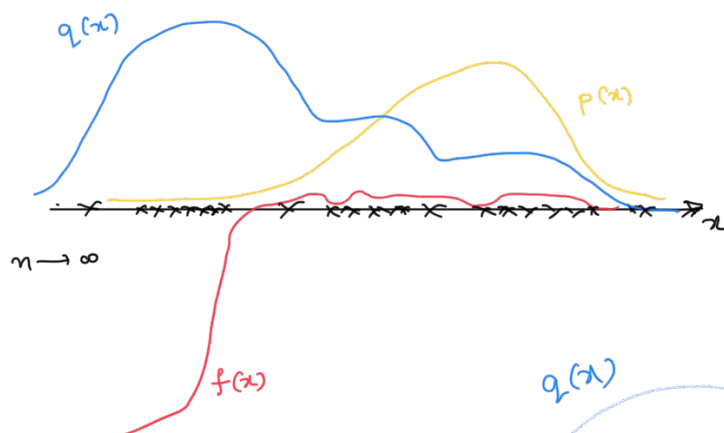
$$2.) \text{Var}[\hat{\mu}_n^{\text{IS}}] = \frac{1}{n} \text{Var}\left[f(x) \frac{p(x)}{q(x)}\right] \quad \frac{\text{MC}}{\text{Var}[f(x)]} \gg \frac{\text{IS}}{\text{Var}\left[f(x) \frac{p(x)}{q(x)}\right]}$$

In fact, it is straightforward to solve for optimal  $q^*(x)$ , but in practice it may be difficult to sample from  $q^*(x)$ .

Scenarios:

- 1.) Can't sample from  $p(x)$ , use IS.
- 2.) Whether or not we sample from  $p(x)$ , use IS to improve upon the convergence of the vanilla MC estimator.

Example: Suppose  $f(x)$  is the return of some investment  $x$ , we want to approximate the expected returns:  $\mathbb{E}_{x \sim p(x)} [f(x)]$



How to choose  $q(x)$ ?

Sampling from the wrong  $q(x)$  can make things horribly wrong.

Choose  $q(x)$  to be large

where  $|f(x)|p(x)$  is large

$$\frac{1}{n} \sum_{i=1}^n f(x_i) \frac{p(x_i)}{q(x_i)}, \quad x_i \stackrel{\text{i.i.d.}}{\sim} q(x)$$

$$n \quad i=1 \quad q(x_i)$$

Limitations : 1. Our intuition on how to choose a good  $q(x)$  breaks down in high dimensions.

2. It is difficult to assess the accuracy of our estimator.

Importance sampling for un-normalized distribution :

Often we may know  $p(x)$  or  $q(x)$  only up to a normalizing const

e.g. : Posterior inference :  $p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta)p(\theta)}{\int p(\mathcal{D}|\theta)p(\theta)d\theta} \propto p(\mathcal{D}|\theta)p(\theta)$

Setup : Assume :  $p(x) = \frac{\tilde{p}(x)}{Z_p}$  ,  $q(x) = \frac{\tilde{q}(x)}{Z_q}$  ,  $\int \tilde{q}(x) dx = Z_q$  ,  $\int \tilde{p}(x) dx = Z_p$ .

$$\begin{aligned} \mathbb{E}_{x \sim p(x)} [f(x)] &= \int f(x) p(x) dx \stackrel{\text{I.S.}}{=} \int \left[ f(x) \frac{p(x)}{q(x)} \right] q(x) dx \\ &= \int f(x) \frac{\tilde{p}(x)}{\tilde{q}(x)} \frac{Z_q}{Z_p} q(x) dx \end{aligned}$$

Assume that we can efficiently sample from  $q(x)$ , and we can evaluate  $\tilde{p}(x), \tilde{q}(x)$ .

$$\begin{aligned} \mathbb{E}_{x \sim p(x)} [f(x)] &= \int f(x) \frac{\tilde{p}(x)}{\tilde{q}(x)} \frac{Z_q}{Z_p} q(x) dx \approx \frac{Z_q}{Z_p} \frac{1}{n} \sum_{i=1}^n f(x_i) \tilde{w}(x_i), \quad (1) \\ &\text{where } x_i \stackrel{\text{i.i.d.}}{\sim} q(x), \text{ and } \tilde{w}(x_i) := \frac{\tilde{p}(x_i)}{\tilde{q}(x_i)} \end{aligned}$$

But we still don't know the normalizing constants ...

Then let's try to approximate them via Monte-Carlo :

$$\begin{aligned} \left\{ \frac{Z_p}{Z_q} \right. &= \frac{1}{Z_q} \int \tilde{p}(x) dx = \int \frac{\tilde{p}(x)}{\tilde{q}(x)} q(x) dx = \mathbb{E}_{x \sim q(x)} \left[ \frac{\tilde{p}(x)}{\tilde{q}(x)} \right] \\ &\approx \frac{1}{n} \sum_{i=1}^n \tilde{w}(x_i) \quad (2) \end{aligned}$$

$$\Rightarrow \mathbb{E}_{x \sim p(x)} [f(x)] \approx \frac{\frac{1}{n} \sum_{i=1}^n f(x_i) \tilde{w}(x_i)}{\frac{1}{n} \sum_{i=1}^n \tilde{w}(x_i)} = \frac{1}{n} \sum_{i=1}^n f(x_i) \hat{w}_i$$

where  $x_i \stackrel{\text{i.i.d}}{\sim} q(x)$ , and  $\hat{w}(x_i) := \frac{\tilde{w}(x_i)}{\frac{1}{n} \sum_{i=1}^n \tilde{w}(x_i)}$  "approx  
import  
weig"

⊛ Keep in mind that we made two MC approximations.

... hence, this is expected to perform worse than regular I.S.