

PySensors: A Python package for sparse sensor placement

24 October 2020

Summary

Successful predictive modeling and control of engineering and natural processes is often entirely determined by *in situ* measurements and feedback from sensors (Brunton and Kutz 2019). However, deploying sensors into complex environments, including in application areas such as manufacturing (Brunton 2018), geophysical environments (Karniadakis 2009), and biological processes (Colvert, Chen, and Kanso 2017; Mohren et al. 2018), is often expensive and challenging. Furthermore, modeling outcomes are extremely sensitive to the location and number of these sensors, motivating optimization strategies for the principled placement of sensors for different decision-making tasks. In general, choosing the globally optimal placement within the search space of a large-scale complex system is an intractable computation, in which the number of possible placements grows combinatorially with the number of candidates. While sensor placement has traditionally been guided by expert knowledge and first principles models, increases in system complexity, emerging sensor technologies, and innovations in data-driven modeling strategies motivates automated algorithms for optimizing sensor placements.

A number of automated sensor placement methods have been developed in recent years, designed to optimize outcomes in the design of experiments (Boyd and Vandenberghe 2004; Joshi and Boyd 2009), convex (Joshi and Boyd 2009; Brunton et al. 2016) and submodular objective functions (Summers, Cortesi, and Lygeros 2015), information theoretic and Bayesian criteria (Caselton and Zidek 1984; Krause, Singh, and Guestrin 2008; Lindley 1956; Sebastiani and Wynn 2000; Paninski 2005), optimal control (Luo 2014; Wolfrum 2014; Zare et al. 2018; K. Manohar, Kutz, and Brunton 2018), for sampling and estimating signals over graphs (Ribeiro and Towsley 2010; Di Lorenzo et al. 2016; Chen et al. 2016; Chepuri and Leus 2016), and reduced order modeling (Barrault et al. 2004; Willcox 2006; Chaturantabut and Sorensen 2010, 2012; Drmac and Gugercin 2016; Krithika Manohar et al. 2018; Clark et al. 2018). Maximizing the impact of sensor placement algorithms requires tools to make them accessible to scientists

and engineers across various domains and at various levels of mathematical expertise and sophistication.

PySensors is a Python package for the scalable optimization of sensor placements from data. In particular, **PySensors** provides tools for sparse sensor placement optimization approaches that employ data-driven dimensionality reduction (Brunton et al. 2016; Krithika Manohar et al. 2018). This approach results in near-optimal placements for various decision-making tasks and can be readily customized using different optimization algorithms and objective functions.

The **PySensors** package can be used by both researchers looking to advance state-of-the-art methods and practitioners seeking simple sparse sensor selection methods for their applications of interest. Straightforward methods and abundant examples help new users to quickly and efficiently leverage existing methods to their advantage. At the same time, modular classes leave flexibility for users to experiment with and plug in new sensor selection algorithms or dimensionality reduction techniques. Users of **scikit-learn** will find **PySensors** objects familiar, intuitive, and compatible with existing **scikit-learn** routines such as cross-validation.

Features

PySensors enables the sparse placement of sensors for two classes of problems: reconstruction and classification. For reconstruction problems the package implements a unified **SensorSelector** class, with methods for efficiently analyzing the effects that data or sensor quantity have on reconstruction performance (Krithika Manohar et al. 2018). Sensor selection is based on the computationally efficient and flexible QR algorithm (Duersch and Gu 2015; Martinsson 2015; Martinsson et al. 2017), which has recently been used for hyper-reduction in reduced-order modeling (Drmac and Gugercin 2016) and for sparse sensor selection (Krithika Manohar et al. 2018). Often different sensor locations impose variable costs, e.g. if measuring sea-surface temperature, it may be more expensive to place buoys/sensors in the middle of the ocean than close to shore. These costs can be taken into account during sensor selection via a built-in cost-sensitive optimization routine (Clark et al. 2018). For classification tasks, the package implements the Sparse Sensor Placement Optimization for Classification (SSPOC) algorithm (Brunton et al. 2016), allowing one to optimize sensor placement for classification accuracy. The algorithm is related to compressed sensing optimization (Tao 59AD; Donoho 2006; Baraniuk 2007), but identifies the sparsest set of sensors that reconstructs a discriminating plane in a feature subspace. This SSPOC implementation is fully general in the sense that it can be used in conjunction with any linear classifier. Additionally, **PySensors** provides methods to enable straightforward exploration of the impacts of primary hyperparameters like the number of sensors or basis modes.

It is well known (Krithika Manohar et al. 2018) that the basis in which one represents measurement data can have a pronounced effect on the sensors that are selected and the quality of the reconstruction. Users can readily switch between different bases typically employed for sparse sensor selection, including principal component analysis (PCA) modes and random projections. Because **PySensors** was built with **scikit-learn** compatibility in mind, it is easy to use cross-validation to select among possible choices of bases, basis modes, and other hyper-parameters.

Finally, included with **PySensors** is a large suite of examples, implemented as Jupyter notebooks. Some of the examples are written in a tutorial format and introduce new users to the objects, methods, and syntax of the package. Other examples demonstrate intermediate-level concepts such as how to visualize model parameters and performance, how to combine **scikit-learn** and **PySensors** objects, selecting appropriate parameter values via cross-validation, and other best-practices. Further notebooks use **PySensors** to solve challenging real-world problems. The notebooks reproduce many of the examples from the papers upon which the package is based (Krithika Manohar et al. 2018; Clark et al. 2018; Brunton et al. 2016). To help users begin applying **PySensors** to their own datasets even faster, interactive versions of every notebook are available on Binder. Together with comprehensive documentation, the examples will compress the learning curve of learning a new software package.

Acknowledgments

The authors acknowledge support from the Air Force Office of Scientific Research (AFOSR FA9550-19-1-0386) and The Boeing Corporation. JNK acknowledges support from the Air Force Office of Scientific Research (AFOSR FA9550-19-1-0011)

References

- Baraniuk, R. G. 2007. “Compressive Sensing.” *IEEE Signal Processing Magazine* 24 (4): 118–20.
- Barrault, Maxime, Yvon Maday, Ngoc Cuong Nguyen, and Anthony T Patera. 2004. “An ‘Empirical Interpolation’ method: Application to Efficient Reduced-Basis Discretization of Partial Differential Equations.” *Comptes Rendus Mathematique* 339 (9): 667–72.
- Boyd, Stephen, and Lieven Vandenberghe. 2004. *Convex Optimization*. Cambridge university press.
- Brunton, Bingni W, Steven L Brunton, Joshua L Proctor, and J Nathan Kutz. 2016. “Sparse Sensor Placement Optimization for Classification.” *SIAM Journal on Applied Mathematics* 76 (5): 2099–2122.

- Brunton, K. Manohar AND T. Hogan AND J. Buttrick AND A. G. Banerjee AND J. N. Kutz AND S. L. 2018. “Predicting Shim Gaps in Aircraft Assembly with Machine Learning and Sparse Sensing.” *Journal of Manufacturing Systems* 48: 87–95.
- Brunton, S. L., and J. N. Kutz. 2019. *Data-Driven Science and Engineering: Machine Learning, Dynamical Systems, and Control*. Cambridge University Press.
- Caselton, William F, and James V Zidek. 1984. “Optimal Monitoring Network Designs.” *Statistics & Probability Letters* 2 (4): 223–27.
- Chaturantabut, Saifon, and Danny C Sorensen. 2010. “Nonlinear Model Reduction via Discrete Empirical Interpolation.” *SIAM Journal on Scientific Computing* 32 (5): 2737–64.
- . 2012. “A State Space Error Estimate for POD-DEIM Nonlinear Model Reduction.” *SIAM Journal on Numerical Analysis* 50 (1): 46–63.
- Chen, Siheng, Rohan Varma, Aarti Singh, and Jelena Kovačević. 2016. “Signal Recovery on Graphs: Fundamental Limits of Sampling Strategies.” *IEEE Transactions on Signal and Information Processing over Networks* 2 (4): 539–54.
- Chepuri, Sundeep Prabhakar, and Geert Leus. 2016. “Subsampling for Graph Power Spectrum Estimation.” In *Sensor Array and Multichannel Signal Processing Workshop (Sam), 2016 Ieee*, 1–5. IEEE.
- Clark, Emily, Travis Askham, Steven L Brunton, and J Nathan Kutz. 2018. “Greedy Sensor Placement with Cost Constraints.” *IEEE Sensors Journal* 19 (7): 2642–56.
- Colvert, Brendan, Kevin Chen, and Eva Kanso. 2017. “Local Flow Characterization Using Bioinspired Sensory Information.” *Journal of Fluid Mechanics* 818: 366–81.
- Di Lorenzo, Paolo, Sergio Barbarossa, Paolo Banelli, and Stefania Sardellitti. 2016. “Adaptive Least Mean Squares Estimation of Graph Signals.” *IEEE Transactions on Signal and Information Processing over Networks* 2 (4): 555–68.
- Donoho, D. L. 2006. “Compressed Sensing.” *IEEE Transactions on Information Theory* 52 (4): 1289–1306.
- Drmac, Zlatko, and Serkan Gugercin. 2016. “A New Selection Operator for the Discrete Empirical Interpolation Method—Improved a Priori Error Bound and Extensions.” *SIAM Journal on Scientific Computing* 38 (2): A631–A648.
- Duersch, Jed A, and Ming Gu. 2015. “True BLAS-3 Performance QRCP Using Random Sampling.” *arXiv Preprint arXiv:1509.06820*.

- Joshi, Siddharth, and Stephen Boyd. 2009. “Sensor Selection via Convex Optimization.” *IEEE Transactions on Signal Processing* 57 (2): 451–62.
- Karniadakis, B. Yildirim AND C. Chrysostomidis AND G. E. 2009. “Efficient Sensor Placement for Ocean Measurements Using Low-Dimensional Concepts.” *Ocean Modelling* 27: 160–73.
- Krause, Andreas, Ajit Singh, and Carlos Guestrin. 2008. “Near-Optimal Sensor Placements in Gaussian Processes: Theory, Efficient Algorithms and Empirical Studies.” *Journal of Machine Learning Research* 9 (Feb): 235–84.
- Lindley, Dennis V. 1956. “On a Measure of the Information Provided by an Experiment.” *The Annals of Mathematical Statistics*, 986–1005.
- Luo, N. K. Dhingra AND M. R. Jovanovic AND Z.-Q. 2014. “An ADMM Algorithm for Optimal Sensor and Actuator Selection.” *53rd IEEE Conference on Decision and Control*, 4039–44.
- Manohar, K., J. N. Kutz, and S. L. Brunton. 2018. “Optimal Sensor and Actuator Placement Using Balanced Model Reduction.” *To Appear in IEEE Transactions on Automatic Control (arXiv Preprint arXiv: 1812.01574)*.
- Manohar, Krithika, Bingni W Brunton, J Nathan Kutz, and Steven L Brunton. 2018. “Data-Driven Sparse Sensor Placement for Reconstruction: Demonstrating the Benefits of Exploiting Known Patterns.” *IEEE Control Systems Magazine* 38 (3): 63–86.
- Martinsson, Per-Gunnar. 2015. “Blocked Rank-Revealing QR Factorizations: How Randomized Sampling Can Be Used to Avoid Single-Vector Pivoting.” *arXiv Preprint arXiv:1505.08115*.
- Martinsson, Per-Gunnar, Gregorio Quintana Ortí, Nathan Heavner, and Robert van de Geijn. 2017. “Householder QR Factorization with Randomization for Column Pivoting (HQRRP).” *SIAM Journal on Scientific Computing* 39 (2): C96–C115.
- Mohren, Thomas L, Thomas L Daniel, Steven L Brunton, and Bingni W Brunton. 2018. “Neural-Inspired Sensors Enable Sparse, Efficient Classification of Spatiotemporal Data.” *Proceedings of the National Academy of Sciences* 115 (42): 10564–9.
- Paninski, Liam. 2005. “Asymptotic Theory of Information-Theoretic Experimental Design.” *Neural Computation* 17 (7): 1480–1507.
- Ribeiro, Bruno, and Don Towsley. 2010. “Estimating and Sampling Graphs with Multidimensional Random Walks.” In *Proceedings of the 10th Acm Sigcomm Conference on Internet Measurement*, 390–403. IMC ’10. New York, NY, USA: ACM.
- Sebastiani, Paola, and Henry P Wynn. 2000. “Maximum Entropy Sampling and Optimal Bayesian Experimental Design.” *Journal of the Royal Statistical*

- Society: Series B (Statistical Methodology)* 62 (1): 145–57.
- Summers, Tyler H, Fabrizio L Cortesi, and John Lygeros. 2015. “On Submodularity and Controllability in Complex Dynamical Networks.” *IEEE Transactions on Control of Network Systems* 3 (1): 91–101.
- Tao, E. J. Candès AND J. Romberg AND T. 59AD. “Stable Signal Recovery from Incomplete and Inaccurate Measurements.” *Communications in Pure and Applied Mathematics* 8 (1207–1223).
- Willcox, Karen. 2006. “Unsteady Flow Sensing and Estimation via the Gappy Proper Orthogonal Decomposition.” *Computers & Fluids* 35 (2): 208–26.
- Wolfrum, U. Munz AND M. Pfister AND P. 2014. “Sensor and Actuator Placement for Linear Systems Based on H_2 and H_∞ Optimization.” *IEEE Transactions on Automatic Control* 59 (11): 2984–9.
- Zare, Armin, Neil K. Dhingra, Mihailo R. Jovanović, and Tryphon T. Georgiou. 2018. “Proximal Algorithms for Large-Scale Statistical Modeling and Optimal Sensor/Actuator Selection.” *arXiv Preprint arXiv: 1807.01739*.