| g | GE Energy                                      | Functional Testing Specification |
|---|--|----------------------------------|
|   |  |                                  |
|   | Inspection & Repair Services<br>Louisville, KY | LOU-GEF<br>IMC-2001-1-B          |

# Test Procedure for a IMC-2001-1-B Slave Amplifier

| REV. | DESCRIPTION     | SIGNATURE | REV. DATE  |
|------|-----------------|-----------|------------|
| Α    | Initial release | C. Wade   | 06/09/2005 |
| В    |                 |           |            |
| С    |                 |           |            |

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|------------------------|-------------|-------------|----------------------------------|
| <b>DATE</b> 06/09/2005 | DATE        | DATE        | <b>DATE</b> 6/9/2005             |

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Louisville, KY

### Test Procedure for an IMC-2001-1-B Amplifier

#### 1. SCOPE

**1.1** This is a functional testing procedure for IMC-2001-1-B Amplifier.

## 2. STANDARDS OF QUALITY

**2.1** Refer to the current revision of the IPC-A-610 standard for workmanship standards.

### 3. APPLICABLE DOCUMENTS

3.1 The following document(s) shall form part of this specification to the extent specified herein. Unless otherwise indicated, the latest issue shall apply.3.1.1

### 4. ENGINEERING REQUIREMENTS

- 4.1 Equipment Cleaning
  - **4.1.1** Equipment should be clean and free of debris prior to applying power unless performing an initial check. Refer to the local documented procedures for cleaning guidelines.
- 4.2 Equipment Inspection
  - **4.2.1** Equipment should be visually inspected for any defects prior to applying power. This inspection should include the following as a minimum:
    - 4.2.1.1 Wires broken or cracked
    - 4.2.1.2 Terminal strips / connectors broken or cracked
    - **4.2.1.3** Loose wires
    - 4.2.1.4 Components visually damaged
    - 4.2.1.5 Capacitors leaking
    - 4.2.1.6 Solder joints damaged or cold
    - 4.2.1.7 Circuit board burned or de-laminated
    - 4.2.1.8 Printed wire runs burned or damaged

### 5. EQUIPMENT REQUIRED

**5.1** The following equipment is required to perform the process requirements. Equipment may be substituted provided that all accuracy's and test ratios are equivalent or better.

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| Qty | Reference #  | Description            |
|-----|--------------|------------------------|
| 1   | IMC-2001-1-B | Encoder Feedback Drive |
| 1   | 15vdc PS     | Power Supply           |
| 1   | Cable Set    | IMC-1150 Cable Set     |
| 1   | Motor        | Motor with encoder     |
| 1   | Variac       | 110vac Variac          |

### 6. TESTING PROCESS

- 6.1 Connection Setup
  - **6.1.1** Before hooking up amplifier ohm check the dipswitches.
- 6.2. Testing Procedure
  - 6.2.1. IMC-2001 Setup
  - 6.2.2. Set dipswitch SW2 to 4, 5, 6, 7, & 8 right, all others switched left. This sets up the address to "0" and allows for communication with PC.
  - 6.2.3. Hook up both 24 and 22 pin connecting cables and place all switches on switch box in the up (open) state. Used IMC-1150 Stepper (single axis) cables.
  - 6.2.4. Hookup the IMC-1150 communication cable to the PC. If communication has been established you should see an echo from the drive every time you hit enter on the PC.
  - 6.2.5. This unit is 110VAC model, be sure to hook up power cable to autotransformer. Hook up power and encoder cable to controller's P2 connector; leave P1 off at this time. Plug encoder into encoder cable.
  - 6.2.6. Use +12V power supply to feed the switch box. Red lead to Red Lead on Switch Box, Black Lead to Black Lead on Switch Box.
  - 6.2.7. Power up computer and amplifiers. Bottom two LEDs (LED 4 & LED 5) should be on. Led 4 & 5 should continue to stay lit until unit is enabled by engaging switch 12 on the switch box.
  - 6.2.8. If over temp light on drive is on shut down and trouble shoot problem.
  - 6.2.9. Access CCS and go to the Terminal Mode. Enter the address of the amplifier, should be (0). Controller communication LED will blink when the enter key is pressed, if you are communicating. The XMIT LED will blink every time screen updates/transmits.
  - 6.2.10. Download IMC-2001 program to controller, it already has a prewritten exercise program.
  - 6.2.11. Flip switches SW10, SW11, & SW12 down on switch box. When drive is enabled, SW12 down, fault light should go out.
  - 6.2.12. This unit does not have motor connections, encoder feedback only. So to check for encoder feedback you will have to turn the stepper motor shaft to get response from unit. See next line.
  - 6.2.13. The Green LED will be on when motor is physically turned in a clockwise direction.
  - 6.2.14. The Amber LED will be on when motor is physically turned in a counterclockwise direction.
  - 6.2.15. Testing the Inputs
  - 6.2.16. Enter command RS at 200 milliseconds in the query mode (F7). You should see the following when switch is flipped. Switches 9, 10, 11, & 12 flipped up. This tests the last 4 four inputs switches.

i. 0011 0011 0000 0101 All switches flipped up. ii. 0000 0000 0000 0101 Switch 12 down.

iii. 0000 0001 0000 0101 Switch 11 down.

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iv. 0000 0000 0000 0101 v. 0000 0000 0010 0101 Switch 10 down.

Switch 9 down.

6.2.17. Disable drive. The next test checks the first eight inputs. Enter Diagnostics 0DG1 and the screen should display the results of switch 1 through 5 when switch 6, 7, or 8 are toggled. If not, you may have to enter 0PE=1 to enable profiles. Check all switches, you will most certainly find drive will display switch status only when SW6, SW7, or SW8 are toggled.

### 6.3. \*\*\*TEST COMPLETE \*\*\*

### 7. NOTES

#### 8. <u>REFERENCES</u>

### Configuration and Test procedures for XMC-2-B

- 1. Use test WETS5402 to calibrate XMC-2 power bd. amped version and WETS5403 to calibrate the ampless version.
- 2. To change power bd. for 220VAC operation, move JP5 to A & B.
- 3. To convert unit from sink to source, change EPROM (U29), set JP1 to A & B and E & F, then remove R76 and put it in R25 spot. JP1 (BC, DE) for sink, and JP1 (AB, EF) for source
- 4. E-proms are as follows:

For IMC-20X0 31450053 (SINK) IMC-20X1 31450044 (SOURCE) CMC-20X0 31450029 (SINK) CMC-20X1 31450034 (SOURCE)

- 5. To convert from IMC to CMC, use applicable EPROM, remove U9 and jumper pins 9 & 11, then remove U8 and replace with 31320090.
- 6. Now mate the power and logic boards together with a shield board between them.
- 7. Connect AC power cable to power board and turn on power. Connect voltmeter positive side to U6 pin 25 and ground to U29 pin 14. Turn R35 pot until meter reads 0volts. Now turn off power and seal pot.
- 8. Go to final test bench and run WETS5429 test procedure.
- 9. After successful completion of testing, forward to assembly.

#### Repairs and what to look for on XMC-2 units

- 1. If the unit is returned for repair, be sure the board is not burned. If it looks repairable, more than likely have to replace R33-36, C32, 36, 38 and D16,18-21. If C20 is shorted replace C20. Need to replace C12-15 only if any one of R33-36 is open.
- 2. In some cases, the logic power and motor power supply sections have been burned. You may just want to replace the power board because there are a lot of parts to replace and it just may not be worth your time.
- 3. To upgrade logic boards, replace U15 with 70004444 bd., replace CR13 with zero ohm resistor, upgrade EPROM to latest revision. Cut out CR10&11 and Q3. Run jumper wire from U29 pin 28 to U30 pin 28. Run more jumper wire from U15 pin 7 to U14 pin 14 and U15 pin 14 to U14 pin 7. Finally, replace U30 ram with battery-backed version 31430050 for IMC's only.
- 4. If troubleshooting new power boards, if power is OK but will not run correctly, be sure no transistors are shorted to the T-bar. Always be on the look out for shorts and missing parts.

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Common components to replace on power supply card.

330uf 35VDC C32, C36, C38

27K 2 Watt R35 30K 2 Watt R34 560uf 250VDC C13, C14 2200uf C33, C34