Basics of

Machine Learning

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Fachine learning is the method of teaching computers to make and improve predictions or behaviours based on some data. The data could be readings from a robot's sensors as it learns to walk, or the correct output of a program for certain input. Suppose there is a problem to recognize a 3D object from a novel viewpoint in new lighting conditions in a clustered scene. So in this case we don't know the program as we don't know how it is done in our brain, else if we even knew the program it would be horrendously complicated. Another example is to compute the probability that a credit card transaction is fraudulent. In this case there may not be any rule that is simple and reliable; we need to combine very large number of weak rules. Fraud is a moving target; the program needs to be changing. Instead of writing a program by hand for each specific task, we collect a large number of examples that specifies the correct output for a given input. program is made right, it works on new problems trained on. If the data changes the program can one to write a task specific program.

Some of the camples of task best solved by machine learning incregating pattern, for example objective read reads. It is slow by hypering etc., the same and deviding the image time layers and the internal control of the same and deviding the image time layers well. In the case of the control of the control of the control of the control control we can read to recognize amounts; like unusual teaperstar control we can read to recognize amounts; like unusual teaperstar can be control of the control can pear parts. In case of pattern than the parts of control can pear parts and control of the control o



Fig. 1 (MNIST database of handwritten digits

There are even more databases beyond MNIST., for example ImageNet, where there are 1000 different object classes in 1.3 million high-resolution training images from the web, and the best system to classify objects in 2010 competition got 47% error for its first choice and 25% error for its top five choices. Some of the earlier examples of the image classification are shown in Fig. 2(i), (ii), (iii).



Fig 2(i) Example of earlier version of Net



Fig 2(ii) It can deal with wide range of objects



Fig 2(iii) It makes really cool errors

From Fig 2(i) (ii) (iii) we can see that it can correctly predict wide range of objects and it does make some really cool errors like the earphone in the figure looks like and from above, and some are very awkward errors which can be predicted when we see it in a different way.

Now one of the most widely used applications of speech is Google voice, and one of the widely used applications of image processing is Google lens. So, a speech recognition task has several stages, it is covered to the state of the several stages, it is covered to the state of the several stages, it is covered to the several stages, it is covered to the several stages, it is covered to the several stages of the several stages in the several stages of the sev

So in the history of the neural networks, deep mean network piemercel by George Dail and Adulf Rahmal holomed are now replacing the previous machine learning nethods for the acoustic respective properties of the previous machine learning tenthod for the acoustic respective properties of the previous properties of the previous appears or independent result of TIMIT was 24-4% and this required outgraging several models. To that from wood errors from 5005, Miller gas several models. To that from wood errors from 5005, Miller 300 hours of training data and it has a curve of 1.8.5 years for the speech. So English broadcast were of 1015 requires 500 hours of training and it gives as error of 1.7.5 when we find in the previous of the previous official knowledges of the previous properties of the previous of the previous properties of the previous properties of the previous official knowledges are official previous for the previous properties.

There are different types of learning task:

Supervised learning - It learns to predict an output when an input vector is given.

There are two types of supervised learning.

Each training case consists of an input vector x and a target output t.

i. Regression: The target output is a real number or a whole vector of real numbers, for example the price of a stock in a six amounths time period or the temperature at the neon temporrow.

 Classification: The target output is a class label. The simplest case is a choice between 0 and 1. We can also have multiple alternative labels. Reinforcement learning-Learn to select an action to maximize payoff.
 In reinforcement learning, the output is an action or sequence of ac-

In reinforcement learning, the output is an action or sequence of actions and the only supervisory signal is an ocasional sealar reward. The goal in selecting each action is to maximize the expected sum of future rewards. We usually use a discount factor for delayed rewards so that we don't have to look too far into the future. Reinforcement learning is difficult since the rewards are typically delayed and so it is hard to know where we went wrong or right. A scalar reward does not supply much information.

 Unsupervised learning- Discover a good internal representation of the input.
 For about 40 years, unsupervised learning was largely ignored by

the mixed referring columnity's solute widely used definitions of what the distancing was the only form of name-privide learning, it is hard to say what the aim of unsupervised learning, it is bard to say what the aim of unsupervised learning, is come again at most proposed to the say of the say

resentation of the imput. High dimicisional inputs typically rive on or near a low dimensional manifold(s). Principal component analysis is a widely used linear method for finding a low-dimensional representation. It provides an economical high-dimensional representation of the input in terms of learned features.