



SPEEDUP

The SPEEDUP Society:

The Swiss Forum for
High-Performance Computing

Advanced MPI: New Features of MPI-3

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Tutorial Outline

1. Introduction to Advanced MPI Usage
 2. Nonblocking Collective Communication
 3. One-Sided Communication
 4. Topology Mapping and Neighborhood Collective Communication
 5. Bonus Material (only if time)
 1. Hybrid Programming Primer
 2. Datatypes
-
- All materials (slides, code examples) at:
http://htor.inf.ethz.ch/teaching/mpi_tutorials/speedup15/



Used Techniques

- Benjamin Franklin "***Tell me, I forget, show me, I remember, involve me, I understand.***"
 - Tell: I will explain the abstract concepts and interfaces/APIs to use them
 - Show: I will demonstrate one or two examples for using the concepts
 - Involve: You will transform a simple MPI code into different semantically equivalent optimized ones
- **Please interrupt me with any question at any point!**

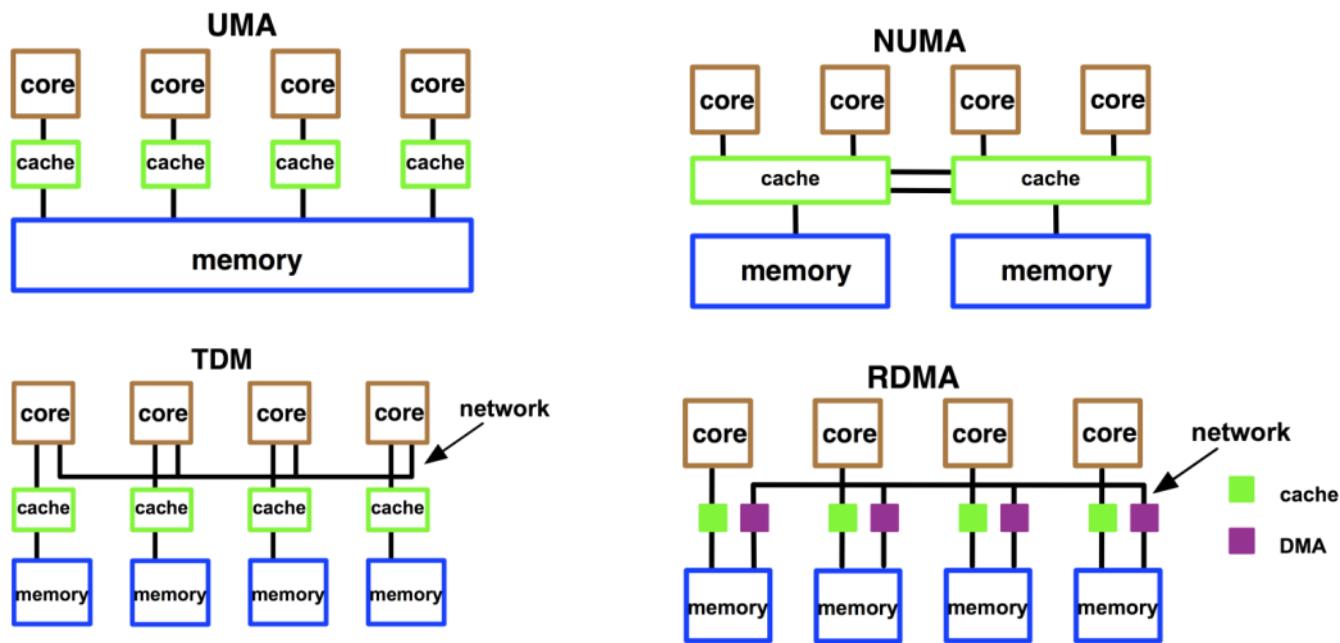


Section I - Introduction



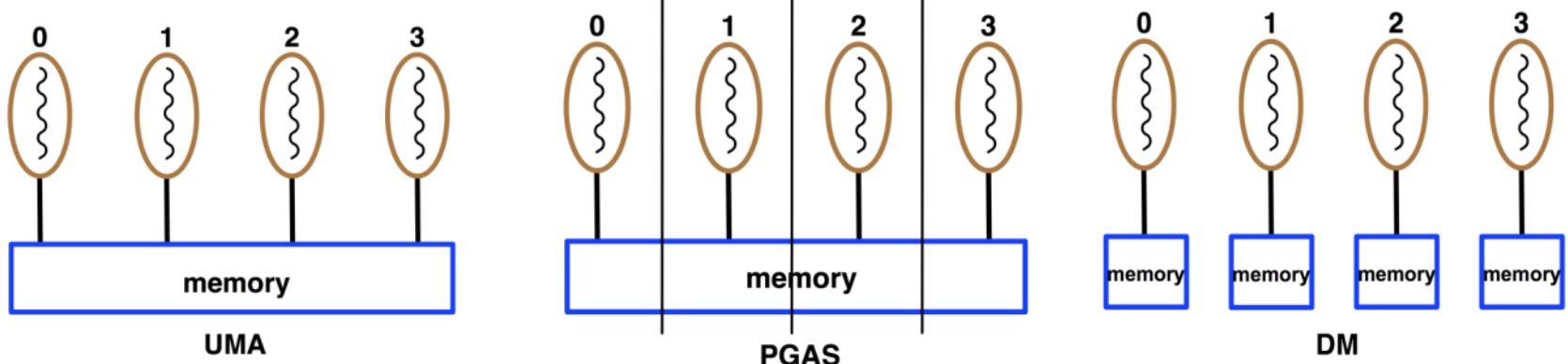
Introduction

- Programming model Overview
- Different systems: UMA, ccNUMA, nccNUMA, RDMA, DM



Introduction

- Different programming models: UMA, PGAS, DM

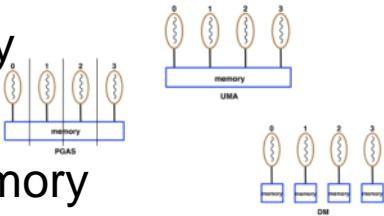


TBB, CILK, OpenMP, MPI-3 SM UPC, CAF, MPI-3 OS

MPI-1, PVM

- The question is all about memory consistency

Programming Models

- **Provide abstract machine models (contract)**
 - Shared memory
 - PGAS
 - Distributed memory

The diagram illustrates three memory models:

 - PGAS:** Shows four nodes connected to a central "memory" block labeled "PGAS". Each node has a local memory space (labeled 0, 1, 2, 3) represented by a wavy line.
 - UMA:** Shows a single large "memory" block labeled "UMA" connected to four nodes. Each node has a local memory space (labeled 0, 1, 2, 3) represented by a wavy line.
 - DM:** Shows four separate "memory" blocks labeled "DM" connected to four nodes. Each node has a local memory space (labeled 0, 1, 2, 3) represented by a wavy line.
- **All models can be mapped to any architecture, more or less efficient (execution model)**
- **MPI is not a programming model**
 - And has never been one!

MPI Governing Principles

- **(Performance) Portability**
 - Declarative vs. imperative
 - Abstraction (of processes)
- **Composability (Libraries)**
 - Isolation (no interference)
 - Opaque object attributes
- **Transparent Tool Support**
 - PMPI, MPI-T
 - Inspect performance and correctness

Main MPI Concepts

- **Communication Concepts:**
 - Point-to-point Communication
 - Collective Communication
 - One Sided Communication
 - (Collective) I/O Operations
- **Declarative Concepts:**
 - Groups and Communicators
 - Derived Datatypes
 - Process Topologies
- **Process Management**
 - Malleability, ensemble applications
- **Tool support**
 - Linking and runtime

MPI History

- An open standard library interface for message passing, ratified by the MPI Forum
- Versions: 1.0 ('94), 1.1 ('95), 1.2 ('97), 1.3 ('08)
 - Basic Message Passing Concepts
- 2.0 ('97), 2.1 ('08)
 - Added One Sided and I/O concepts
- 2.2 ('09)
 - Merging and smaller fixes
- 3.0 ('12)
 - Several additions to react to new challenges
- 3.1 ('15)
 - Several smaller issues and (hopefully) FT
- 4.0 ('??)
 - Unclear (come next week to Kobe!!)



What MPI is Not

- **No explicit support for active messages**
 - Can be emulated at the library level
- **Not a programming language**
 - But it's close, semantics of library calls are clearly specified
 - MPI-aware compilers under development
- **It's not magic**
 - Manual data decomposition (cf. libraries, e.g., ParMETIS)
Some MPI mechanisms (Process Topologies, Neighbor Colls.)
 - Manual load-balancing (see libraries, e.g., ADLB)
- **It's neither complicated nor bloated**
 - Six functions are sufficient for any program
 - 250+ additional functions that offer abstraction, performance portability and convenience for experts



What is this MPI Forum?

- **An open Forum to discuss MPI**
 - You can join! No membership fee, no perks either
- **Since 2008 meetings every two months for three days (switching to four months and four days)**
 - 5x in the US, once in Europe (with EuroMPI → next week)
- **Votes by organization, eligible after attending two of the three last meetings, often unanimously**
- **Everything is voted twice in two distinct meetings**
 - Tickets as well as chapters





Recommended Development Workflow

1. Identify a scalable algorithm

- Analyze for memory and runtime

2. Is there a library that can help me?

- Computational libraries

PPM, PBGL, PETSc, PMTL, ScaLAPACK

- Communication libraries

AM++, LibNBC

- Programming Model Libraries

ADLB, AP

- Utility Libraries

HDF5, Boost.MPI

3. Plan for modularity

- Writing (parallel) libraries has numerous benefits

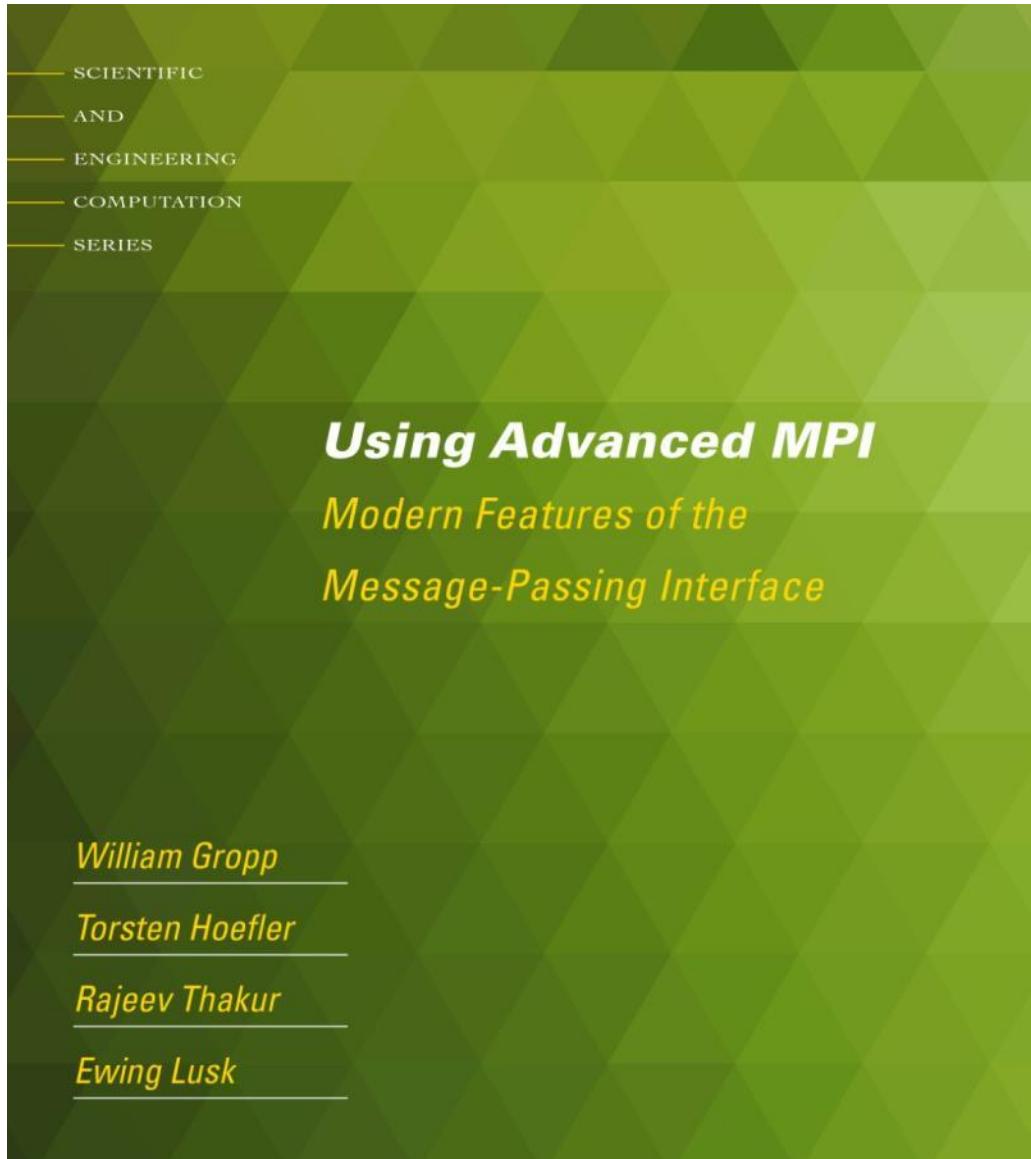


Things to Keep in Mind

- **MPI is an open standardization effort**
 - Talk to us or join the forum
 - There will be a public comment period
- **The MPI standard**
 - Is **free** for everybody
 - Is **not** intended for end-users (no replacement for books and tutorials)
 - Is the last instance in MPI questions



Any Deeper Questions – Advanced MPI



includes all of MPI-3.0

appeared November 2014
(on sale on Amazon now)

Section II - Nonblocking and Collective Communication



Nonblocking and Collective Communication

- **Nonblocking communication**
 - Deadlock avoidance
 - Overlapping communication/computation
- **Collective communication**
 - Collection of pre-defined optimized routines
- **Nonblocking collective communication**
 - Combines both advantages
 - System noise/imbalance resiliency
 - Semantic advantages
 - Examples

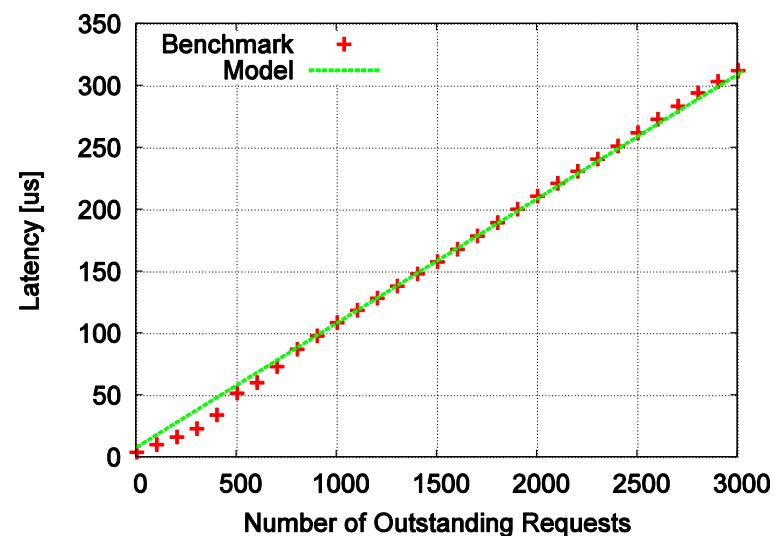
Nonblocking Communication

- **Semantics are simple:**
 - Function returns no matter what
 - No progress guarantee!
- E.g., `MPI_Isend(<send-args>, MPI_Request *req);`
- **Nonblocking tests:**
 - Test, Testany, Testall, Testsome
- **Blocking wait:**
 - Wait, Waitany, Waitall, Waitsome

Nonblocking Communication

- **Blocking vs. nonblocking communication**
 - Mostly equivalent, nonblocking has constant request management overhead
 - Nonblocking may have other non-trivial overheads
- **Request queue length**
 - Linear impact on performance
 - E.g., BG/P: 100ns/req

Tune unexpected queue length!

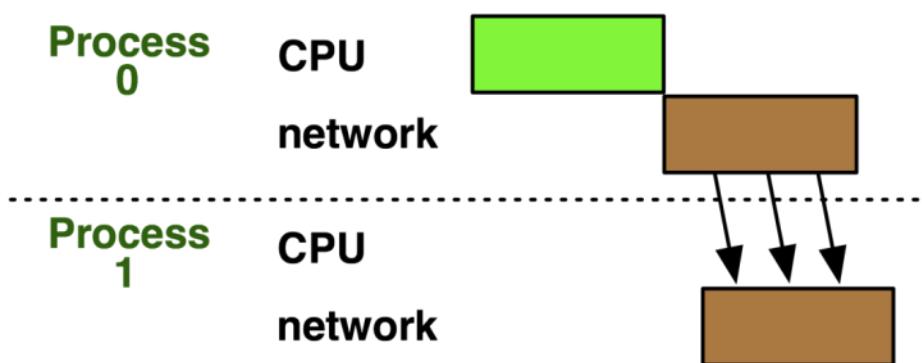


Nonblocking Communication

- An (important) implementation detail
 - Eager vs. Rendezvous
- Most/All MPIs switch protocols
 - Small messages are copied to internal remote buffers
And then copied to user buffer
Frees sender immediately (cf. bsend)
 - Large messages wait until receiver is ready
Blocks sender until receiver arrived
 - Tune eager limits!

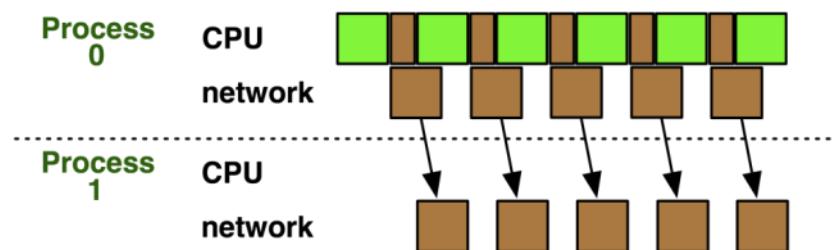
Software Pipelining - Motivation

```
if(r == 0) {  
    for(int i=0; i<size; ++i) {  
        arr[i] = compute(arr, size);  
    }  
    MPI_Send(arr, size, MPI_DOUBLE, 1, 99, comm);  
} else {  
    MPI_Recv(arr, size, MPI_DOUBLE, 0, 99, comm, &stat);  
}
```



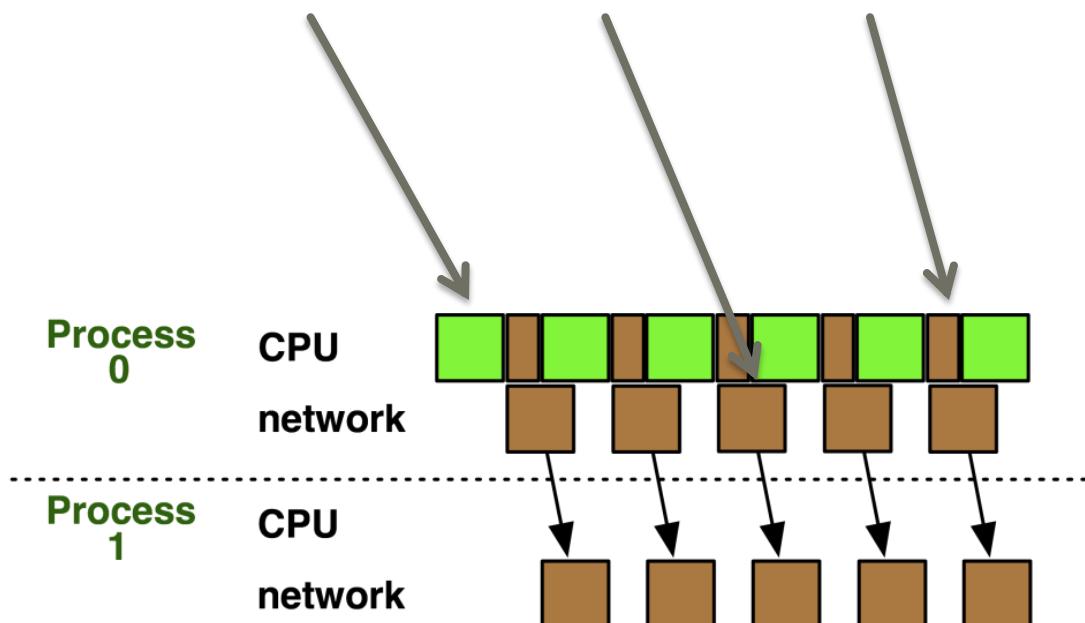
Software Pipelining - Motivation

```
if(r == 0) {  
    MPI_Request req=MPI_REQUEST_NULL;  
    for(int b=0; b<nblocks; ++b) {  
        if(b) {  
            if(req != MPI_REQUEST_NULL) MPI_Wait(&req, &stat);  
            MPI_Isend(&arr[(b-1)*bs], bs, MPI_DOUBLE, 1, 99, comm, &req);  
        }  
        for(int i=b*bs; i<(b+1)*bs; ++i) arr[i] = compute(arr, size);  
    }  
    MPI_Send(&arr[(nblocks-1)*bs], bs, MPI_DOUBLE, 1, 99, comm);  
} else {  
    for(int b=0; b<nblocks; ++b)  
        MPI_Recv(&arr[b*bs], bs, MPI_DOUBLE, 0, 99, comm, &stat);  
}
```



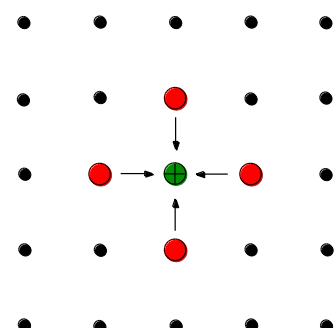
A Simple Pipeline Model

- **No pipeline:**
 - $T = T_{\text{comp}}(s) + T_{\text{comm}}(s) + T_{\text{startc}}(s)$
- **Pipeline:**
 - $T = \text{nblocks} * [\max(T_{\text{comp}}(\text{bs}), T_{\text{comm}}(\text{bs})) + T_{\text{startc}}(\text{bs})]$



2D Jacobi Example

- Many 2d electrostatic problems can be reduced to solving Poisson's or Laplace's equation
 - Solution by finite difference methods
 - $p_{\text{new}}(i,j) = (p(i-1,j)+p(i+1,j)+p(i,j-1)+p(i,j+1))/4$
 - natural 2d domain decomposition
 - State of the Art:
Compute, communicate
Maybe overlap inner computation



Simplified Serial Code

```
for(int iter=0; iter<niters; ++iter) {  
    for(int i=1; i<n+1; ++i) {  
        for(int j=1; j<n+1; ++j) {  
            anew[ind(i,j)] = apply(stencil); // actual computation  
            heat += anew[ind(i,j)]; // total heat in system  
        }  
    }  
    for(int i=0; i<nsources; ++i) {  
        anew[ind(sources[i][0],sources[i][1])] += energy; // heat source  
    }  
    tmp=anew; anew=aold; aold=tmp; // swap arrays  
}
```

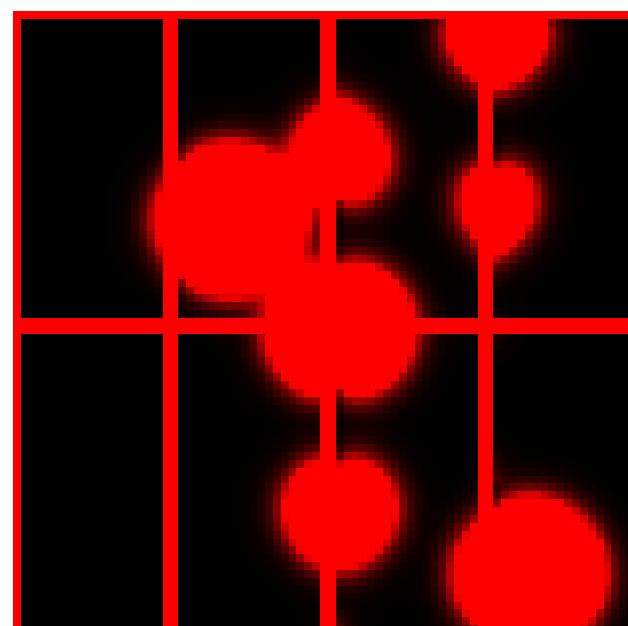
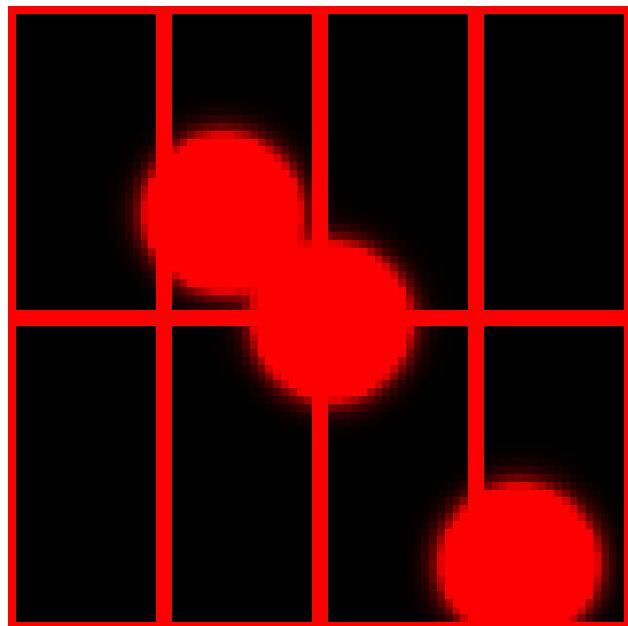
Simple 2D Parallelization

- **Why 2D parallelization?**
 - Minimizes surface-to-volume ratio
- **Specify decomposition on command line (px, py)**
- **Compute process neighbors manually**
- **Add halo zones (depth 1 in each direction)**
- **Same loop with changed iteration domain**
- **Pack halo, communicate, unpack halo**
- **Global reduction to determine total heat**



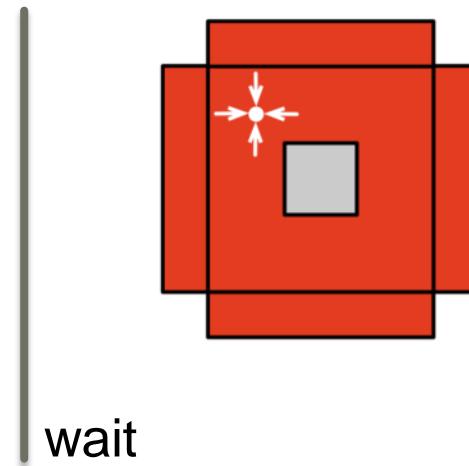
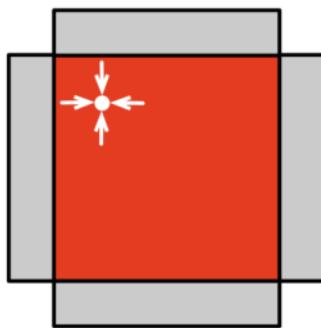
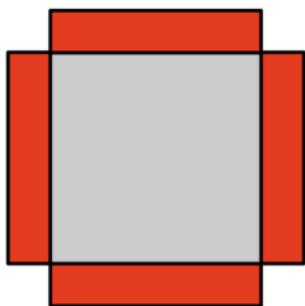
Source Code Example

- Browse through code (`stencil_mpi.cpp`)



Stencil Example - Overlap

- `stencil_mpi_ddt_overlap.cpp`



- Steps:
 - Start halo communication
 - Compute inner zone
 - Wait for halo communication
 - Compute outer zone
 - Swap arrays



Collective Communication

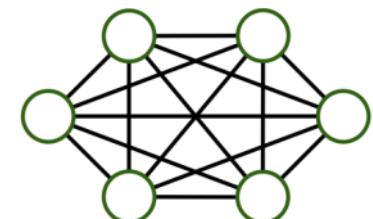
- **Three types:**
 - Synchronization (Barrier)
 - Data Movement (Scatter, Gather, Alltoall, Allgather)
 - Reductions (Reduce, Allreduce, (Ex)Scan, Reduce_scatter)
- **Common semantics:**
 - no tags (communicators can serve as such)
 - Blocking semantics (return when complete)
 - Not necessarily synchronizing (only barrier and all*)
- **Overview of functions and performance models**



Collective Communication

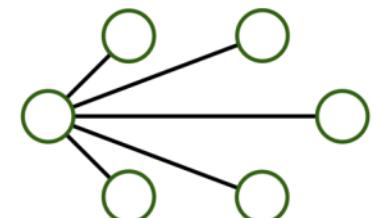
- **Barrier** –
 - Often $\alpha + \beta \log_2 P$

$$\Omega(\log(P))$$



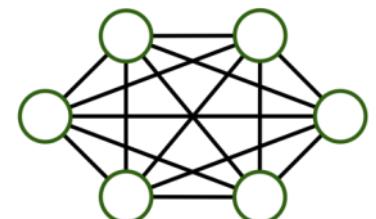
- **Scatter, Gather** –
 - Often $\alpha P + \beta Ps$

$$\Omega(\log(P) + Ps)$$



- **Alltoall, Allgather** -
 - Often $\alpha P + \beta Ps$

$$\Omega(\log(P) + Ps)$$





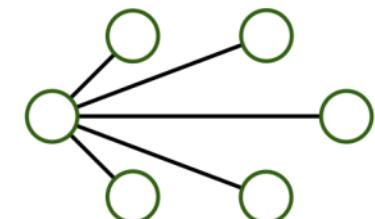
Collective Communication

- **Reduce –**
 - Often $\alpha \log_2 P + \beta m + \gamma m$

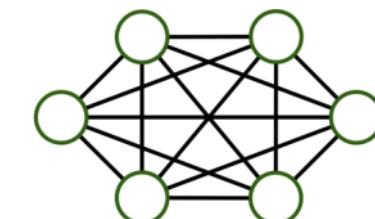
- **Allreduce –**
 - Often $\alpha \log_2 P + \beta m + \gamma m$

- **(Ex)scan –**
 - Often $\alpha P + \beta m + \gamma m$

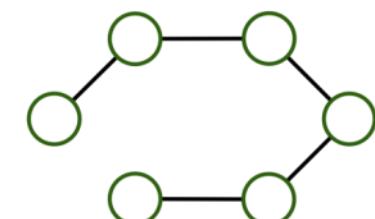
$$\Omega(\log(P) + s)$$



$$\Omega(\log(P) + s)$$



$$\Omega(\log(P) + s)$$



Nonblocking Collective Communication

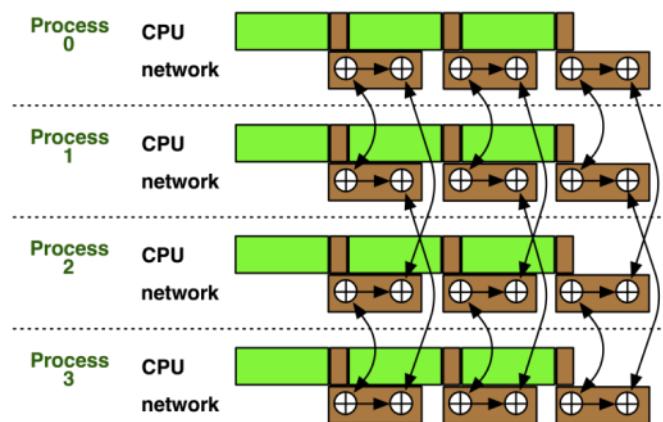
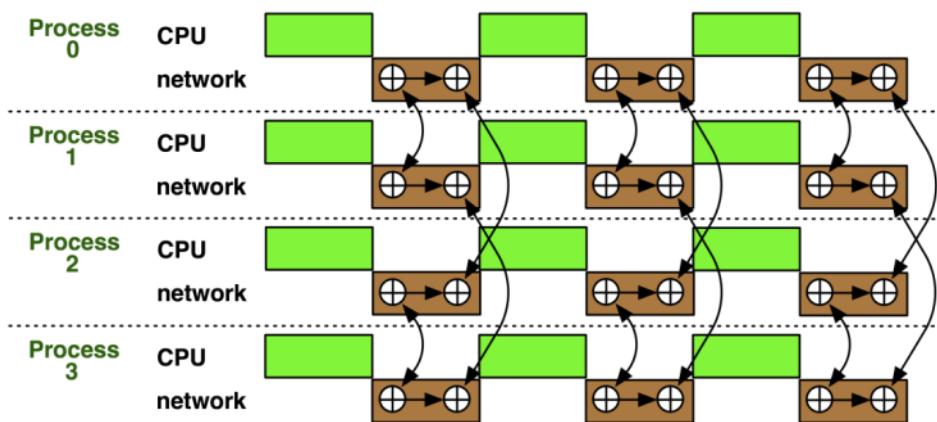
- **Nonblocking variants of all collectives**
 - MPI_Ibcast(<bcast args>, MPI_Request *req);
- **Semantics:**
 - Function returns no matter what
 - No guaranteed progress (quality of implementation)
 - Usual completion calls (wait, test) + mixing
 - Out-of order completion
- **Restrictions:**
 - No tags, in-order matching
 - Send and vector buffers may not be touched during operation
 - MPI_Cancel not supported
 - No matching with blocking collectives

Nonblocking Collective Communication

- **Semantic advantages:**
 - Enable asynchronous progression (and manual)
Software pipelining
 - Decouple data transfer and synchronization
Noise resiliency!
 - Allow overlapping communicators
See also neighborhood collectives
 - Multiple outstanding operations at any time
Enables pipelining window

Nonblocking Collectives Overlap

- Software pipelining, similar to point-to-point
 - More complex parameters
 - Progression issues
 - Not scale-invariant



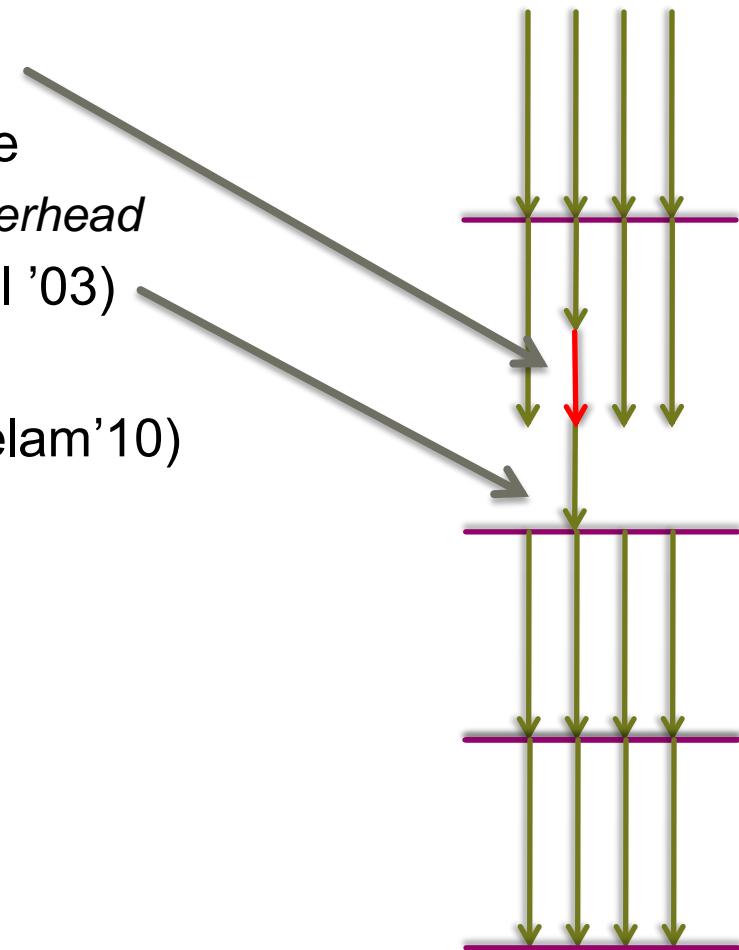


Nonblocking Collectives Overlap

- **Complex progression**
 - MPI's global progress rule!
- **Higher CPU overhead (offloading?)**
- **Differences in asymptotic behavior**
 - Collective time often $\Omega(\log(P) + Ps)$
 - Computation $\mathcal{O}(\frac{N}{P})$
- → Performance modeling ☺
- One term often dominates and complicates overlap

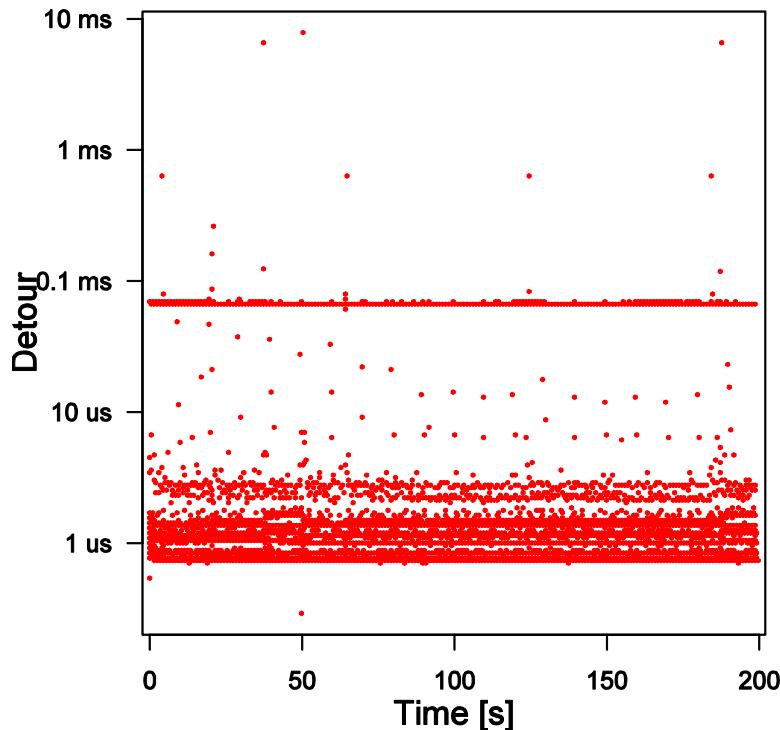
System Noise – Introduction

- **CPUs are time-shared**
 - Deamons, interrupts, etc. steal cycles
 - No problem for single-core performance
Maximum seen: 0.26%, average: 0.05% overhead
 - “Resonance” at large scale (Petrini et al '03)
- **Numerous studies**
 - Theoretical (Agarwal'05, Tsafrir'05, Seelam'10)
 - Injection (Beckman'06, Ferreira'08)
 - Simulation (Sottile'04)



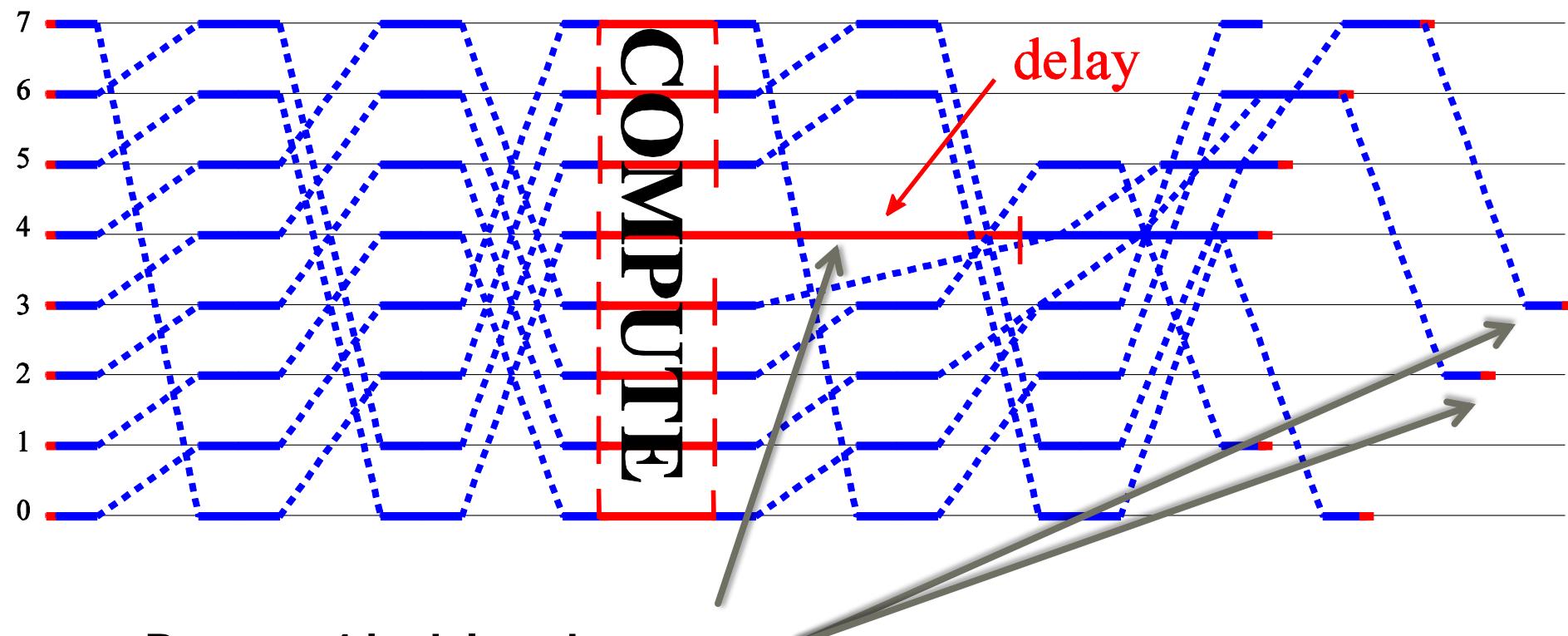


Measurement Results – Cray XE



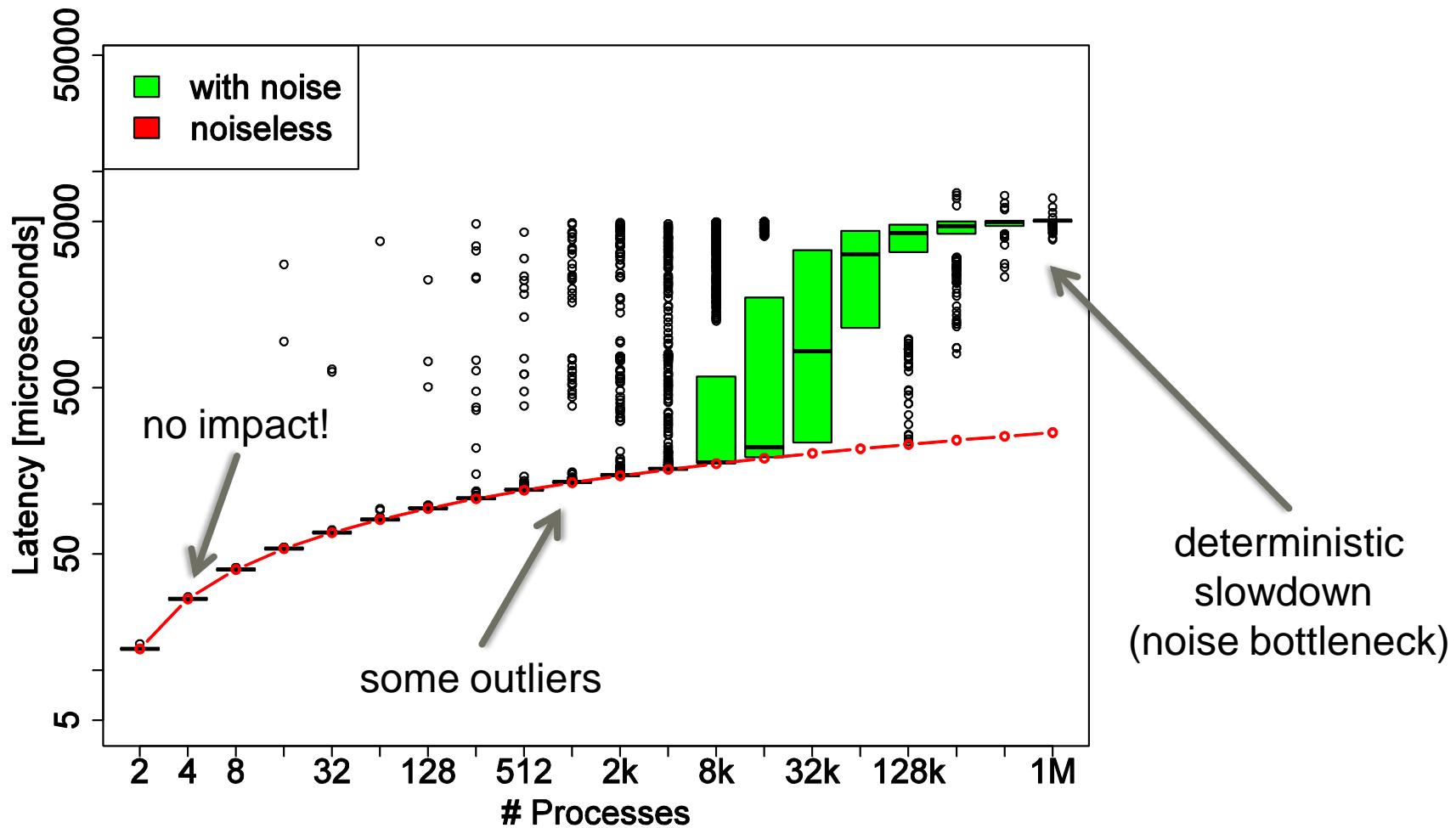
- **Resolution: 32.9 ns, noise overhead: 0.02%**

A Noisy Example – Dissemination



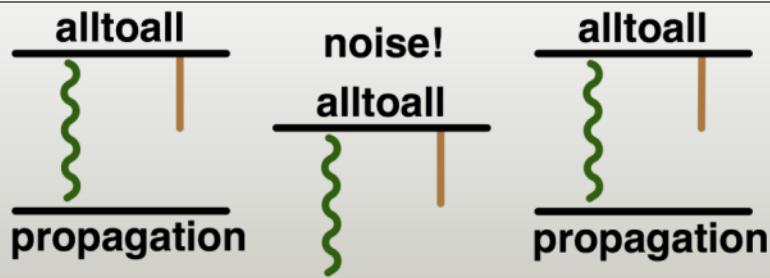
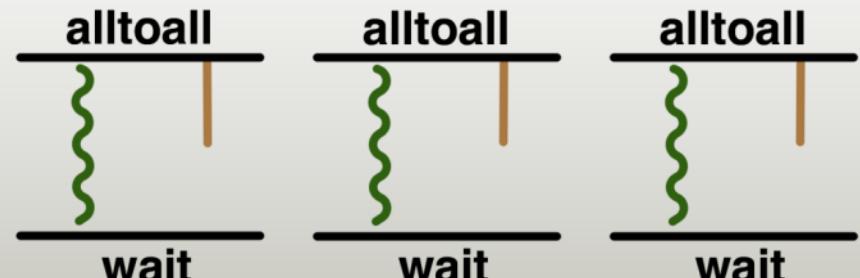
- **Process 4 is delayed**
 - Noise propagates “wildly” (of course deterministic)

Single Byte Dissemination on Jaguar



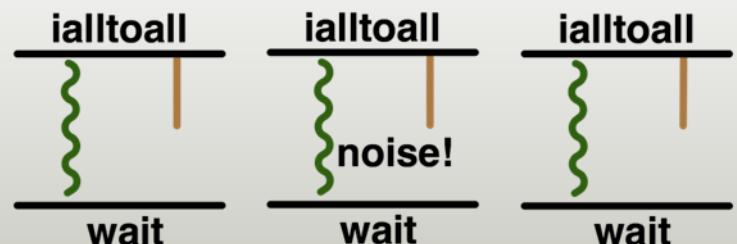
Nonblocking Collectives vs. Noise

No Noise, blocking



Noise, blocking

Noise, nonblocking

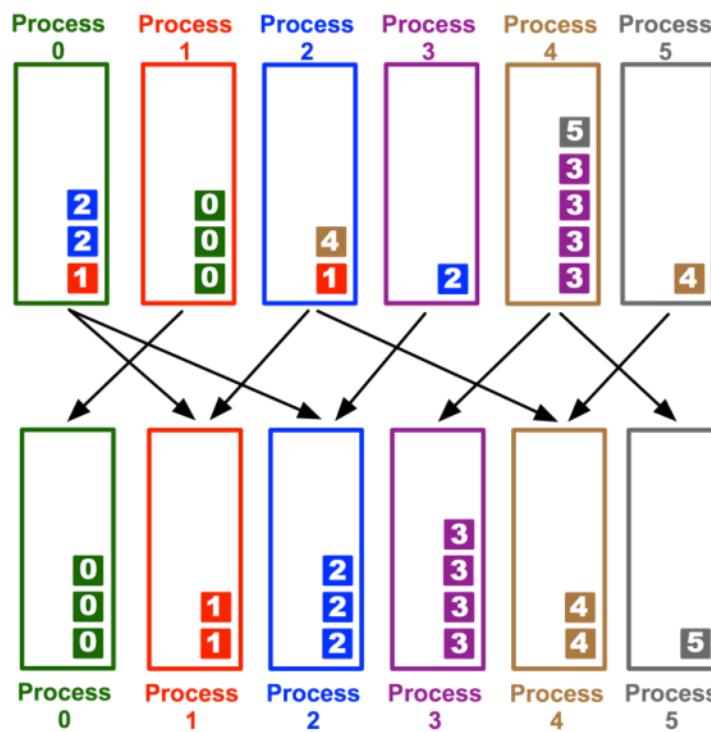


A Non-Blocking Barrier?

- **What can that be good for? Well, quite a bit!**
- **Semantics:**
 - MPI_Ibarrier() – calling process entered the barrier, **no** synchronization happens
 - Synchronization **may** happen asynchronously
 - MPI_Test/Wait() – synchronization happens **if** necessary
- **Uses:**
 - Overlap barrier latency (small benefit)
 - Use the split semantics! Processes **notify** non-collectively but **synchronize** collectively!

A Semantics Example: DSDE

- **Dynamic Sparse Data Exchange**
 - Dynamic: comm. pattern varies across iterations
 - Sparse: number of neighbors is limited ($\mathcal{O}(\log P)$)
 - Data exchange: only senders know neighbors



Dynamic Sparse Data Exchange (DSDE)

■ Main Problem: metadata

- Determine who wants to send how much data to me
(I must post receive and reserve memory)

OR:

- Use MPI semantics:

Unknown sender

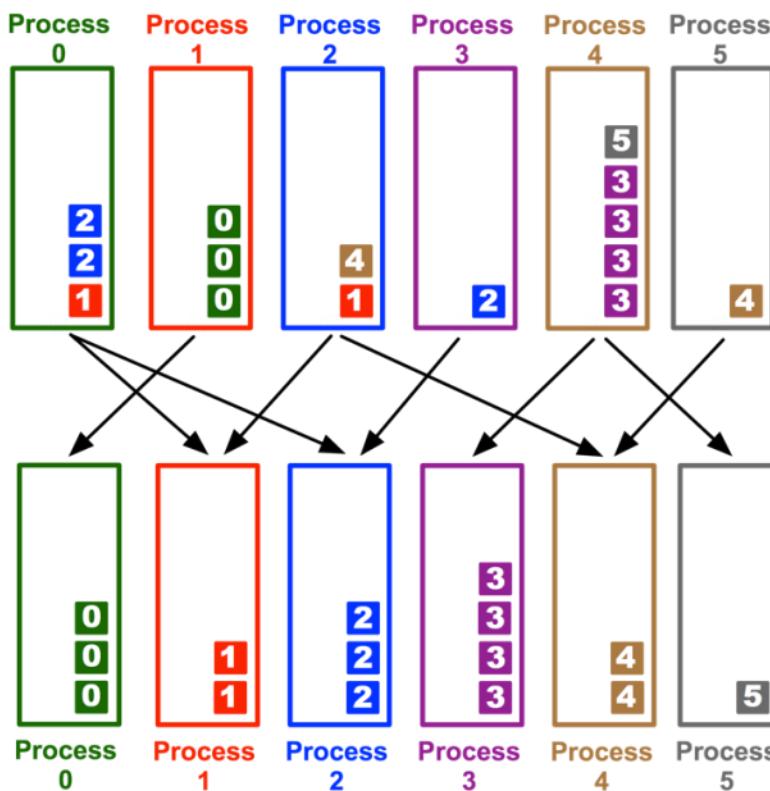
`MPI_ANY_SOURCE`

Unknown message size

`MPI_PROBE`

*Reduces problem to counting
the number of neighbors*

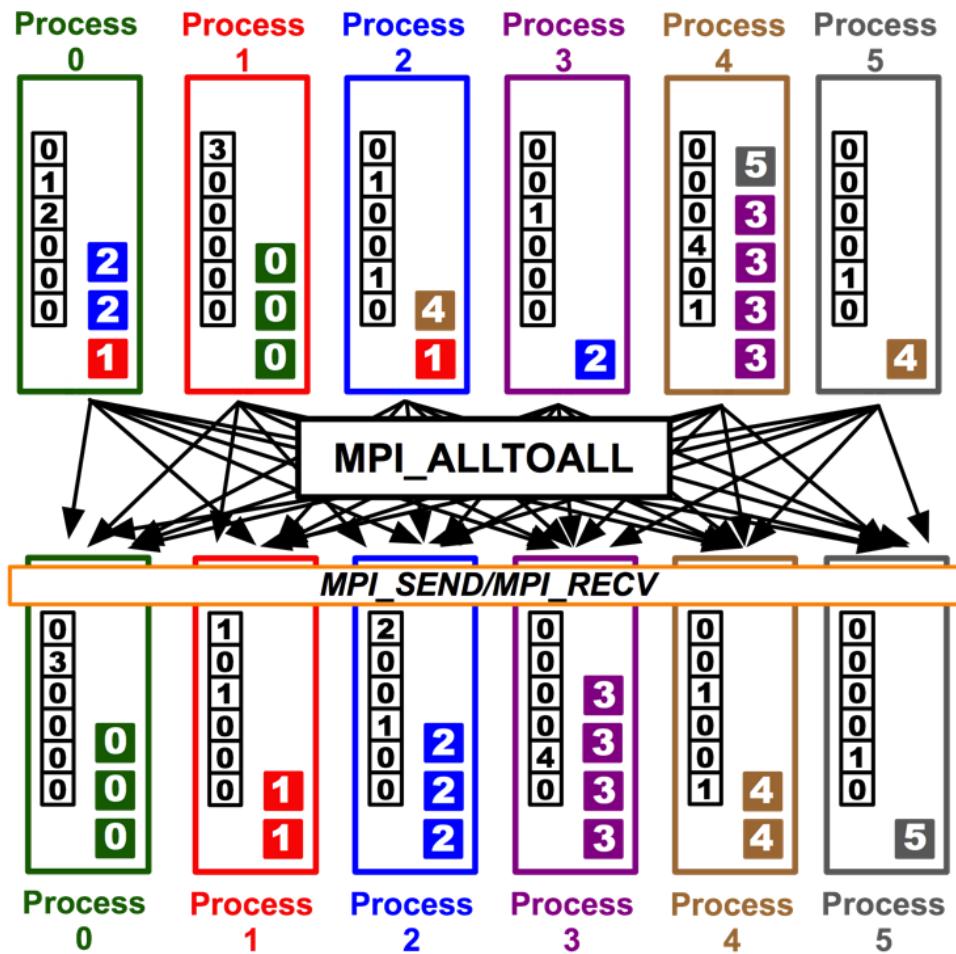
Allow faster implementation!



Using Alltoall (PEX)

- Based on Personalized Exchange ($\Theta(P)$)

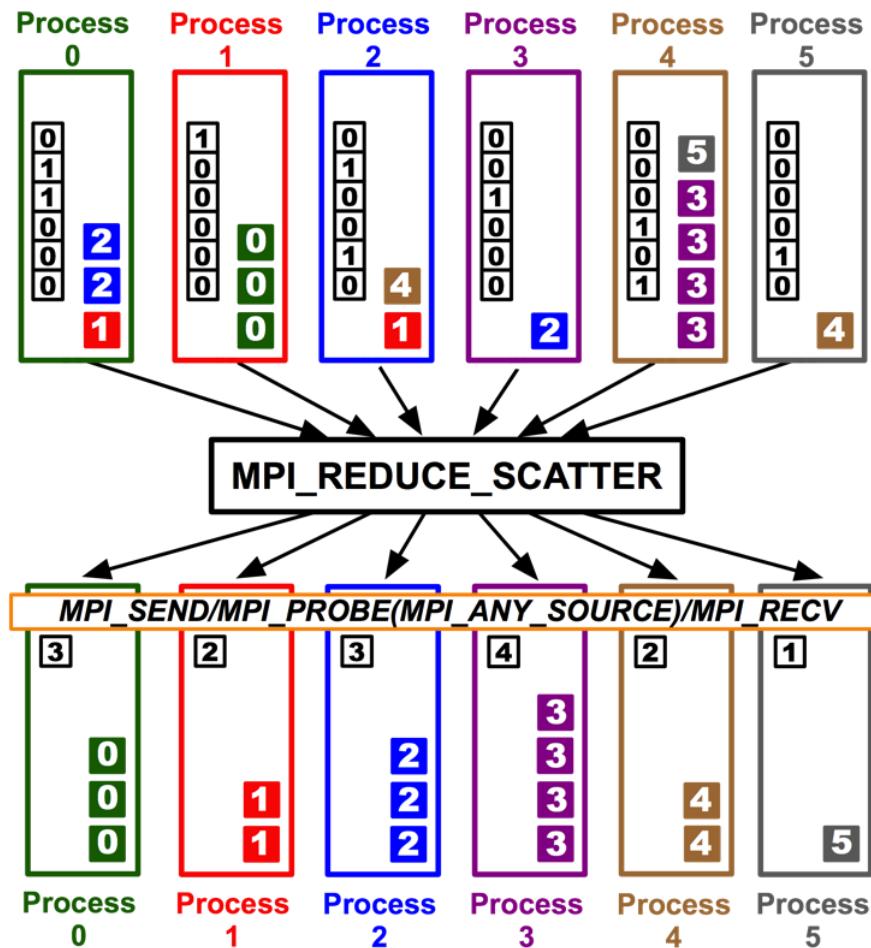
- Processes exchange metadata (sizes) about neighborhoods with all-to-all
- Processes post receives afterwards
- Most intuitive but least performance and scalability!



Reduce_scatter (PCX)

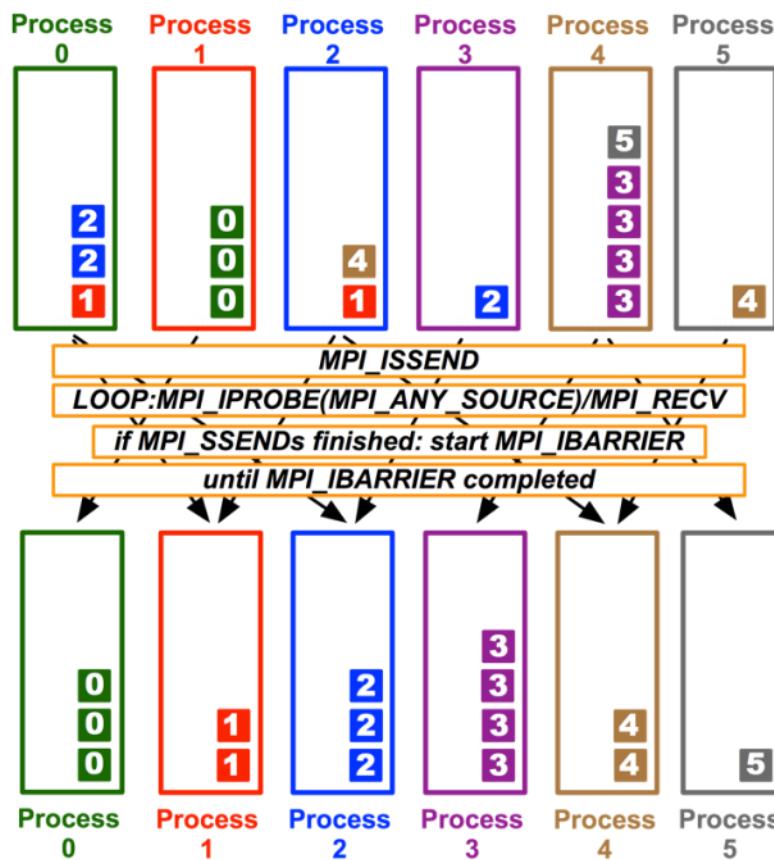
- **Bases on Personalized Census ($\Theta(P)$)**

- Processes exchange metadata (counts) about neighborhoods with reduce_scatter
- Receivers checks with wildcard MPI_IPROBE and receives messages



MPI_Ibarrier (NBX)

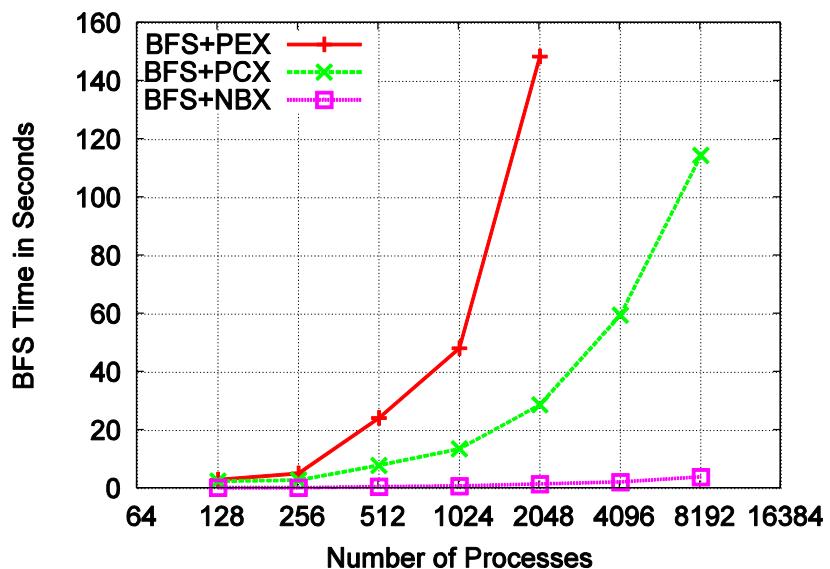
- **Complexity - census (barrier): $(\Theta(\log(P)))$**
 - Combines metadata with actual transmission
 - Point-to-point synchronization
 - Continue receiving until barrier completes
 - Processes start coll. synch. (barrier) when p2p phase ended
barrier = distributed marker!
- Better than PEX, PCX, RSX!



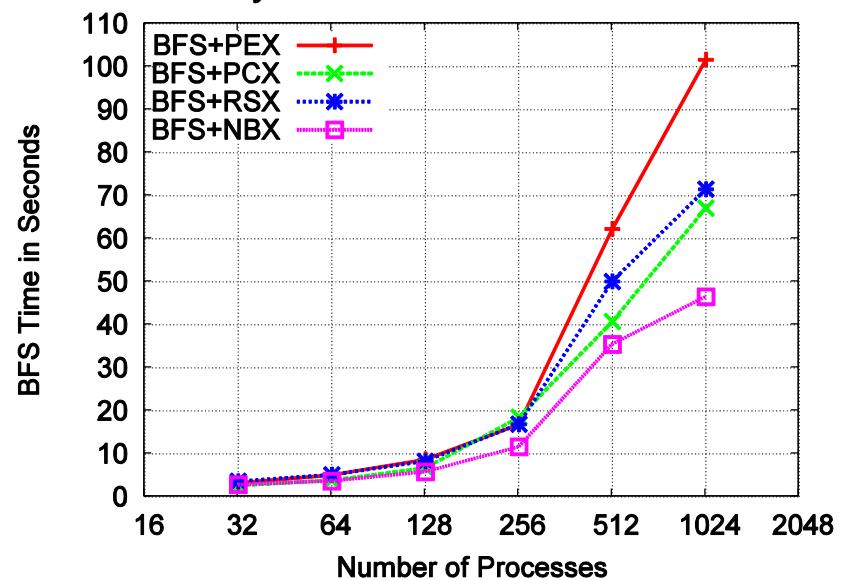
Parallel Breadth First Search

- On a clustered Erdős-Rényi graph, weak scaling
 - 6.75 million edges per node (filled 1 GiB)

BlueGene/P – with HW barrier!



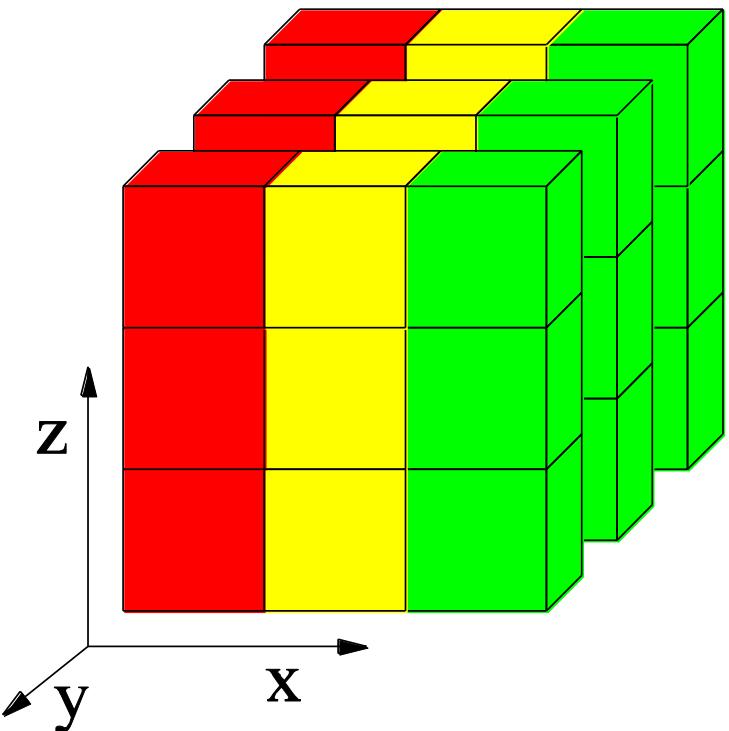
Myrinet 2000 with LibNBC



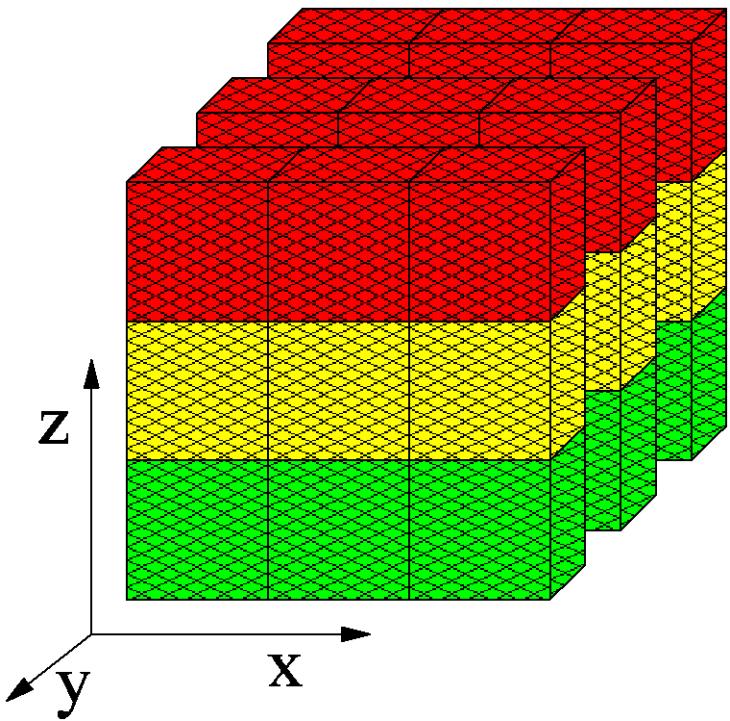
- HW barrier support is significant at large scale!

Parallel Fast Fourier Transform

- **1D FFTs in all three dimensions**
 - Assume 1D decomposition (each process holds a set of planes)
 - Best way: call optimized 1D FFTs in parallel → alltoall



→ Alltoall



- Red/yellow/green are the (three) different processes!

A Complex Example: FFT

```
for(int x=0; x<n/p; ++x) 1d_fft(/* x-th stencil */);
```

// pack data for alltoall

```
MPI_Alltoall(&in, n/p*n/p, cplx_t, &out, n/p*n/p, cplx_t, comm);
```

// unpack data from alltoall and transpose

```
for(int y=0; y<n/p; ++y) 1d_fft(/* y-th stencil */);
```

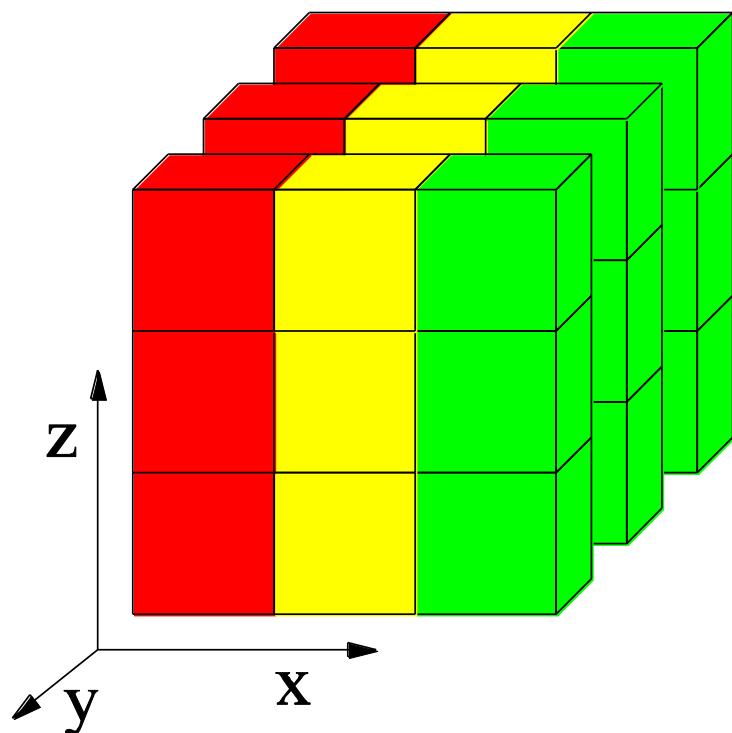
// pack data for alltoall

```
MPI_Alltoall(&in, n/p*n/p, cplx_t, &out, n/p*n/p, cplx_t, comm);
```

// unpack data from alltoall and transpose

Parallel Fast Fourier Transform

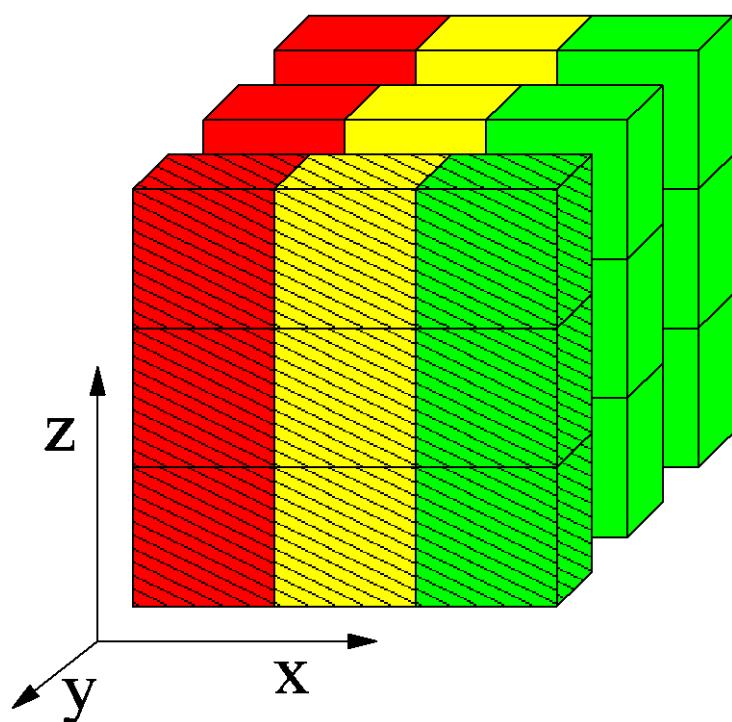
- Data already transformed in y-direction





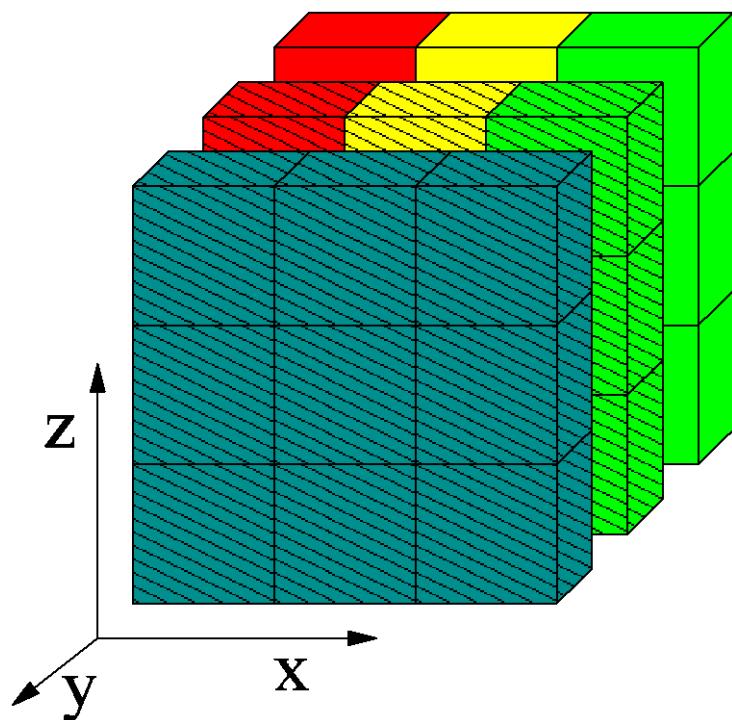
Parallel Fast Fourier Transform

- Transform first y plane in z



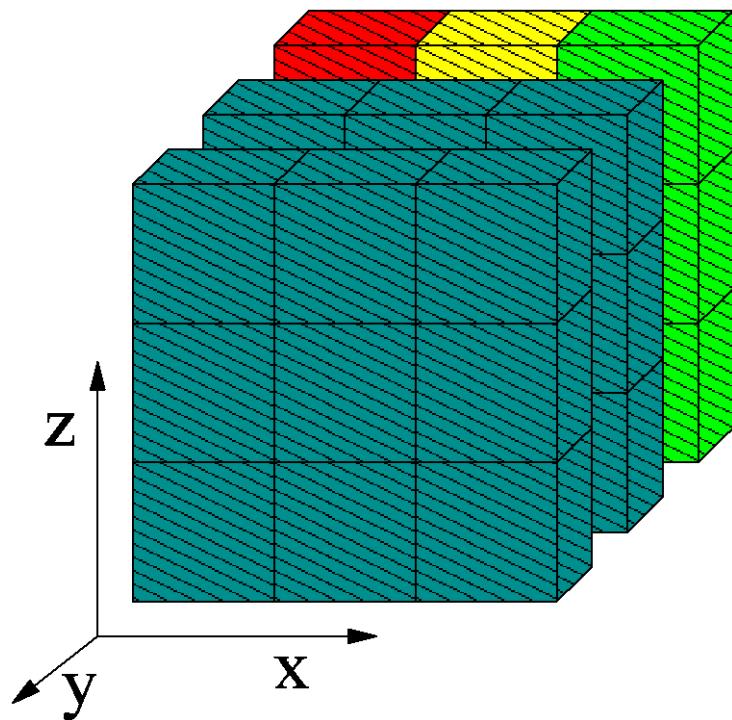
Parallel Fast Fourier Transform

- Start `ialltoall` and transform second plane



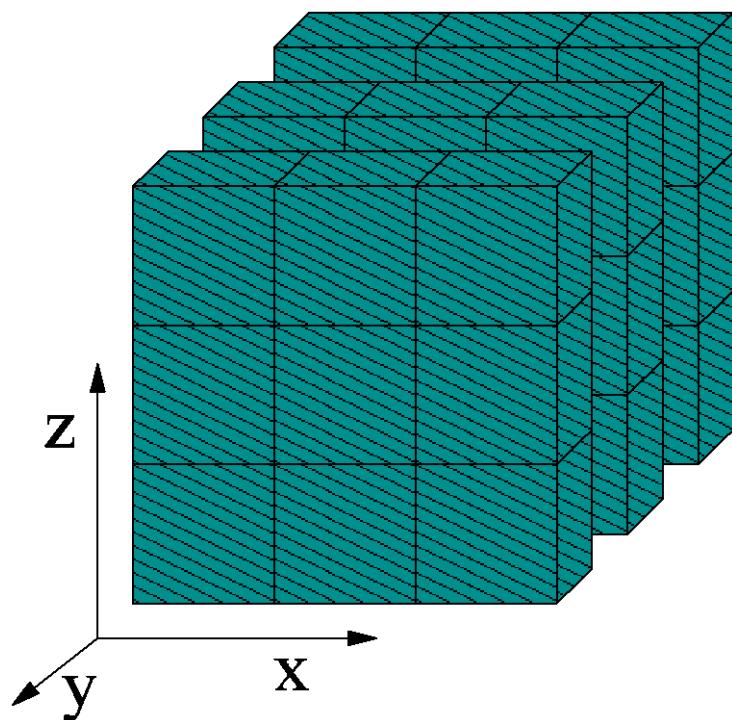
Parallel Fast Fourier Transform

- Start `ialltoall` (second plane) and transform third



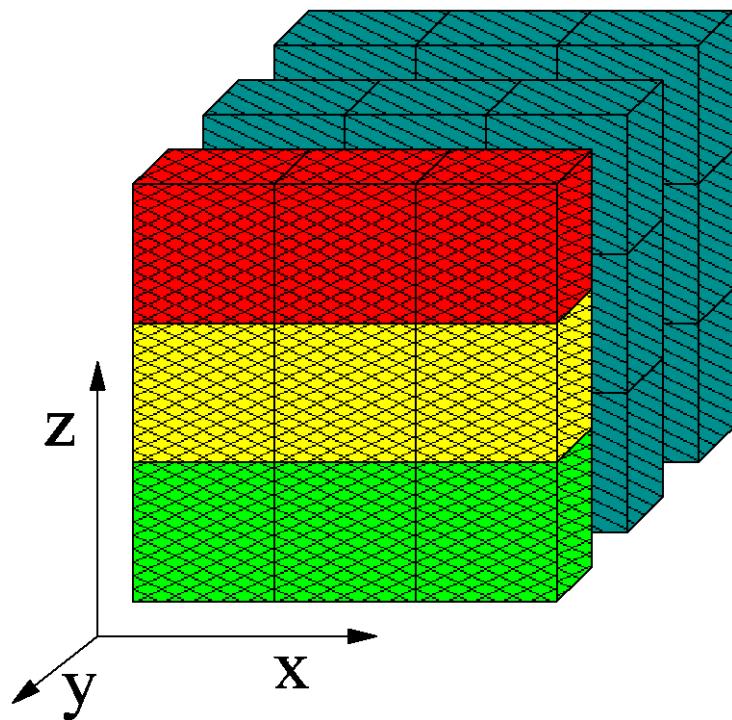
Parallel Fast Fourier Transform

- Start parallel alltoall of third plane and ...



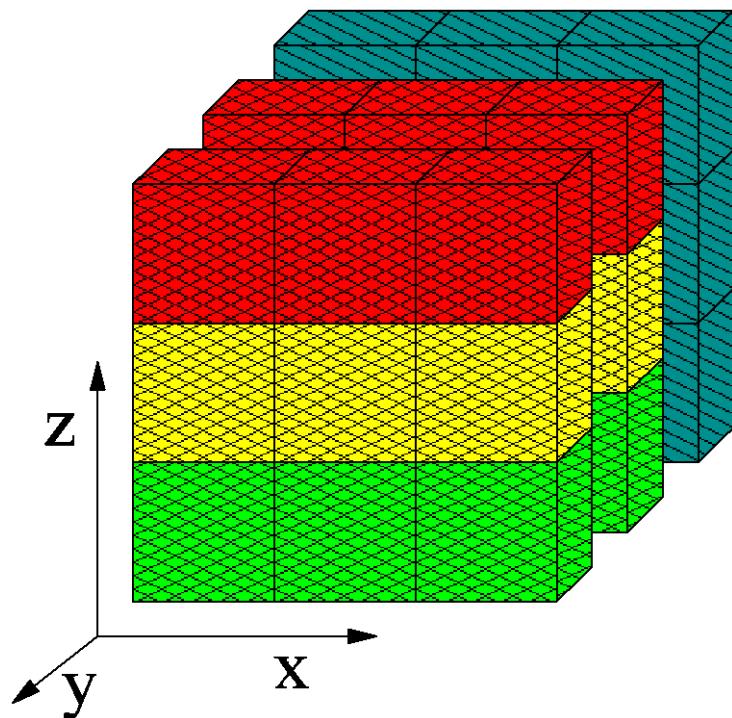
Parallel Fast Fourier Transform

- Finish parallelization of first plane, start x transform



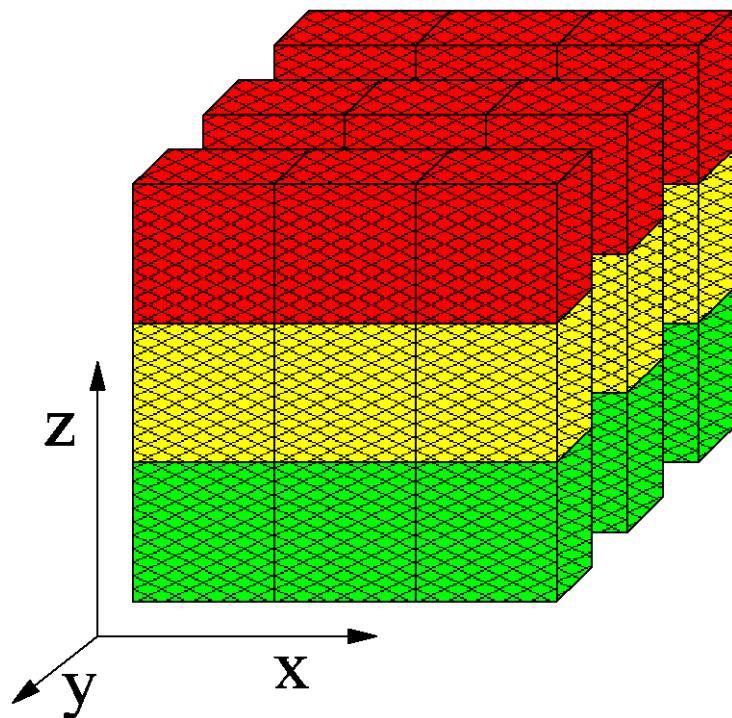
Parallel Fast Fourier Transform

- Finish second `ialltoall`, transform second plane



Parallel Fast Fourier Transform

- Transform last plane → done



FFT Software Pipelining

```
MPI_Request req[nb];
for(int b=0; b<nb; ++b) { // loop over blocks
    for(int x=b*n/p/nb; x<(b+1)n/p/nb; ++x) 1d_fft(/* x-th stencil */);

    // pack b-th block of data for alltoall
    MPI_Ialltoall(&in, n/p*n/p/bs, cplx_t, &out, n/p*n/p, cplx_t, comm, &req[b]);
}
MPI_Waitall(nb, req, MPI_STATUSES_IGNORE);

// modified unpack data from alltoall and transpose
for(int y=0; y<n/p; ++y) 1d_fft(/* y-th stencil */);
// pack data for alltoall
MPI_Alltoall(&in, n/p*n/p, cplx_t, &out, n/p*n/p, cplx_t, comm);
// unpack data from alltoall and transpose
```

Nonblocking And Collective Summary

- **Nonblocking comm does two things:**
 - Overlap and relax synchronization
- **Collective comm does one thing**
 - Specialized pre-optimized routines
 - Performance portability
 - Hopefully transparent performance
- **They can be composed**
 - E.g., software pipelining

Section III - One Sided Communication





One Sided Communication

- **Terminology**
- **Memory exposure**
- **Communication**
- **Accumulation**
 - Ordering, atomics
- **Synchronization**
- **Shared memory windows**
- **Memory models & semantics ☺**



One Sided Communication – The Shock

- **The syntax is weird, really!**
 - It grew – MPI-3.0 is backwards compatible!
- **Think PGAS (with a library interface)**
 - Remote memory access (put, get, accumulates)
- **Forget locks 😊**
 - Win_lock_all is not a lock, opens an epoch
- **Think transactional memory with optional isolation ;-)**
 - That's really what "lock" means (lock/unlock can be like an atomic region, does not necessarily "lock" anything)
- **Decouple transfers from synchronization**
 - Separate transfer and synch functions

One Sided Communication – Terms

- **Origin process:** Process with the source buffer, initiates the operation
- **Target process:** Process with the destination buffer, does not explicitly call communication functions
- **Epoch:** Virtual time where operations are in flight. Data is consistent after new epoch is started.
 - Access epoch: rank acts as origin for RMA calls
 - Exposure epoch: rank acts as target for RMA calls
- **Ordering:** only for accumulate operations: order of messages between two processes (default: in order, can be relaxed)
- **Assert:** assertions about how One Sided functions are used, “fast” optimization hints, cf. Info objects (slower)

One Sided Overview

- **Creation**
 - Expose memory collectively - Win_create
 - Allocate exposed memory – Win_allocate
 - Dynamic memory exposure – Win_create_dynamic
- **Communication**
 - Data movement (put, get, rput, rget)
 - Accumulate (acc, racc, get_acc, rget_acc, fetch&op, cas)
- **Synchronization**
 - Active - Collective (fence); Group (PSCW)
 - Passive - P2P (lock/unlock); One epoch (lock_all)

Memory Exposure

```
MPI_Win_create(void *base, MPI_Aint size, int disp_unit, MPI_Info info,  
MPI_Comm comm, MPI_Win *win)
```

- **Expose consecutive memory (base, size)**
- **Collective call**
- **Info args:**
 - no_locks – user asserts to not lock win
 - accumulate_ordering – comma-separated rar, war, raw, waw
 - accumulate_ops – same_op or same_op_no_op (default) – assert used ops for related accumulates

```
MPI_Win_free(MPI_Win *win)
```

Memory Exposure

```
MPI_Win_allocate(MPI_Aint size, int disp_unit, MPI_Info info,  
MPI_Comm comm, void *baseptr, MPI_Win *win)
```

- **Similar to `win_create` but allocates memory**
 - Should be used whenever possible!
 - May consume significantly less resources
- **Similar info arguments plus**
 - `same_size` – if true, user asserts that size is identical on all calling processes
- **`Win_free` will deallocate memory!**
 - Be careful ☺

Memory Exposure

```
MPI_Win_create_dynamic(MPI_Info info, MPI_Comm comm, MPI_Win  
*win)
```

- **Coll. memory exposure may be cumbersome**
 - Especially for irregular applications
- **Win_create_dynamic creates a window with no memory attached**

```
MPI_Win_attach(MPI_Win win, void *base, MPI_Aint size)  
MPI_Win_detach(MPI_Win win, const void *base)
```

- **Register non-overlapping regions locally**
- **Addresses are communicated for remote access!**
 - MPI_Aint will be big enough on heterogeneous systems

One Sided Communication

```
MPI_Put(const void *origin_addr, int origin_count, MPI_Datatype
origin_datatype, int target_rank, MPI_Aint target_disp, int target_count,
MPI_Datatype target_datatype, MPI_Win win)
```

- **Two similar communication functions:**
 - Put, Get
 - Nonblocking, bulk completion at end of epoch
- **Conflicting accesses are not erroneous**
 - But outcome is undefined!
 - One exception: polling on a single byte in the unified model (for fast synchronization)

One Sided Communication

```
MPI_Rput(..., MPI_Request *request)
```

- **MPI_Rput, MPI_Rget for request-based completion**
 - Also non-blocking but return request
 - Expensive for each operation (vs. bulk completion)
- **Only for local buffer consistency**
 - Get means complete!
 - Put means buffer can be re-used, nothing known about remote completion

One Sided Accumulation

```
MPI_Accumulate(const void *origin_addr, int origin_count,  
MPI_Datatype origin_datatype, int target_rank, MPI_Aint target_disp, int  
target_count, MPI_Datatype target_datatype, MPI_Op op, MPI_Win win)
```

- **Remote accumulations (only predefined ops)**
 - Replace value in target buffer with accumulated
 - MPI_REPLACE to emulate MPI_Put
- **Allows for non-recursive derived datatypes**
 - No overlapping entries at target (datatype)
- **Conflicting accesses are allowed!**
 - Ordering rules apply

One Sided Accumulation

```
MPI_Get_accumulate(const void *origin_addr, int origin_count,  
MPI_Datatype origin_datatype, void *result_addr, int result_count,  
MPI_Datatype result_datatype, int target_rank, MPI_Aint target_disp, int  
target_count, MPI_Datatype target_datatype, MPI_Op op, MPI_Win win)
```

- **MPI's generalized fetch and add**
 - 12 arguments 😊
 - MPI_REPLACE allows for fetch & set
 - New op: MPI_NO_OP to emulate get
- **Accumulates `origin` into the `target` , returns content before accumulation in `result`**
 - Atomically of course

One Sided Accumulation

```
MPI_Fetch_and_op(const void *origin_addr, void *result_addr,  
MPI_Datatype datatype, int target_rank, MPI_Aint target_disp,  
MPI_Op op, MPI_Win win)
```

- **Get_accumulate may be very slow (needs to cover many cases, e.g., large arrays etc.)**
 - Common use-case is single element fetch&op
 - Fetch_and_op offers relevant subset of Get_acc
- **Very similar to Get_accumulate**
 - Same semantics, just more limited interface
 - No request-based version

One Sided Accumulation

```
MPI_Compare_and_swap(const void *origin_addr, const void
*compare_addr, void *result_addr, MPI_Datatype datatype, int target_rank,
MPI_Aint target_disp, MPI_Win win)
```

- **CAS for MPI (no CAS2 but can be emulated)**
- **Single element, binary compare (!)**
- **Compares compare buffer with target and replaces value at target with origin if compare and target are identical. Original target value is returned in result.**



Accumulation Semantics

- **Accumulates allow concurrent access!**
 - Put/Get does not! They're not atomic
- **Emulating atomic put/get**
 - Put = MPI_Accumulate(..., op=MPI_REPLACE, ...)
 - Get = MPI_Get_accumulate(..., op=MPI_NO_OP, ...)
 - Will be slow (thus we left it ugly!)
- **Ordering modes**
 - Default ordering allows “no surprises” (cf. UPC)
 - Can (should) be relaxed with info (accumulate_ordering = raw, waw, rar, war) during window creation



Synchronization Modes

- **Active target mode**
 - Target ranks are calling MPI
 - Either BSP-like collective: MPI_Win_fence
 - Or group-wise (cf. neighborhood collectives): PSCW
- **Passive target mode**
 - Lock/unlock: no traditional lock, more like TM (without rollback)
 - Lockall: locking all processes isn't really a lock ☺

MPI_Win_fence Synchronization

```
MPI_Win_fence(int assert, MPI_Win win)
```

- **Collectively synchronizes all RMA calls on win**
- **All RMA calls started before fence will complete**
 - Ends/start access and/or exposure epochs
- **Does not guarantee barrier semantics (but often synchronizes)**
- **Assert allows optimizations, is usually 0**
 - MPI_MODE_NOPRECEDE if no communication (neither as origin or destination) is outstanding on win

PSCW Synchronization

```
MPI_Win_post(MPI_Group group, int assert, MPI_Win win)
MPI_Win_start(MPI_Group group, int assert, MPI_Win win)
MPI_Win_complete(MPI_Win win)
MPI_Win_wait(MPI_Win win)
```

- **Specification of access/exposure epochs separately:**
 - Post: start exposure epoch to group, nonblocking
 - Start: start access epoch to group, may wait for post
 - Complete: finish prev. access epoch, origin completion only (not target)
 - Wait: will wait for complete, completes at (active) target
- **As asynchronous as possible**

Lock/Unlock Synchronization

```
MPI_Win_lock(int lock_type, int rank, int assert, MPI_Win win)  
MPI_Win_unlock(int rank, MPI_Win win)
```

- **Initiates RMA access epoch to rank**
 - No concept of exposure epoch
- **Unlock closes access epoch**
 - Operations have completed at origin and target
- **Type:**
 - Exclusive: no other process may hold lock to rank
More like a real lock, e.g., for local accesses
 - Shared: other processes may hold lock

Lock_all Synchronization

```
MPI_Win_lock_all(int assert, MPI_Win win)
```

```
MPI_Win_unlock_all(MPI_Win win)
```

- **Starts a shared access epoch from origin to all ranks!**
 - Not collective!
- **Does not really lock anything**
 - Opens a different mode of use, see following slides!

Synchronization Primitives (passive)

```
MPI_Win_flush(int rank, MPI_Win win)
```

```
MPI_Win_flush_all(MPI_Win win)
```

- **Flush/Flush_all**
- **Completes all outstanding operations at the target rank (or all) at origin and target**
 - Only in passive target mode

```
MPI_Win_flush_local(int rank, MPI_Win win)
```

```
MPI_Win_flush_local_all(MPI_Win win)
```

- **Completes all outstanding operations at the target rank (or all) at origin (buffer reuse)**
 - Only in passive target mode

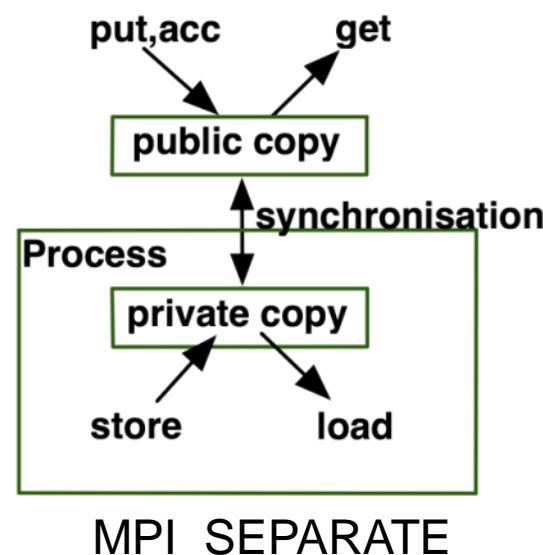
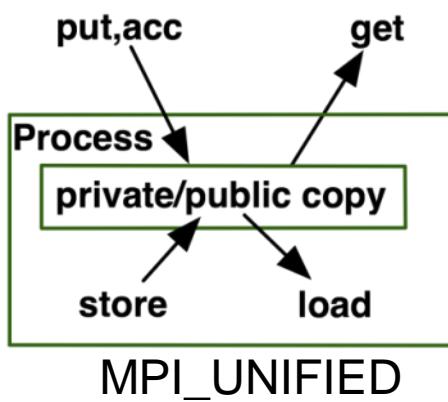
Synchronization Primitives (passive)

```
MPI_Win_sync(MPI_Win win)
```

- **Synchronizes private and public window copies**
 - Same as closing and opening access and exposure epochs on the window
 - Does not complete any operations though!
- **Cf. memory barrier**

Memory Models

- **MPI offers two memory models:**
 - Unified: public and private window are identical
 - Separate: public and private window are separate
- **Type is attached as attribute to window**
 - MPI_WIN_MODEL



Separate Semantics

- Very complex, rules-of-thumb at target:

	Load	Store	Get	Put	Acc
Load	OVL+NOV L	OVL+NOV L	OVL+NOV L	NOVL	NOVL
Store	OVL+NOV L	OVL+NOV L	NOVL	X	X
Get	OVL+NOV L	NOVL	OVL+NOV L	NOVL	NOVL
Put	NOVL	X	NOVL	NOVL	NOVL
Acc	NOVL	X	NOVL	NOVL	OVL+NOV L

- OVL – overlapping
- NOVL - non-overlapping
- X - undefined

Unified Semantics

- Very complex, rules-of-thumb at target:

	Load	Store	Get	Put	Acc
Load	OVL+NOV L	OVL+NOV L	OVL+NOV L	NOVL+BO VL	NOVL+BO VL
Store	OVL+NOV L	OVL+NOV L	NOVL	NOVL	NOVL
Get	OVL+NOV L	NOVL	OVL+NOV L	NOVL	NOVL
Put	NOVL+BO VL	NOVL	NOVL	NOVL	NOVL
Acc	NOVL+BO VL	NOVL	NOVL	NOVL	OVL+NOV L

- OVL – Overlapping operations
- NOVL – Nonoverlapping operations
- BOVL – Overlapping operations at a byte granularity
- X – undefined



Stencil One-Sided Example

- `stencil_mpi_ddt_rma.cpp`

Distributed Hashtable Example

- **hashtable_mpi.cpp**
- **Use first two bytes as hash**
 - Trivial hash function (2^{16} values)
- **Static 2^{16} table size**
 - One direct value
 - Conflicts as linked list
- **Static heap**
 - Linked list indexes into heap
 - Offset as pointer

0	val	next
1	val	next
2	val	next
...		
65535	val	next
<hr/>		
val	next	val
next	val	next
...		
next	val	next



Distributed Hashtable Example

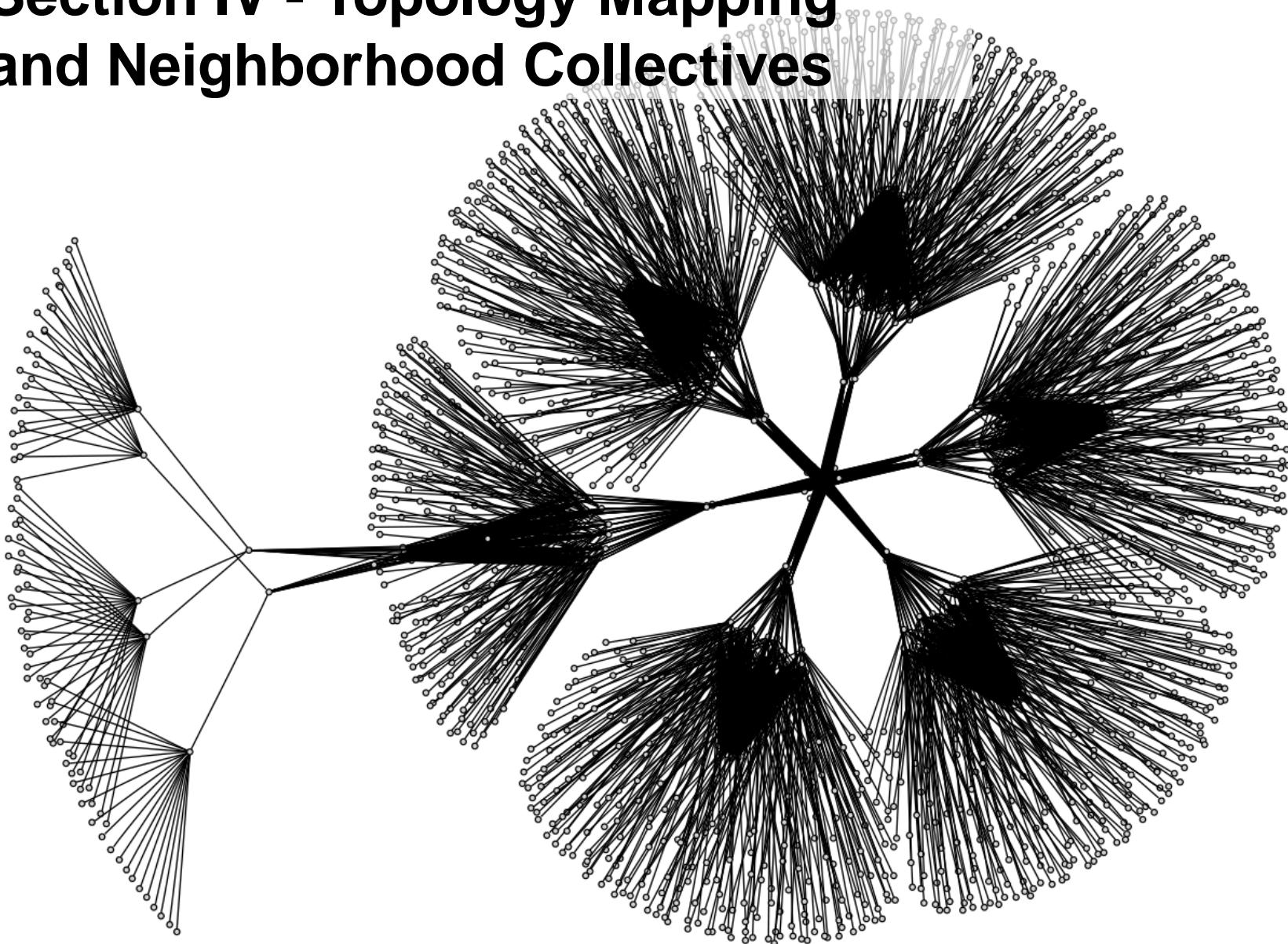
```
int insert(t_hash *hash, int elem) {
    int pos = hashfunc(elem);
    if(hash->table[pos].value == -1) { // direct value in table
        hash->table[pos].value = elem;
    } else { // put on heap
        int newelem=hash->nextfree++; // next free element
        if(hash->table[pos].next == -1) { // first heap element
            // link new elem from table
            hash->table[pos].next = newelem;
        } else { // direct pointer to end of collision list
            int newpos=hash->last[pos];
            hash->table[newpos].next = newelem;
        }
        hash->last[pos]=newelem;
        hash->table[newelem].value = elem; // fill allocated element
    }
}
```

DHT Example – In MPI-3.0

```
int insert(t_hash *hash, int elem) {  
    int pos = hashfunc(elem);  
    if(hash->table[pos].value == -1) { // direct value in table  
        hash->table[pos].value = elem;  
    } else { // put on heap  
        int newelem=hash->nextfree++; // next free element  
        if(hash->table[pos].next == -1) { // first heap element  
            // link new elem from table  
            hash->table[pos].next = newelem;  
        } else { // direct pointer to end of collision list  
            int newpos=hash->last[pos];  
            hash->table[newpos].next = newelem;  
        }  
        hash->last[pos]=newelem;  
        hash->table[newelem].value = elem; // fill allocated element  
    }  
}
```

Which function would
you choose?

Section IV - Topology Mapping and Neighborhood Collectives



Topology Mapping and Neighborhood Collectives

- **Topology mapping basics**
 - Allocation mapping vs. rank reordering
 - Ad-hoc solutions vs. portability
- **MPI topologies**
 - Cartesian
 - Distributed graph
- **Collectives on topologies – neighborhood colls**
 - Use-cases

Topology Mapping Basics

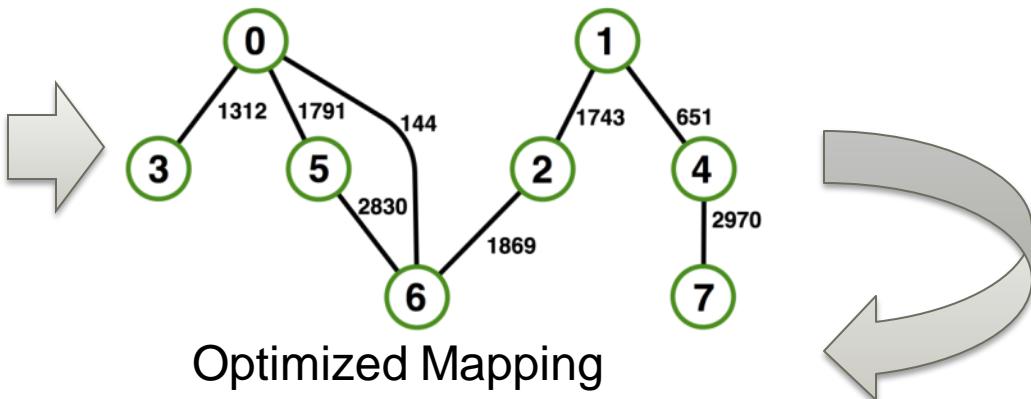
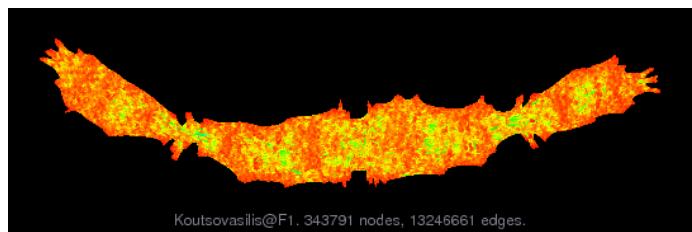
- **First type: Allocation mapping**
 - Up-front specification of communication pattern
 - Batch system picks good set of nodes for given topology
- **Properties:**
 - Not supported by current batch systems
 - Either predefined allocation (BG/P), random allocation, or “global bandwidth maximization”
 - Also problematic to specify communication pattern upfront, not always possible (or static)



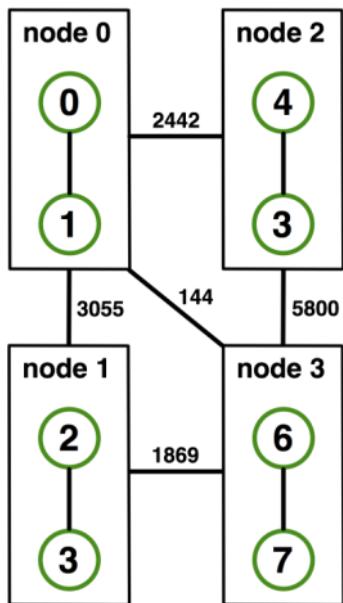
Topology Mapping Basics

- **Rank reordering**
 - Change numbering in a given allocation to reduce congestion or dilation
 - Sometimes automatic (early IBM SP machines)
- **Properties**
 - Always possible, but effect may be limited (e.g., in a bad allocation)
 - Portable way: MPI process topologies
 - Network topology is not exposed*
 - Manual data shuffling after remapping step

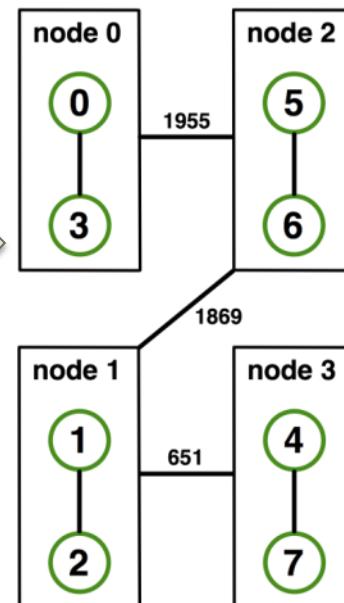
On-Node Reordering



Naïve Mapping



Optimized Mapping



Topomap

MPI Topology Intro

- **Convenience functions (in MPI-1)**
 - Create a graph and query it, nothing else
 - Useful especially for Cartesian topologies
 - Query neighbors in n -dimensional space*
 - Graph topology: each rank specifies full graph ☹
- **Scalable Graph topology (MPI-2.2)**
 - Graph topology: each rank specifies its neighbors **or** arbitrary subset of the graph
- **Neighborhood collectives (MPI-3.0)**
 - Adding communication functions defined on graph topologies (neighborhood of distance one)

MPI_Cart_create

```
MPI_Cart_create(MPI_Comm comm_old, int ndims, const int *dims, const
int *periods, int reorder, MPI_Comm *comm_cart)
```

- **Specify `ndims`-dimensional topology**
 - Optionally periodic in each dimension (Torus)
- **Some processes may return `MPI_COMM_NULL`**
 - Product sum of dims must be $\leq P$
- **Reorder argument allows for topology mapping**
 - Each calling process may have a new rank in the created communicator
 - Data has to be remapped manually



MPI_Cart_create Example

```
int dims[3] = {5,5,5};  
int periods[3] = {1,1,1};  
MPI_Comm topocomm;  
MPI_Cart_create(comm, 3, dims, periods, 0, &topocomm);
```

- **Creates logical 3-d Torus of size 5x5x5**
- **But we're starting MPI processes with a one-dimensional argument (-p X)**
 - User has to determine size of each dimension
 - Often as “square” as possible, MPI can help!

MPI_Dims_create

```
MPI_Dims_create(int nnodes, int ndims, int *dims)
```

- **Create dims array for Cart_create with nnodes and ndims**
 - Dimensions are as close as possible (well, in theory)
- **Non-zero entries in dims will not be changed**
 - nnodes must be multiple of all non-zeroes



MPI_Dims_create Example

```
int p;  
MPI_Comm_size(MPI_COMM_WORLD, &p);  
MPI_Dims_create(p, 3, dims);  
  
int periods[3] = {1,1,1};  
MPI_Comm topocomm;  
MPI_Cart_create(comm, 3, dims, periods, 0, &topocomm);
```

Cartesian Query Functions

- Library support and convenience!
- **MPI_Cartdim_get()**
 - Gets dimensions of a Cartesian communicator
- **MPI_Cart_get()**
 - Gets size of dimensions
- **MPI_Cart_rank()**
 - Translate coordinates to rank
- **MPI_Cart_coords()**
 - Translate rank to coordinates

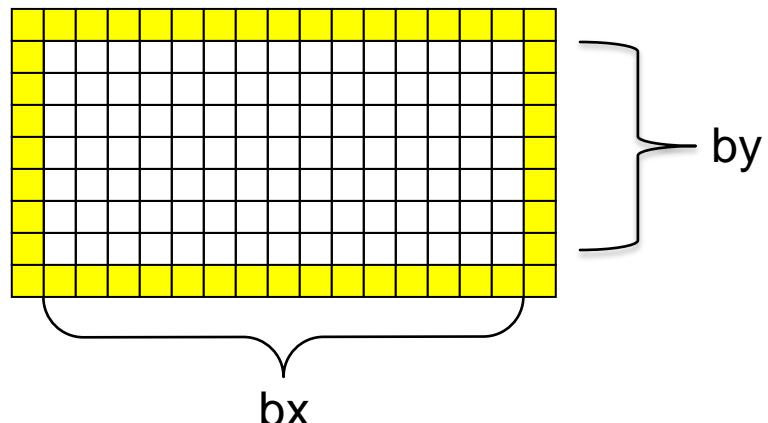
Cartesian Communication Helpers

```
MPI_Cart_shift(MPI_Comm comm, int direction, int disp,  
int *rank_source, int *rank_dest)
```

- **Shift in one dimension**
 - Dimensions are numbered from 0 to ndims-1
 - Displacement indicates neighbor distance (-1, 1, ...)
 - May return MPI_PROC_NULL
- **Very convenient, all you need for nearest neighbor communication**
 - No “over the edge” though

Code Example

- `stencil_mpi_ddt_overlap_carttopo.cpp`
- Adds calculation of neighbors with topology



MPI_Graph_create

```
MPI_Graph_create(MPI_Comm comm_old, int nnodes, const int *index,  
const int *edges, int reorder, MPI_Comm *comm_graph)
```

- **nnodes is the total number of nodes**
- **index i stores the total number of neighbors for the first i nodes (sum)**
 - Acts as offset into edges array
- **edges stores the edge list for all processes**
 - Edge list for process j starts at index[j] in edges
 - Process j has index[j+1]-index[j] edges

MPI_Graph_create

```
MPI_Graph_create(MPI_Comm comm_old, int nnodes, const int *index,  
const int *edges, int reorder, MPI_Comm *comm_graph)
```

- **nnodes is the total number of nodes**
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 - Acts as offset into edges array
- **edges stores the edge list for all processes**
 - Edge list for process j starts at index[j] in edges
 - Process j has index[j+1]-index[j] edges

Distributed graph constructor

- **MPI_Graph_create is discouraged**
 - Not scalable
 - Not deprecated yet but hopefully soon
- **New distributed interface:**
 - Scalable, allows distributed graph specification
Either local neighbors or any edge in the graph
 - Specify edge weights
Meaning undefined but optimization opportunity for vendors!
 - Info arguments
Communicate assertions of semantics to the MPI library
E.g., semantics of edge weights

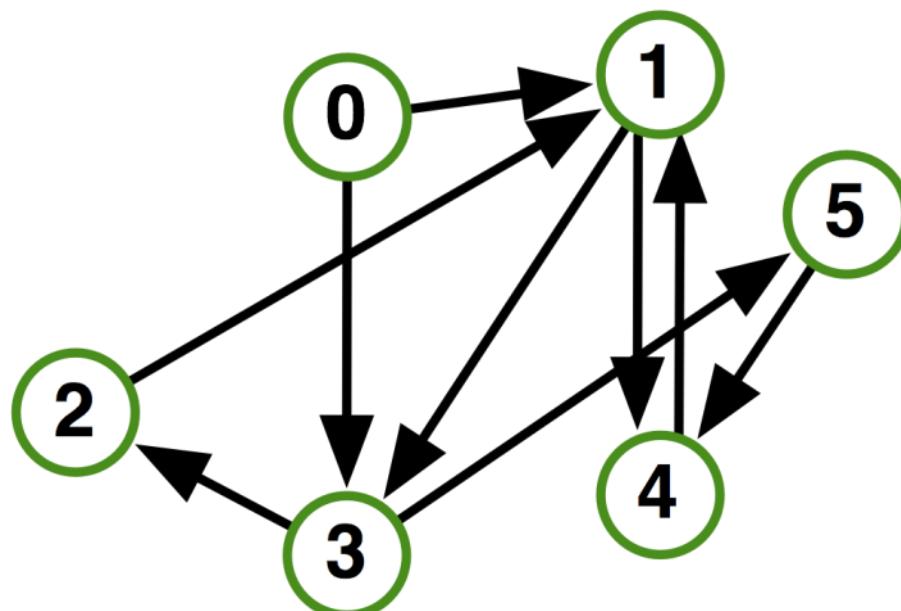
MPI_Dist_graph_create_adjacent

```
MPI_Dist_graph_create_adjacent(MPI_Comm comm_old, int indegree,  
const int sources[], const int sourceweights[], int outdegree, const int  
destinations[], const int destweights[], MPI_Info info,int reorder, MPI_Comm  
*comm_dist_graph)
```

- **indegree, sources, ~weights – source proc. Spec.**
- **outdegree, destinations, ~weights – dest. proc. spec.**
- **info, reorder, comm_dist_graph – as usual**
- **directed graph**
- **Each edge is specified twice, once as out-edge (at the source) and once as in-edge (at the dest)**

MPI_Dist_graph_create_adjacent

- **Process 0:**
 - Indegree: 0
 - Outdegree: 2
 - Dests: {3,1}
- **Process 1:**
 - Indegree: 3
 - Outdegree: 2
 - Sources: {4,0,2}
 - Dests: {3,4}
- ...



MPI_Dist_graph_create

```
MPI_Dist_graph_create(MPI_Comm comm_old, int n,  
                      const int sources[], const int degrees[],  
                      const int destinations[], const int weights[], MPI_Info info,  
                      int reorder, MPI_Comm *comm_dist_graph)
```

n – number of source nodes

- **sources – n source nodes**
- **degrees – number of edges for each source**
- **destinations, weights – dest. processor specification**
- **info, reorder – as usual**
- **More flexible and convenient**
 - Requires global communication
 - Slightly more expensive than adjacent specification

MPI_Dist_graph_create

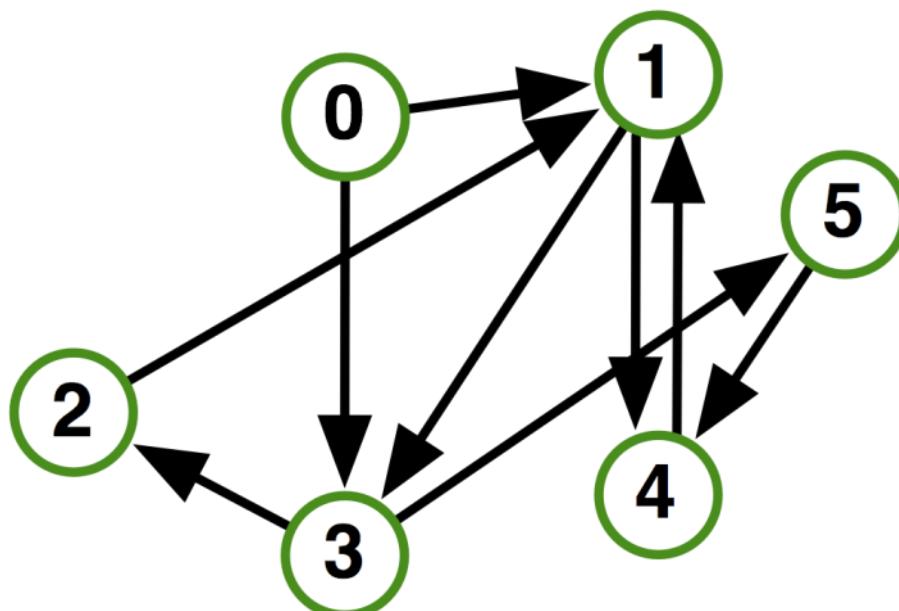
- **Process 0:**

- N: 2
- Sources: {0,1}
- Degrees: {2,1} *
- Dests: {3,1,4}

- **Process 1:**

- N: 2
- Sources: {2,3}
- Degrees: {1,1}
- Dests: {1,2}

- ...



* Note that in this example, process 0 specifies only one of the two outgoing edges of process 1; the second outgoing edge needs to be specified by another process

Distributed Graph Neighbor Queries

```
MPI_Dist_graph_neighbors_count(MPI_Comm comm,  
                               int *indegree,int *outdegree, int *weighted)
```

- **Query the number of neighbors of calling process**
- **Returns indegree and outdegree!**
- **Also info if weighted**

```
MPI_Dist_graph_neighbors(MPI_Comm comm, int maxindegree,  
                         int sources[], int sourceweights[], int maxoutdegree,  
                         int destinations[],int destweights[])
```

- **Query the neighbor list of calling process**
- **Optionally return weights**

Further Graph Queries

```
MPI_Topo_test(MPI_Comm comm, int *status)
```

- **Status is either:**
 - MPI_GRAPH (ugs)
 - MPI_CART
 - MPI_DIST_GRAPH
 - MPI_UNDEFINED (no topology)
- **Enables to write libraries on top of MPI topologies!**

Neighborhood Collectives

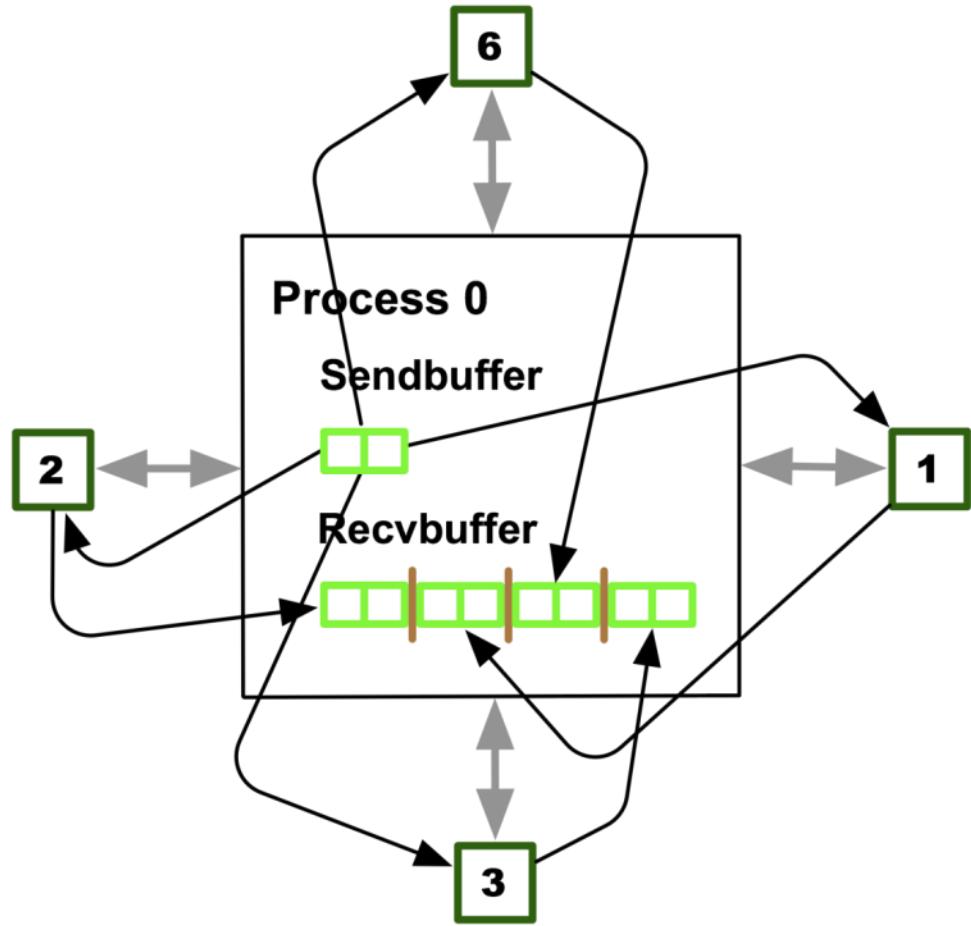
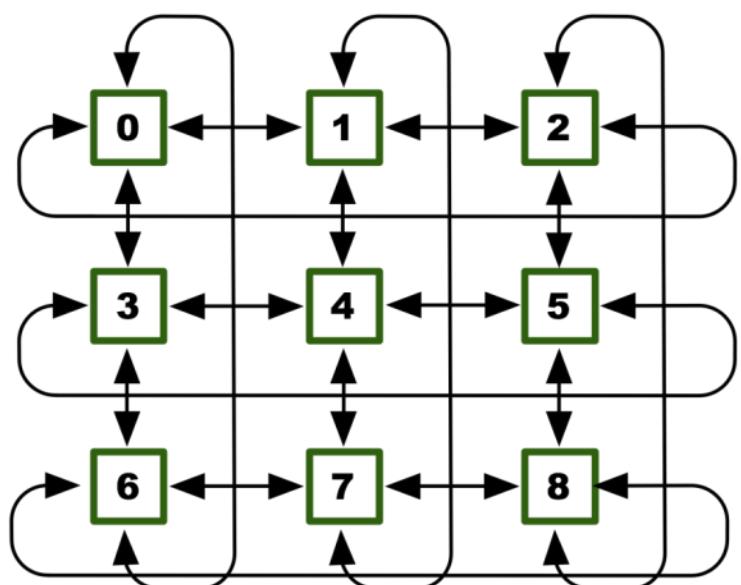
- **Topologies implement no communication!**
 - Just helper functions
- **Collective communications only cover some patterns**
 - E.g., no stencil pattern
- **Several requests for “build your own collective” functionality in MPI**
 - Neighborhood collectives are a simplified version
 - Cf. Datatypes for communication patterns!

Cartesian Neighborhood Collectives

- **Communicate with direct neighbors in Cartesian topology**
 - Corresponds to `cart_shift` with `disp=1`
 - Collective (all processes in comm must call it, including processes without neighbors)
 - Buffers are laid out as neighbor sequence:
*Defined by order of dimensions, first negative, then positive
2*ndims sources and destinations*
Processes at borders (`MPI_PROC_NULL`) leave holes in buffers (will not be updated or communicated)!

Cartesian Neighborhood Collectives

- Buffer ordering example:



Graph Neighborhood Collectives

- **Collective Communication along arbitrary neighborhoods**
 - Order is determined by order of neighbors as returned by (dist_)graph_neighbors.
 - Distributed graph is directed, may have different numbers of send/recv neighbors
 - Can express dense collective operations ☺
 - Any persistent communication pattern!

MPI_Neighbor_allgather

```
MPI_Neighbor_allgather(const void* sendbuf, int sendcount,  
                      MPI_Datatype sendtype, void* recvbuf, int recvcount,  
                      MPI_Datatype recvtype, MPI_Comm comm)
```

- **Sends the same message to all neighbors**
- **Receives indegree distinct messages**
- **Similar to MPI_Gather**
 - The all prefix expresses that each process is a “root” of his neighborhood
- **Vector version for full flexibility**

MPI_Neighbor_alltoall

```
MPI_Neighbor_alltoall(const void* sendbuf, int sendcount,  
                      MPI_Datatype sendtype, void* recvbuf, int recvcount,  
                      MPI_Datatype recvtype, MPI_Comm comm)
```

- **Sends outdegree distinct messages**
- **Received indegree distinct messages**
- **Similar to MPI_Alltoall**
 - Neighborhood specifies full communication relationship
- **Vector and w versions for full flexibility**

Nonblocking Neighborhood Collectives

```
MPI_Ineighbor_allgather(..., MPI_Request *req); MPI_Ineighbor_alltoall(...,  
MPI_Request *req);
```

- **Very similar to nonblocking collectives**
- **Collective invocation**
- **Matching in-order (no tags)**
 - No wild tricks with neighborhoods! In order matching per communicator!



Walkthrough of 2D Stencil Code with Neighborhood Collectives

- `stencil_mpi_carttopo_neighcolls.cpp`

Why is Neighborhood Reduce Missing?

```
MPI_Inneighbor_allreducev(...);
```

- **Was originally proposed (see original paper)**
- **High optimization opportunities**
 - Interesting tradeoffs!
 - Research topic
- **Not standardized due to missing use-cases**
 - My team is working on an implementation
 - Offering the obvious interface

Topology Summary

- **Topology functions allow to specify application communication patterns/topology**
 - Convenience functions (e.g., Cartesian)
 - Storing neighborhood relations (Graph)
- **Enables topology mapping (reorder=1)**
 - Not widely implemented yet
 - May require manual data re-distribution (according to new rank order)
- **MPI does not expose information about the network topology (would be very complex)**

Neighborhood Collectives Summary

- **Neighborhood collectives add communication functions to process topologies**
 - Collective optimization potential!
- **Allgather**
 - One item to all neighbors
- **Alltoall**
 - Personalized item to each neighbor
- **High optimization potential (similar to collective operations)**
 - Interface encourages use of topology mapping!



Section Summary

- **Process topologies enable:**
 - High-abstraction to specify communication pattern
 - Has to be relatively static (temporal locality)
Creation is expensive (collective)
 - Offers basic communication functions
- **Library can optimize:**
 - Communication schedule for neighborhood colls
 - Topology mapping



Section V - Hybrid Programming Primer





Hybrid Programming Primer

- **No complete view, discussions not finished**
 - Considered very important!
- **Modes: shared everything (threaded MPI) vs. shared something (SHM windows)**
 - And everything in between!
- **How to deal with multicore and accelerators?**
 - OpenMP, Cuda, UPC/CAF, OpenACC?
 - Very specific to actual environment, no general statements possible (no standardization)
 - MPI is generally compatible, minor pitfalls

Threads in MPI-2.2

- **Four thread levels in MPI-2.2**
 - Single – only one thread exists
 - Funneled – only master thread calls MPI
 - Serialized – no concurrent calls to MPI
 - Multiple – concurrent calls to MPI
- **But how do I call this function – oh well 😊**
- **To add more confusion: MPI processes may be OS threads!**

Matched Probe

- **MPI_Probe to receive messages of unknown size**
 - MPI_Probe(..., status)
 - size = get_count(status)*size_of(datatype)
 - buffer = malloc(size)
 - MPI_Recv(buffer, ...)
- **MPI_Probe peek in matching queue**
 - Does not change it → stateful object



Matched Probe

- **Two threads, A and B perform probe, malloc, receive sequence**
 - $A_P \rightarrow A_M \rightarrow A_R \rightarrow B_P \rightarrow B_M \rightarrow B_R$
- **Possible ordering**
 - $A_P \rightarrow B_P \rightarrow B_M \rightarrow B_R \rightarrow A_M \rightarrow A_R$
 - Wrong matching!
 - Thread A's message was “stolen” by B
 - Access to queue needs mutual exclusion ☹

MPI_Mprobe to the Rescue

- **Avoid state in the library**
 - Return handle, remove message from queue

```
MPI_Message msg; MPI_Status status;  
/* Match a message */  
MPI_Mprobe(MPI_ANY_SOURCE, MPI_ANY_TAG, MPI_COMM_WORLD,  
           &msg, &status);  
/* Allocate memory to receive the message */  
int count; MPI_get_count(&status, MPI_BYTE, &count);  
char* buffer = malloc(count);  
/* Receive this message. */  
MPI_Mrecv(buffer, count, MPI_BYTE, &msg, MPI_STATUS_IGNORE);
```



Shared Memory Use-Cases

- **Reduce memory footprint**
 - E.g., share static lookup tables
 - Avoid re-computing (e.g., NWChem)
- **More structured programming than MPI+X**
 - Share what needs to be shared!
 - Not everything open to races like OpenMP
- **Speedups (very tricky!)**
 - Reduce communication (matching, copy) overheads
 - False sharing is an issue!

Shared Memory Windows

```
MPI_Win_allocate_shared(MPI_Aint size, MPI_Info info, MPI_Comm  
comm, void *baseptr, MPI_Win *win)
```

- **Allocates shared memory segment in win**
 - Collective, fully RMA capable
 - All processes in comm must be in shared memory!
- **Returns pointer to start of own part**
- **Two allocation modes:**
 - Contiguous (default): process i's memory starts where process i-1's memory ends
 - Non Contiguous (info key alloc_shared_noncontig)
possible ccNUMA optimizations

Shared Memory Comm Creation

```
MPI_Comm_split_type(MPI_Comm comm, int split_type, int key, MPI_Info info, MPI_Comm *newcomm)
```

- **Returns disjoint comms based on split type**
 - Collective
- **Types (only one so far):**
 - MPI_COMM_TYPE_SHARED – split into largest subcommunicators with shared memory access
- **Key mandates process ordering**
 - Cf. comm_split

SHM Windows Address Query

```
MPI_Win_shared_query(MPI_Win win, int rank, MPI_Aint *size, void  
*baseptr)
```

- **User can compute remote addresses in contig case but needs all sizes**
 - Not possible in noncontig case!
 - Processes **cannot** communicate base address, may be different at different processes!
- **Base address query function!**
 - MPI_PROC_NULL as rank returns lowest offset

New Communicator Creation Functions

- **Noncollective communicator creation**
 - Allows to create communicators without involving all processes in the parent communicator
 - Very useful for some applications (dynamic sub-grouping) or fault tolerance (dead processes)
- **Nonblocking communicator duplication**
 - MPI_Comm_idup(..., req) – like it sounds
 - Similar semantics to nonblocking collectives
 - Enables the implementation of nonblocking libraries



Section VI – Derived Datatypes



Derived Datatypes

Abelson & Sussman: “*Programs must be written for people to read, and only incidentally for machines to execute.*”

- **Derived Datatypes exist since MPI-1.0**
 - Some extensions in MPI-2.x and MPI-3.0
- **Why do I talk about this really old feature?**
 - It is a very advanced and elegant declarative concept
 - It enables many elegant optimizations (zero copy)
 - It falsely has a bad reputation (which it earned in early days)

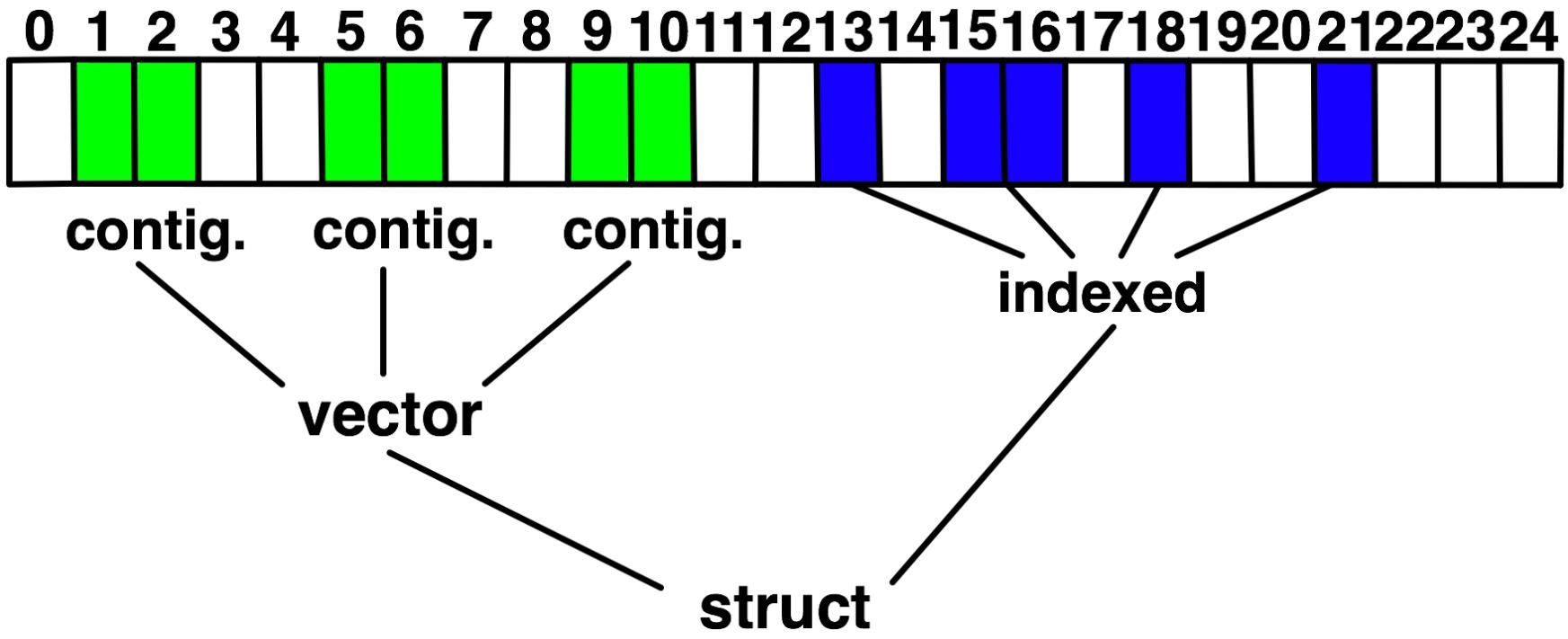
Quick MPI Datatype Introduction

- **Datatypes allow to (de)serialize arbitrary data layouts into a message stream**
 - Networks provide serial channels
 - Same for block devices and I/O
- **Several constructors allow arbitrary layouts**
 - Recursive specification possible
 - *Declarative* specification of data-layout
 - “what” and not “how”, leaves optimization to implementation (many unexplored possibilities!)
 - Choosing the right constructors is not always simple

Derived Datatype Terminology

- **Type Size**
 - Size of DDT signature (total occupied bytes)
 - Important for matching (signatures must match)
- **Lower Bound**
 - Where does the DDT start
 - Allows to specify “holes” at the beginning
- **Extent**
 - Complete size of the DDT
 - Allows to interleave DDT, relatively “dangerous”

Derived Datatype Example



- Explain Lower Bound, Size, Extent

What is Zero Copy?

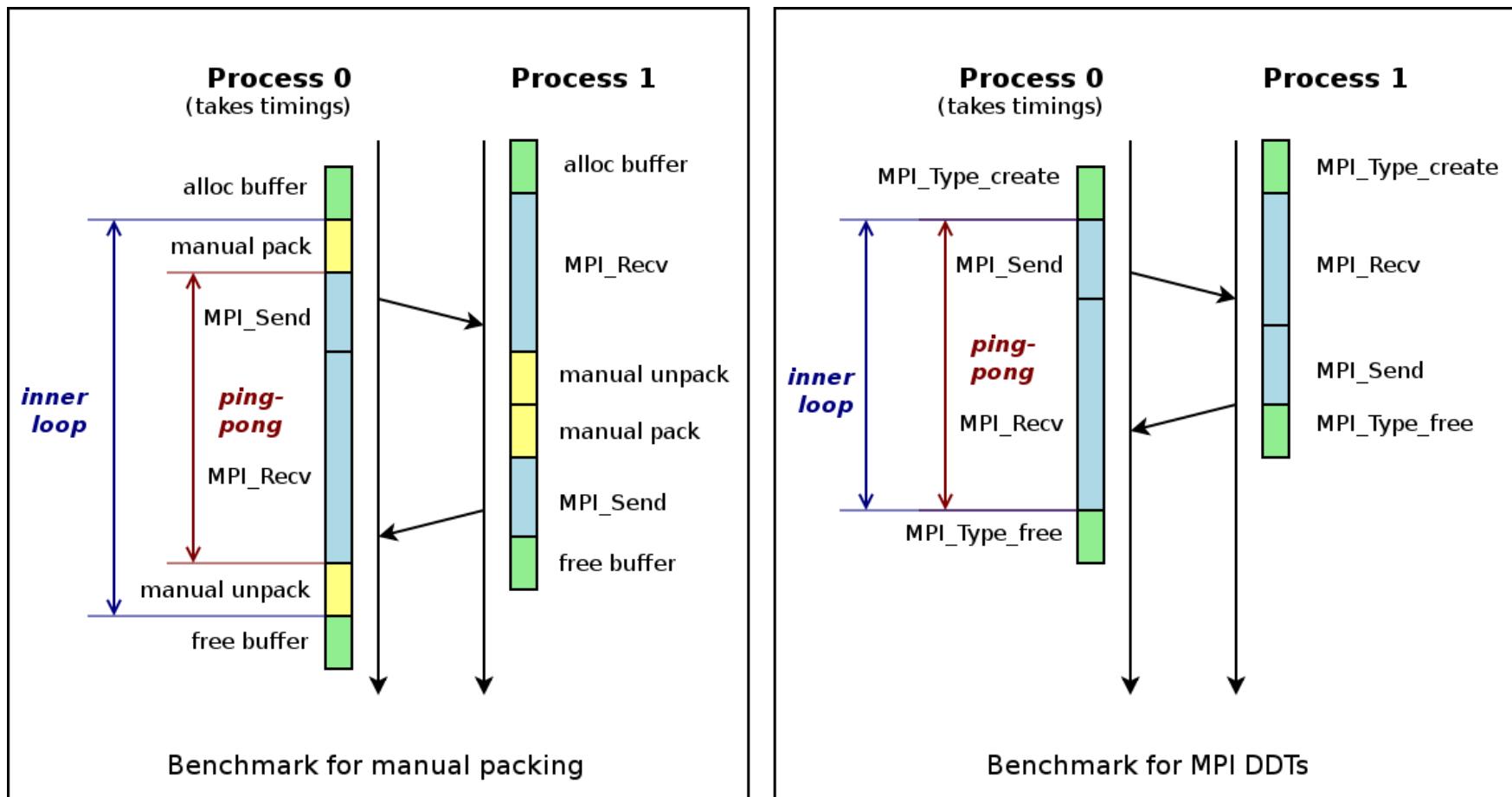
- **Somewhat weak terminology**
 - MPI forces “remote” copy , assumed baseline
- **But:**
 - MPI **implementations** copy internally
 - E.g., networking stack (TCP), packing DDTs*
 - Zero-copy is possible (RDMA, I/O Vectors, SHMEM)*
 - MPI **applications** copy too often
 - E.g., manual pack, unpack or data rearrangement*
 - DDT can do both!*



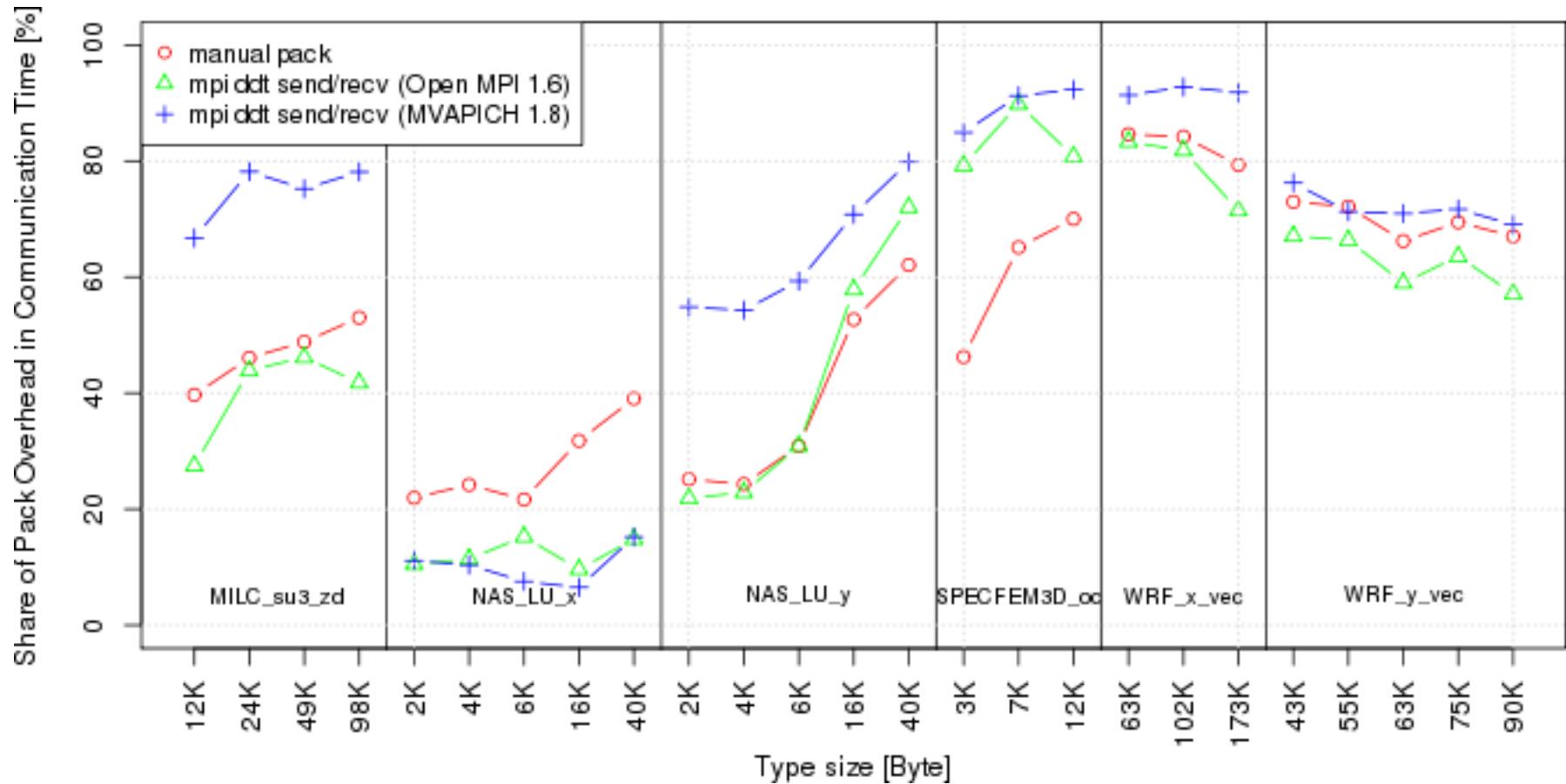
Purpose of this Section

- **Demonstrate utility of DDT in practice**
 - Early implementations were bad → folklore
 - Some are still bad → chicken egg problem
- **Show creative use of DDTs**
 - Encode local transpose for FFT
 - Enable you to create more!
- **Gather input on realistic benchmark cases**
 - Guide optimization of DDT implementations

A new Way of Benchmarking

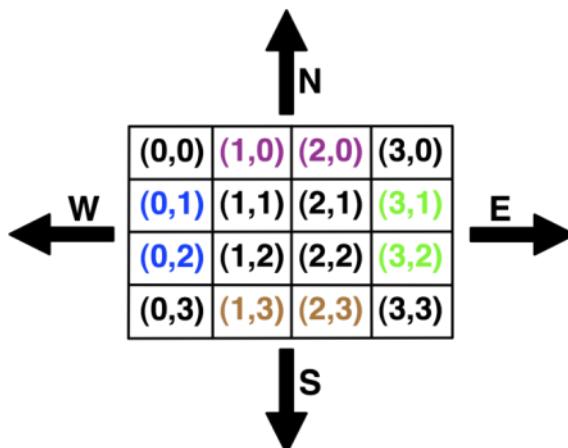


Motivation

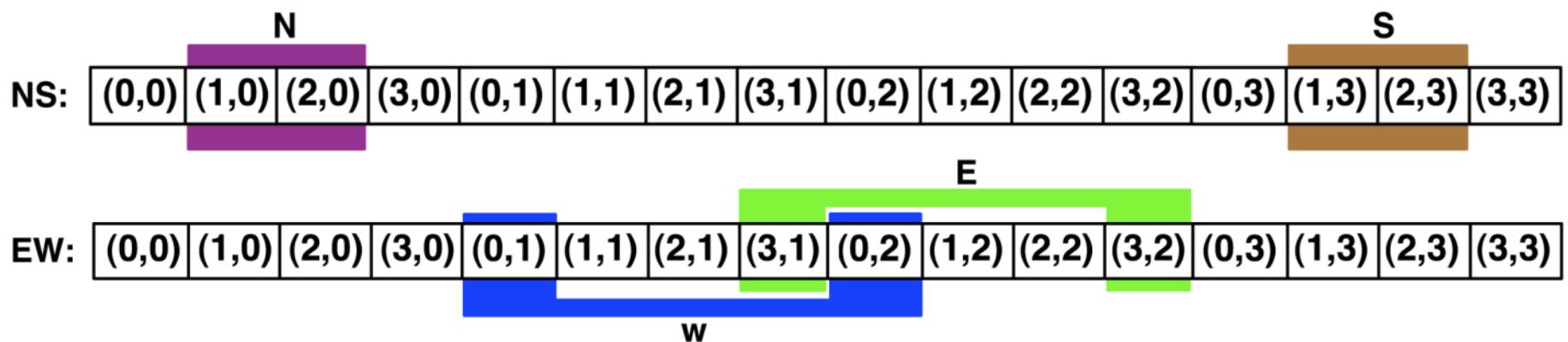


Datatypes for the Stencil

- stencil_mpi_ddt.cpp



(0,0)	(1,0)	(2,0)	(3,0)	(0,1)	(1,1)	(2,1)	(3,1)	(0,2)	(1,2)	(2,2)	(3,2)	(0,3)	(1,3)	(2,3)	(3,3)
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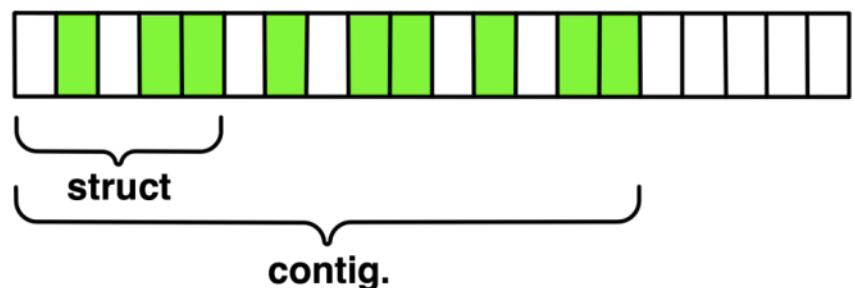
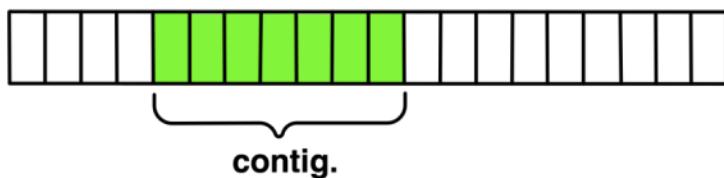
MPI's Intrinsic Datatypes

- **Why intrinsic types?**
 - Heterogeneity, nice to send a Boolean from C to Fortran
 - Conversion rules are complex, not discussed here
 - Length matches to language types
 - Avoid sizeof(int) mess*
- **Users should generally use intrinsic types as basic types for communication and type construction!**
 - MPI_BYTE should be avoided at all cost
- **MPI-2.2 adds some missing C types**
 - E.g., unsigned long long

MPI_Type_contiguous

```
MPI_Type_contiguous(int count, MPI_Datatype  
oldtype, MPI_Datatype *newtype)
```

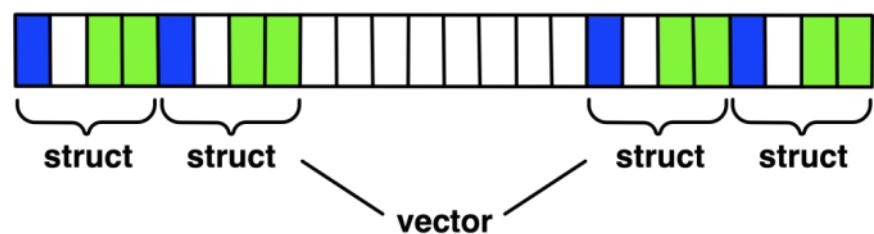
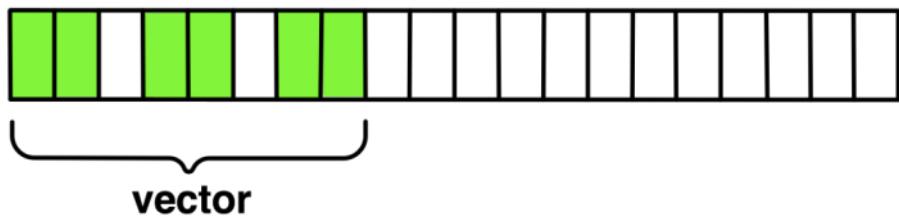
- **Contiguous array of oldtype**
- **Should not be used as last type (can be replaced by count)**



MPI_Type_vector

```
MPI_Type_vector(int count, int blocklength, int stride, MPI_Datatype
oldtype, MPI_Datatype *newtype)
```

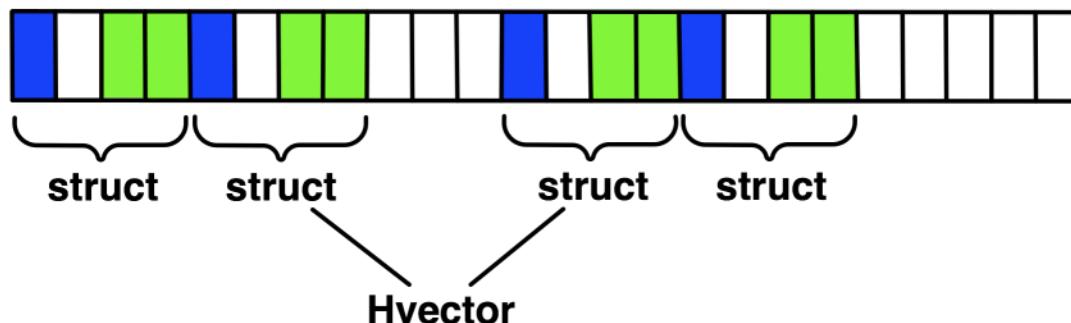
- **Specify strided blocks of data of oldtype**
- **Very useful for Cartesian arrays**



MPI_Type_create_hvector

```
MPI_Type_create_hvector(int count, int blocklength, MPI_Aint stride, MPI_Datatype oldtype, MPI_Datatype *newtype)
```

- **Create non-unit strided vectors**
- **Useful for composition, e.g., vector of structs**



MPI_Type_indexed

```
MPI_Type_indexed(int count, int *array_of_blocklengths,  
int *array_of_displacements, MPI_Datatype oldtype,  
MPI_Datatype *newtype)
```

- **Pulling irregular subsets of data from a single array (cf. vector collectives)**
 - dynamic codes with index lists, expensive though!

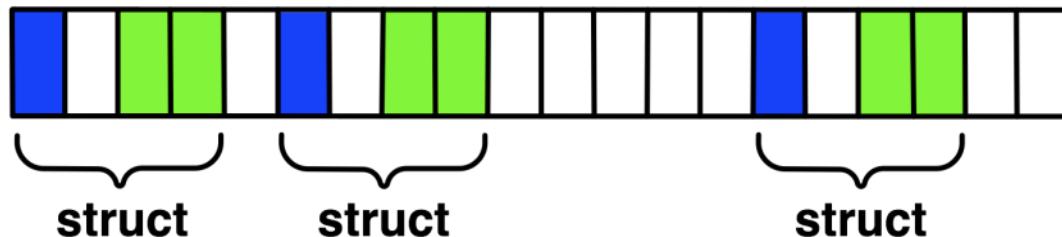


- blen={1,1,2,1,2,1}
- displs={0,3,5,9,13,17}

MPI_Type_create_hindexed

```
MPI_Type_create_hindexed(int count, int *arr_of_blocklengths, MPI_Aint  
*arr_of_displacements, MPI_Datatype oldtype, MPI_Datatype *newtype)
```

- **Indexed with non-unit displacements, e.g., pulling types out of different arrays**



MPI_Type_create_indexed_block

```
MPI_Type_create_indexed_block(int count, int blocklength,  
int *array_of_displacements, MPI_Datatype oldtype,  
MPI_Datatype *newtype)
```

- Like Create_indexed but **blocklength is the same**

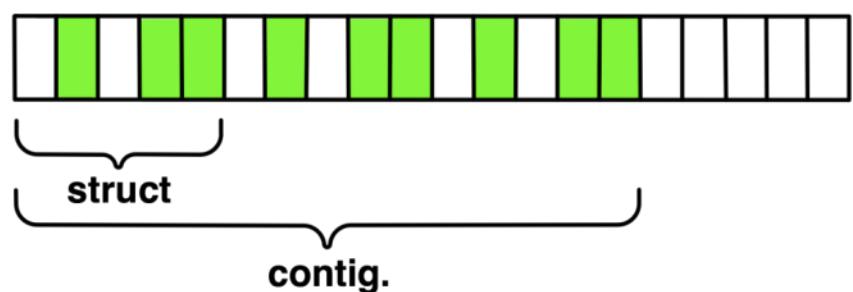
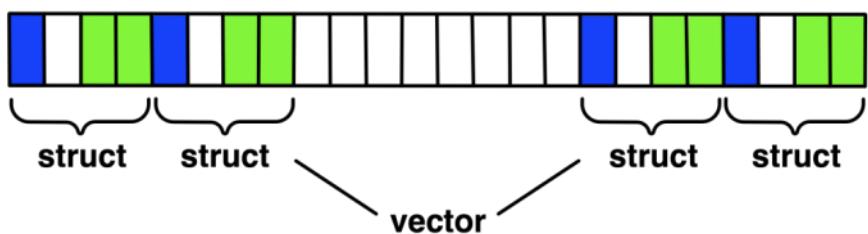


- blen=2
- displs={0,5,9,13,18}

MPI_Type_create_struct

```
MPI_Type_create_struct(int count, int array_of_blocklengths[],  
MPI_Aint array_of_displacements[], MPI_Datatype array_of_types[],  
MPI_Datatype *newtype)
```

- **Most general constructor (cf. Alltoallw), allows different types and arbitrary arrays**



MPI_Type_create_subarray

```
MPI_Type_create_subarray(int ndims, int array_of_sizes[],  
int array_of_subsizes[], int array_of_starts[], int order,  
MPI_Datatype oldtype, MPI_Datatype *newtype)
```

- **Specify subarray of n-dimensional array (sizes) by start (starts) and size (subsize)**

(0,0)	(1,0)	(2,0)	(3,0)
(0,1)	(1,1)	(2,1)	(3,1)
(0,2)	(1,2)	(2,2)	(3,2)
(0,3)	(1,3)	(2,3)	(3,3)

MPI_Type_create_darray

```
MPI_Type_create_darray(int size, int rank, int ndims,  
int array_of_gsizes[], int array_of_distrib[], int  
array_of_dargs[], int array_of_psizes[], int order,  
MPI_Datatype oldtype, MPI_Datatype *newtype)
```

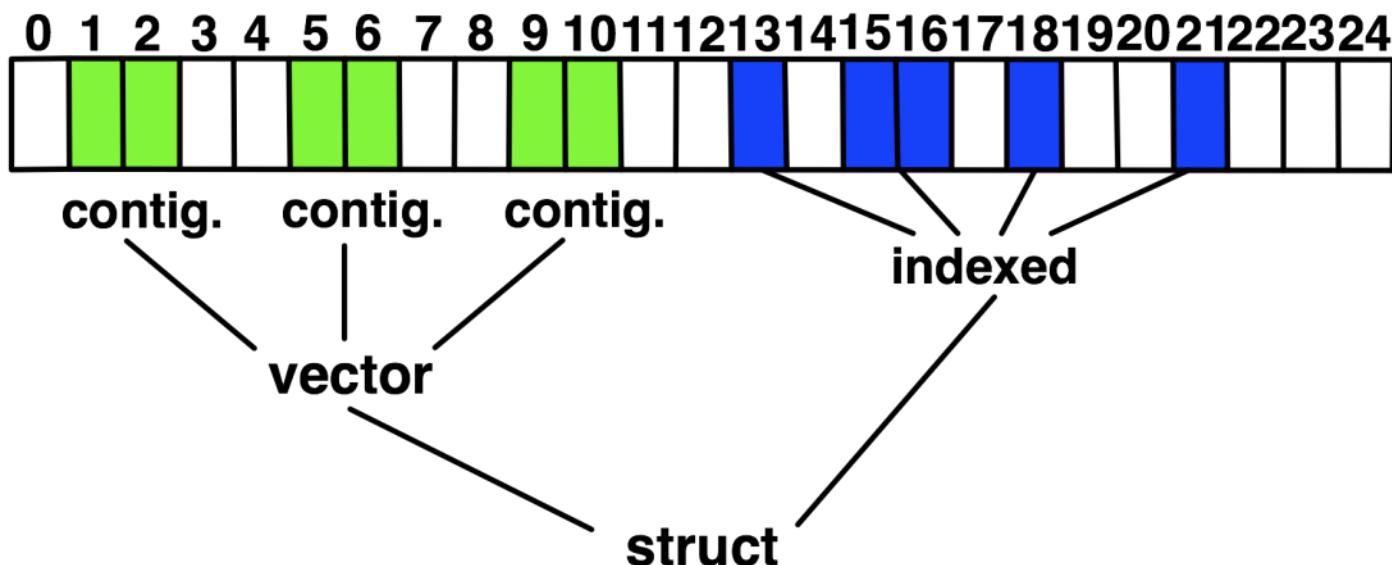
- **Create distributed array, supports block, cyclic and no distribution for each dimension**
 - Very useful for I/O

MPI_BOTTOM and MPI_Get_address

- **MPI_BOTTOM is the absolute zero address**
 - Portability (e.g., may be non-zero in globally shared memory)
- **MPI_Get_address**
 - Returns address relative to MPI_BOTTOM
 - Portability (do not use "&" operator in C!)
- **Very important to**
 - build struct datatypes
 - If data spans multiple arrays

Recap: Size, Extent, and Bounds

- **MPI_Type_size** returns size of datatype
- **MPI_Type_get_extent** returns lower bound and extent



Commit, Free, and Dup

- **Types must be committed before use**
 - Only the ones that are used!
 - MPI_Type_commit may perform heavy optimizations (and will hopefully)
- **MPI_Type_free**
 - Free MPI resources of datatypes
 - Does not affect types built from it
- **MPI_Type_dup**
 - Duplicated a type
 - Library abstraction (composability)

Other DDT Functions

- **Pack/Unpack**
 - Mainly for compatibility to legacy libraries
 - You should not be doing this yourself
- **Get_envelope/contents**
 - Only for expert library developers
 - Libraries like MPITypes¹ make this easier
- **MPI_Create_resized**
 - Change extent and size (dangerous but useful)

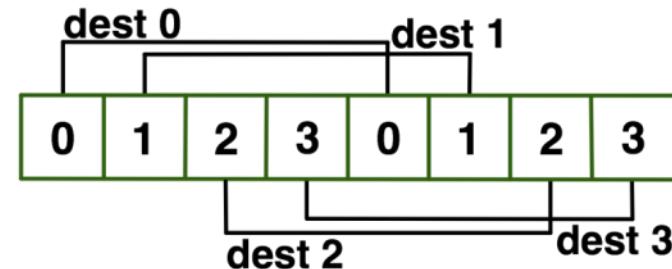
Datatype Selection Tree

- **Simple and effective performance model:**
 - More parameters == slower
- **contig < vector < index_block < index < struct**
- **Some (most) MPIs are inconsistent**
 - But this rule is portable
- **Advice to users:**
 - Try datatype “compression” bottom-up

Datatypes and Collectives

- Alltoall, Scatter, Gather and friends expect data in rank order
 - 1st rank: offset 0
 - 2nd rank: offset <extent>
 - ith rank: offset: i*<extent>
- Makes tricks necessary if types are overlapping → use extent (create_resized)

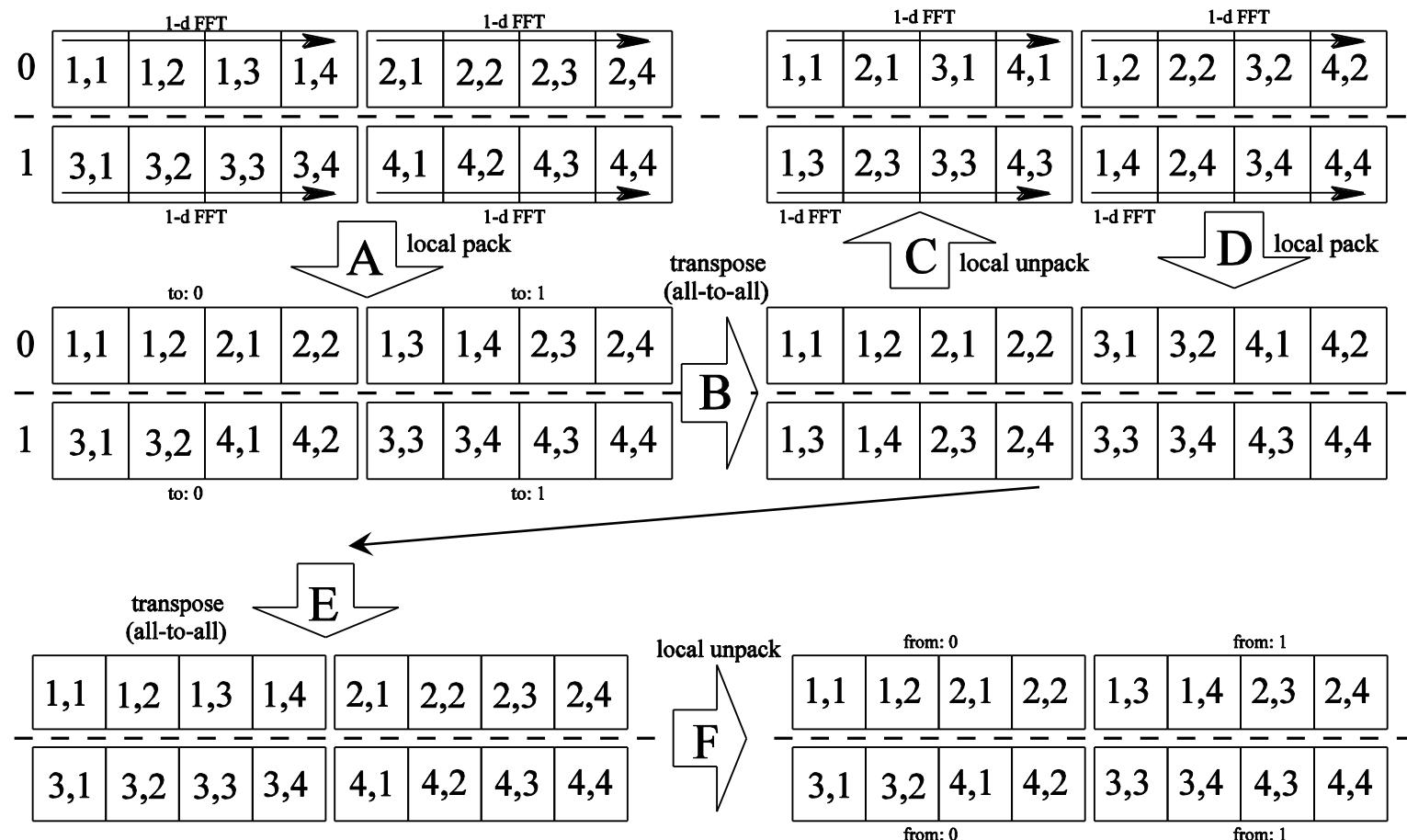
0	0	1	1	2	2	3	3
---	---	---	---	---	---	---	---



A Complex Example - FFT

1. perform N_x/P 1-d FFTs in y -dimension (N_y elements each)
2. pack the array into a sendbuffer for the all-to-all (A)
3. perform global all-to-all (B)
4. unpack the array to be contiguous in x -dimension (each process has now N_y/P x -pencils) (C)
5. perform N_y/P 1-d FFTs in x -dimension (N_x elements each)
6. pack the array into a sendbuffer for the all-to-all (D)
7. perform global all-to-all (E)
8. unpack the array to its original layout (F)

A Complex Example - FFT



2d-FFT Optimization Possibilities

1. Use DDT for pack/unpack (obvious)

- Eliminate 4 of 8 steps
Introduce local transpose

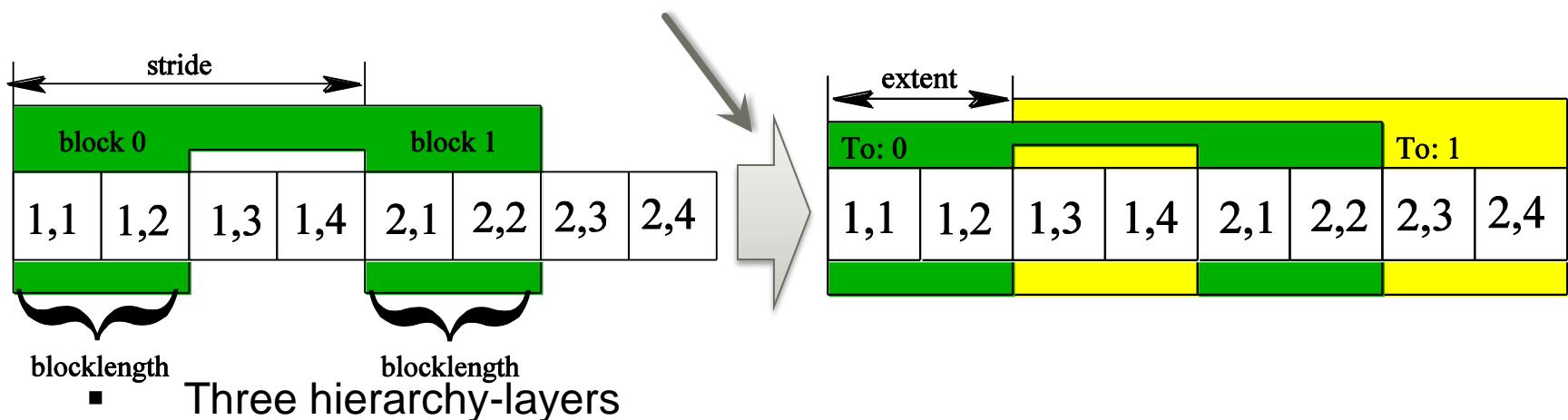
2. Use DDT for local transpose

- After unpack
- Non-intuitive way of using DDTs
Eliminate local transpose

The Send Datatype

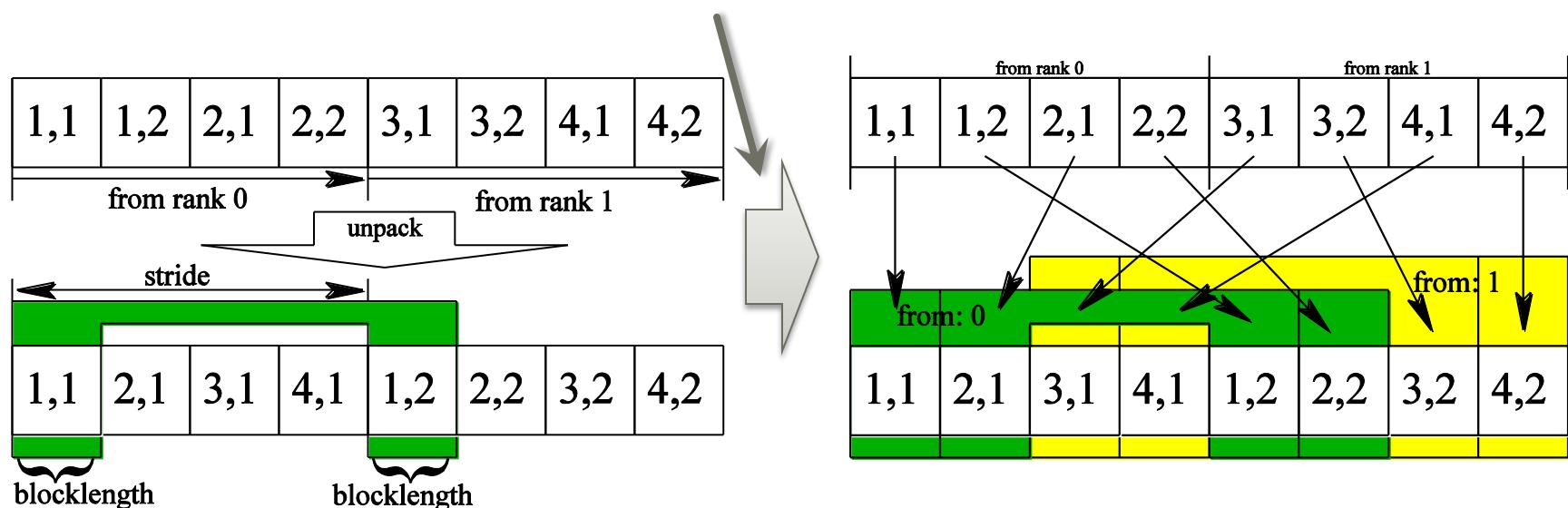
1. Type_struct for complex numbers
2. Type_contiguous for blocks
3. Type_vector for stride

*Need to **change extent** to allow overlap (create_resized)*



The Receive Datatype

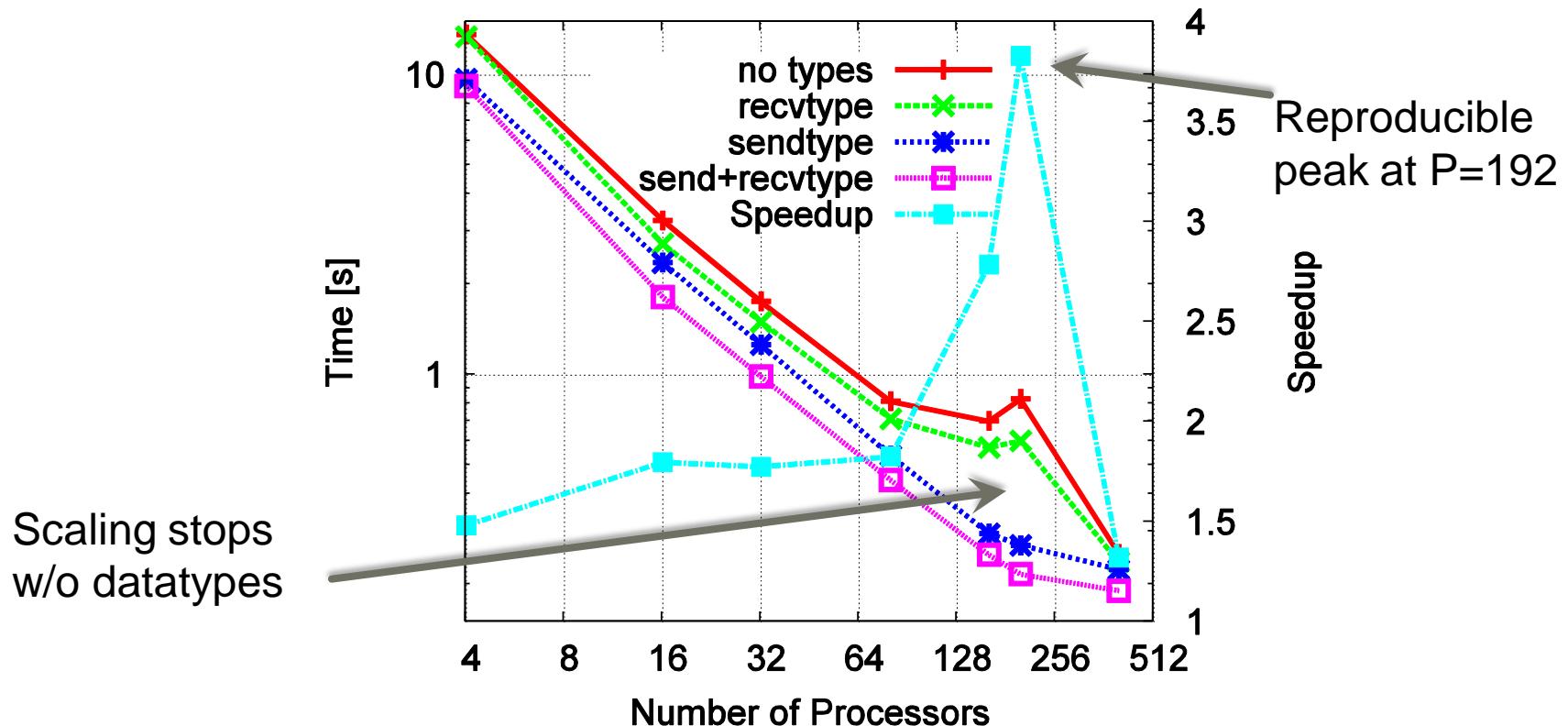
- Type_struct (complex)
- Type_vector (no contiguous, local transpose)
Needs to change extent (create_resized)



Experimental Evaluation

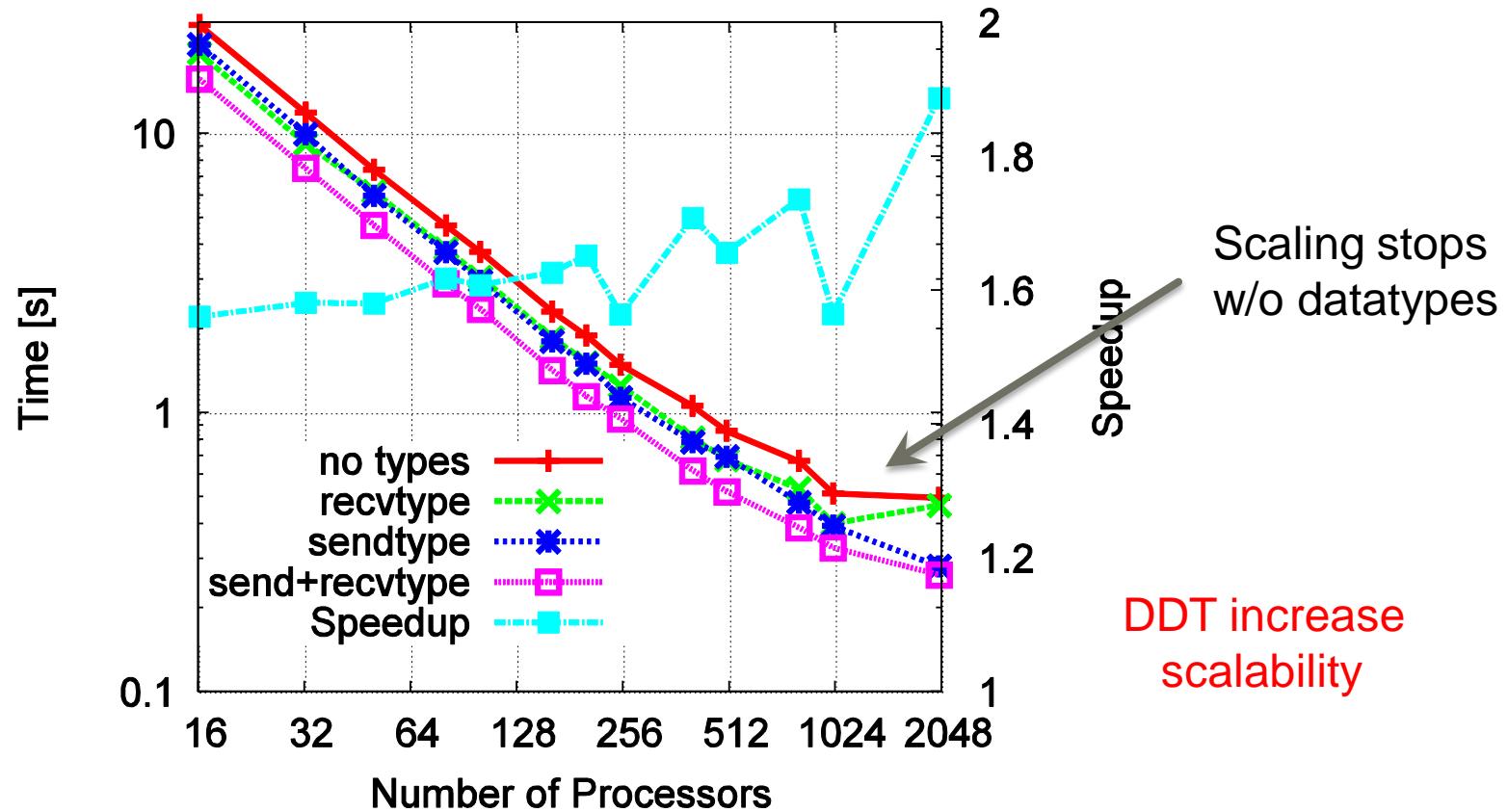
- **Odin @ IU**
 - 128 compute nodes, 2x2 Opteron 1354 2.1 GHz
 - SDR InfiniBand (OFED 1.3.1).
 - Open MPI 1.4.1 (openib BTL), g++ 4.1.2
- **Jaguar @ ORNL**
 - 150152 compute nodes, 2.1 GHz Opteron
 - Torus network (SeaStar).
 - CNL 2.1, Cray Message Passing Toolkit 3
- **All compiled with “-O3 –mtune=opteron”**

Strong Scaling - Odin (8000^2)



- 4 runs, report smallest time, <4% deviation

Strong Scaling – Jaguar ($20k^2$)



Datatype Conclusions

- **MPI Datatypes allow zero-copy**
 - Up to a factor of 3.8 or 18% speedup!
 - Requires some implementation effort
- **Declarative nature makes debugging hard**
 - Simple tricks like index numbers help!
- **Some MPI DDT implementations are slow**
 - Some nearly surreal (IBM) ☺
 - Complain to your vendor if performance is not consistent!



Tutorial Conclusion

- **Thanks for attending!**
 - Ask any questions you have – anytime
 - The book contains all advanced topics (*not datatypes, which are included in the “Using MPI” book*)
 - I hope you enjoyed



The SPEEDUP Society:
The Swiss Forum for
High-Performance Computing

- All materials (slides, code examples) at:
http://htor.inf.ethz.ch/teaching/mpi_tutorials/speedup15/

