

# Manual for MQDT post process

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## 1 Theory background

Following the manual for MQDT solver, the discrete levels can be obtained by searching the cross point of

$$F(x_i, U_{i\alpha}, \mu_\alpha) = \det[U_{i\alpha} \sin \pi(x_i + \mu_\alpha)] = 0, \quad (1a)$$

$$v_y(v_x) = \frac{q}{[I_y - I_x + q^2/v_x^2]^{1/2}} \quad (1b)$$

where,

$$x_i = \begin{cases} v_i & \text{for } i \in \text{closed channels,} \\ -\tau & \text{for } i \in \text{open channels,} \end{cases}$$

For the autoionization region, the center of resonances are at local maximum of the energy derivative of phase shift,

$$\frac{d\tau}{dE} = \frac{v_x^3}{2q^2} \frac{d\tau}{dv_x}. \quad (2)$$

the local maximum can be found by searching for root of the derivative of expression (??).

$$\frac{d}{dv_x} \left( \frac{v_x^3}{2q^2} \frac{d\tau}{dv_x} \right) \Big|_{v_{res}} = 0. \quad (3)$$

## 2 Program structure

```
1 constants      # global constants and parameters
2 type_def       # user defined complex data structure for easier data communication
3 numerical      # frequently used numerical algorithms
4 file_cmdl_io   # file i/o and commandline parser
5 stdio          # frequently used string operations and block output.
6 envset         # setting up machine-dependent systematic parameters (EPS, PI, Nan ...)
7 interpolate    # a set of interpolation functions, employed in root finding algorithms
8
9 darray         # dynamical array for easier data storage
10 search_root    # search levels and resonances and create readable and easy to plot
                  # files, if provide energy levels, generate a comparison file.
```

### 3 Numerical algorithms

#### (i) discrete level finding

- First roughly search for cross  
Scan x axis for  $v_x^f$  where the sign of the difference of  $G(v_x) = F(x_i, U_{i\alpha}, \mu_\alpha) - v_y(v_x)$  flips.
- Finer search  
Choose a suitable vicinity of  $v_x^f$ , find the root of the difference function  $G(v_x)$ . Where the actual value of  $F(x_i, U_{i\alpha}, \mu_\alpha)$  and  $v_y(v_x)$  are calculated on-the-fly ( $F(x_i, U_{i\alpha}, \mu_\alpha)$  is obtained by spline-interpolation).

#### (ii) resonance finding

- First rough search  
The Local peaks are  $\frac{d}{dE}\tau(x_{i-1}) \leq \frac{d}{dE}\tau(x_i) \leq \frac{d}{dE}\tau(x_{i+1})$ . There might be small fluctuations of the derivative due to numerical operations (especially two-point interpolation is used). So we need to filter out some of them.
- Noise filter  
noise filter threshold is automatically determined based on the widest resonance width  $\max\{\delta_\alpha\}$ . The widths are estimated by the imaginary part of projected  $K_{cc}$  matrix. ( J. M. Lecomte, J. Phys. B: At. Mol. Phys. 20 (1987) 3645-3662.)  
Or you can manually specify one by adding option `[-filter XXX]` to the command line.
- Finer search  
Employ bisect searching algorithm to search for the derivative of  $\frac{d}{dE}\tau$  function in a suitable vicinity. The function and it's derivative are Spline-interpolated on-the-fly.
- Eigenchannel sort

### 4 Program input

Required input files:

```
1 miuang.out      # S matrix prepared by smooth-toolkits
2 [dalfa.in]      # dipole matrix moment, if provided, automatically calculate oscillator
  strength (density)
3 mqdt.in         # MQDT solver control file
4 Anorm.out       # Normalized A-coefficients
5 Ara.out         # Unnormalized A-coefficients
6 Dn.out          # Normalization factor N for A-coefficients.
7 [NormDos.out]   # Density of States if discrete calculation
8 [elev.exp]      # experimental levels(resonances) to compare. (If provided, the program
  will generate comparison files automatically.)
```

The major control file `mqdt.in` is the **same** as that for mqt solver. You can add **blank lines and # to comment**. You can also use `{ }` to wrap the data block, you can put them in one line or break the wrapper into multiple lines.

Table 1: Options in *mqdt.in*

Z	target charge
nchan	number of physical channels ( <b>optional</b> , program will determine it from S-matrix input file)
nop	number of open channels ( <b>optional</b> , program will determine it from the energy region and the choice of x-axis threshold $IP_x$ .)
nip	number of ionization potentials (IP), ( <b>optional</b> , program will determine from the IP array block $IP = \{ \dots \}$ ).
IP_unit	<b>optional</b> unit for IP, cm-1, ryd, au, a.u., ev, Hartree are accepted (case-insensitive). It will be treated as <b>cm-1</b> if not specified
IP	IP array block $IP = \{ \dots \}$ , the {} wrapper accept , and space to divide strings.
IP_seq	indices to assign IP to each physical channel.
IPy	threshold to present effective quantum defect/phase-shift. channels associated to threshold $IP \leq IP_y$ will be treated <b>opened</b> . You <b>must</b> specify it for <b>bound-state</b> calculation. It will be determined internally in <b>continuum</b> calculation.
IPx	threshold to present energy. channels associated to threshold $IP \geq IP_x$ will be treated <b>closed</b> . You <b>must</b> specify it for <b>bound-state</b> calculation. It will be determined internally in <b>continuum</b> calculation.
xrange	<b>optional</b> $v_x$ with respect to $IP_x$ . You must either specify xrange or E_continuum.
E_continuum	<b>optional</b> continuum electron energy with respect to the first IP $I_1$ . You can specify unit for the energy range string e.g. $E\_continuum = \{0.0:0.20\_ryd\}$ . Accepted energy units are IP, cm-1, ryd, au, a.u., ev, Hartree (case-insensitive). The unit is <b>cm-1</b> by default.
x_grid_type	Options: mu-eigen / mu-proj / uniform
y_grid_type	Options: adaptive / uniform
nx_flat	number of grid per X-grid segment for the flat region.
nx_spike	number of grid per X-grid segment for the sharp peaks.
ny_init_guess	number of grid per Y-grid segment in the initiative guess algorithm
ny_adapt	number of grid per Y-grid segment in the adaptive algorithm
x_fine	<b>optional</b> . Manually refine the X-grid. You can specify several sections by {} wrapper. For example $x\_fine = \{2.19:2.21\%1000, 2.29:2.31\%1000\}$ , where %1000 means you want to use 1000 times finer grid for this section.
y_fine	<b>optional</b> . Manually refine the Y-grid. Usage the same as $x\_fine$ .
eqnsolv_method	How to solve the MQDT equation. Options are: hyb, bisect, newton.
relax	<b>optional</b> . Relaxation coefficient to prevent oscillation. Default 1.0.
dmu	<b>optional</b> . Constant correction to $\mu_\alpha$ . Specify it with {} wrapper: $dmu = \{0.0 \ 0.0 \ 0.0 \ 0.0 \ 0.0 \ 0.0\}$
au_peak_search_method	<b>For postmqdt</b> . Either search the steepest change of each collisional-channel phase shift or the total phase shift. Options: tot / chan.
k_mat_cofact	the column index for cofactor when solving the A-coefficients from the secular equations (asymptotic boundary condition). $\forall i \leq nchan$ will work, this is only left for debugging purpose.
twoJ	<b>Not used currently</b> . $2j$ of the system, used to calculate Lande-g factor.