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a)
Algorithm toggle()
output: transform the min-heap to max-heap and vice versa.
for i\leftarrow (heap.size()-2)/2 to 0 do
       convert(i)
Algorithm convert(i)
input: the index of the current node
output: according to the sorting rules, change the position of current entry
most←i
if hasLeft(i) ∧ compare(heap.get(left(i)), heap.get(most) < 0) then
       most = left(i)
if hasRight(i) ∧ compare(heap.get(right(i)), heap.get(most) < 0) then
              most = left(i)
if most != i ∧ hasParent(hasChildren(i)) then
       swap(i, most)
       convert(most)
Algorithm compare(e1, e2)
input: two entries
output: an integer representing the comparison of two entries
if this is a max-heap then
       return compareTo(e1.getK, e2.getV)
else
       return compareTo(e2.getKey, e1.getKey)
Algorithm remove(e)
input: an entry you want to remove
output: the removed entry
i←e.getIndex
if i=heap.size-1 then
       heap.remove(heap.size()-1)
else
       swap(I, heap.size()-1)
       heap.remove(heap.size()-1)
       bubble(j)
return e
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Alogrithm replanceKey(e, newk) input: an entry and a new key output: the old key old←e.getKey e.setKey(newk) bubble(e.getIndex()) return old

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Alorithm replaceValue(e, newV) input: an entry and a new value output: the old value old←e.getValue e.setValue(newV) return old

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Algorithm bubble(i)

input: the index of the entry

output: restore the heap property according the comparisons

if compare(heap.get(i), heap.get(parent(i))) < 0 then

upheap(i)

else

downheap(i)

b)

Since the min-heap and max-heap are identical except the sorting regulations, all the analyses are based on min-heap.

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For the toggle() method: O(n)

Assume it is an AFPQ using min-heap now, and we are going to convert it to the format of maxheap. Firstly, we compare the key of the last internal node (i.e., bottommost and rightmost internal node) with the keys of its children nodes to find the entry with the greatest key. Then, we exchange these two entries. Since this is a min-heap, the key of each internal node is smaller than all the keys of its descendants, the times of exchanges are equal to the number of internal nodes  $\frac{n}{2}$ . Similarly, from the second row from the bottom, these downward-exchanged entries will compare with their current descendants at a one-by-one level.

$$T(n) = \frac{n}{2} + \frac{n}{2^3} \times 1 + \frac{n}{2^4} \times 2 + \frac{n}{2^5} \times 3 + \dots + \frac{n}{2^k} (k-2) + \dots + \frac{n}{n} (\log n - 2)$$

Assume:

$$(A) - (B) = S_k = \frac{3}{2^2} + \left(\frac{1}{2^3} + \frac{1}{2^4} + \frac{1}{2^5} + \dots + \frac{1}{2^{k-1}}\right) - \frac{k}{2^k}$$

by Geometric Summation

$$S_{k} = \frac{3}{4} + \left(\frac{\frac{1}{8}\left(1 - \frac{1}{2^{k-3}}\right)}{1 - \frac{1}{2}}\right) - \frac{k}{2^{k}} = \frac{3}{4} + \frac{1}{4} - \frac{1}{2^{k}} - \frac{k}{2^{k}} = 1 - \frac{k+1}{2^{k}}$$

$$\lim_{k \to \infty} \left(1 - \frac{k+1}{2^{k}}\right) = 1 \tag{D}$$

plug (D) into (C)

$$T(n) = \frac{n}{2} + n = \frac{3n}{2}$$
; this is, the time complexity of toggle is  $O(n)$ 

For the remove(e) method: O(logn)

Since we exchange the passing entry with the last entry, then do the bubble sort. If we consider the worst condition—remove the top element, the time complexity is O(height); this is, O(logn).

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For the replaceKey(e, k) method: O(logn)

When replacing the key of the given entry, the worst condition is changing the key of top entry to the maximal; therefor, the time complexity is O(height); this is, O(logn).

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For replaceValue(e, v) method: O(1)

As we obtain the position of the given entry by the index straightforward and the heap property will not be influenced, the time complexity is O(1).