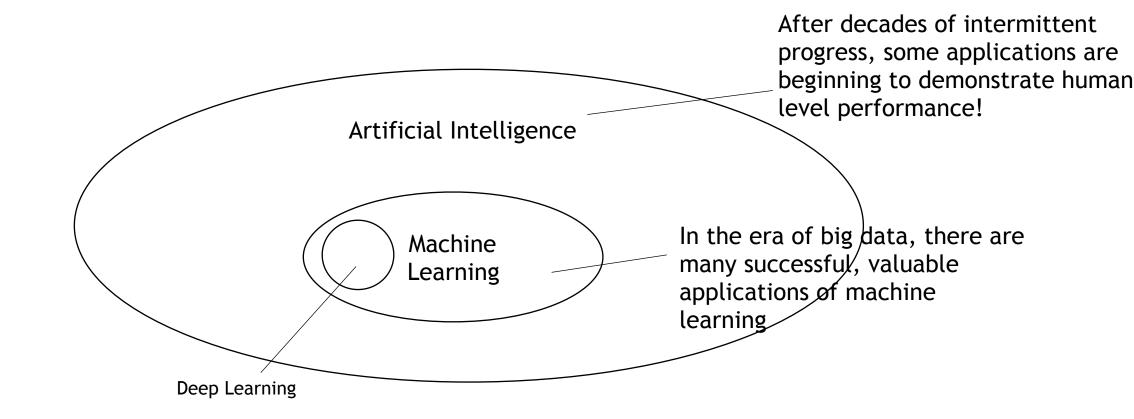
# An Introduction to Human-Aided Deep Learning

James K Baker, Bhiksha Raj, Rita Singh

#### Opportunities in Machine Learning

Great advances are being made in machine learning



### Machine Learning is All Around You, Every Day

- Machine Learning (From A. Ng, Coursera course)
  - Grew out of Al
  - New capabilities for computers
  - You probably use machine learning many times a day without even realizing it (Google search, product recommendations, advertising)

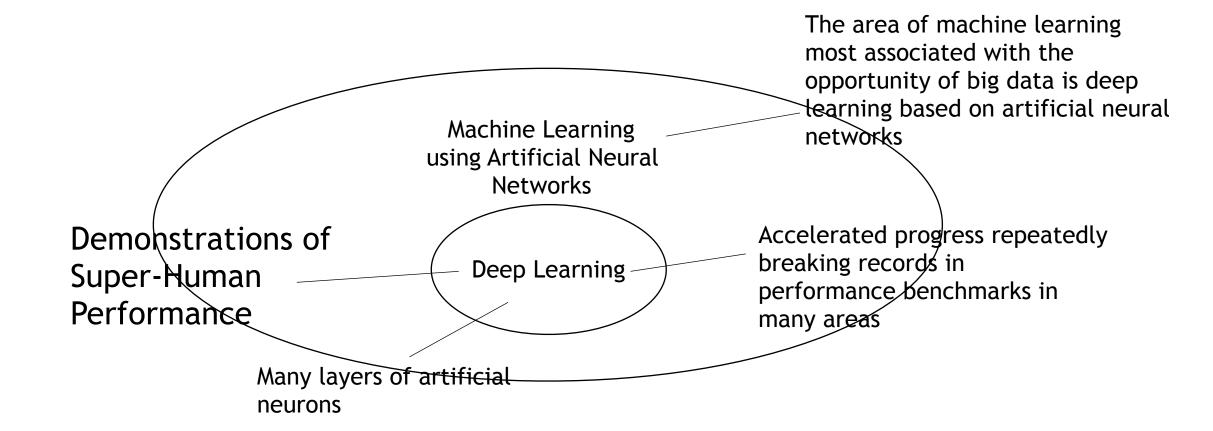
#### Examples:

- Database mining
  - Large data from growth of automation/web
  - E.g.: Web click data, medical records, biology, engineering
- Applications we can't program by hand
  - E.g.: Autonomous vehicles, handwriting rec, speech rec, NLP, computer vision
- Self-customizing programs
  - E.g.: Netflix, Amazon product recommendations
- Understanding human learning
  - E.g.: Modeling the human brain, real Al
- Deep learning approaching or exceeding human performance

### Opportunities in Machine Learning with Artificial Neural Networks

Great advances are being made in deep learning

Artificial neural networks are networks of simple representations of neurons.



#### Some of the Recent Successes of Deep Learning

- Super-human performance reading street signs
- Beating a top human player in the game of Go
- Beating previous performance by training an image recognition network with over 100 layers
- Human parity in recognizing conversational speech
- End-to-end training of state-of-the-art question answering in natural language
- Substantial improvement in naturalness of speech synthesis
- Approaching the accuracy of average human translators on some datasets

### It is important to do it right!

#### The New York Times

CMU in the news

New Research Center to Explore Ethics of Artificial Intelligence

By JOHN MARKOFF NOV. 1, 2016



The Chimp robot, built by a Carnegic Mellon team, took third place in a competition held by DARPA last year. The school is starting a research center focused on the ethics of artificial intelligence. Chip Somodevilla/Getty Images

Deep learning raises particular issues because it is very difficult to interpret, much less control, what the millions of inner layer nodes represent or what they are doing.

More on this subject later.

### Brief History of Pattern Recognition with Artificial Neural Networks

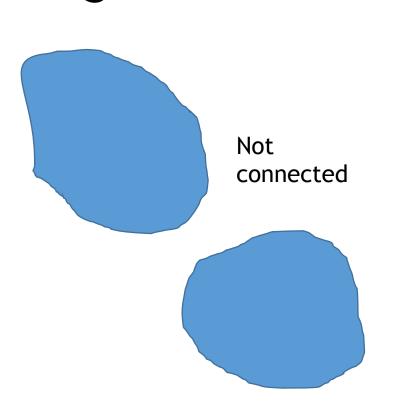
- 1950s Single neurons (Perceptron) Rosenblatt, Principles of Neurodynamics
  - Adaptive learning
- 1960s Single layer of neurons
  - Stochastic gradient descent (perceptron convergence theorem)
  - Negative result: some things can never be learned with a single layer, no matter how big (e.g. millions in retina)
  - Multiple layers is a hard integer programming problem
- Gap in progress ...
- ... 1980s and later (continued on a later slide)

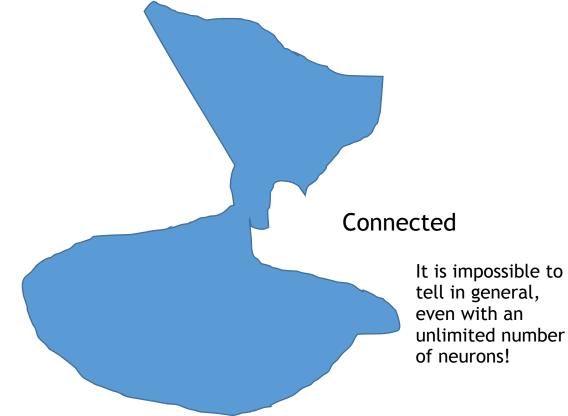
# Why was there a gap in progress

 Sometimes problems that seem very easy can actually be very hard

It seems easy to tell at a glance whether two

regions are connected

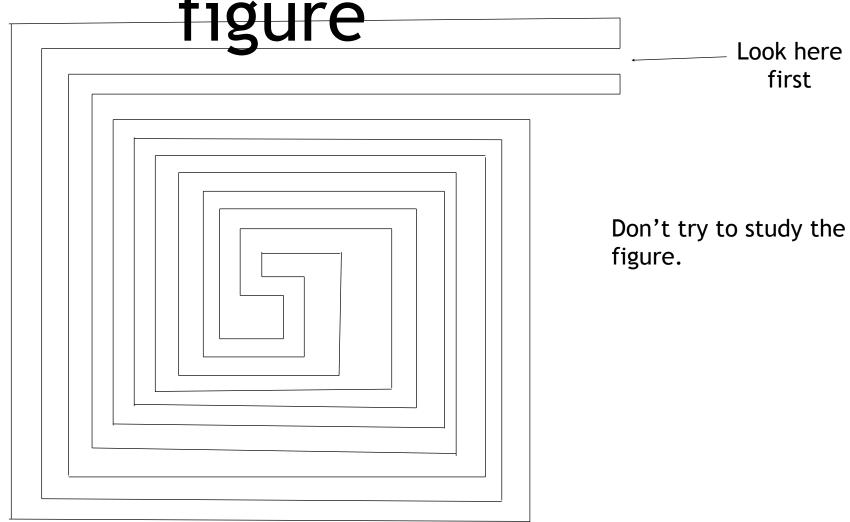




Minsky, Papert, Perceptrons: An Introduction to Computational Geometry

It looks easy to tell if a region is connected. Just glance at the figure on the next slide.

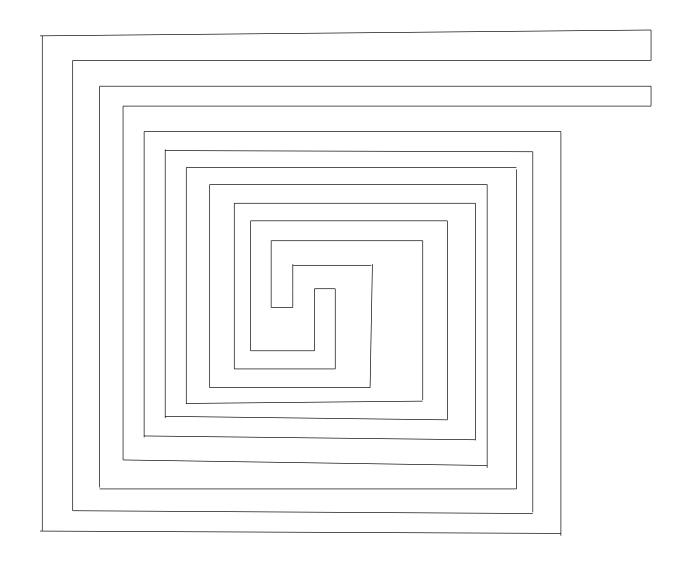
# Just glance at this figure



#### Was that one snake or two?

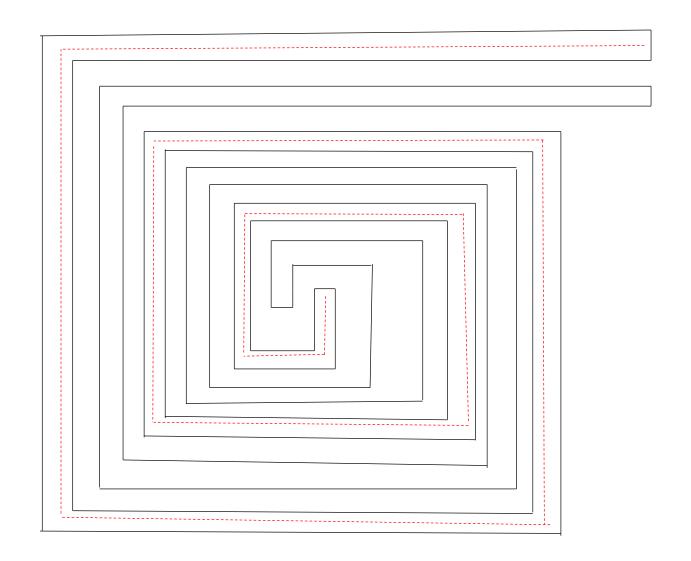
Are you sure?

#### One snake or two?



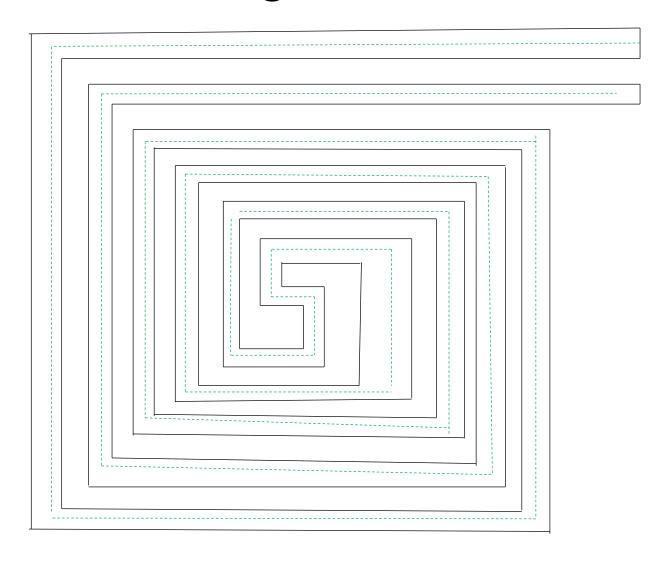
Were you sure?
Take more time.
Did your answer change?

#### One snake or two?



Did your answer change?
Did you get it right in the first diagram?

### But that wasn't the original diagram, this is



This example is in the spirit of the Minsky, Papert book, which was about computer vision. A much simpler example is that the Boolean function Xor cannot be represented with a single layer of perceptrons.

Do you still think you got the original problem correct?
One snake or two?

### Brief History of Pattern Recognition with Artificial Neural Networks

- 1950s Single neurons (perceptron)
- 1960s Single layer of neurons
- Gap in progress

J. J. Hopfield, "Neural networks and physical systems with emergent collective computational abilities", Proceedings of the National Academy of Sciences of the USA,

- 1982: New interest (Hopfield network) Process (Hopfield network)
- 1986: Breakthrough: Error backpropagation algorithm
  - Allows an extra layer (a "hidden" layer between input and output)
  - Key insight: Use a differentiable threshold function (sometimes problems that seem hard are easy)

Rumelhart, D., Hinton, G., Williams, R., Learning representations by back propagating errors, Nature vol. 323, 9 October 1986.

### Brief History of Pattern Recognition with Artificial Neural Networks

- 1960s Single layer of neurons
- 1986: Backprop: One hidden layer
  - Many successes, but it was difficult to train more than one hidden layer
  - Other machine learning algorithms eventually beat benchmarks set by ANNs
- 1990s 2006: Research continued, but progress

**Seco**, M. et al. Cackpropagation Applied to Handwritten Zip Code Recognition, Neural Computation 1:(4)-541-551, 1989. (Convolutional neural networks)

Hochreiter, S. & Schmidhuber, J. Long short-term memory. Neural Comput. 9, 1735-1780 (1997). (Recurrent neural networks and LSTM)

LeCun, Buttou, et al, Effiicient Backpropagation, in Orr and Muller, *Neural Networks: Tricks of the Trade*, 1998 (Various tricks, including how to initialize the weights)

 2006: Breakthrough: Efficiently training multiple hidden layers

Hinton, G.E., Osindero, S. & Teh, Y.-W. A fast learning algorithm for deep belief nets. Neural Comp. 18, 1527-1554 (2006).

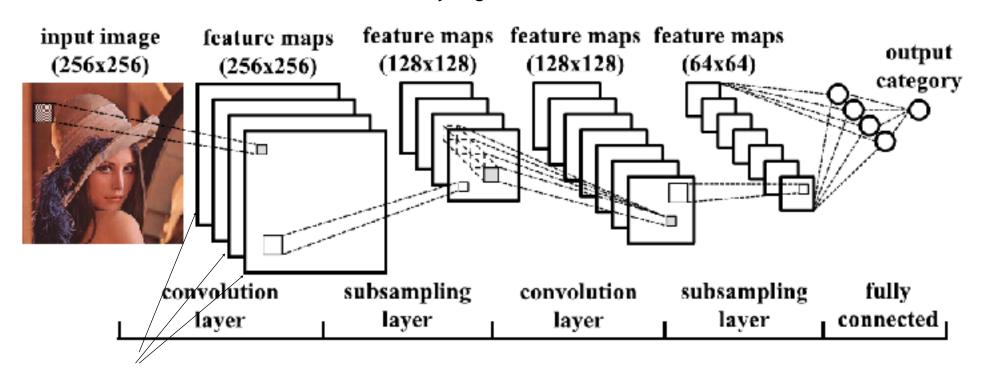
#### Artificial Neural Networks 1986 - 2006

- ANNs set several new pattern recognition benchmarks
- Innovations continued (convolutional neural nets, recurrent networks, LSTM)
- But, new methods (SVMs, random forests) began having higher performance than ANNs)
- Although backpropagation can be done with multiple hidden layers, there was little success applying it (slow convergence, problems with local minima, overfitting)
- Progress slowed, but didn't stop

# Architecture of Convolutional Neural Network

Suggested by processing in real eyes and brains.

Greatly reduces the amount of computation required to train very large networks.



The same weights are used, shifted in position. Thus the output is the input convolved with the weights.

Because the weights are shared, there is more data per update estimate. Also, there is less memory required, so a larger network fits into RAM. There is also somewhat less computation.

The subsampling reduces both the number of nodes and the number of weights.

#### Fast Training for Deep Belief Nets - 2006

Game changing result: Launched the era of deep learning

- Unsupervised training one layer at a time
  - Unsupervised training allows one layer at a time
- Requires special architecture
  - Top two layers form an undirected associative memory
- Efficiently trained nets with many layers and millions of nodes
- After unsupervised training of all layers, do an up-down pass of supervised training
- Achieved 20 year goal of efficient multi-layer training for large networks

Hinton, G.E., Osindero, S. & Teh, Y.-W. A fast learning algorithm for deep belief nets. Neural Comp. 18, 1527-1554 (2006).

### Training Deep Learning Nets – 2006+

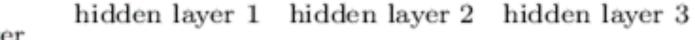
- First, it turned out that the special architecture was not required
  - Other methods of unsupervised training to get the initial weights for multi-layered feedforward nets, followed by supervised training with backprop were also successful
- Gradually, it became clear that even the initial unsupervised training was not essential, other fairly simple ways were found to get adequate initial

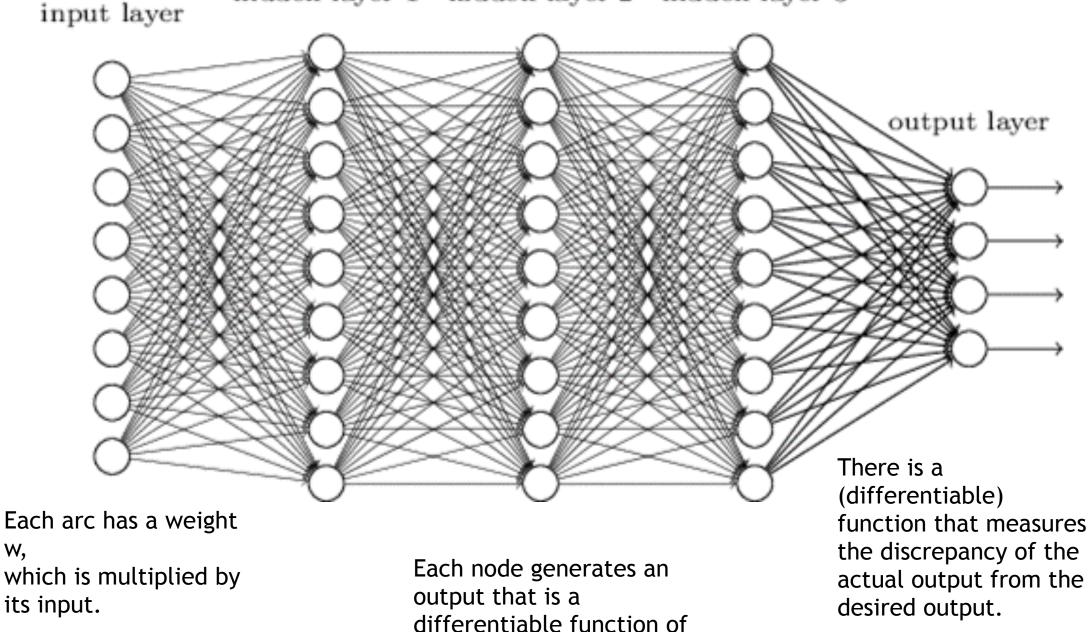
(Various Tricks, including how to initialize the weights)

Glorot, Bengio, Understanding the difficulty of training deep feedforward neural networks, AISTATS, 2010

- What did make the difference?
  - Large networks, very large amounts of data, very large amount of computation
  - 1980-90s computers were not fast enough and did not have enough memory

#### Deep neural network





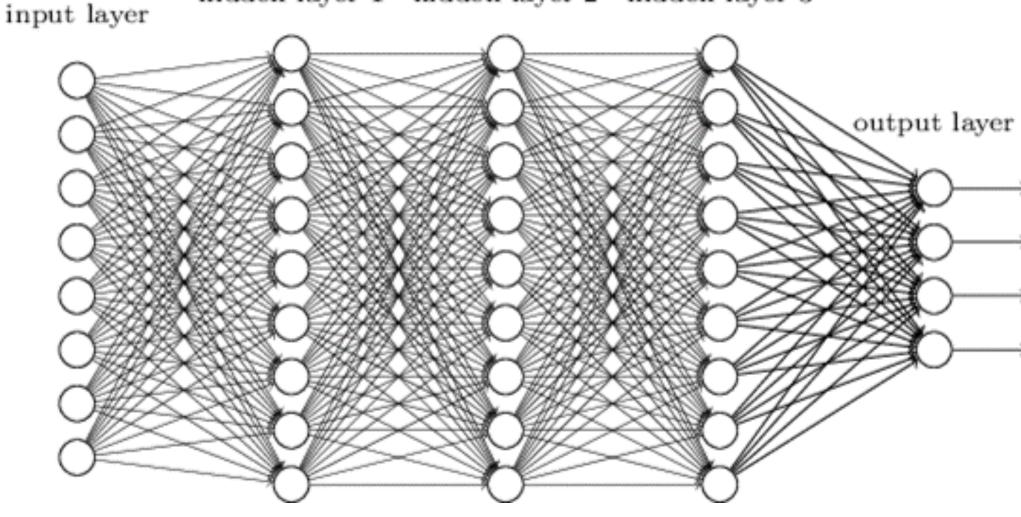
Forward computation: The computation of the output of each layer of nodes proceeds from left to right.

the sum of its inputs.

W,

#### Deep neural network

hidden layer 1 hidden layer 2 hidden layer 3



Backpropagation: The computation of the derivative of the error function with respect to the weights proceeds backwards. (This is just the ordinary chain rule of elementary calculus.) Make an incremental update to each weight proportional to minus the

Rumelhart, D., Hinton, G., Williams, R., Learning representations by back propagating errors, Nature vol. 323, 9 October 1986.

### Training a deep neural network

- It is (almost) as easy as it looks (I have left out some details)
  - Just do the {feedforward, backprop, update weights} computation for each item of training data (an epoch), and then repeat epochs until convergence
- But, it requires a lot of computation
  - Millions of nodes, billions weights, thousands of epochs, and as many data items per epoch as possible (sometimes millions)
- Fortunately, it is easy to implement for parallel computation
  - Implementation on GPUs typically speeds up the computation by two orders of magnitude

### Other Issues (with some solutions)

- With the very large number of parameters, there is always a danger of overfitting the training data
  - Several things can reduce the amount of overfitting
  - One of the best is dropout; For each data item, randomly pick some of the nodes to "dropout" and not participate
- Some large problems still require too much computation for general purpose networks (e.g. computer vision, speech recognition)
  - But they have a repetitive specialized structure: use convolutional neural nets
- Some problems require learning sequences (number grows exponentially with length)
  - Use recurrent neural nets to track the sequences (with LSTM)
- There are other issues which remain as problems; they will be discussed later
  - Vanishing gradient, overfitting, degradation with more layers, noninterpretablility, knowledge not explicit, non-use of domain-specific knowledge

#### Some of the Recent Successes of Deep Learning (Short List)

- Super-human performance reading street signs
- Beating a top human player in the game of Go
- Beating previous performance by training an image recognition network with over 100 layers
- Human parity in recognizing conversational speech
- Substantial improvement in naturalness of speech synthesis
- Distilling the knowledge of a large number of networks into a single network of the same size

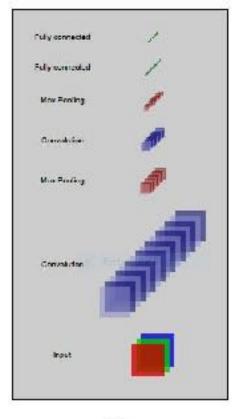
### Multi-Column Architecture

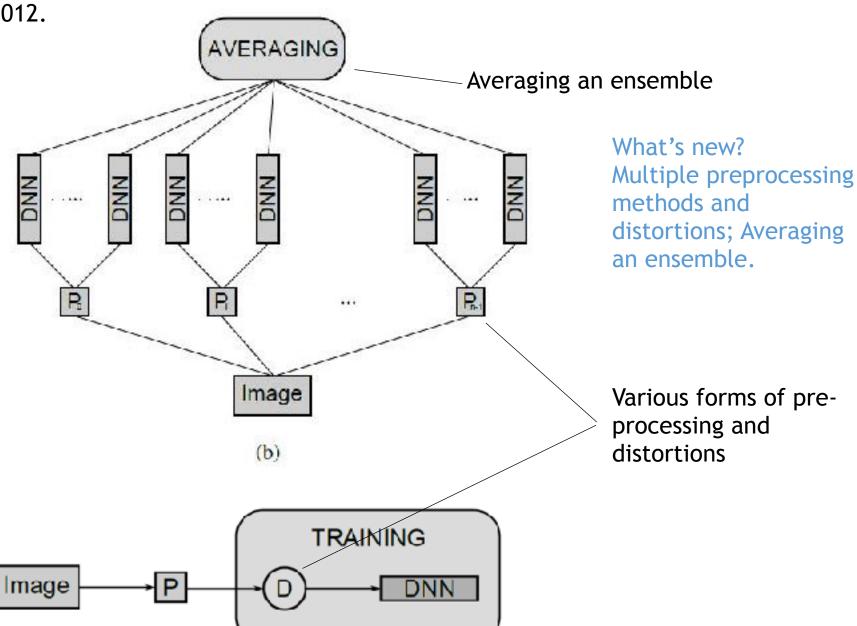
(On traffic signs, outperforms humans by factor of two)

Ciresan, Meier, Masci, Schmidhuber; Multi-column deep neural network for traffic sign

classification; 2012.





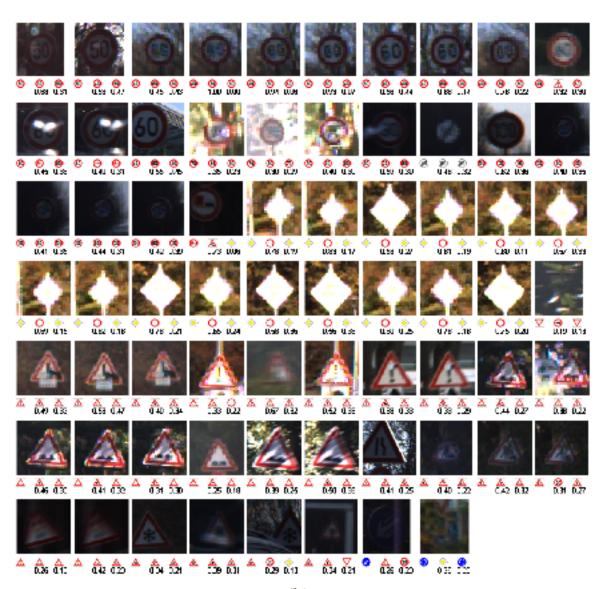


### Traffic Signs Dataset

Ciresan, Meier, Masci, Schmidhuber; Multi-column deep neural network for traffic sign classification; 2012.

- 12569 images, only 68 errors
  - Human error rate twice as high
  - Second best algorith
     3 times as many errors

Here are the 68 images it missed



### Machine Learning and Games

- Perfect information games (like checkers, chess, Othello, and Go) can be represented as a tree, with a node for each possible position and a branch for each possible move from that position
- If the tree is too large for exhaustive search:
  - Define a *policy function* setting the probability distribution among the possible moves (cuts done on the effective number of branches at each node)
  - Define a *value function* to give an estimated value for each node when the search is terminated before end
- Most successful game algorithms use Monte Carlo tree search (MCTS)
  - The computer plays games against itself and keeps a tree representing all games played
  - As more games are played, the value function becomes more accurate
  - The policy also improves by selected children with higher values
  - Further enhanced by policies that attempt to match human experts
  - Prior art: Shallow policies or value functions based on linear combination of input features

### Alpha Go

Silver, Huang, et al, Hassabis, mastering the game of Go with deep neural networks and tree search, Nature VOL 529, 28 January 2016

- Three deep neural networks: SL policy, RL policy, RL value
  - The architecture of each of the networks is a 2-d convolutional neural network based on the 19x19 grid of the Go board
- Stage one: The SL policy network is trained to imitate the play of professional Go players, using supervised learning
- Stage two (MCST): The algorithm plays games against itself and trains the RL policy and RL value networks using reinforcement learning

Using deep learning to train the value function rather than simple linear combination of features.

#### The New York Times

**ASIA PACIFIC** 

#### Google's Computer Program Beats Lee Se-dol in Go Tournament

By CHOE SANG-HUN MARCH 15, 2016



Lee Se-dol with his daughter Lee Hye-lim on his way to the last Go match with Google's AlphaGo artificial intelligence program in Seoul, South Korea. Kim Hong-Ji/Routers

News about AlphaGo, (Silver, Huang, et al, Hassabis, mastering the game of Go with deep neural networks and tree search, Nature VOL 529, 28 January 2016)

### Milestone: Achieving Human Parity in Conversational Speech Recognition

Xiong, et al, Zweig, Achieving Human Parity in Conversational Speech Recognition, Microsoft Technical Report MSR-TR-2016-71

**Table 7**. Word error rates (%) on the NIST 2000 CTS test set with different acoustic models. Unless otherwise noted, models are trained on the full 2000 hours of data and have 9k senones. Our automated system makes about a dozen fewer errors than people on the SWB set, not visible below due to rounding.

Model	N-gram LM		RNN-LM		LSTM-LM	
	CH	SWB	СН	SWB	CH	SWB
300h ResNet	19.2	10.0	17.7	8.2	17.0	7.7
ResNet GMM alignment	15.3	8.8	13.7	7.3	12.8	6.9
ResNet	14.8	8.6	13.2	6.9	12.5	6.6
VGG + ResNet	14.5	8.4	13.0	6.9	12.2	6.4
VGG	15.7	9.1	14.1	7.6	13.2	7.1
LACE	14.8	8.3	13.5	7.1	12.7	6.7
BLSTM	16.6	8.9	15.1	7.4	14.4	7.0
BLSTM 27k senones	16.2	8.7	14.6	7.5	13.6	7.0
BLSTM 27k, spatial smoothing	14.9	8.3	13.7	7.0	13.0	6.7
Final ASR System	13.3	7.4	12.0	6.2	11.1	5.9
Human Performance	-	-	-	-	11.3	5.9

Each system is a carefully engineered combination of previously successful system components with a few innovations.

Ensemble performance

Conclusion: Ensembles win benchmarks

Matches human performance!

# Can you get better learning just by adding more layers?

- Problem: Vanishing gradient
  - After back propagating many layers, the gradient is close to 0
  - This problem was eventually solved (intermediate normalization layers)
- Another problem: With additional layers, accuracy saturates and then rapidly degrades (Why?)
  - Not due to overfitting: performance on training data also degrades
  - (See a solution in next paper)

### Deep Residual Learning for Image Recognition

https://arxiv.org/abs/.03385 (He, Zhang, Ren, Sun, Deep residual learning for image recognition, 2015; Building DNNs with many more layers; Winner of ISVRC & COCO 2015 competitions)

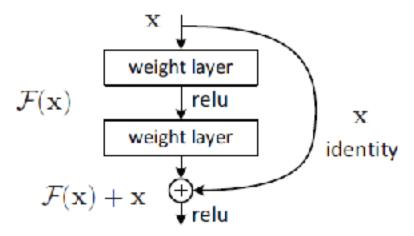
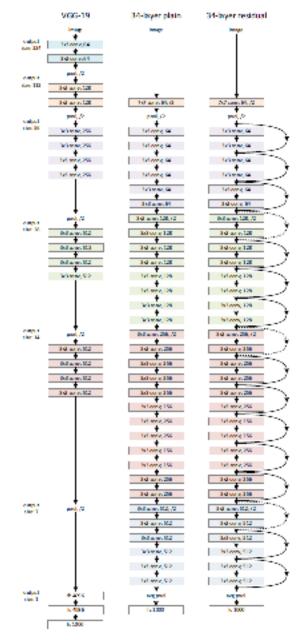


Figure 2. Residual learning: a building block.

### Deep Residual Learning for Image Recognition

https://arxiv.org/abs/.03385 (He, Zhang, Ren, Sun, Deep residual learning for image recognition, 2015; Building DNNs with many more layers; Winner of ISVRC & COCO 2015 competitions)

Comparison of three systems, each with many layers.



Deep residual learning allows so many layers that it is difficult to show them on a slide.

### Deep Residual Learning for Image Recognition

Deep residual learning wins the 2015 competition.

method	top-1 err.	top-5 err.
VGG [41] (ILSVRC'14)	-	8.43 <sup>†</sup>
GoogLeNet [44] (ILSVRC'14)	-	7.89
VGG [41] (v5)	24.4	7.1
PReLU-net [13]	21.59	5.71
BN-inception [16]	21.99	5.81
ResNet-34 B	21.84	5.71
ResNet-34 C	21.53	5.60
ResNet-50	20.74	5.25
ResNet-101	19.87	4.60
ResNet-152	19.38	4.49

Residual learning successfully trained 152 layers.

Table 4. Error rates (%) of **single-model** results on the ImageNet validation set (except † reported on the test set).

https://arxiv.org/abs/.03385 (He, Zhang, Ren, Sun, Deep residual learning for image recognition, 2015; Building DNNs with many more layers; Winner of ISVRC & COCO 2015 competitions)

# WaveNet: A Generative Model for Raw Audio

#### 2.1 DILATED CAUSAL CONVOLUTIONS

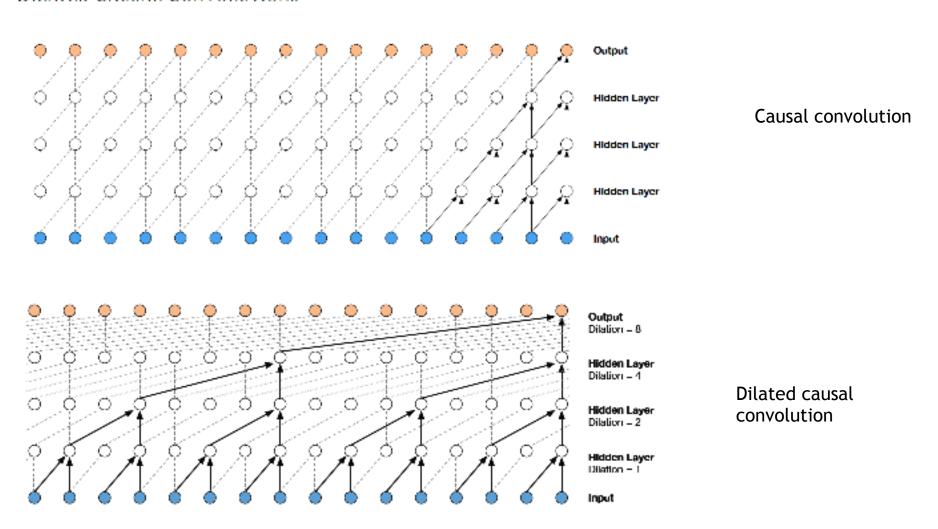


Figure 3: Visualization of a stack of dilated causal convolutional layers.

https://regmedia.co.uk/2016/09/09/wavenet.pdf (van den Oord, et al, WaveNet: A Generative Model for Raw Audio, DeepMind, 2016)

# WaveNet: A Generative Model for Raw Audio

https://regmedia.co.uk/2016/09/09/wavenet.pdf (van den Oord, et al, WaveNet: A Generative Model for Raw Audio, DeepMindRL2016) AND SKIP CONNECTIONS

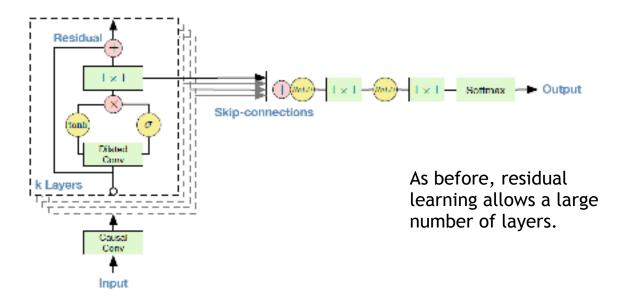


Figure 4: Overview of the residual block and the entire architecture.

With <u>dilated causal convolution</u>, using residual learning to enable training many layers, WaveNet is able to produce synthetic speech that sounds much more natural than any previous systems.

Dilated causal convolution and residual learning.

# A Sample of Handwritten Digits (MNIST)

```
21956218
8912500664
6701636370
3779466182
2934398725
1598365723
9319158084
5626858899
3770918543
264706923
```

### Soft Decisions (Hinton, 2015)

The "dark knowledge" is the knowledge available from the 2<sup>nd</sup> best and other scores. However, the scores need to be "softened" because the ensemble is too confident in the right answer.

The blue regions all look black with normal "hard" scoring. The extra knowledge is in these "dark" regions.

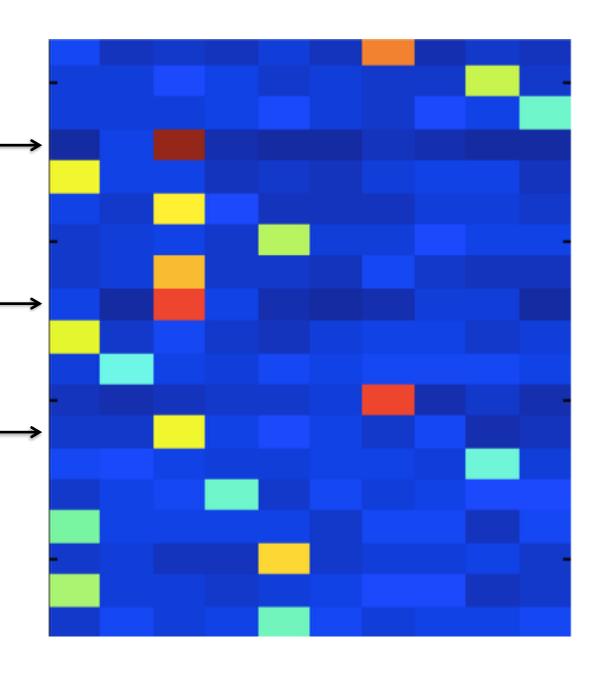
this 2 resembles a 1 \_ and nothing much else

this 2 resembles 0, 3, 7, 8

this 2 resembles 4 and 7

https://arxiv.org/abs/1503.02531

(Distilling the Knowledge of a Neural Network, Hinton, 2015, Uses MNIST as an example)



# Distillation of Knowledge from an Ensemble to a Single Network

- Train the ensemble
- Average a soften version of the output of each member of the ensemble
- Use this average as the objective for training a single network

  Uses output of ensemble as supervision for a single network; Softens the output before averaging.
- Result: The single network is much closer to the performance of the ensemble than to the performance of a conventionally trained single network

https://arxiv.org/abs/1503.02531 (Distilling the Knowledge of a Neural Network, Hinton, 2015, Uses MNIST as an example)

# About the Course: An Introduction to Human-Aided Deep Learning

- This is a reading and research course
  - That means that you will read state-of-the-art papers like those I have summarized and present them to your fellow students
  - We will begin with simpler papers providing background in the techniques
  - You will also have projects implementing these techniques
  - You will eventually implement a state-of-the-art benchmark (up to the capacity of our computing facility)
  - You will also have an opportunity to go beyond

### Some Remaining Problems

- Deep learning systems lack the wisdom of Socrates
  - "The only thing I know is that I don't know anything."
- They are mysterious

Over confidence.

- It is difficult or impossible to know what the nodes and weights of inner layers represent
- End-to-end training with no supplied expert knowledge is a major AI milestone
  - But it is also a major weakness and limitation
- Ethical issue
  - How can we control systems if we don't know what they are doing, and they don't take advice or guidance?

# The Missing Ingredient: Human Knowledge

- Dilemma: How can we give advice or control deep neural nets if we can't what the node activations and connections weights mean?
- Idea: deep learning networks are good at learning many different things. Why not use a deep learning network to learn how to communicate with deep learning networks?
- Introducing the concept of a Socratic coach: A Socratic coach is a second deep learning system associated with a primary deep learning system. However, rather than studying the primary data, the Socratic coach studies the primary deep learning system itself.
- This concept changes the game.

# How the Objective of the Game Changes

- Being able to learn things on their own is one of the major achievements of deep learning systems. Does assistance from humans undercut that achievement?
- In my opinion, if we can use machine learning to facilitate communication with end-to-end trained machines, we will have added to the achievement. The objective becomes the performance of the combined system.
- The Socratic coach automates the task of a machine learning researcher. That is, it does a task requiring intelligence better than a human can do it.

# How the Tactics of the Game Change

- Using an outside expect, the Socratic coach, that acquires knowledge about the primary machine learning system greatly facilitates development of improvements in the primary system.
  - The Socratic coach learns to understand the primary system in ways that the primary system itself can't even represent.
  - The Socratic coach can automate development testing, doing many more experiments than could be done by hand.

# How the Game Changes for You

- Everything that you learn about deep learning can be applied to designing and developing Socratic coaches, which can in turn be used to help develop better primary systems.
- You will immediately be working at the cutting edge of new developments.
- There may be an opportunity to put this to practice in a follow-on course or as an intern for a start-up.

#### Take Action

• If you are excited about deep learning or about this opportunity to be at the cutting edge, please take the course 11-364: Introduction to Human-Aided Deep Learning

 In any case, best wishes to you and thank you for your attention.

### S-17 --11-364: An Introduction to Human-Aided Deep Learning and Socratic Coaches

- You will read papers like those that I have discussed
  - You will present summaries of these papers to your peers
  - These papers are not be easy to read.
    - They assume a lot of prior knowledge from other papers.
- You will implement at least one of the systems
- You will replicate state-of-the-art results

This will be a challenging course, but you will learn a lot. I hope you will learn more than from any normal course. How much you learn will be up to you.

 Potential follow-on: Implementing ideas never tried before and/or interning with a start-up