

# COMS 4771 Machine Learning (2018 Fall)

## Homework 1

Jing Qian - jq2282@columbia.edu

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### Problem 2

(iii).

$$\begin{aligned}\mathbb{E}[x] &= \frac{1}{n} \sum_{i=1}^n [1 \times b + 0 \times (1 - b)] \\ &= \frac{1}{n} \sum_{i=1}^n b \\ &= b, \\ \mathbb{E}[x^2] &= \frac{1}{n} \sum_{i=1}^n [1^2 \times b + 0^2 \times (1 - b)] \\ &= \frac{1}{n} \sum_{i=1}^n b \\ &= b, \\ \text{Var}[x] &= \mathbb{E}[x^2] - \mathbb{E}[x]^2 \\ &= b - b^2.\end{aligned}\tag{1}$$

(iv). Using the invariance property of MLE shown in Problem 1(ii), the MLE for the coin's variance is the variance function of the MLE bias  $\hat{b}$ . From subproblem (i), we get the MLE bias  $\hat{b} = \frac{\sum_{i=1}^n x_i}{n}$ . From subproblem (ii), we get the variance of this coin is  $\text{Var}[x] = b - b^2$ . So the MLE for the coin's variance is :

$$\hat{\text{Var}}[x] = \hat{b} - \hat{b}^2 = \frac{\sum_{i=1}^n x_i}{n} - \left(\frac{\sum_{i=1}^n x_i}{n}\right)^2.\tag{2}$$

(v).

(vi). When the parameter  $b$  has uniform distribution, MAP estimate equals MLE. From the definition, the MLE and MAP estimations of parameter  $b$  are:

$$\begin{aligned}
 b_{\text{MLE}} &= \arg \max_b \prod_{i=1}^N P(\vec{x}_i | b) \\
 &= \arg \max_b \sum_{i=1}^N \log P(\vec{x}_i | b), \\
 b_{\text{MAP}} &= \arg \max_b \prod_{i=1}^N P(b | \vec{x}_i) \\
 &= \arg \max_b \prod_{i=1}^N P(\vec{x}_i | b) P(b) \\
 &= \arg \max_b (\log P(b) + \sum_{i=1}^N \log P(\vec{x}_i | b)).
 \end{aligned} \tag{3}$$

The difference between two estimations is the  $\log P(b)$  term in  $b_{\text{MAP}}$ . To make  $b_{\text{MLE}} = b_{\text{MAP}}$ ,  $\arg \max_b \log P(b)$  must be zero, which means  $P(b)$  is constant and hence is uniform distribution. In other words, MAP estimate equals MLE when  $P(b)$  is a uniform distribution.

## Problem 3.2

Let  $f$  be the median of  $y$  given  $x$ . Then  $f$  would be the optimal predictor if we have  $Q(g) - Q(f) \geq 0$  for any  $x$  in the domain.

If  $f < g$ :

$$\begin{aligned}
 \mathbb{E}[|g - y|] - \mathbb{E}[|f - y|] &= \mathbb{E}[|g - y| - |f - y|] \\
 &= \Pr[y \leq f](|g - y| - |f - y|) + \Pr[y > f](|g - y| - |f - y|) \\
 &= \Pr[y \leq f](g - y - f + y) + \Pr[y > f](|y - g| - |y - f|) \\
 &\geq \Pr[y \leq f](g - f) + \Pr[y > f][-(g - f)] \\
 &= (g - f)[\Pr[y \leq f] - \Pr[y > f]] \\
 &\geq 0
 \end{aligned} \tag{4}$$

according to the property of median. On the other hand, if  $f > g$ , similarly, we have:

$$\begin{aligned}
 \mathbb{E}[|g - y|] - \mathbb{E}[|f - y|] &= \mathbb{E}[|g - y| - |f - y|] \\
 &= \Pr[y \geq f](|g - y| - |f - y|) + \Pr[y < f](|g - y| - |f - y|) \\
 &\geq \Pr[y \geq f](f - g) + \Pr[y < f][-(f - g)] \\
 &= (f - g)[\Pr[y \geq f] - \Pr[y < f]] \\
 &\geq 0
 \end{aligned} \tag{5}$$

Since  $\mathbb{E}[|g - y|] - \mathbb{E}[|f - y|] \geq 0$  at any given  $x$ ,  $Q(g) \geq Q(f)$ , the median of  $y$  is the optimal predictor.

## Problem 5

For every training set with  $(x_1, y_1), \dots, (x_n, y_n)$  i.i.d. samples, we could find one unique  $w$  to minimize its training error  $\mathcal{R}$ . That is to say,

$$\hat{w} = \arg \min \hat{\mathcal{R}}(w) = \arg \min \frac{1}{n} \sum_{i=1}^n (w \cdot x_i - y_i)^2. \quad (6)$$

For any  $w$ , we have  $\hat{\mathcal{R}}(\hat{w}) \leq \hat{\mathcal{R}}(w)$ .

Similarly, for another i.i.d. random sample consisted of  $(\tilde{x}_1, \tilde{y}_1), \dots, (\tilde{x}_n, \tilde{y}_n)$ :

$$\tilde{w} = \arg \min \tilde{\mathcal{R}}(w) = \arg \min \frac{1}{n} \sum_{i=1}^n (w \cdot \tilde{x}_i - \tilde{y}_i)^2. \quad (7)$$

For any  $w$ , we have  $\tilde{\mathcal{R}}(\tilde{w}) \leq \tilde{\mathcal{R}}(w)$ . Here the inequality holds for  $\hat{w}$  since it holds for any  $w$ ,  $\hat{\mathcal{R}}(\tilde{w}) \leq \tilde{\mathcal{R}}(\hat{w})$ .

Since both sets are i.i.d. samples from the same domain:

$$\begin{aligned} \mathbb{E}[\hat{\mathcal{R}}(\hat{w})] &= \min \mathbb{E}[(w \cdot x - y)^2] \\ \mathbb{E}[\tilde{\mathcal{R}}(\tilde{w})] &= \min \mathbb{E}[(w \cdot x - y)^2] \end{aligned} \quad (8)$$

So the expectations of training error of two i.i.d. random samples equal:  $\mathbb{E}[\hat{\mathcal{R}}(\hat{w})] = \mathbb{E}[\tilde{\mathcal{R}}(\tilde{w})]$ . Then we have:

$$\mathbb{E}[\hat{\mathcal{R}}(\hat{w})] = \mathbb{E}[\tilde{\mathcal{R}}(\tilde{w})] \leq \mathbb{E}[\tilde{\mathcal{R}}(\hat{w})]. \quad (9)$$

Since the set  $(\tilde{x}_1, \tilde{y}_1), \dots, (\tilde{x}_n, \tilde{y}_n)$  is a i.i.d. random sample from the domain, the inequality above holds for the generalization of any i.i.d. random samples with squared error  $\mathcal{R}$ . In other words:

$$\mathbb{E}[\hat{\mathcal{R}}(\hat{w})] \leq \mathbb{E}[\mathcal{R}(\hat{w})]. \quad (10)$$