torch_geometric.transforms

class Compose(transforms) [source]

Composes several transforms together.

Parameters: transforms (list of transform objects) – List of transforms to compose.

class Constant(value=1, cat=True) [source]

Adds a constant value to each node feature.

Parameters: • value (int, optional) – The value to add. (default: 1)

• cat (bool, optional) — If set to False, all existing node features will be replaced. (default: True)

class Distance(norm=True, max_value=None, cat=True) [source]

Saves the Euclidean distance of linked nodes in its edge attributes.

Parameters:

- **norm** (*bool*, *optional*) If set to <code>False</code>, the output will not be normalized to the interval [0, 1]. (default: <code>True</code>)
- max_value (float, optional) If set and norm=True, normalization will be performed based on this value instead of the maximum value found in the data. (default: None)
- cat (bool, optional) If set to False, all existing edge attributes will be replaced. (default: True)

class Cartesian(norm=True, max_value=None, cat=True) [source]

Saves the relative Cartesian coordinates of linked nodes in its edge attributes.

Parameters:

- **norm** (*bool*, *optional*) If set to False, the output will not be normalized to the interval [0, 1]^D. (default: True)
- max_value (float, optional) If set and norm=True, normalization will be performed based on this value instead of the maximum value found in the data. (default: None)
- cat (bool, optional) If set to False, all existing edge attributes will be

replaced (default: True)

class LocalCartesian(cat=True) [source]

Saves the relative Cartesian coordinates of linked nodes in its edge attributes. Each coordinate gets *neighborhood-normalized* to the interval $[0, 1]^D$.

Parameters: cat (bool, optional) – If set to False, all existing edge attributes will be replaced. (default: True)

class Polar(norm=True, max_value=None, cat=True) [source]

Saves the relative polar coordinates of linked nodes in its edge attributes.

Parameters:

- **norm** (*bool*, *optional*) If set to <code>False</code>, the output will not be normalized to the interval $[0, 1]^2$. (default: <code>True</code>)
- max_value (float, optional) If set and norm=True, normalization will be performed based on this value instead of the maximum value found in the data. (default: None)
- cat (bool, optional) If set to False, all existing edge attributes will be replaced. (default: True)

class Spherical(norm=True, max_value=None, cat=True) [source]

Saves the relative spherical coordinates of linked nodes in its edge attributes.

Parameters:

- **norm** (*bool*, *optional*) If set to False, the output will not be normalized to the interval [0, 1]³. (default: True)
- max_value (float, optional) If set and norm=True, normalization will be performed based on this value instead of the maximum value found in the data. (default: None)
- cat (bool, optional) If set to False, all existing edge attributes will be replaced. (default: True)

class PointPairFeatures(cat=True) [source]

Computes the rotation-invariant Point Pair Features

$$\left(\|\mathbf{d_{j,i}}\|, \angle(\mathbf{n}_i, \mathbf{d_{j,i}}), \angle(\mathbf{n}_j, \mathbf{d_{j,i}}), \angle(\mathbf{n}_i, \mathbf{n}_j)\right)$$

of linked nodes in its edge attributes, where $\mathbf{d}_{j,i}$ denotes the difference vector between, and \mathbf{n}_i and \mathbf{n}_j denote the surface normals of node i and j respectively.

Parameters: cat (bool, optional) – If set to False, all existing edge attributes will be replaced. (default: True)

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class OneHotDegree(max_degree, cat=True) [source]

Adds the node degree as one hot encodings to the node features.

Parameters:

- max_degree (*int*) Maximum degree.
- cat (bool, optional) Concat node degrees to node features instead of replacing them. (default: True)

class TargetIndegree(norm=True, max_value=None, cat=True) [source]

Saves the globally normalized degree of target nodes

$$\mathbf{u}(i,j) = \frac{\deg(j)}{\max_{v \in V} \deg(v)}$$

in its edge attributes.

Parameters: cat (bool, optional) – Concat pseudo-coordinates to edge attributes instead

of replacing them. (default: True)

class LocalDegreeProfile [source]

Appends the Local Degree Profile (LDP) from the "A Simple yet Effective Baseline for Non-attribute Graph Classification" paper

$$\mathbf{x}_i = \mathbf{x}_i \| (\deg(i), \min(DN(i)), \max(DN(i)), \max(DN(i)), \operatorname{std}(DN(i)))$$

to the node features, where $DN(i) = \{\deg(j) \mid j \in N(i)\}$.

class Center [source]

Centers node positions around the origin.

class NormalizeRotation(max_points=-1) [source]

Rotates all points so that the eigenvectors overlie the axes of the Cartesian coordinate system. If the data additionally holds normals saved in data.norm these will be also rotated.

Parameters: max_points (int, optional) – If set to a value greater than [a], only a random

number of max_points points are sampled and used to compute

eigenvectors. (default: -1)

class NormalizeScale [source]

Centers and normalizes node positions to the interval (-1, 1).

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class RandomTranslate(translate) [source]

Translates node positions by randomly sampled translation values within a given interval. In contrast to other random transformations, translation is applied separately at each position.

Parameters: translate (sequence or float or int) – Maximum translation in each

dimension, defining the range (- translate, + translate) to sample from. If translate is a number instead of a sequence, the same range is used for

each dimension.

class RandomFlip(axis, p=0.5) [source]

Flips node positions along a given axis randomly with a given probability.

Parameters: • axis (*int*) – The axis along the position of nodes being flipped.

p (float, optional) – Probability that node positions will be flipped.
 (default: 0.5)

class LinearTransformation(matrix) [source]

Transforms node positions with a square transformation matrix computed offline.

Parameters: matrix (Tensor) – tensor with shape [D, D] where D corresponds to the

dimensionality of node positions.

class RandomScale(scales) [source]

Scales node positions by a randomly sampled factor s within a given interval, e.g., resulting in the transformation matrix

$$\begin{bmatrix} s & 0 & 0 \\ 0 & s & 0 \\ 0 & 0 & s \end{bmatrix}$$

for three-dimensional positions.

Parameters: scale (*tuple*) – scaling factor interval, e.g. (a, b) , then scale is randomly

sampled from the range $a \le \text{scale} \le b$.

class RandomRotate(degrees, axis=0) [source]

Rotates node positions around a specific axis by a randomly sampled factor within a given interval.

Parameters:

- degrees (tuple or float) Rotation interval from which the rotation angle is sampled. If degrees is a number instead of a tuple, the interval is given by [degrees, degrees].
- axis (int, optional) The rotation axis. (default: 0)

class RandomShear(shear) [source]

Shears node positions by randomly sampled factors *s* within a given interval, *e.g.*, resulting in the transformation matrix

$$\begin{bmatrix} 1 & s_{xy} & s_{xz} \\ s_{yx} & 1 & s_{yz} \\ s_{zx} & z_{zy} & 1 \end{bmatrix}$$

for three-dimensional positions.

Parameters: shear (*float or int*) – maximum shearing factor defining the range (– shear, + shear) to sample from.

class NormalizeFeatures [source]

Row-normalizes node features to sum-up to one.

class AddSelfLoops [source]

Adds self-loops to edge indices.

class KNNGraph(k=6, loop=False, force_undirected=False) [source]

Creates a k-NN graph based on node positions.

Parameters: • k (in:

- **k** (*int*, *optional*) The number of neighbors. (default: 6)
- **loop** (*bool*, *optional*) If True, the graph will contain self-loops. (default: False)
- **force_undirected** (*bool, optional*) If set to True, new edges will be undirected. (default: False)

class RadiusGraph(r, loop=False, max_num_neighbors=32) [source]

Creates edges based on node positions to all points within a given distance.

Parameters:

- r (float) The distance.
- **loop** (*bool*, *optional*) If True, the graph will contain self-loops. (default: False)
- max_num_neighbors (int, optional) The maximum number of neighbors to return for each element in y. This flag is only needed for CUDA tensors. (default: 32)

class FaceToEdge(remove_faces=True) [source]

Converts mesh faces [3, num_faces] to edge indices [2, num_edges].

Parameters: remove_faces (bool, optional) – If set to False, the face tensor will not be removed.

class SamplePoints(num, remove_faces=True, include_normals=False) [source]

Uniformly samples num points on the mesh faces according to their face area.

Parameters:

- **num** (*int*) The number of points to sample.
- remove_faces (bool, optional) If set to False, the face tensor will not be removed. (default: True)
- include_normals (bool, optional) If set to True, then compute normals for each sampled point. (default: False)

class ToDense(num_nodes=None) [source]

Converts a sparse adjacency matrix to a dense adjacency matrix with shape [num_nodes, num_nodes, *].

Parameters: num_nodes (*int*) – The number of nodes. If set to None, the number of nodes will get automatically inferred. (default: None)

class TwoHop [source]

Adds the two hop edges to the edge indices.

class LineGraph(force_directed=False) [source]

Converts a graph to its corresponding line-graph:

$$L(G) = (V', E')$$

 $V' = E$
 $E' = \{(e_1, e_2) : e_1 \cap e_2 \neq \emptyset\}$

Line-graph node indices are equal to indices in the original graph's coalesced edge_index. For undirected graphs, the maximum line-graph node index is (data.edge_index.size(1) // 2) - 1.

New node features are given by old edge attributes. For undirected graphs, edge attributes for reciprocal edges (row, col) and (col, row) get summed together.

Parameters: force_directed (bool, optional) – If set to True, the graph will be always treated as a directed graph. (default: False)

class GenerateMeshNormals [source]

Generate normal vectors for each mesh node based on neighboring faces.