

3F3 Statistical Signal Processing

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1 Probability Space

1.1 Notation

- $x \in \mathbf{A}$ x is an element of \mathbf{A} "Set membership"
- $\mathbf{A} \subseteq \Omega$ \mathbf{A} is a subset of Ω
- $\mathbf{A} \subset \Omega$ \mathbf{A} is a proper subset of Ω
- $\mathbf{A} \cup \mathbf{B}$ Union of two sets
- $\mathbf{A} \cap \mathbf{B}$ Intersection of two sets
- \mathbf{A}^c Complementary Set
- $\mathbf{A} \setminus \mathbf{B}$ $\mathbf{A} \cap \mathbf{B}^c$ intersection of \mathbf{A} with not \mathbf{B}
- \emptyset Empty set

1.2 Probability Space

- **Random experiment** is used to describe any situation which has a set of possible outcomes, each of which occurs with a particular probability.
- **Sample space** Ω is the set of all possible outcomes of the **random experiment**.
- **Event** any subset $\mathbf{A} \subseteq \Omega$
- **Probability** P mapping/function from events to a number in the interval $[0, 1]$. Therefore, specify $\{P(\mathbf{A}), \mathbf{A} \subset \Omega\}$
- **Probability Space** defined as: (Ω, P)
- **Indicator function** for a set or event E defined as:

$$\mathbb{I}_E(t) = \begin{cases} 1 & \text{if } t \in E, \\ 0 & \text{if } t \notin E \end{cases}$$

- Examples:
 - Toss a coin twice. $\Omega = \{HH, HT, TH, TT\}$ - Finite set

- The temperature is a perturbation of seasonal average. $\Omega = (-\infty, \infty)$ - Real line
- Toss a coin n times. One elementary outcome is $\omega = (o_1, o_2, \dots, o_n)$

$$\Omega = \{\omega = (o_1, o_2, \dots, o_n) : o_i \in \{H, T\}\}.$$

- Toss a coin n times, the event **E** that the first head Occurs on third toss is:

$$\mathbf{E} = \{\omega = (T, T, H, o_4, o_5, \dots, o_n) : o_i \in \{H, T\} \text{ for } i > 3\}.$$

$$P(\mathbf{E}) = (1/2)^3$$

1.3 Axioms of probability

A probability P assigns each event **E**, $\mathbf{E} \subset \Omega$, a number in $[0,1]$ and P must satisfy following properties:

- $P(\Omega) = 1$
- For events A, B such that $\mathbf{A} \cap \mathbf{B} = \emptyset$ (i.e. disjoint) then $P(\mathbf{A} \cup \mathbf{B}) = P(\mathbf{A}) + P(\mathbf{B})$
- if A_1, A_2, \dots are disjoint then $P(\cup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$.
- The third one implies the second one.

Examples:

(i) Show that, if event $\mathbf{A} \subset \mathbf{B}$ then $P(A) \leq P(B)$.

$$B = (B \cap A^c) \cup A = (B \setminus A) \cup A$$

$$P(B) = P(B \setminus A) + P(A) \geq P(A)$$

(ii) Show that, $P(A^c) = 1 - P(A)$

$$\Omega = A \cup A^c$$

$$P(\Omega) = P(A) + P(A^c) = 1$$

(iii) Defining P : Ω is a finite discrete set, i.e. $\Omega = \{\omega_1, \omega_2, \dots, \omega_n\}$. Let p_1, p_2, \dots, p_n be non negative numbers that add to 1. For any event A , set,

$$P(A) = \sum_{i=1}^n \mathbb{I}_A(\omega_i) P_i$$

Let $P_i = 1/n$. Then

$$P(\{\omega_i\}) = p_i = 1/n$$

i.e. each outcome is equally likely. This is the *uniform probability distribution*.

1.4 Conditional Probability

- Definition: The conditional probability of event A occurring given that event B has occurred :

$$P(A|B) = \frac{P(A \cap B)}{P(B)}, \text{ for } P(B) > 0$$

- Think of $P(A|B)$ as the fraction of times A occurs among those in which B occurs.
- AB is shorthand for $A \cap B$
- Example: Verify any set given set G is a probability i.e. $P(\cdot|G)$ is a probability

$$\text{Firstly, } P(\Omega|G) = P(\Omega \cap G)/p(G) = 1$$

$$\begin{aligned} \text{Secondly, for disjoint events A and B } P(A \cap B|G) &= P(AG \cap BG)/p(G) \\ &= (P(AG) + P(BG))/p(G) \\ &= P(A|G) + P(B|G) \end{aligned}$$

- Probability Chain Rule

$$P(A_1 \dots A_n) = P(A_1)P(A_2|A_1) \dots P(A_n|A_{n-1}, \dots, A_1) = P(A_1) \prod_{i=2}^n P(A_i|A_{i-1}, \dots, A_1) = \prod_{i=1}^n P(A_i|A_{i-1}, \dots, A_1)$$

- Independence: two events A and B are independent if

$$P(AB) = P(A \cap B) = P(A)P(B)$$

- if A and B are independent then $P(A|B) = P(A)$

- Bayes' Theorem:

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

- Example: A is the event the email is spam and B is the event the email contains "free". We know $P(B|A) = 0.8$ and $P(B|not A) = 0.1$ and $P(A) = 0.25$ What is the probability the email is spam given the email contains "Free"?

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)} = \frac{0.8 * 0.25}{0.8 * 0.25 + 0.1 * 0.75} = 0.727$$

- This is an example of an *expert* system.

1.5 Random Variables

- Definition: Given a probability space (Ω, P) , a random variable is a function $X(\omega)$ which maps each element ω of the sample space Ω onto a point on the real line.
- Example: Flipping a coin twice. Sample Space: $\Omega = \{HH, HT, TH, TT\}$ Define $X(\omega)$ be the number of heads.

| ω | $P(\{\omega\})$ | $X(\omega)$ |
|----------|-----------------|-------------|
| TT | 0.25 | 0 |
| TH | 0.25 | 1 |
| HT | 0.25 | 1 |
| HH | 0.25 | 2 |

| x | $\Pr(X = x)$ |
|-----|--------------|
| 0 | 0.25 |
| 1 | 0.5 |
| 2 | 0.25 |

- The second table does not mention the sample space. The range of X is listed along with the probability associated.
- However, there is a sample space lurking behind every definition of a rv.
- The Probability that $X = x$ is inherited from the definition of (Ω, P) and the mapping $X(\omega)$
- For any set $A \subset (-\infty, \infty)$, we define

$$Pr(X \in A) = P(\{\omega : X(\omega) \in A\})$$

- Discrete random variable: range is a finite set, say $\{x_1, \dots, x_i, \dots, x_M\}$ or a countable set, say $\{x_1, x_2, \dots\}$.
 - A set E is countable if you can define a one-to-one mapping from E to the set of integers .
 - Examples: all rational number, all even number. The interval $[0, 1]$ is not countable.
 - Definition: Discrete rv X with range $\{x_1, x_2, \dots\}$, the pmf is the function $p_x : \{x_1, x_2, \dots\} \rightarrow [0, 1]$ where

$$p_X(x_i) = Pr(X = x_i) \text{ and } \sum_{i=1}^{\infty} p_X(x_i) = 1$$

The pmf is a complete description: for any set A ,

$$Pr(X \in A) = \sum_{i=1}^{\infty} \mathbb{I}_A(x_i) p_X(x_i)$$

- Continuous random variable: defined as having a probability density function(pdf)
 - Definition: A random variable is continuous if there exists a non-negative function $f_X(x) \geq 0$ such that $\int_{-\infty}^{\infty} f_X(x) dx = 1$ and for any set A

$$Pr(X \in A) = \int_{-\infty}^{\infty} \mathbb{I}_A(x) f_X(x) dx$$

- Example: $A = [a, b]$ then

$$Pr(X \in A) = Pr(a \leq X \leq b) = \int_a^b f_X(x) dx$$

- * pdf f_X assigns 0 probability to any particular point $x \in \mathbb{R}$ Thus $Pr(X = x) = 0$ for all x .

$$Pr(X \in [a, b]) = Pr(X \in (a, b]) = Pr(X \in (a, b))$$

- * This means a continuous rv has no concentration of probability at points like a discrete rv does

- Cumulative distribution function: Describe both discrete and continuous random variables and is defined to be

$$F_X(x) = Pr(X \leq x)$$

Properties:

1. $0 \leq F_X(x) \leq 1$
2. $F_X(x)$ is non-decreasing as x increases
3. $Pr(x_1 < X \leq x_2) = F_X(x_2) - F_X(x_1)$
4. $\lim_{x \rightarrow -\infty} F_X(x) = 0$ and $\lim_{x \rightarrow \infty} F_X(x) = 1$
5. If X is a continuous r.v. then $F_X(x)$ is continuous
6. If X is discrete then $F_X(x)$ is right-continuous: $F_X(x) = \lim_{t \downarrow x} F(t)$ for all x

For Property 6

- For a discrete rv with range $x_1, \dots, x_i, \dots, x_M$

$$F_X(x) = \sum_{j=1}^M P(x_j) \mathbb{I}_{[x_j, \infty)}(x) \quad ([\text{ touch } (\text{ not touch })$$

is a step function

- CDF and PDF for continuous rv

$$F_X(x) = Pr(X \leq x) = \int_{-\infty}^x f_x(t) dt$$

$$f_X(t) = \frac{dF_X(t)}{dx}$$

- CDF is useful when transformation of a random variable

$$\begin{aligned} Y &= r(X) \quad r \text{ is a strictly increasing function} \\ F_Y(y) &= Pr(Y \leq y) \\ &= Pr(r(X) \leq y) \\ &= Pr(X \leq r^{-1}(y)) \\ &= F_X(r^{-1}(y)) \\ f_Y(y) &= f_X(r^{-1}(y)) * \frac{dr^{-1}(y)}{dy} \end{aligned}$$

2 Multivariates

2.1 Bivariates

2.1.1 Discrete bivariate

- joint pmf: $p_{X,Y}(x_i, y_j) = Pr(X = x_i, Y = y_j)$
- marginal pmf:

$$P_X(x_k) = \sum_{j=1}^n P_{X,Y}(x_k, y_j), \quad P_Y(y_k) = \sum_{i=1}^m P_{X,Y}(x_i, y_k)$$

- Independent if:

$$p_{X,Y}(x, y) = p_X(x)p_Y(y) \quad \text{for all } (x, y)$$

- Conditional Probability

$$p_{X|Y}(x|y) = \frac{p(X, Y)(x, y)}{P_Y(y)}$$

2.1.2 Continuous bivariate

- For continuous random variables X and Y , we call $f(x, y)$ their **Joint probability density function**:

- $\int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} f(x, y) dx \right) dy = 1$ and
- for any sets (events) $A \subset \mathbb{R}$ and $B \subset \mathbb{R}$

$$Pr(X \in A, Y \in B) = \int_{-\infty}^{\infty} \mathbb{I}_B(y) \left(\int_{-\infty}^{\infty} \mathbb{I}_A(x) f(x, y) dx \right) dy$$

- Independent

$$\text{If and only if: } f_{X,Y}(x, y) = f_X(x)f_Y(y)$$

- Conditional probability density function:

$$f_{X|Y}(x|y) = \frac{f(X, Y)(x, y)}{f_Y(y)}$$

Moreover, for all sets A

$$Pr(X \in A | Y = y) = \int_{-\infty}^{\infty} \mathbb{I}_A(x) f_{X|Y}(x|y) dx$$

Example: Let X_1, X_2 be two independent rvs with $f_1(x_1), f_2(x_2)$ and let $Y = X_1 + X_2$. Find the pdf $f_{X_1, Y}$ and f_Y .

Write the joint pdf using conditional pdf formula:

$$f_{X_1, Y}(x_1, y) = f_1(x_1) f_{Y|X_1}(y|x_1).$$

Since $Y = X_2 + x_1$, $f_{Y|X_1}(y|x_1) = f_2(y - x_1)$

$$f_Y(y) = \int_{-\infty}^{\infty} f_2(y - x_1) f_1(x_1) dx_1$$

which is the convolution of f_1 and f_2

2.1.3 Expected Value Operations

- Expectation

– Definition: The *Expected value* or *mean value* or *first moment* of X is

$$\mathbb{E}\{X\} = \begin{cases} \sum_x x p_X(x) & \text{Discrete} \\ \int_{-\infty}^{\infty} x f_X(x) dx & \text{Continuous} \end{cases}$$

- Expectation of a function of rv

- Definition: For any function $r(\cdot)$ compute $\mathbb{E}\{r(X)\}$ by replacing x in the above formulae with $r(x)$ For example, the higher moments are $\mathbb{E}(X^n)$ set $r(X) = X^n$
- Example: For an event A :

$$\mathbb{E}\{\mathbb{I}_A(X)\} = \begin{cases} \sum_x \mathbb{I}_A(x) p_X(x) & \text{Discrete} \\ \int_{-\infty}^{\infty} \mathbb{I}_A(x) f_X(x) dx & \text{Continuous} \end{cases}$$

Then $\mathbb{E}\{\mathbb{I}_A(X)\} = \Pr\{X \in A\}$

- Example: Take a unit length stick and break it at random. Find the mean of the long piece. Call the longer piece Y and the break point X . Then X is a uniform rv in $[0, 1]$, $Y = \max\{X, 1 - X\}$ and,

$$\begin{aligned} \mathbb{E}Y &= \mathbb{E}(\max\{X, 1 - X\}) \\ &= \int_{-\infty}^{\infty} \max\{x, 1 - x\} f_X(x) dx \\ &= \int_0^1 \max\{x, 1 - x\} dx \\ &= \int_0^{.5} (1 - x) dx + \int_{.5}^1 x dx = 0.75 \end{aligned}$$

- Expectation of a function of bivariate

- Definition: The mean of a function $r(X, Y)$ of the bivariate (X, Y) is

$$\mathbb{E}\{r(X, Y)\} = \begin{cases} \sum_y \sum_x r(x, y) p_{X,Y}(x, y) & \text{Discrete} \\ \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} r(x, y) f_{X,Y}(x, y) dx dy & \text{Continuous} \end{cases}$$

- The conditional expectation is

$$\mathbb{E}\{r(X, Y)|Y = y\} = \begin{cases} \sum_x r(x, y) p_{X|Y}(x|y) & \text{Discrete} \\ \int_{-\infty}^{\infty} r(x, y) f_{X|Y}(x|y) dx & \text{Continuous} \end{cases}$$

- By using conditional probability we can calculate $\mathbb{E}\{r(X, Y)\}$:

$$\begin{aligned} \mathbb{E}\{r(X, Y)\} &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} r(x, y) f_{X,Y}(x, y) dx dy \\ &= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} r(x, y) f_{X|Y}(x|y) dx \right) dy \\ &= \int_{-\infty}^{\infty} \mathbb{E}\{r(X, Y)|Y = y\} f_Y(y) dy \end{aligned}$$

- Rule of iterated expectation

Discrete:

$$\mathbb{E}\{r(X, Y)\} = \mathbb{E}(\mathbb{E}\{r(X, Y)|Y\})$$

Continuous:

$$\begin{aligned} \mathbb{E}\{r(X, Y)|Y = y\} &= \int_{-\infty}^{\infty} r(x, y) f_{X|Y}(x|y) dx \\ \mathbb{E}\{r(X, Y)\} &= \int_{-\infty}^{\infty} \mathbb{E}\{r(X, Y)|Y = y\} f_Y(y) dy \end{aligned}$$

2.2 Multivariates

2.2.1 Definition

- Let X_1, X_2, \dots, X_n be n continuous/discrete random variables. We call $X = (X_1, \dots, X_n) \in \mathbb{R}^n$ a continuous/discrete random vector.
- Let $X = (X_1, \dots, X_n) \in \mathbb{R}^n$ be a continuous random vector. Let $f(x_1, \dots, x_n)$ be a non-negative function that integrates to 1. Then f is called the pdf of the random vector X if

$$Pr(X_1 \in A_1, \dots, X_n \in A_n) = \int_{-\infty}^{\infty} \mathbb{I}_{A_n}(x_n) \dots \int_{-\infty}^{\infty} \mathbb{I}_{A_1}(x_1) f(x_1, \dots, x_n) dx_1 \dots dx_n$$

- pdf of X_i is obtained by integrating $f(x_1, \dots, x_n)$ over the full range except x_i :

$$f_{X_i}(x_i) = \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} f(x_1, \dots, x_n) dx_1 \dots dx_{i-1} dx_{i+1} \dots dx_n$$

This is called the i th marginal of $f(x_1, \dots, x_n)$

2.2.2 Independence

- Definition: The n random variables X_1, \dots, X_n are independent if and only if for every A_1, \dots, A_n

$$Pr(X_1 \in A_1, \dots, X_n \in A_n) = Pr(X_1 \in A_1) \dots Pr(X_n \in A_n)$$

- joint pdf = product of marginals:

$$f(x_1, \dots, x_n) = f_{X_1}(x_1) \dots f_{X_n}(x_n)$$

- Example: The pdf $f(x_1, \dots, x_n)$ of a Gaussian random vector $X = (X_1, \dots, X_n)$ is

$$\frac{1}{(2\pi)^{n/2} (\det C)^{1/2}} \exp \left\{ -\frac{1}{2} (x - m)^T C^{-1} (x - m) \right\}$$

Where $m = (m_1, \dots, m_n)$ is the row vector of means and C is the covariance matrix

$$m_i = \mathbb{E}\{X_i\} \quad \text{and} \quad [C]_{i,j} = \mathbb{E}\{(X_i - m_i)(X_j - m_j)\}$$

Show that if independent, $C_{i,j} = 0$ for $i \neq j$ then

$$f(x_1, \dots, x_n) = f_{X_1}(x_1) \dots f_{X_n}(x_n)$$

Proof: Call $C_{i,i} = \sigma_i^2$

$$(x - m)^T C^{-1} (x - m) = \sum_{i=1}^n \frac{(x_i - m_i)^2}{\sigma_i^2}$$

Hence $f(x_1, \dots, x_n)$ is

$$\begin{aligned} & \frac{1}{(2\pi)^{n/2} (\det C)^{1/2}} \exp \left\{ -\frac{1}{2} \sum_{i=1}^n \frac{(x_i - m_i)^2}{\sigma_i^2} \right\} \\ &= \frac{1}{\sqrt{(2\pi)\sigma_1} \dots \sqrt{(2\pi)\sigma_n}} \prod_{i=1}^n \exp \left\{ -\frac{1}{2} \frac{(x_i - m_i)^2}{\sigma_i^2} \right\} \\ &= f_{X_1}(x_1) \dots f_{X_n}(x_n) \end{aligned}$$

- If X_1, \dots, X_n are independent then

$$\mathbb{E}\left\{\prod_{i=1}^n X_i\right\} = \prod_{i=1}^n \mathbb{E}\{X_i\}$$

That is the expectation of the product is the product of expectation

2.2.3 Change of variables

- The change of variable formula can be applied to random vectors. Let

$$\begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} g_1(X_1, \dots, X_n) \\ \vdots \\ g_n(X_1, \dots, X_n) \end{bmatrix}$$

or

$$Y = G(X)$$

- If G is invertible then $X = G^{-1}(Y)$. Let $H(Y) = G^{-1}(Y)$. So

$$\begin{bmatrix} X_1 \\ \vdots \\ X_n \end{bmatrix} = \begin{bmatrix} h_1(Y_1, \dots, Y_n) \\ \vdots \\ h_n(Y_1, \dots, Y_n) \end{bmatrix}$$

- The *Jacobian* matrix of partial derivatives of $H(y)$ is formed:

$$J(y) = \begin{bmatrix} \frac{\partial}{\partial y_1} h_1 & \dots & \frac{\partial}{\partial y_n} h_1 \\ \vdots & & \vdots \\ \frac{\partial}{\partial y_1} h_n & \dots & \frac{\partial}{\partial y_n} h_n \end{bmatrix}$$

Then

$$f_Y(y) = f_X(H(y)) |\det J(y)|$$

- Example: Let X_1, \dots, X_n be independent Gaussian rv where X_i is $\mathcal{N}(0, 1)$ Let S be an invertible matrix and m a column vector. Let $Y = m + SX$ where $X = (X_1, \dots, X_n)^T$. Show Y is also a Gaussian random vector.

Use the Change of variable result:

$$H(Y) = S^{-1}(Y - m)$$

The Jacobian Matrix $J(y)$:

$$J(y) = S^{-1}$$

Applying change of variable formula gives

$$f_Y(y) = f_X(S^{-1}(y - m)) |\det S^{-1}|$$

where $f_X(x_1, \dots, x_n) = \frac{1}{(2\pi)^{n/2}} \exp\left\{-\frac{1}{2}x^T x\right\}$

$$f_Y(y) = \frac{|\det S^{-1}|}{(2\pi)^{n/2}} \exp\left\{-\frac{1}{2}(y - m)^T (S^{-1})^T S^{-1}(y - m)\right\}$$

is the density of a Gaussian vector with mean m and covariance matrix SS^T . Note that $\det S^{-1} = 1/\det S$, $\det(SS^T) = \det S \det S^T = (\det S)^2$

- An affine transformation of a Gaussian vector is still a Gaussian vector. This gives a method for generating any Gaussian vector from iid Gaussian random variables.
- To Generate a $\mathcal{N}(m, \Sigma)$ vector:
 - * Decompose the symmetric matrix $\Sigma = SS^T$.
 - * Output $m + SX$ where $X = (X_1, \dots, X_n)^T$ where X_1, \dots, X_n are independent $\mathcal{N}(0, 1)$

2.2.4 Characteristic function

- Definition: The characteristic function of a discrete or continuous random variable X is:

$$\varphi_X(t) = \mathbb{E}\{\exp(itX)\}, \quad t \in \mathbb{R}$$

For a random vector $X = (X_1, X_2, \dots, X_n)$,

$$\varphi_X(t) = \mathbb{E}\{\exp(it^T X)\}, \quad t \in \mathbb{R}^n$$

Similarly to Fourier Transform, the characteristic function uniquely describes a pdf.

- Example: Show $\varphi_X(t) = \exp(it\mu) \exp(-\frac{1}{2}\sigma^2 t^2)$ when X is a Gaussian random variable with mean μ and variance σ^2 .

$$\begin{aligned} & \mathbb{E}\{\exp(itX)\} \\ &= \int_{-\infty}^{\infty} e^{itx} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right) dx \\ &= e^{it\mu} \int_{-\infty}^{\infty} e^{its} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2\sigma^2}s^2\right) ds, \quad \text{let } s = x - \mu \\ &= e^{it\mu} e^{-\frac{1}{2}\sigma^2 t^2} \quad \text{Fourier transform table} \end{aligned}$$

- Example: Compute the characteristic function $\varphi_Y(t)$ of $Y = \sum_{i=1}^n X_i$ where X_i are [independent](#) random variables.

$$\begin{aligned} & \mathbb{E}\{\exp(itY)\} \\ &= \mathbb{E}\{\exp(itX_1) \exp(itX_2) \dots \exp(itX_n)\} \\ &= \mathbb{E}\{\exp(itX_1)\} \mathbb{E}\{\exp(itX_2)\} \dots \mathbb{E}\{\exp(itX_n)\} \\ &= \varphi_{X_1}(t) \dots \varphi_{X_n}(t) \end{aligned}$$

The characteristic function of the [sum of independent random variables](#) is the [product](#) of their individual characteristic functions.

- Example: (Moments) Using $\varphi_X(t)$, compute $\mathbb{E}\{X^n\}$