HW3: MATH/CSCI-4800-02 Numerical Computing

- 1. Text problem on p.43: problem 8. (if you use 2nd edition of the book, it is problem 8 on p. 41).
- 2. Find each fixed point of $g(x) = x^2 \frac{3}{2}x + \frac{3}{2}$ and decide whether fixed point iteration is locally convergent to it.
- 3. Express $2x^3 x + e^x = 0$ as a fixed point problem x = g(x) in three different ways.
- 4. Text problem on p.44: problem 14 (refer to Definition 1.5 in the textbook for the linear convergence rate S, as well as Theorem 1.6).

 (if you use 2nd edition of the book, it is problem 14 on p.41).
- 5. Text problem on p.121: problem 2(c). (if you use 2nd edition of the book, it is problem 2(c) on p.116.).
- 6. This is to revisit some examples and theories discussed in class. To solve Ax = b, where

$$A = \begin{bmatrix} 3 & 1 \\ 1 & 2 \end{bmatrix}. \tag{1}$$

Note that this A is strictly diagonally dominant. It is known that both Jacobi and Gauss-Seidel methods lead to iterative methods in the following form

$$x^{k+1} = Bx^k + d, (2)$$

for some $B \in \mathbb{R}^{2 \times 2}$ and $d \in \mathbb{R}^2$.

For each of Jacobi and Gauss-Seidel methods, answer the following. You can either calculate by hand or use Matlab.

- What is B?
- What is the spectral radius $\rho(B)$ of B. Here $\rho(B) = \max(|\lambda_1|, |\lambda_2|)$ where λ_1, λ_2 are the two eigenvalues of B. (If you want to calculate using matlab, you may find eigs useful.)
- From the value of $\rho(B)$, decide whether the corresponding scheme (2) converges or diverges.
- Repeat the three questions above for the following A,

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix}. \tag{3}$$

Note that this A is not strictly diagonally dominant.

7. Recommended Reading: Section 2.5.2 about SOR method (this is not covered in the exam), and the comparison of three methods in Example 2.24.