# CIVIL-557

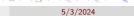
# Decision-aid methodologies in transportation

Review II Branch-and-Price

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### VRP Set-partitioning formulation

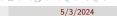
### Master problem (MP)

$$Minimize \sum_{r \in \Omega} c_r \lambda_r \tag{1}$$

$$s.t. \sum_{r \in \Omega} a_{ir} \lambda_r = 1 \qquad \forall i \in N,$$
 (2)

$$\lambda_r \in \{0,1\}$$
  $\forall r \in \Omega.$ 





#### Restricted Master Problem

### What is the **RMP**? optimal if reduced cost are non negative

- The set  $\Omega$  is too big ( $\approx (|N|-1)!$ ).
- Lets consider a smaller set of variables, e.g.,  $P \subset \Omega$
- Where |P| is a small number, i.e., not exponential.
- The following model is the Restricted Master Problem (RMP):

$$(\mathsf{RMP}) \qquad \qquad \sum_{r \in P} c_r \lambda_r$$
 
$$s.t. \ \sum_{r \in P} a_{ir} \lambda_r = 1 \qquad \qquad \forall i \in N,$$
 
$$1 \geq \lambda_r \geq 0 \qquad \qquad \forall r \in P.$$

5/3/2024

## Optimal solution of the MP

When does the MP = RMP?

#### Optimal if the reduced costs of NB varibles is non negative

- Recall that a basic solution is optimal if there are no non-basic variables ( $\lambda_{NB}$ ) with a negative reduced cost.
- We must find non-basic variables (i.e., routes) that have a negative reduced cost to add to the set *P* and reoptimize.
- If we can proof that all non-basic variables have a non-negative reduced cost, the current basic solution of the RMP is also optimal for the MP and we do not have to search for more variables.

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## Minimum reduced cost route (Pricing problem)

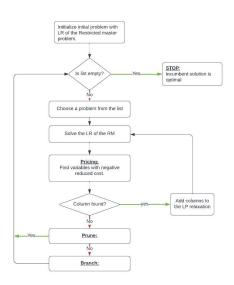
Elemetary Shortest Path Problem with Resource Constraints (ESPPRC)

$$\begin{aligned} &\mathit{Min} \sum_{i \in V} \sum_{j \in V} \hat{c}_{ij} x_{ij} \\ &\mathit{s.t.} \sum_{i \in N} q_i \sum_{j \in V} x_{ij} \leq Q, \\ &\sum_{j \in N} x_{0j} = 1, \\ &\sum_{i \in V} x_{i0} = 1, \\ &\sum_{i \in N} x_{ih} - \sum_{j \in N} x_{hj} = 0 & \forall h \in N, \\ &T_i + t_{ij} - M_{ij} (1 - x_{ij}) \leq T_j & \forall i, j \in V, \\ &a_i \leq T_i \leq b_i & \forall i \in N, \\ &x_{ij} \in \{0,1\} & \forall i, j \in N. \end{aligned}$$

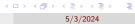
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### B&P







#### Feasible solutions

#### **Dummy variable**

$$\begin{aligned} & \min \ M \lambda_D \\ & s.t. \ \lambda_D = 1 & \forall i \in \textit{N}, \\ & 1 \geq \lambda_D \geq 0 \end{aligned}$$

Add more variables that satisfy constraints to the model to make  $\lambda_D=0$ . If  $\lambda_D=0$  is not possible, then, the problem is infeasible.





### Branching

**Branching** on the variables of the master problem  $(\lambda)$  makes the pricing problem more difficult to solve at each branch.

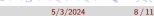
$$\lambda^j = 0$$

ESPPRC and Forbidden Paths. Every time we set a variable  $\lambda$  to 0, we must make sure the the path is not produced by the pricing problem

### $\lambda^{j}=1$

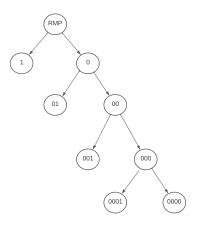
The path "i" has to be in the solution, thus, we can eliminate the customers that are visited in j and have an easier problem to solve. The ESPPRC becomes smaller since the number of customers to visit is reduced.





## **Branching**

**Unbalanced binary tree:** Branching on variables makes the binary tree unbalanced since most paths are not in the optimal solution. Setting  $\lambda=0$  is not significant.







### Pricing problem

#### ESPPRC and Forbidden Paths.

$$\begin{aligned} & \textit{Min} \sum_{i \in V} \sum_{j \in V} \hat{c}_{ij} x_{ij} \\ & \textit{s.t.} \sum_{i \in N} q_i \sum_{j \in V} x_{ij} \leq Q, \\ & \sum_{j \in N} x_{0j} = 1, \\ & \sum_{i \in V} x_{i0} = 1, \\ & \sum_{i \in V} x_{ih} - \sum_{j \in N} x_{hj} = 0 & \forall h \in N, \\ & \sum_{i \in N} x_{i,j} \leq |\mathcal{P}| - 1 \leftarrow \textit{Forbiddenpath} & \forall \mathcal{P} \in \mathcal{B}, \\ & \sum_{i \in N} x_{i,j} \leq |\mathcal{P}| - 1 \leftarrow \textit{Forbiddenpath} & \forall \mathcal{P} \in \mathcal{B}, \\ & \sum_{i \in N} x_{i,j} \leq |\mathcal{P}| - 1 \leftarrow \textit{Forbiddenpath} & \forall \mathcal{P} \in \mathcal{B}, \\ & \sum_{i \in N} x_{i,j} \leq |\mathcal{P}| - 1 \leftarrow \textit{Forbiddenpath} & \forall i,j \in V, \\ & a_i \leq T_i \leq b_i & \forall i \in N, \\ & x_{ij} \in \{0,1\} & \forall i,j \in N. \end{aligned}$$

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## Branching

### Option

**Branch:** On  $x_{ij}$  variables instead.

- At each node of the branch-and-bound tree set the corresponding variables to 1 or 0, and solve the pricing problem.
- The pricing problem will not produce routes that contain the variables that are set to 0.





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