Monte Carlo Tree Search

Algorithm 1 Monte Carlo Tree Search

```
1: function MCTS(s_{root})
         while within computational budget do
             s \leftarrow \text{TreePolicy}(s_{root})
 3:
             winner\leftarrowDefaultPolicy(s)
 4:
 5:
             Backup(s, winner)
        end while
 6:
        return Action(\operatorname{argmax}_{s' \in \operatorname{children}(s_{root})} \frac{Q(s')}{N(s')})
 7:
    end function
 8:
9:
    function TreePolicy(s)
10:
        while s is not terminal do
11:
12:
            if s is not fully expanded then
                 return Expand(s)
13:
             else
14:
                 s \leftarrow \text{BestChild(s)}
15:
            end if
16:
        end while
17:
        return s
18:
19: end function
20:
21: function EXPAND(s)
        child \leftarrow previously unexpanded child of s
22:
         Update the tree with (s, child)
23:
24:
        return child
25: end function
26:
27: function BestChild(s)
        return \operatorname{argmax}_{s' \in \operatorname{children}(s)} \left( \frac{Q(s')}{N(s')} + c \sqrt{\frac{\ln N(s)}{N(s')}} \right)
28:
29: end function
30:
31: function DefaultPolicy(s)
32:
        while s is not terminal do
             s \leftarrow \text{random child of } s
33:
34.
        end while
        return winner
35:
36: end function
37:
38: function Backup(s, winner)
         while s is not Null do
                                                                                                         ▶ Parent of root is Null
39:
             N(s) \leftarrow N(s) + 1
40:
             Q(s) \leftarrow Q(s) + \Delta(s, winner)
                                                                 \triangleright Update winning count based on who's in control of s
41:
             s \leftarrow \operatorname{parent}(s)
42:
        end while
43:
44: end function
```

In the simplest form, $\Delta(s, winner)$ is 1 if the player in **control of** s (i.e., s is the outcome of that player's action) has won in the rollout, and 0 otherwise.